

# HAOFEI HOU

📞 +86-18054399790 📩 yuechuhaoxi020609@outlook.com 🌐 <https://yuechuhaoxi020609.github.io/>

## EDUCATION

### Peking University

*School of Mechanics and Engineering Science, Mechanical Engineering*

Sept 2024 – Present

Beijing

### Huazhong University of Science and Technology

*School of Software Engineering, Software Engineering - 93.87 - (1/120)*

Sept 2020 – Jun 2024

Wuhan, Hubei

## RESEARCH INTERESTS

My academic work centers on natural language processing and robotics, especially the structural representation of complex human instructions and its applications. I am interested in the planning and execution of lab automation with structured knowledge and instructions, and in integrating them with vision-language-action models.

## PUBLICATIONS

### BioPIE: A Biomedical Protocol Information Extraction Dataset for High-Reasoning-Complexity Experiment Question Answer ↗ 01 2026

- **Haofei Hou\***, Shunyi Zhao\*, Fanxu Meng\*, Kairui Yang, Lecheng Ruan, Qining Wang (Equal contribution\*).
- We introduce Biomedical Protocol Information Extraction Dataset (BioPIE), a dataset that provides procedure-centric KGs of experimental entities, actions, and relations that supports reasoning over biomedical experiments.
- We evaluate information extraction methods on BioPIE, and implement a QA system that leverages BioPIE, showcasing performance gains. *Under submission to ACL'26*

### Human-Inspired Linear Temporal Logic Translation via Constrained Learning 11 2025

- Fanxu Meng\*, **Haofei Hou\***, Kairui Yang, Mengchen Cai, Lecheng Ruan, Qining Wang (Equal contribution\*).
- We proposed an framework for translating natural language instructions into LTL specifications by integrating constraints extracted from parallel corpora. *Under submission to IJRR*

### Expert-level protocol translation for self-driving labs ↗ 09 2024

- Yu-Zhe Shi\*, Fanxu Meng\*, **Haofei Hou\***, Zhangqian Bi, Qiao Xu, Lecheng Ruan, Qining Wang (Equal contribution\*).
- We automate the protocol translation process through a three-stage workflow.
- We incrementally construct Protocol Dependence Graphs (PDGs) that approach structured in the syntax level, completed in the semantics level, and linked in the execution level. *NeurIPS'24*

### AutoDSL: Automated domain-specific language design for structural representation of procedures with constraints 05 2024

- Yu-Zhe Shi\*, **Haofei Hou\***, Zhangqian Bi, Fanxu Meng, Lecheng Ruan, Qining Wang (Equal contribution\*).
- We automate DSL-based action constraint design across protocols from various domains
- Constraints include syntactic constraints and abstracts semantic constraints.
- Quantitative and qualitative analyses of the DSLs highlights its potential as an auxiliary module for language models, aiming to improve procedural planning and execution. *ACL'24*

## PROJECTS

### A Marker-Free Motion Capture System Built on Unsyncronized Cameras ↗ 09 2025

- **Haofei Hou\***, Shunyi Zhao\*, Zuxin Fan, Wei Jin, Lecheng Ruan, Qining Wang (Equal contribution\*).
- We propose a marker-free MoCap system that is built on unsynchronized cameras. Our system introduces two crucial components: multi-view temporal post-processing and temporal augmentation training. *ICIRA'25*

### Prosthetic Control by Learning: A Multi-Agent Cooperative Game Framework ↗ 04 2025

- **Haofei Hou\***, Wenduo Zhu\*, Lecheng Ruan, Qining Wang (Equal contribution\*).
- We develop a model-free reinforcement learning framework that enables the prosthesis to adapt to diverse human movement patterns through cooperative policy learning. *ICORR'25*

### Abductive task abstractions in physical problem-solving | CoCoSci, Meta-RL, Web 10 2022

- Web-based game development: Built an interactive web-based problem-solving game environment (ProbSol) for studying task abstraction under controlled goals and constraints.
- Human behavioral experiments: Designed and conducted human-subject experiments.
- Maskable MetaQ Learning: Proposed a maskable MetaQ learning framework and demonstrated that gradient-based RL (MetaQ, PPO) fails to generate task abstraction, in contrast to human behavior and imitation learning agents.

## TECHNICAL SKILLS

**Languages:** Python, Numpy, Java, C, SQL

**Technologies/Frameworks:** Figma, Pytorch, Linux

## CERTIFICATIONS

### National Olympiad in Informatics in Provinces (NOIP)

*First Prize in Shandong Province*

12 2017

### Undergraduate National Scholarship Honors

12 2021