
Lab 3A: Eye See You

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Review

Least-Squares Fitting (Linear)

- If we have n points $(x_1, y_1), (x_2, y_2), \dots, (x_n, y_n)$ and need to find the approach linear function to fit these n points, we can use “least-squares fitting” to solve.

Least-Squares Fitting (Linear)

- Suppose these linear function is $y = ax + b$ and fit $(x_1, y_1), \dots, (x_n, y_n)$. The method of least-squares fitting is try to solve the following equation.

$$\min_{a,b} \left\| \begin{pmatrix} 1 & x_1 \\ \cdot & \cdot \\ \cdot & \cdot \\ \cdot & \cdot \\ 1 & x_n \end{pmatrix} \begin{pmatrix} b \\ a \end{pmatrix} - \begin{pmatrix} y_1 \\ \cdot \\ \cdot \\ \cdot \\ y_n \end{pmatrix} \right\|_2 = \min_b \|Ab - Y\|_2$$

Hands On

Goal (Non-Linear)

- You will get the several points (x, y) from your own image.

$$x = f(t) \quad y = g(t)$$

- You will also use the following periodic functions for the least-squares fitting.

$$f(t) = b_1 + b_2 \cos(2\pi t) + b_3 \cos(4\pi t) + b_4 \cos(6\pi t) + b_5 \sin(2\pi t) + b_6 \sin(4\pi t) + b_7 \sin(6\pi t)$$

$$g(t) = c_1 + c_2 \cos(2\pi t) + c_3 \cos(4\pi t) + c_4 \cos(6\pi t) + c_5 \sin(2\pi t) + c_6 \sin(4\pi t) + c_7 \sin(6\pi t)$$

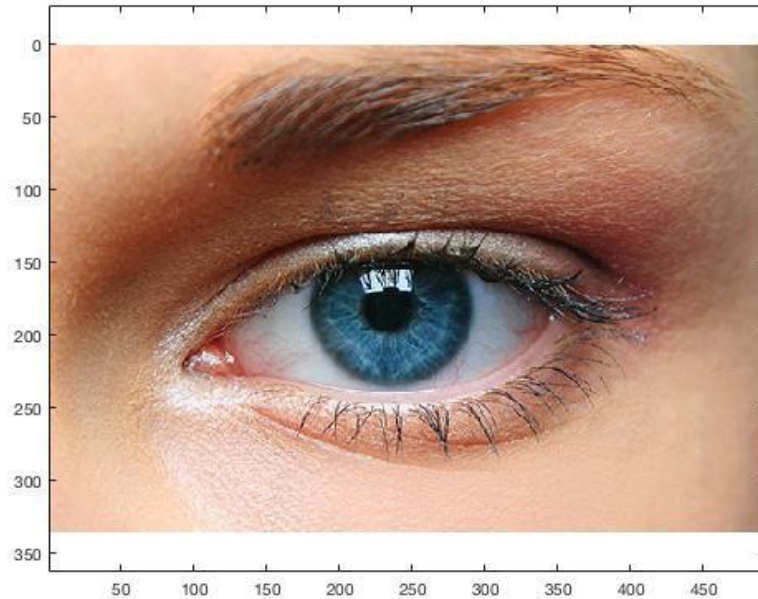
Preparation

- Please download the file “Lab3A_Eye_See_You.zip” in the folder “Homeworks” (Google Drive).
- Use the file “EyeSeeYou.m” to do the following steps.

Step 1

- Using your phone, take a picture of an open eye.
- Load the image into MATLAB using `imread` and display this image.

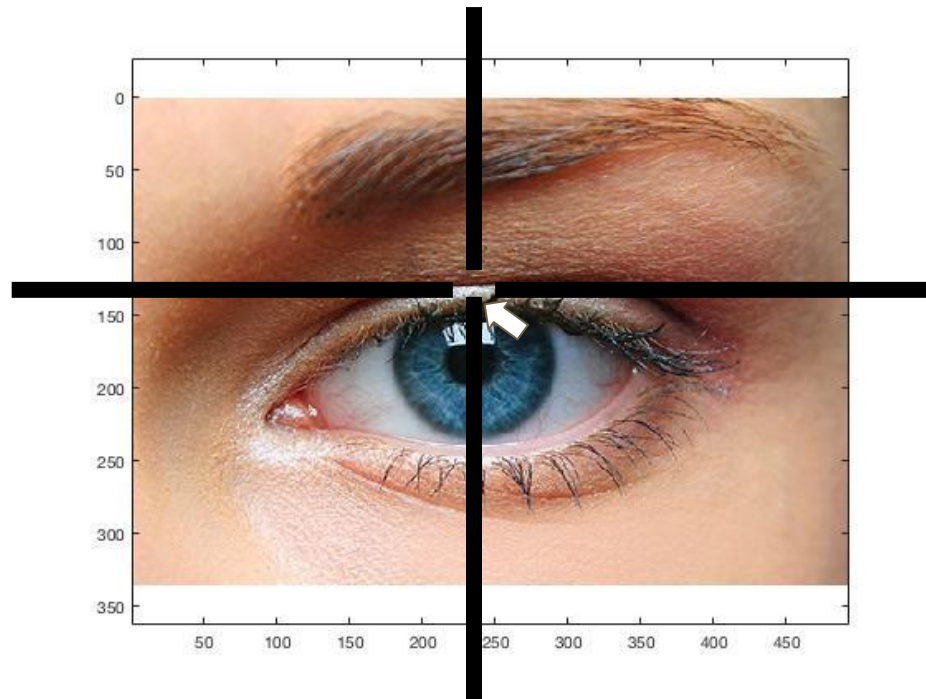
Step 1



Step 2

- Using the command `ginput(10)`, collect the upper 10 points of your eye **from right to left**.

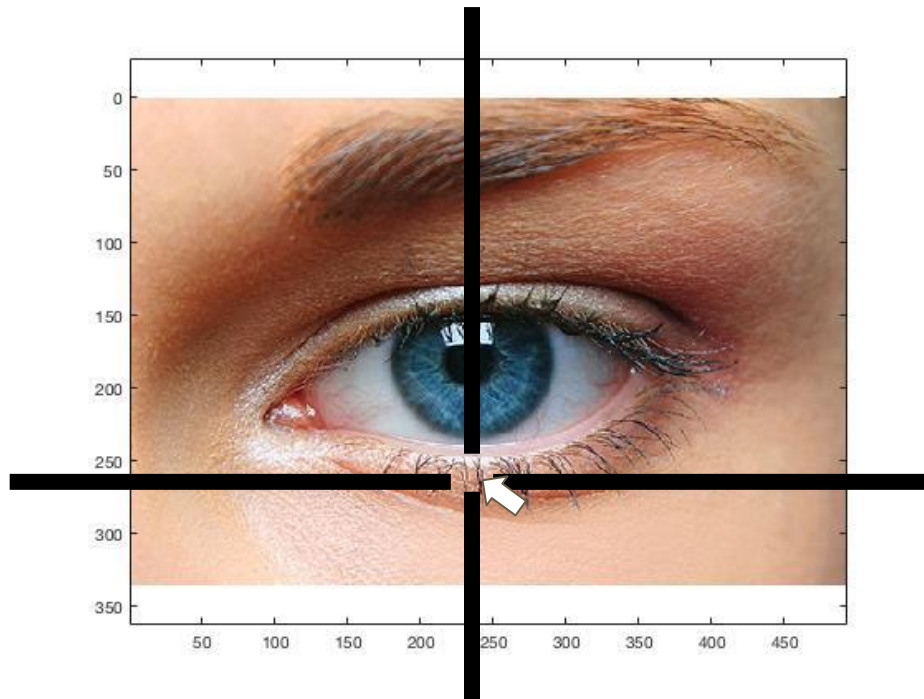
Step 2



Step 3

- Repeat step 2, using the command `ginput(10)`, collect the lower **10** points of your eye **from left to right**.

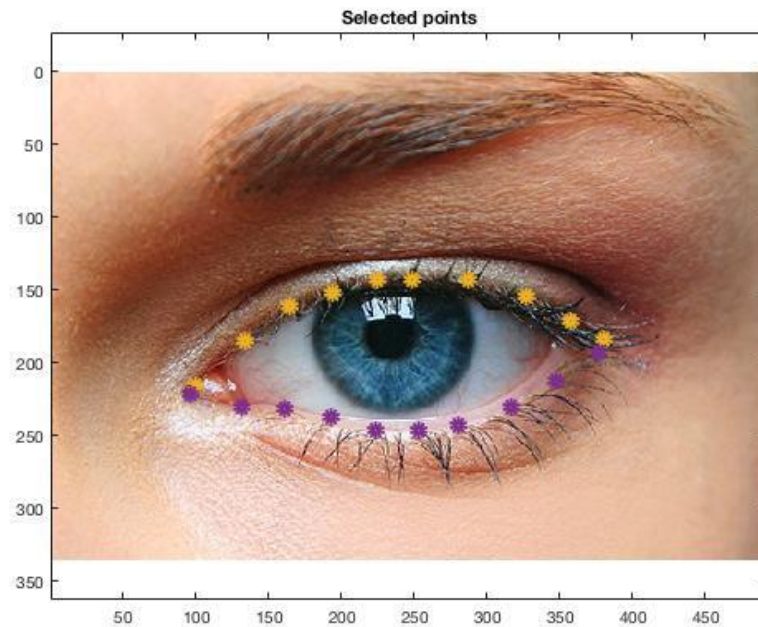
Step 3



Step 4

- Stack x_{up} and x_{lo} into a vector x , and stack y_{up} and y_{lo} into a vector y .
- Plot the points using 'o' markers.

Step 4



Step 5

- Now let \mathbf{t} be a vector where $t_i = (i - 1)/20$ for $i = 1, \dots, 20$. Referring back to equation, create a 20×7 matrix \mathbf{A} whose columns are the values of the functions $1, \cos(2\pi t)$, and so on, through $\sin(6\pi t)$.

(2):

$$f(t) = b_1 + b_2 \cos(2\pi t) + b_3 \cos(4\pi t) + b_4 \cos(6\pi t) + b_5 \sin(2\pi t) + b_6 \sin(4\pi t) + b_7 \sin(6\pi t)$$

(3):

$$g(t) = c_1 + c_2 \cos(2\pi t) + c_3 \cos(4\pi t) + c_4 \cos(6\pi t) + c_5 \sin(2\pi t) + c_6 \sin(4\pi t) + c_7 \sin(6\pi t)$$

Step 5

t =

0
0.0500
0.1000
0.1500
0.2000
0.2500
0.3000
0.3500
0.4000
0.4500
0.5000
0.5500
0.6000
0.6500
0.7000
0.7500
0.8000
0.8500
0.9000
0.9500

A =

| | | | | | | |
|--------|---------|---------|---------|---------|---------|---------|
| 1.0000 | 1.0000 | 1.0000 | 1.0000 | 0 | 0 | 0 |
| 1.0000 | 0.9511 | 0.8090 | 0.5878 | 0.3090 | 0.5878 | 0.8090 |
| 1.0000 | 0.8090 | 0.3090 | -0.3090 | 0.5878 | 0.9511 | 0.9511 |
| 1.0000 | 0.5878 | -0.3090 | -0.9511 | 0.8090 | 0.9511 | 0.3090 |
| 1.0000 | 0.3090 | -0.8090 | -0.8090 | 0.9511 | 0.5878 | -0.5878 |
| 1.0000 | 0.0000 | -1.0000 | -0.0000 | 1.0000 | 0.0000 | -1.0000 |
| 1.0000 | -0.3090 | -0.8090 | 0.8090 | 0.9511 | -0.5878 | -0.5878 |
| 1.0000 | -0.5878 | -0.3090 | 0.9511 | 0.8090 | -0.9511 | 0.3090 |
| 1.0000 | -0.8090 | 0.3090 | 0.3090 | 0.5878 | -0.9511 | 0.9511 |
| 1.0000 | -0.9511 | 0.8090 | -0.5878 | 0.3090 | -0.5878 | 0.8090 |
| 1.0000 | -1.0000 | 1.0000 | -1.0000 | 0.0000 | -0.0000 | 0.0000 |
| 1.0000 | -0.9511 | 0.8090 | -0.5878 | -0.3090 | 0.5878 | -0.8090 |
| 1.0000 | -0.8090 | 0.3090 | 0.3090 | -0.5878 | 0.9511 | -0.9511 |
| 1.0000 | -0.5878 | -0.3090 | 0.9511 | -0.8090 | 0.9511 | -0.3090 |
| 1.0000 | -0.3090 | -0.8090 | 0.8090 | -0.9511 | 0.5878 | 0.5878 |
| 1.0000 | -0.0000 | -1.0000 | 0.0000 | -1.0000 | 0.0000 | 1.0000 |
| 1.0000 | 0.3090 | -0.8090 | -0.8090 | -0.9511 | -0.5878 | 0.5878 |
| 1.0000 | 0.5878 | -0.3090 | -0.9511 | -0.8090 | -0.9511 | -0.3090 |
| 1.0000 | 0.8090 | 0.3090 | -0.3090 | -0.5878 | -0.9511 | -0.9511 |
| 1.0000 | 0.9511 | 0.8090 | 0.5878 | -0.3090 | -0.5878 | -0.8090 |

Step 6

- Apply linear least squares (using backslash) to solve for the coefficients b_j in (2) using the x data, and to solve for the coefficients c_j in (3) using the y data.

(2):

$$f(t) = b_1 + b_2 \cos(2\pi t) + b_3 \cos(4\pi t) + b_4 \cos(6\pi t) + b_5 \sin(2\pi t) + b_6 \sin(4\pi t) + b_7 \sin(6\pi t)$$

(3):

$$g(t) = c_1 + c_2 \cos(2\pi t) + c_3 \cos(4\pi t) + c_4 \cos(6\pi t) + c_5 \sin(2\pi t) + c_6 \sin(4\pi t) + c_7 \sin(6\pi t)$$

Step 7

- Evaluate the functions in (2) and (3) at 500 equally spaced values of t between 0 and 1.
- On top of the axes showing the eye image and the selected points, and using the coefficients from the previous step, plot the curve defined by equation (1).

(1):

$$x = f(t) \quad y = g(t)$$

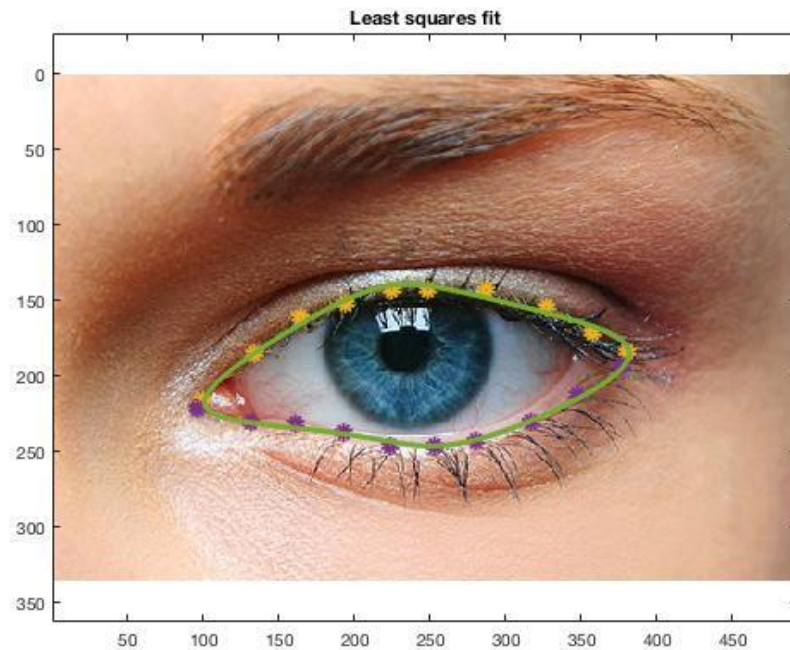
(2):

$$f(t) = b_1 + b_2 \cos(2\pi t) + b_3 \cos(4\pi t) + b_4 \cos(6\pi t) + b_5 \sin(2\pi t) + b_6 \sin(4\pi t) + b_7 \sin(6\pi t)$$

(3):

$$g(t) = c_1 + c_2 \cos(2\pi t) + c_3 \cos(4\pi t) + c_4 \cos(6\pi t) + c_5 \sin(2\pi t) + c_6 \sin(4\pi t) + c_7 \sin(6\pi t)$$

Step 7



Homework

- Please write the report on A4 pages and hand in at 4:30 pm on 2018/10/29 (Monday).

What We Learned?

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- How to use MATLAB to solve the “nonlinear least-squares fitting” problem from a practical example.

Questions or comments?