### STAT6018 Research Frontiers in Data Science

Topic II: Introduction to empirical process theory

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## Course Logistics

**Course website:** https://yugu-stat.github.io/teaching/stat6018

**Lectures:** Attendance is required

**Final presentation:** At Week 4, present an arbitrary theorem/lemma and its proof from the references within 20 mins (including Q & A).

#### References:

- van der Vaart, A. W. & Wellner, J. A. (1996). Weak Convergence and Empirical Processes. New York: Springer.
- Sen, B. (2018). A gentle introduction to empirical process theory and applications.
- Kosorok, M. R. (2008). Introduction to empirical processes and semiparametric inference. New York: Springer.

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- Chapter 1: Introduction to empirical processes
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## What is an empirical process?

- A *stochastic process* is a collection of random variables  $\{X(t), t \in T\}$  on the same probability space, indexed by an arbitrary index set T.
- In general, an *empirical process* is a stochastic process based on a random sample, usually of n i.i.d. random variables  $X_1, \ldots, X_n$ .

## Example: empirical distribution function

Let  $X_1, \ldots, X_n$  be i.i.d. real-valued random variables with cumulative distribution function (c.d.f.) F. Then the *empirical distribution function* (e.d.f.) is defined as

$$\mathbb{F}_n(t) := \frac{1}{n} \sum_{i=1}^n \mathbf{1}(X_i \leq t), \quad t \in \mathbb{R}.$$

 $\mathbb{F}_n(t)$  is one of the simplest examples of an empirical process.

## Example: Kaplan-Meier estimator

Let  $(X_1, \delta_1), \ldots, (X_n, \delta_n)$  be a sample of right-censored failure time observations. Then the *Kaplan-Meier estimator* of the survival function is given by

$$\widehat{S}(t) = \prod_{k:T_k^0 \leq t} \left\{ 1 - \frac{\sum_{i=1}^n \delta_i \mathbf{1}(X_i = T_k^0)}{\sum_{i=1}^n \mathbf{1}(X_i \geq T_k^0)} \right\},\,$$

where  $T_1^0 < T_2^0 < \cdots < T_K^0$  are unique observed failure times.

 $\widehat{S}(t)$  is another simple example of an empirical process.

## General features of an empirical process

- The i.i.d. sample  $X_1, \ldots, X_n$  is drawn from a probability measure P on an arbitrary sample space  $\mathcal{X}$ .
- Define the *empirical measure* to be  $\mathbb{P}_n = n^{-1} \sum_{i=1}^n \delta_{X_i}$ , where  $\delta_X$  denotes the Dirac measure at X.
- For a measurable function  $f: \mathcal{X} \mapsto \mathbb{R}$ , define

$$\mathbb{P}_n f := \int f d\mathbb{P}_n = \frac{1}{n} \sum_{i=1}^n f(X_i).$$

• For any class  $\mathcal{F}$  of such real-valued functions on  $\mathcal{X}$ ,  $\{\mathbb{P}_n f : f \in \mathcal{F}\}$  is the empirical process indexed by  $\mathcal{F}$ .

## Start with the classical e.d.f. $\mathbb{F}_n$

- Setting  $\mathcal{X} = \mathbb{R}$ ,  $\mathbb{F}_n$  can be re-expressed as the empirical process  $\{\mathbb{P}_n f : f \in \mathcal{F}\}$ , where  $\mathcal{F} = \{\mathbb{1}(x \leq t), t \in \mathbb{R}\}$ .
- By the law of large numbers,  $\mathbb{F}_n(t) \stackrel{a.s.}{\to} F(t)$  for each  $t \in \mathbb{R}$ .
- By the central limit theorem, for each  $t \in \mathbb{R}$ ,

$$\mathbb{G}_n(t) := \sqrt{n} \left( \mathbb{F}_n(t) - F(t) \right) \stackrel{d}{\to} N \left( 0, F(t)(1 - F(t)) \right).$$

- From the functional perspective, uniform results over  $t \in \mathbb{R}$  would be more appealing.
  - Need theory of empirical processes

# Strengthened results on $\mathbb{F}_n$ and $\mathbb{G}_n$

 Glivenko (1933) and Cantelli (1933) demonstrated that the previous result could be strengthened to

$$\|\mathbb{F}_n - F\|_{\infty} = \sup_{t \in \mathbb{R}} |\mathbb{F}_n(t) - F(t)| \stackrel{a.s.}{\to} 0.$$

• Donsker (1952) showed that

$$\mathbb{G}_n \stackrel{d}{\to} \mathbb{B}(F) \quad \text{in } \ell^{\infty}(\mathbb{R}),$$

where  $\mathbb B$  is the standard Brownian bridge process on [0, 1]; for any index set T,  $\ell^\infty(T)$  denotes the space of all bounded functions  $f: T \mapsto \mathbb R$ .

## Extend to general empirical processes

- Properties of the approximation of Pf by  $\mathbb{P}_n f$ , uniformly in  $\mathcal{F}$ 
  - ▶ the random quantity  $\|\mathbb{P}_n P\|_{\mathcal{F}} := \sup_{f \in \mathcal{F}} |\mathbb{P}_n f P f|$
  - the empirical process  $\mathbb{G}_n := \sqrt{n}(\mathbb{P}_n P)$
- Two special classes
  - ▶ Glivenko-Cantelli: F is P-Glivenko-Cantelli if

$$\|\mathbb{P}_n - P\|_{\mathcal{F}} \stackrel{a.s.}{\to} 0.$$

▶ **Donsker:** F is P-Donsker if

$$\mathbb{G}_n \stackrel{d}{\to} \mathbb{G} \quad \text{in } \ell^{\infty}(\mathcal{F}),$$

where  $\mathbb{G}$  is a mean zero Gaussian process indexed by  $\mathcal{F}$ , and  $\ell^{\infty}(\mathcal{F}) = \{x : \mathcal{F} \mapsto \mathbb{R} | \ \|x\|_{\mathcal{F}} < \infty \}.$ 

### Remarks

- Glivenko-Cantelli (GC): uniform almost surely convergence
- Donsker: uniform central limit theorem
- Donsker  $\Rightarrow$  GC
- ullet GC or Donsker properties depend crucially on the complexity of  ${\cal F}.$

# Complexity of ${\mathcal F}$

For a given norm  $\|\cdot\|$ , such as the  $L_r(Q)$ -norms, define the covering and bracketing numbers as follows:

#### **Covering number**

- denoted by  $N(\epsilon, \mathcal{F}, \|\cdot\|)$
- ullet minimum number of balls  $B(f;\epsilon):=\{g:\|g-f\|\leq\epsilon\}$  needed to cover  $\mathcal F$
- entropy without bracketing:  $\log N(\epsilon, \mathcal{F}, \|\cdot\|)$

#### **Bracketing number**

- denoted by  $N_{\Pi}(\epsilon, \mathcal{F}, \|\cdot\|)$
- ullet minimum number of brackets  $[\ell,u]$  with  $\|\ell-u\|<\epsilon$  needed to cover  ${\mathcal F}$
- entropy with bracketing:  $\log N_{\parallel}(\epsilon, \mathcal{F}, \|\cdot\|)$

### GC theorems

## Theorem 1 (GC with bracketing)

A function class  $\mathcal{F}$  is a P-Glivenko-Cantelli if

$$N_{[]}(\epsilon, \mathcal{F}, L_1(P)) < \infty$$
, for every  $\epsilon > 0$ .

## Theorem 2 (GC without bracketing)

A function class  $\mathcal{F}$  is a P-Glivenko-Cantelli if

$$\sup_{Q} N(\epsilon \|F\|_{L_1(Q)}, \mathcal{F}, L_1(Q)) < \infty, \quad \text{ for every } \epsilon > 0,$$

where F is an envelope function<sup>a</sup> of  $\mathcal{F}$ , and the supremum is over all probability measures Q on  $\mathcal{X}$ .



<sup>&</sup>lt;sup>a</sup>An envelope function of a class  $\mathcal F$  is any function  $x\mapsto F(x)$  such that  $|f(x)|\le F(x)$ , for every x and  $f\in \mathcal F$ .

### Donsker theorems

## Theorem 3 (Donsker with bracketing entropy integral)

A function class F is a P-Donsker if

$$\int_{0}^{\infty} \sqrt{\log N_{[]}\left(\epsilon, \mathcal{F}, L_{2}(P)\right)} d\epsilon < \infty.$$

## Theorem 4 (Donsker with uniform entropy integral)

A function class  $\mathcal{F}$  is a P-Donsker if

$$\int_0^\infty \sup_{Q} \sqrt{\log N\left(\epsilon \|F\|_{Q,2}, \mathcal{F}, L_2(Q)\right)} d\epsilon < \infty,$$

where F is an envelope function of  $\mathcal{F}$ , and the supremum is over all probability measures Q on  $\mathcal{X}$ .

### *M*-estimators

- Definition:
  - Metric space: (⊖, d)
  - ▶  $m_{\theta}: \mathcal{X} \to \mathbb{R}$ , for each  $\theta \in \Theta$
  - "Empirical gain":  $M_n(\theta) = \mathbb{P}_n m_\theta$
  - *M*-estimator:  $\hat{\theta}_n = \arg\max_{\theta \in \Theta} M_n(\theta)$
- Examples:
  - Maximum (penalized) likelihood estimator
  - Least squares estimator
  - Nonparametric maximum likelihood estimator

## Application: consistency of *M*-estimators

- Two assumptions:
  - 1.  $\mathcal{F} := \{ m_{\theta}(\cdot) : \theta \in \Theta \}$  is P-GC
  - 2.  $\theta_0$  is a well-separated maximizer of  $M(\theta) = Pm_{\theta}$ , i.e., for every  $\delta > 0$ ,  $M(\theta_0) > \sup_{\theta \in \Theta: d(\theta, \theta_0) > \delta} M(\theta)$ .
- For fixed  $\delta > 0$ , let  $\psi(\delta) = M(\theta_0) \sup_{\theta \in \Theta: d(\theta, \theta_0) > \delta} M(\theta) > 0$

$$\left\{ d(\hat{\theta}_{n}, \theta_{0}) \geq \delta \right\} \Rightarrow M(\hat{\theta}_{n}) \leq \sup_{\theta \in \Theta: d(\theta, \theta_{0}) \geq \delta} M(\theta) 
\Leftrightarrow M(\hat{\theta}_{n}) - M(\theta_{0}) \leq -\psi(\delta) 
\Rightarrow M(\hat{\theta}_{n}) - M(\theta_{0}) + \left( M_{n}(\theta_{0}) - M_{n}(\hat{\theta}_{n}) \right) \leq -\psi(\delta) 
\Rightarrow 2 \sup_{\theta \in \Theta} |M_{n}(\theta) - M(\theta)| \geq \psi(\delta)$$

$$\Rightarrow \mathbb{P}\left(d(\hat{\theta}_n,\theta_0)\geq \delta\right)\leq \mathbb{P}\left(\sup_{\theta\in\Theta}|M_n(\theta)-M(\theta)|\geq \psi(\delta)/2\right)\to 0.$$

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## Covering and packing numbers

Let  $(\Theta, d)$  be an arbitrary semi-metric space.

## Definition 5 (Covering number)

The  $\epsilon$ -covering number  $N(\epsilon, \Theta, d)$  is the minimal number of balls  $B(x; \epsilon) := \{ y \in \Theta : d(x, y) \le \epsilon \}$  of radius  $\epsilon$  needed to cover the set  $\Theta$ . The corresponding entropy number is  $\log N(\epsilon, \Theta, d)$ .

## Definition 6 (Packing number)

Call a collection of points  $\epsilon$ -separated if the distance between each pair of points is larger than  $\epsilon$ . The packing number  $D(\epsilon, \Theta, d)$  is the maximum number of  $\epsilon$ -separated points in  $\Theta$ .

# Covering and packing numbers (cont.)

### Lemma 7 (Covering vs packing numbers)

$$D(2\epsilon, \Theta, d) \leq N(\epsilon, \Theta, d) \leq D(\epsilon, \Theta, d), \quad \forall \epsilon > 0.$$

Thus, packing and covering numbers have the same scaling in the radius  $\epsilon$ .

- The first inequality can be easily proved by contradiction.
- The second inequality follows by the fact that  $\Theta$  can be covered by the balls  $B(\theta_i; \epsilon)$  (i = 1, ..., D), where  $\theta_1, ..., \theta_D$  are the  $\epsilon$ -separated points associated with the packing number D.

## Example: bounded sets on Euclidean space

### Example 8 (Bounded sets on Euclidean space)

For any bounded subset  $\Theta \subset \mathbb{R}^p$ , there exist constants c < C such that

$$c\left(\frac{1}{\epsilon}\right)^{\rho} \leq N(\epsilon,\Theta,\|\cdot\|) \leq C\left(\frac{1}{\epsilon}\right)^{\rho}, \quad \forall \epsilon \in (0,1).$$

### Proof.

The union of  $D(\epsilon,\Theta,\|\cdot\|)$  number of  $\epsilon$ -separated balls of radius  $\epsilon/2$  is contained in the set  $\Theta':=\{\theta\in\mathbb{R}^p:\|\theta-\Theta\|<\epsilon/2\}$ . Thus,  $D(\epsilon,\Theta,\|\cdot\|)v_p\left(\frac{\epsilon}{2}\right)^p\leq Vol(\Theta')$ , where  $v_p$  is the volume of the unit ball. On the other hand,  $D(2\epsilon,\Theta,\|\cdot\|)$  number of  $2\epsilon$ -separated balls cover the set  $\Theta$ . Thus,  $D(2\epsilon,\Theta,\|\cdot\|)v_p(2\epsilon)^p\geq Vol(\Theta)$ . The desired inequalities then follow by the above results and Lemma 7.

## Example: bounded Lipschitz functions

### Example 9 (Bounded Lipschitz functions)

Let  $\mathcal{F}:=\{f:[0,1]\mapsto [0,1]\mid f \text{ is } 1\text{-Lipschitz}\}$ . Then there exists some constant A such that

$$\log N(\epsilon, \mathcal{F}, \|\cdot\|_{\infty}) \leq \frac{A}{\epsilon}, \quad \forall \epsilon > 0.$$

#### Proof.

If  $\epsilon \geq 1$ , take  $f_0 \equiv 0$  and observe that  $\forall f \in \mathcal{F}$ ,  $\|f - f_0\|_{\infty} \leq 1 \leq \epsilon$ . Then  $N(\epsilon, \mathcal{F}, \|\cdot\|_{\infty}) = 1$ .

Let  $0 < \epsilon < 1$ . Define a  $\epsilon$ -grid of the interval [0,1] (for both axes), i.e.

 $0 = a_0 < a_1 < \cdots, a_N = 1$  where  $N = \lfloor 1/\epsilon \rfloor + 1$  and  $a_k = k\epsilon$  for

 $k=1,\cdots,N-1.$ 

Let  $B_1 := [a_0, a_1]$  and  $B_k := (a_{k-1}, a_k]$  for  $k = 2, \dots, N$ .



# Example: bounded Lipschitz functions (cont.)

### Proof (cont.)

For each  $f \in \mathcal{F}$ , define the step function  $\tilde{f}: [0,1] \mapsto \mathbb{R}$  as

$$\tilde{f}(x) = \sum_{k=1}^{N} \epsilon \left\lfloor \frac{f(a_k)}{\epsilon} \right\rfloor \mathbb{1}_{B_k}(x).$$

Clearly,  $\tilde{f}$  is constant on each interval  $B_k$  and can only take values of the form  $i\epsilon$  for  $i=0,\cdots,N-1$ .

For any  $x \in [0,1]$ , suppose that  $x \in B_k$ . By the Lipschitz property of f and the construction of  $\tilde{f}$ ,

$$|f(x)-\tilde{f}(x)| \leq |f(x)-f(a_k)|+|f(a_k)-\tilde{f}(a_k)| \leq 2\epsilon.$$

Therefore,  $\|f - \tilde{f}\|_{\infty} \leq 2\epsilon$ .

# Example: bounded Lipschitz functions (cont.)

### Proof (cont.)

Now we count the number of distinct  $\tilde{f}$ 's obtained as f varies over  $\mathcal{F}$ . There are at most N choices for  $\tilde{f}(a_1)$ . Further, note that for any  $\tilde{f}$  and  $k=2,\cdots,N$ ,

$$\begin{aligned} & |\tilde{f}(a_k) - \tilde{f}(a_{k-1})| \\ & \leq |\tilde{f}(a_k) - f(a_k)| + |f(a_k) - f(a_{k-1})| + |f(a_{k-1}) - \tilde{f}(a_{k-1})| \leq 3\epsilon. \end{aligned}$$

Thus, for fixed  $\tilde{f}(a_{k-1})$ , there are at most 7 choices left for  $\tilde{f}(a_k)$ . Therefore,

$$N(2\epsilon, \mathcal{F}, \|\cdot\|_{\infty}) \leq (\lfloor 1/\epsilon \rfloor + 1) 7^{\lfloor 1/\epsilon \rfloor},$$

which completes the proof.



## Bracketing numbers

Let  $(\mathcal{F}, \|\cdot\|)$  be a subset of a normed space of real functions  $f: \mathcal{X} \mapsto \mathbb{R}$  on some set  $\mathcal{X}$ .

## Definition 10 (Bracketing number)

Given two functions  $I(\cdot)$  and  $u(\cdot)$ , the bracket [I,u] is the set of all functions  $f \in \mathcal{F}$  with  $I(x) \leq f(x) \leq u(x), \forall x \in \mathcal{X}$ . An  $\epsilon$ -bracket is a bracket [I,u] with  $\|I-u\| < \epsilon$ . The bracketing number  $N_{[]}(\epsilon,\mathcal{F},\|\cdot\|)$  is the minimum number of the  $\epsilon$ -brackets needed to cover  $\mathcal{F}$ . The entropy with bracketing is  $\log N_{[]}(\epsilon,\mathcal{F},\|\cdot\|)$ .

# Bracketing numbers (cont.)

### Theorem 11 (Bracketing vs covering numbers)

Suppose that  $\|\cdot\|$  has the Riesz property<sup>a</sup>. Then

$$N(\epsilon, \mathcal{F}, \|\cdot\|) \le N_{\|}(2\epsilon, \mathcal{F}, \|\cdot\|), \quad \forall \epsilon > 0.$$

a|f| < |g| implies that ||f|| < ||g||.

- The proof uses the fact that every f within the  $2\epsilon$ -bracket [I, u] falls within the ball  $B(\frac{I+u}{2}; \epsilon)$ .
- In general, there is no converse inequality, so that bracketing numbers are bigger than covering numbers.
- A bracket gives pointwise control over a function.
- A ball under the  $L_r(Q)$ -norm gives integrated control over a function.

## Example: distribution functions

## Example 12 (Distribution functions)

Recall that the function class relevant to the e.d.f.  $\mathbb{F}_n$  is  $\mathcal{F} = \{\mathbb{1}_{(-\infty,t]} \mid t \in \mathbb{R}\}$ . The bracketing numbers of  $\mathcal{F}$  are of polynomial orders:

$$N_{[]}(\epsilon, \mathcal{F}, L_1(P)) \le \frac{2}{\epsilon},$$
  
$$N_{[]}(\epsilon, \mathcal{F}, L_2(P)) \le \frac{2}{\epsilon^2}.$$

#### Proof.

Consider the brackets of the form  $[\mathbbm{1}_{(-\infty,t_{i-1}]},\mathbbm{1}_{(-\infty,t_i]}]$  for a grid of points  $-\infty=t_0< t_1<\cdots< t_N=\infty$  such that  $F(t_i)-F(t_{i-1})<\epsilon$  for  $i=1,\ldots,N$ , where  $N=\lfloor 1/\epsilon\rfloor+1<2/\epsilon$ .

Clearly, these brackets can cover  $\mathcal{F}$ . Moreover, these brackets have  $L_1(P)$ -size  $\epsilon$  and  $L_2(P)$ -size bounded by  $\sqrt{\epsilon}$  (since  $Pf^2 \leq Pf$  for every  $0 \leq f \leq 1$ ).

## Example: classes Lipschitz in a parameter

## Example 13 (Classes Lipschitz in a parameter)

Consider a function class  $\mathcal{F} = \{m_{\theta} : \theta \in \Theta\}$  which has a Lipschitz dependence on  $\theta$ , i.e., there exists some function  $F : \mathcal{X} \mapsto \mathbb{R}$  such that

$$|m_{\theta_1}(x) - m_{\theta_2}(x)| \le F(x)d(\theta_1, \theta_2), \quad \forall \theta_1, \theta_2 \in \Theta, \forall x \in \mathcal{X}.$$

Then, for any norm  $\|\cdot\|$ ,

$$N_{\parallel}(2\epsilon \|F\|, \mathcal{F}, \|\cdot\|) \leq N(\epsilon, \Theta, d).$$

#### Proof.

Let  $\theta_1, \dots, \theta_p$  be an  $\epsilon$ -cover of  $\Theta$  (under the metric d).

Then for every  $\theta \in B(\theta_i; \epsilon)$ ,  $|m_{\theta}(x) - m_{\theta_i}(x)| \le \epsilon F(x)$ .

Thus, the brackets  $[m_{\theta_i} - \epsilon F, m_{\theta_i} + \epsilon F]$   $(i = 1, \dots, p)$ , each of size  $2\epsilon ||F||$ , can cover  $\mathcal{F}$ .

### Monotone functions

### Theorem 14 (Monotone functions)

The class  $\mathcal{F}$  of monotone functions  $f:\mathbb{R}\mapsto [0,1]$  satisfies

$$\log N_{[]}(\epsilon, \mathcal{F}, L_r(Q)) \leq K(\frac{1}{\epsilon}), \quad \forall \epsilon > 0,$$

for every probability measure Q, every  $r \ge 1$ , and some constant K that depends on r only.

- The result implies that  $\mathcal{F}$  is Donsker (by Theorem 3).
- See Theorem 2.7.5 of VW for the proof.

### Smooth functions

- $\mathcal{X}$ : bounded, convex subset of  $\mathbb{R}^p$  with nonempty interior
- $\underline{\alpha}$ : largest integer smaller than  $\alpha$ , for any  $\alpha > 0$
- $D^k$ : differential operator of order k
- For a function  $f: \mathcal{X} \mapsto \mathbb{R}$ , define

$$\|f\|_{\alpha} = \max_{k \le \underline{\alpha}} \sup_{D^k, x} |D^k f(x)| + \sup_{D^{\underline{\alpha}}, x, y} \frac{|D^{\underline{\alpha}} f(x) - D^{\underline{\alpha}} f(y)|}{\|x - y\|^{\alpha - \underline{\alpha}}}$$

•  $C_M^{\alpha}(\mathcal{X})$ : set of all continuous functions  $f: \mathcal{X} \mapsto \mathbb{R}$  with  $\|f\|_{\alpha} \leq M$  (f has uniformly bounded partial derivatives and the highest partial derivatives are Lipschitz)

# Smooth functions (cont.)

### Theorem 15 (Smooth functions)

There exists a constant K depending only on  $\alpha$ , diam $\mathcal{X}$ , and p such that

$$\log N(\epsilon, C_1^{\alpha}(\mathcal{X}), \|\cdot\|_{\infty}) \leq K\left(\frac{1}{\epsilon}\right)^{p/\alpha},$$
$$\log N_{\parallel}(\epsilon, C_1^{\alpha}(\mathcal{X}), L_r(Q)) \leq K\left(\frac{1}{\epsilon}\right)^{p/\alpha},$$

for every  $\epsilon > 0$ ,  $r \geq 1$ , and probability measure Q.

See Theorem 2.7.1 and Corollary 2.7.2 of VW for the proofs.

### Convex functions

### Theorem 16 (Convex functions)

For a compact, convex subset  $C \subset \mathbb{R}^p$ , the class  $\mathcal{F}$  of all convex functions  $f: C \mapsto [0,1]$  that are L-Lipschitz satisfies

$$\log N(\epsilon, \mathcal{F}, \|\cdot\|_{\infty}) \leq K(1+L)^{p/2} \left(\frac{1}{\epsilon}\right)^{p/2},$$

for some constant K depending on p and C only.

See Corollary 2.7.10 of VW for the proof.

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# Tail probability of random variables

Markov's inequality

Let  $Z \ge 0$  be a random variable. Then for any t > 0,

$$P(Z \geq t) \leq \frac{EZ}{t}$$
.

Cheyshev's inequality
 If Z has a finite variance Var(Z), then

$$P(|Z - EZ| \ge t) \le \frac{Var(Z)}{t^2}.$$

But these inequalities can only yield a tail bound of order  $t^{-2}$ , which may be too relaxed. The tail bound can be improved to an exponential decrease in  $t^2$  by Hoeffding's inequality.

# Hoeffding's inequality

## Lemma 17 (Hoeffding's inequality)

Let  $X_1, \ldots, X_n$  be independent bounded random variables such that  $X_i \in [a_i, b_i]$  with probability 1. Let  $S_n = \sum_{i=1}^n X_i$ . Then,

$$\begin{split} &P(S_n - ES_n \geq t) \leq e^{-2t^2/\sum_{i=1}^n (b_i - a_i)^2}, \\ &P(S_n - ES_n \leq -t) \leq e^{-2t^2/\sum_{i=1}^n (b_i - a_i)^2}. \end{split}$$

The proof uses Markov's inequality and the following lemma:

#### Lemma 18

Let X be a random variable with EX = 0 and  $X \in [a, b]$  with probability 1. Then for any  $\lambda > 0$ ,

$$E(e^{\lambda X}) \leq e^{\lambda^2(b-a)^2/8}$$
.

### Sub-Gaussian random variables

## Definition 19 (Sub-Gaussian random variables)

A random variable X is called sub-Gaussian if there exist constants C, v > 0 such that  $P(|X| > t) \le Ce^{-vt^2}$  for every t > 0.

Some equivalent characterizations of sub-Gaussian random variables:

- There exists a > 0 such that  $E[e^{aX^2}] < \infty$ .
- Laplace transform condition:  $\exists B, b > 0$  such that  $\forall \lambda \in \mathbb{R}, Ee^{\lambda(X-E[X])} < Be^{\lambda^2 b}$ .
- Moment condition:  $\exists K > 0$  such that  $\forall p \geq 1$ ,  $(E|X|^p)^{1/p} \leq K\sqrt{p}$ .
- Union bound condition:  $\exists c > 0$  such that  $\forall n \geq c$ ,

$$E[\max\{|X_1 - E[X]|, \dots, |X_n - E[X]|\}] \le c\sqrt{\log n}$$

where  $X_1, \ldots, X_n$  are i.i.d. copies of X.



## Sub-Gaussian processes

## Definition 20 (Sub-Gaussian processes)

Let (T, d) be a semi-metric space and  $\{X_t, t \in T\}$  be a stochastic process indexed by T. Then  $X_t$  is called sub-Gaussian w.r.t. the semi-metric d if

$$P(|X_s - X_t| > u) \le 2 \exp\left(-\frac{u^2}{2d(s,t)^2}\right), \quad \forall s, t \in T, u > 0.$$

Any Gaussian process is sub-Gaussian w.r.t. the standard deviation semi-metric  $d(s,t)=\sqrt{{\sf Var}(X_s-X_t)}$ .

## Rademacher process and Hoeffding's inequality

Consider the Rademacher process

$$X_a = \sum_{i=1}^n a_i \varepsilon_i, \quad a = (a_1, \dots, a_n) \in \mathbb{R}^n, \tag{1}$$

where  $\varepsilon_i$ 's are independent Radermacher variables which take values +1 and -1 with probability 1/2.

By the following special case of Hoeffding's inequality, Rademacher process is also sub-Gaussian (w.r.t. the Euclidean distance).

## Lemma 21 (Hoeffding's inequality)

The Rademacher process  $\{X_a : a \in \mathbb{R}^n\}$  defined in (1) satisfies

$$P(|X_a| > t) \le 2e^{-t^2/(2||a||^2)}$$
.

## Bernstein's inequality

The following result gives tail bounds for random variables with larger than normal tails.

## Lemma 22 (Bernstein's inequality)

For independent random variables  $Y_1, \ldots, Y_n$  with zero means and bounded ranges [-M, M], there exists a constant  $v \ge Var(\sum_{i=1}^n Y_i)$  such that

$$P(|\sum_{i=1}^{n} Y_i| > t) \le 2e^{-\frac{t^2}{2(v+Mt/3)}}.$$

- See page 855 of Shorack and Wellner (1986)<sup>1</sup> for the proof.
- Compared to the normal tail bound  $e^{-t^2/(2v)}$ , the extra term 2Mt/3 can be seen as a penalty for the non-normality.
- When  $n \to \infty$ , Mt/3 is typically negligible w.r.t. v.

<sup>&</sup>lt;sup>1</sup>Shorack, G. R., & Wellner, J. A. (1986). Empirical Processes with Applications to Statistics. Wiley, New York. 📳 🔻 💈 🔻 💆 🕙 🔍 🖎

## Maximal inequalities

## Lemma 23 (Maximal inequality for sub-Gaussian variables)

Suppose that  $Y_1, \ldots, Y_N$  (not necessarily independent) are sub-Gaussian in the sense that  $Ee^{\lambda Y_i} \leq e^{\lambda^2 \sigma^2/2}$  for all  $\lambda > 0$  and  $i = 1, \ldots, N$ . Then,

$$E \max_{i=1,\ldots,N} Y_i \le \sigma \sqrt{2 \log N}.$$

#### Proof.

By Jensen's inequality, we have

$$e^{\lambda E \max_{i=1,...,N} Y_i} \leq E e^{\lambda \max_{i=1,...,N} Y_i} \leq \sum_{i=1}^N E e^{\lambda Y_i} \leq N e^{\lambda^2 \sigma^2/2}.$$

Tanking logarithms yields

$$E \max_{i=1,\dots,N} Y_i \leq \frac{\log N}{\lambda} + \frac{\lambda \sigma^2}{2} \leq \sigma \sqrt{2 \log N}.$$



# Maximal inequalities (cont.)

#### Lemma 24

Let  $\psi$  be a strictly increasing, convex, non-negative function. Suppose that  $\xi_1, \ldots, \xi_N$  are random variables such that  $E[\psi(|\xi_i|/c_i)] \leq L$  for  $i=1,\ldots,N$  and some constant L. Then,

$$E \max_{1 \leq i \leq N} |\xi_i| \leq \psi^{-1}(LN) \max_{1 \leq i \leq N} c_i.$$

#### Proof.

By the properties of  $\psi$ ,

$$\psi\left(\frac{E\max|\xi_i|}{\max c_i}\right) \leq \psi\left(E\max\frac{|\xi_i|}{c_i}\right) \leq \sum_{i=1}^N E\psi\left(\frac{|\xi_i|}{c_i}\right) \leq LN.$$

Apply  $\psi^{-1}$  to both sides.



# Maximal inequalities (cont.)

### Corollary 25

Let  $\xi_1, \ldots, \xi_N$  be Rademacher linear combinations, i.e.,  $\xi_i = \sum_{k=1}^n a_k^{(i)} \varepsilon_k$ . Then there exists some constant C > 0 such that for  $N \ge 2$ ,

$$E\max_{1\leq i\leq N}|\xi_i|\leq C\sqrt{\log N}\max_{1\leq i\leq N}\|a^{(i)}\|,$$

where 
$$a^{(i)} = (a_1^{(i)}, \dots, a_n^{(i)}) \in \mathbb{R}^n$$
.

#### Proof.

Use the fact that  $E[e^{\xi_i^2/\left(6\|a^{(i)}\|^2\right)}] \le 2$  and Lemma 24 with  $\psi(x) = e^{x^2}$ .



## Symmetrization

#### Symmetrized empirical process:

$$f\mapsto \mathbb{P}_n^{\circ}f=\frac{1}{n}\sum_{i=1}^n\varepsilon_if(X_i),$$

where  $\varepsilon_1, \ldots, \varepsilon_n$  are i.i.d. Rademacher random variables.

- $\varepsilon_1, \ldots, \varepsilon_n$  are independent of  $(X_1, \ldots, X_n)$
- $E(\mathbb{P}_n^o f) = 0$
- For fixed  $(X_1, \ldots, X_n)$ ,  $\mathbb{P}_n^o$  is a Rademacher process (hence sub-Gaussian).

# Symmetrization result

### Theorem 26 (Symmetrization)

For any class  $\mathcal F$  of measurable functions,

$$E \|\mathbb{P}_n - P\|_{\mathcal{F}} \leq 2E \|\mathbb{P}_n^o\|_{\mathcal{F}}.$$

#### Proof.

Let  $Y_i$  be independent copies of  $X_i$ . For fixed  $(X_1, \ldots, X_n)$ ,

$$\|\mathbb{P}_n - P\|_{\mathcal{F}} = \sup_{f \in \mathcal{F}} \frac{1}{n} \left| \sum_{i=1}^n [f(X_i) - Ef(Y_i)] \right| \leq E_Y \sup_{f \in \mathcal{F}} \frac{1}{n} \left| \sum_{i=1}^n [f(X_i) - f(Y_i)] \right|.$$

Taking expectation with respect to  $(X_1, \ldots, X_n)$ , we obtain

$$E \|\mathbb{P}_n - P\|_{\mathcal{F}} \leq E \left\| \frac{1}{n} \sum_{i=1}^n \left[ f(X_i) - f(Y_i) \right] \right\|_{\mathcal{F}}.$$



# Symmetrization result (cont.)

### Proof (cont.)

We can see that adding a minus sign in front of  $[f(X_i) - f(Y_i)]$  just exchanges X's and Y's, so the expectation remains unchanged. Thus,  $E \frac{1}{n} \| \sum_{i=1}^n e_i [f(X_i) - f(Y_i)] \|_{\mathcal{F}}$  is the same for any  $(e_1, \ldots, e_n) \in \{-1, +1\}^n$ . Hence.

$$E\|\mathbb{P}_{n} - P\|_{\mathcal{F}} \leq E_{\varepsilon} E_{X,Y} \left\| \frac{1}{n} \sum_{i=1}^{n} \varepsilon_{i} [f(X_{i}) - f(Y_{i})] \right\|_{\mathcal{F}}$$

$$\leq E_{\varepsilon} E_{X} \left\| \frac{1}{n} \sum_{i=1}^{n} \varepsilon_{i} f(X_{i}) \right\|_{\mathcal{F}} + E_{\varepsilon} E_{Y} \left\| \frac{1}{n} \sum_{i=1}^{n} \varepsilon_{i} f(Y_{i}) \right\|_{\mathcal{F}}$$

$$= 2E \|\mathbb{P}_{n}^{o}\|_{\mathcal{F}}.$$