# Quantum error correction III:

Introduction to stabilizers

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Let's start with some notation, we need signed tensor product of the matrices:

$$I=egin{pmatrix} 1&0\0&1 \end{pmatrix}, X=egin{pmatrix} 0&1\1&0 \end{pmatrix}, Y=egin{pmatrix} 0&-i\i&0 \end{pmatrix}, Z=egin{pmatrix} 1&0\0&-1 \end{pmatrix}$$

eq: 
$$-X\otimes I\otimes Z\otimes Z\otimes Y$$

or more compactly: -XIZZY

A signed tensor product will also simply be called an operator

The simplest stabilizers are just operators that leave some useful state unchanged, eg:

$$Z|0
angle = |0
angle \ -Z|1
angle = |1
angle \ X|+
angle = |+
angle \ -X|-
angle = |-
angle$$

These states are called eigenstates of their associated stabilizer, and are unique up to global phase given the stabilizer

The simplest stabilizers are just operators that leave some useful state unchanged, eg:

$$egin{aligned} Z|0
angle &= |0
angle \ -Z|1
angle &= |1
angle \ X|+
angle &= |+
angle \ -X|-
angle &= |-
angle \end{aligned} \qquad egin{aligned} |0
angle 
ightarrow +Z \ |1
angle 
ightarrow -Z \ |+
angle 
ightarrow +X \ |-
angle 
ightarrow -X \end{aligned}$$

Since the eigenstates are uniquely specified by the stabilizers, we can write them instead of the states.

Consider 
$$|\Psi
angle=rac{1}{\sqrt{2}}(|000
angle+|111
angle)$$

This state is stabilized by 3 independent stabilizers +ZZI +IZZ

For complex states, the list of independent stabilizers can be far more compact than the state itself

+XXX

# Some algebra

Let's work through one example of showing a stabilizer stabilizes a state:

$$egin{aligned} ZZI|\Psi
angle &= rac{1}{\sqrt{2}}ZZI(|000
angle + |111
angle) \ &= rac{1}{\sqrt{2}}(ZZI|000
angle + ZZI|111
angle) \ &= rac{1}{\sqrt{2}}\Big(|000
angle + (-1)^2|111
angle\Big) \ &= rac{1}{\sqrt{2}}(|000
angle + |111
angle) \ &= |\Psi
angle \end{aligned}$$

### What about errors?

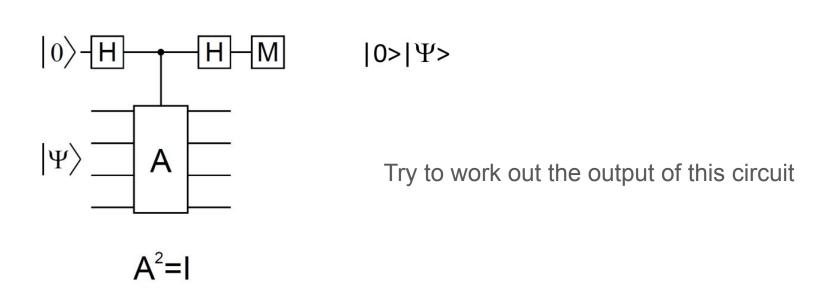
Consider the effect of errors: 
$$X_2 |\Psi
angle = rac{1}{\sqrt{2}}(|100
angle + |011
angle)$$

What does this do to our stabilizers? 
$$Z_2Z_1X_2|\Psi
angle=Z_2X_2Z_1|\Psi
angle =-X_2Z_2Z_1|\Psi
angle =-X_2|\Psi
angle$$

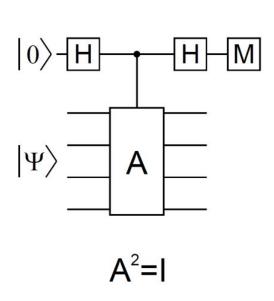
To say the same thing another way: 
$$(-Z_2Z_1)X_2|\Psi
angle=X_2|\Psi
angle$$
 or:  $-$ ZZI  $+$ IZZ

If we can work out how to measure the sign of a stabilizer, we can detect errors.

# General operator measurement



# General operator measurement



$$\begin{split} |0\rangle|\Psi\rangle \\ & \text{H} \rightarrow \frac{1}{\sqrt{2}}(|0\rangle + |1\rangle)|\Psi\rangle \\ &= \frac{1}{\sqrt{2}}(|0\rangle|\Psi\rangle + |1\rangle|\Psi\rangle) \\ \text{controlled-A} \rightarrow \frac{1}{\sqrt{2}}(|0\rangle|\Psi\rangle + |1\rangle A|\Psi\rangle) \\ & \text{H} \rightarrow \frac{1}{\sqrt{2}}\left(\frac{1}{\sqrt{2}}(|0\rangle + |1\rangle)|\Psi\rangle + \frac{1}{\sqrt{2}}(|0\rangle - |1\rangle)A|\Psi\rangle\right) \\ &= \frac{1}{\sqrt{2}}\left(|0\rangle\frac{1}{\sqrt{2}}(|\Psi\rangle + A|\Psi\rangle) + |1\rangle\frac{1}{\sqrt{2}}(|\Psi\rangle - A|\Psi\rangle)\right) \end{split}$$

A zero measurement means the output is the +1 eigenstate of A, one means -1 eigenstate

### Locating an error with stabilizers

$$X_2|\Psi
angle = rac{1}{\sqrt{2}}(|100
angle + |011
angle) -$$

$$|X_1|\Psi
angle=rac{1}{\sqrt{2}}(|010
angle+|101
angle).$$

$$|X_0|\Psi
angle=rac{1}{\sqrt{2}}(|001
angle+|110
angle)$$

What will the signs of the stabilizers be after these errors?

# Locating an error with stabilizers

$$X_2|\Psi
angle=rac{1}{\sqrt{2}}(|100
angle+|011
angle) -$$

$$X_0|\Psi
angle = rac{1}{\sqrt{2}}(|001
angle + |110
angle) -$$
rzz

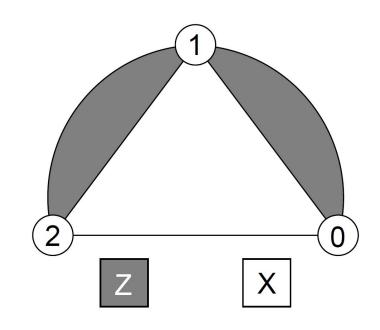
# Representing stabilizers as a picture

$$|\Psi
angle=rac{1}{\sqrt{2}}(|000
angle+|111
angle)$$

+XXX

+ZZI

+IZZ



These are all the same state. What happens after a Z error?

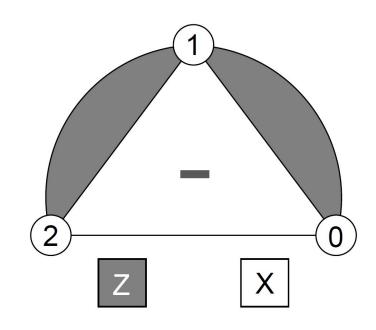
# Representing stabilizers as a picture

$$|Z|\Psi
angle=rac{1}{\sqrt{2}}(|000
angle-|111
angle)$$

-XXX

+ZZI

+IZZ



X stabilizer is flipped.

Next time: the surface code