

Demystifying projection heads in contrastive learning: an expansion and shrinkage perspective



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Contrastive learning for unsupervised classification

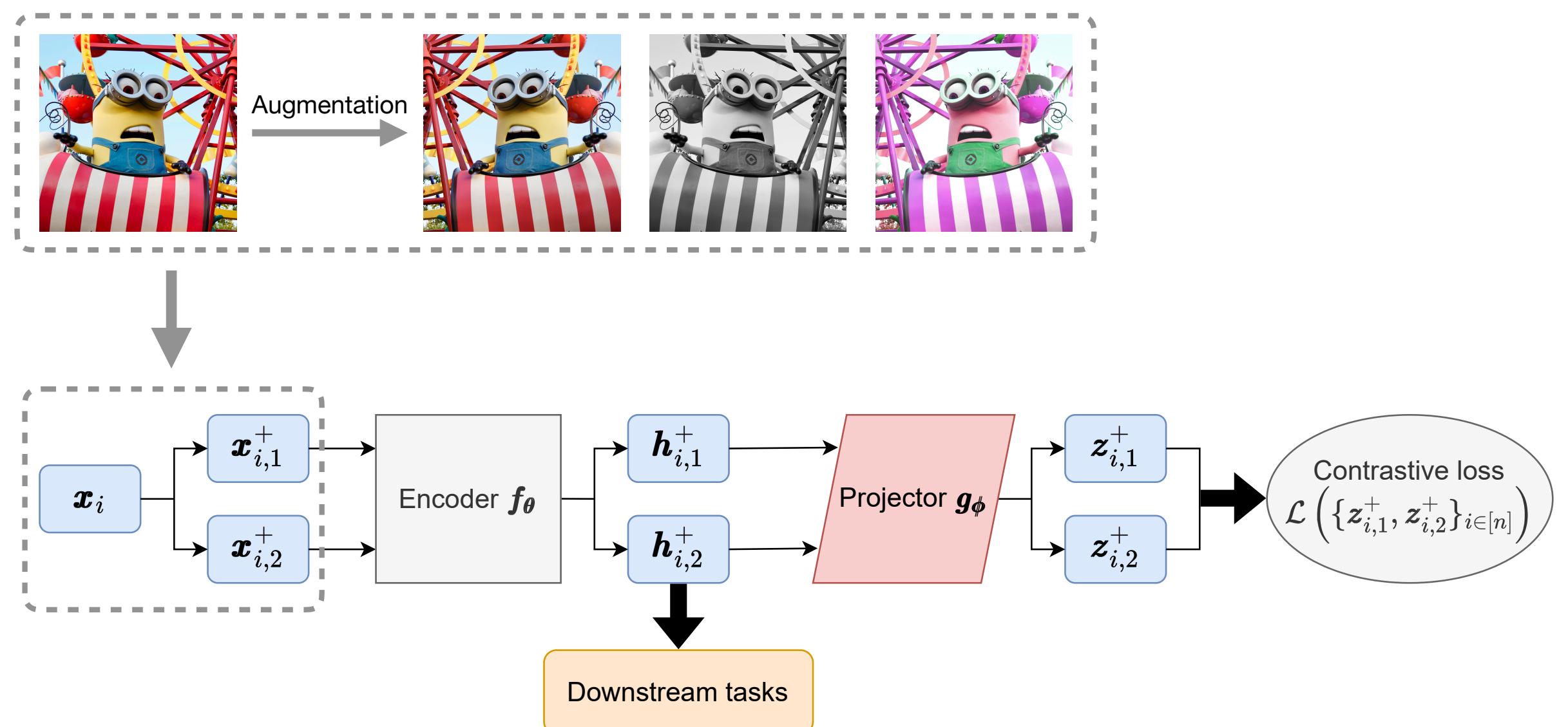


Figure 1. Encoder-projector framework.

- Positive pairs: $(\mathbf{x}_{i,k}^+, \mathbf{x}_{i,l}^+)$; Negative pairs: $(\mathbf{x}_{i,k}^+, \mathbf{x}_{j,l}^+), i \neq j$
- Goal:** learn representations by
 - encouraging proximity between positive pairs
 - forcing negative pairs to be far
- Contrastive loss (cross-entropy with pseudo labels)

$$\min_{\theta, \varphi} \sum_i \sum_{j \sim i} -\log \frac{\exp(\frac{1}{\tau} \text{sim}(\mathbf{z}_i, \mathbf{z}_j))}{\sum_{k \neq i} \exp(\frac{1}{\tau} \text{sim}(\mathbf{z}_i, \mathbf{z}_k))}, \quad \text{sim}(\mathbf{z}, \mathbf{z}') = \langle \frac{\mathbf{z}}{\|\mathbf{z}\|}, \frac{\mathbf{z}'}{\|\mathbf{z}'\|} \rangle$$

Motivating questions

- Effect of contrastive learning on representation and role of hyperparameters?
- Causes of dimensional collapse in both features and embeddings?
- Role of the projector? (removed after training in practice)

Expansion and shrinkage of the signal

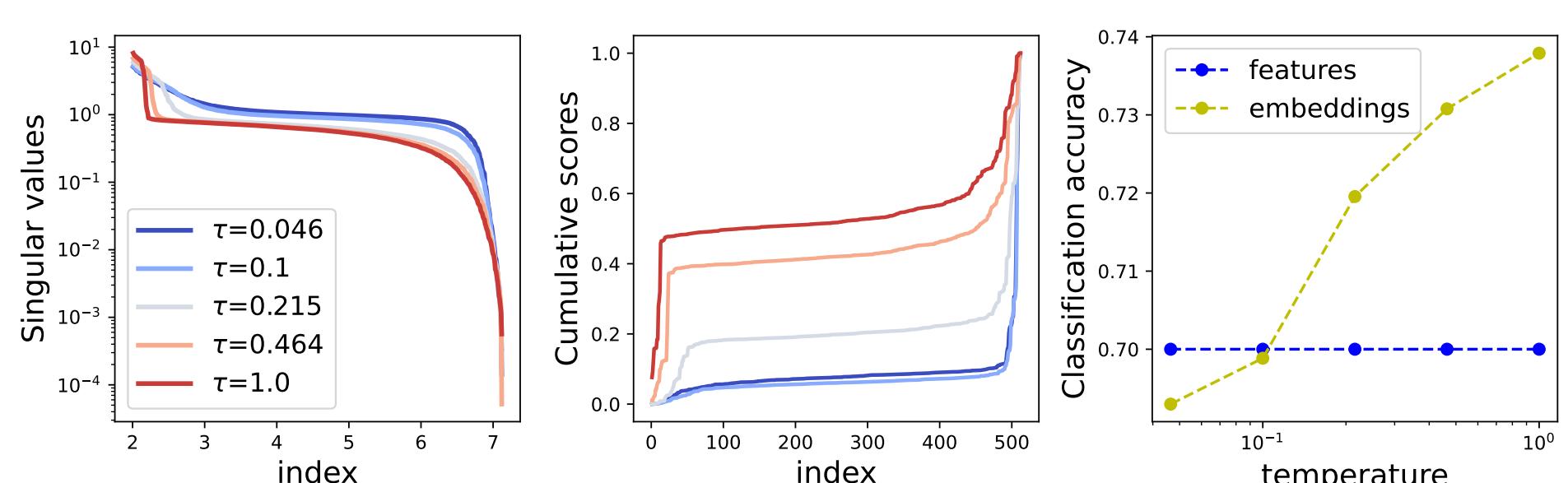


Figure 2. Results with the pretrained encoder and a one-layer linear projector.

$$\text{score}_i = \sum_{j \leq i} \frac{\langle \mathbf{v}_j, \boldsymbol{\mu}_{c_1, c_2} \rangle^2}{\|\boldsymbol{\mu}_{c_1, c_2}\|^2}$$

Feature-level GMM modeling

- 2-GMM features: $\mathbf{h}_i \stackrel{\text{i.i.d.}}{\sim} \frac{1}{2} \mathcal{N}(-\boldsymbol{\mu}, \mathbf{I}_p) + \frac{1}{2} \mathcal{N}(\boldsymbol{\mu}, \mathbf{I}_p)$
- Augmentations: $\mathbf{h}_{i,1}^+, \mathbf{h}_{i,2}^+ | \mathbf{h}_i \stackrel{\text{i.i.d.}}{\sim} \mathcal{N}(\mathbf{h}_i, \sigma_{\text{aug}}^2 \mathbf{I}_p), \mathbf{h}_i^- \stackrel{d}{=} \mathbf{h}_{j,1}^+, i \neq j$
- Linear projector: $\mathbf{z}_i = \mathbf{W}\mathbf{h}_i$
- Population loss:

$$\begin{aligned} \mathcal{L}(\mathbf{W}) = & \frac{1}{2\tau} \cdot \frac{\mathbb{E}[\|\mathbf{W}\mathbf{h}_1^+ - \mathbf{W}\mathbf{h}_2^+\|^2]}{(\mathbb{E}[\|\mathbf{W}\mathbf{h}_1^+\|^2] \cdot \mathbb{E}[\|\mathbf{W}\mathbf{h}_2^+\|^2])^{1/2}} \\ & + \log \left(\mathbb{E} \exp \left(-\frac{1}{2\tau} \cdot \frac{\|\mathbf{W}\mathbf{h}_1^+ - \mathbf{W}\mathbf{h}_2^-\|^2}{(\mathbb{E}[\|\mathbf{W}\mathbf{h}_1^+\|^2] \cdot \mathbb{E}[\|\mathbf{W}\mathbf{h}_2^-\|^2])^{1/2}} \right) \right) \end{aligned}$$

Expansion-shrinkage phase transition in GMM features

Denote $\tau^* = 2\|\boldsymbol{\mu}\|^2 \{ (1 + \sigma_{\text{aug}}^2 + \|\boldsymbol{\mu}\|^2) \log(1 + 2\sigma_{\text{aug}}^2) \}^{-1}$. A three-parameter configuration $(\sigma_{\text{aug}}^2, \tau, \|\boldsymbol{\mu}\|^2)$ is said to be in the

- expansion regime if $\tau \geq \tau^*$ and shrinkage regime if $\tau < \tau^*$.

Theorem 1

Consider minimizer \mathbf{W}^* of certain first-order approximation $\tilde{\mathcal{L}}(\mathbf{W})$.

- When $\tau \geq \tau^*$ (expansion regime), $\mathbf{W}^* = \sum_j \sigma_j^* \mathbf{u}_j^* \mathbf{v}_j^{*\top}$ satisfies $\sigma_2^* = \dots = \sigma_p^* = 0, \langle \mathbf{v}_1^*, \boldsymbol{\mu} \rangle^2 = \|\boldsymbol{\mu}\|^2$ i.e., perfect alignment
- When $\tau < \tau^*$ (shrinkage regime),
if $\sigma_{\text{aug}}^2 \rightarrow 0$, then $\max_j |\sigma_j \langle \mathbf{v}_j^*, \boldsymbol{\mu} \rangle| \rightarrow 0$ i.e., compress if correlated

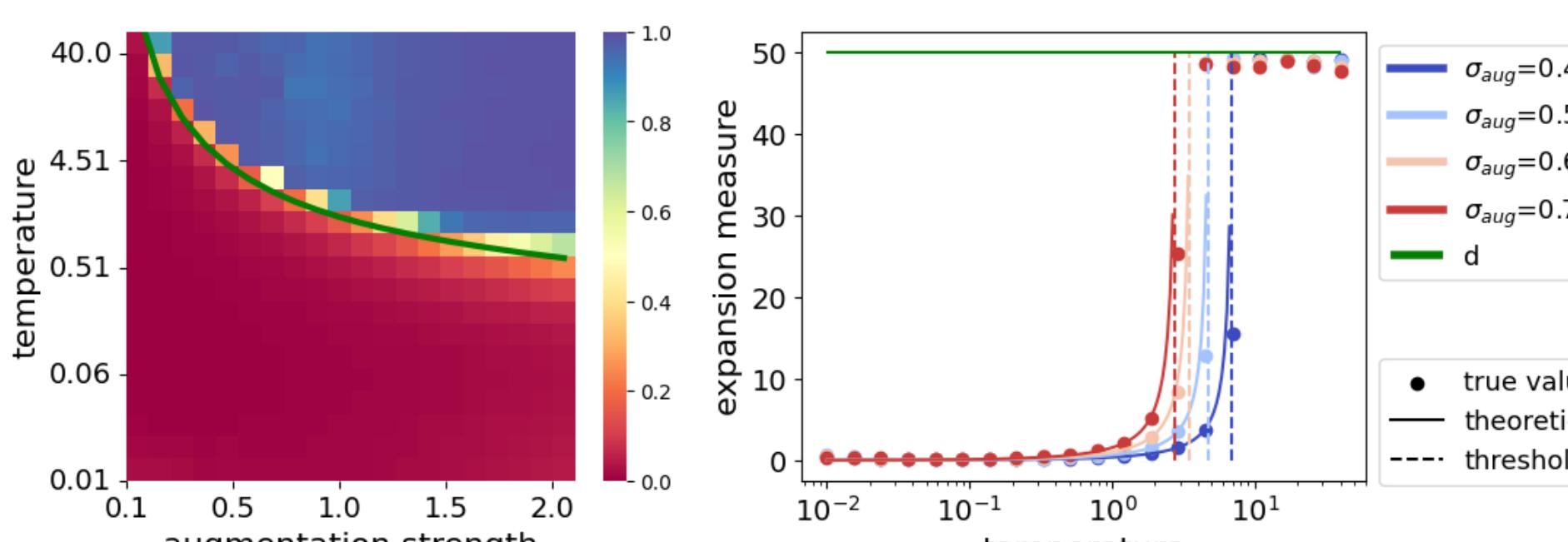


Figure 3. Expansion measure $\tilde{t}(\mathbf{W}) = \|\mathbf{W}\boldsymbol{\mu}\|^2 / (\|\mathbf{W}\|_F^2 \|\boldsymbol{\mu}\|^2)$.

Empirical evidence for feature-level modeling

- Linear separable features after a few epochs
- Contrastive loss decomposition at each epoch t ,

$$\mathcal{L}(\boldsymbol{\theta}^{(t)}, \boldsymbol{\varphi}^{(t)}) = \min_{\boldsymbol{\varphi}} \mathcal{L}(\boldsymbol{\theta}^{(t)}, \boldsymbol{\varphi}) + \mathcal{L}^\perp(\boldsymbol{\theta}^{(t)}, \boldsymbol{\varphi}^{(t)}),$$

which satisfies $\mathcal{L}^\perp(\boldsymbol{\theta}^{(t)}, \boldsymbol{\varphi}^{(t)}) \ll \min_{\boldsymbol{\varphi}} \mathcal{L}(\boldsymbol{\theta}^{(t)}, \boldsymbol{\varphi})$ and

$$\|\tilde{\boldsymbol{\varphi}}^{(t)} - \boldsymbol{\varphi}^{(t)}\| \ll \|\boldsymbol{\varphi}^{(t)}\|, \quad \tilde{\boldsymbol{\varphi}}^{(t)} = \operatorname{argmin}_{\boldsymbol{\varphi}} \mathcal{L}(\boldsymbol{\theta}^{(t)}, \boldsymbol{\varphi})$$

Effect of projectors on generalization accuracy

- Motivating question:** how does expansion/shrinkage affect generalization in downstream tasks?
- Consider the linear projection from the following class: $\mathcal{W} = \{\mathbf{W}_\eta = \mathbf{I}_p + \eta \cdot \rho^{-1} \boldsymbol{\mu} \boldsymbol{\mu}^\top : \eta > -1\}$, where $\rho = \|\boldsymbol{\mu}\|^2$

Invariance of generalization error in low-dimensional regime

- ℓ_2 -regularized logistic regression for non-separable data $\ell_n(\gamma, \beta; \lambda_n) = \mathbb{E}_n \left\{ \log \left[1 + e^{-y(\gamma + \mathbf{z}^\top \beta)} \right] \right\} + \lambda_n \|\beta\|^2$
- Classification error $\text{Err}(\gamma, \beta; \eta, \lambda_n) = \mathbb{P}(\gamma + y' \langle \mathbf{z}', \beta \rangle < 0)$

Proposition

Let $(\hat{\gamma}, \hat{\beta})$ be the minimizer of $\ell_n(\gamma, \beta; \lambda_n)$.

- If $\lambda_n = a \cdot b_n > 0$ with constant $a > 0$ and $0 < b_n \ll \sqrt{n}$, then the test error $\text{Err}(\hat{\gamma}, \hat{\beta}; \eta, \lambda_n) = \Phi(-\|\boldsymbol{\mu}\|) + O_{\mathbb{P}}(b_n n^{-1/2})$.
- If $\lambda_n = a\sqrt{n}$ with constant $a > 0$, then $\text{Err}(\hat{\gamma}, \hat{\beta}; \eta, \lambda_n)$ is decreasing in η .

Decreasing generalization error in high-dimensional regime

- Implicit bias in overparametrized models: GD for logistic regression converges to max-margin classifier for separable data

$$\begin{aligned} \max_{\beta} & \quad \min_{i \leq n} y_i \langle \mathbf{z}_i, \beta \rangle \\ \text{subject to} & \quad \|\beta\| \leq 1 \end{aligned}$$

- Classification error $\text{Err}(\hat{\beta}; \eta) = \mathbb{P}(y' \langle \mathbf{z}', \hat{\beta} \rangle < 0)$
- A linear layer $\mathbf{z}_i = \mathbf{W}\mathbf{h}_i$ can be interpreted as reparametrization

Theorem 2

Suppose $n/p \rightarrow \delta > 0$. There exists threshold $\delta^*(\rho) > 0$ such that

- (separability) if $\delta < \delta^*$, there exists a unique solution $\hat{\beta}$ with the margin

$$\hat{\kappa} = \min_{i \leq n} y_i \langle \mathbf{z}_i, \hat{\beta} \rangle \xrightarrow{p} \kappa^*(\|\boldsymbol{\mu}\|, \eta) > 0$$

and conversely data are not separable w.h.p. if $\delta > \delta^*$.

- (monotone error) if $\delta < \delta^*$, the asymptotic error $\text{Err}^*(\eta)$, namely

$$\text{Err}(\hat{\beta}; \eta) \xrightarrow{p} \text{Err}^*(\eta),$$

is decreasing in η .

References

- [1] Yu Gui, Cong Ma, and Yiqiao Zhong. Demystifying projection heads in contrastive learning: an expansion and shrinkage perspective. In preparation, 2023.