EM Algorithm

Chapter 9, Statistical learning methods

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K-means

K-means recap

• Randomly initialize K centers

• Classify: Assign each point $j \in \{1, ..., N\}$ to nearest center:

$$\triangleright C^{(t)}(j) \leftarrow \arg\min_{i} \|\mu_i - x_j\|^2$$

• Recenter: μ_i becomes centroid of its points

$$ho \; \mu_i^{(t+1)} \leftarrow rg \min_{\mu} \; \sum_{i: C(i)=i} \left\| \mu - x_i
ight\|^2$$

 \triangleright Equivalent to $\mu_i \leftarrow$ average of its points!

What is K-means optimizing?

• Potential function $F(\mu, C)$ of centers μ and point allocations C:

$$F(\mu, C) = \sum_{j=1}^{N} \|\mu_{C(j)} - x_j\|^2$$
 (1)

Optimal K-means:

$$\triangleright \min_{\mu} \min_{C} F(\mu, C)$$

K-means algorithm

Optimize potential function:

$$\min_{\mu} \min_{C} F(\mu, C) = \min_{\mu} \min_{C} \sum_{i=1}^{K} \sum_{j:C(j)=i} \|\mu_{i} - x_{i}\|^{2}$$
 (2)

- K-means algorithm:
 - \triangleright (1) Fix μ , optimize C

$$\min_{C} \sum_{j=1}^{N} \| \mu_{C(j)} - x_{j} \|^{2} = \sum_{j=1}^{N} \min_{C(j)} \| \mu_{C(j)} - x_{j} \|^{2}$$

Exactly first step: assign each point to the nearest cluster center

K-means algorithm

Optimize potential function:

$$\min_{\mu} \min_{C} F(\mu, C) = \min_{\mu} \min_{C} \sum_{i=1}^{K} \sum_{j:C(j)=i} \|\mu_{i} - x_{i}\|^{2}$$
 (2)

- K-means algorithm:
 - \triangleright (2) Fix C, optimize μ

$$\min_{\mu} \sum_{i=1}^{K} \sum_{j:C(j)=i} \|\mu_i - x_j\|^2 = \sum_{i}^{K} \min_{\mu_i} \sum_{j:C(j)=i} \|\mu_i - x_j\|^2$$

Exactly second step: average of points in cluster i

K-means algorithm

Optimize potential function:

$$\min_{\mu} \min_{C} F(\mu, C) = \min_{\mu} \min_{C} \sum_{i=1}^{K} \sum_{j:C(j)=i} \|\mu_{i} - x_{i}\|^{2}$$
 (2)

- K-means algorithm:
 - \triangleright (1) Fix μ , optimize C

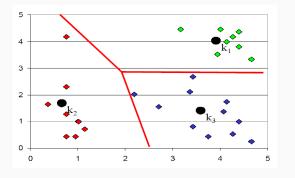
Expectation step

 \triangleright (2) Fix C, optimize μ Maximization step

EM algorithm

Iterations of K-means

K-means decision boundaries

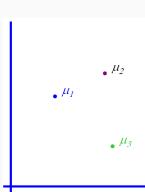


"Linear"
Decision
Boundaries

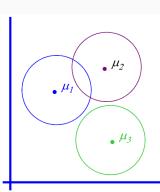
Generative Model:

Assume data comes from a mixture of K Gaussians distributions with same variance.

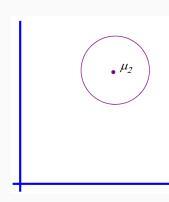
- There are *K* components
- Component i has an associated mean vector μ_i



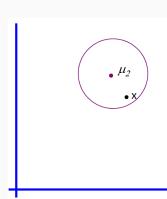
- There are K components
- Component i has an associated mean vector μ_i
- Each component generates data from a Gaussian with mean μ_i and covariance matrix σ^2



- Each data point is generated according to the following recipe:
- (1) Pick a component at random: choose component i with probability P(y = i)



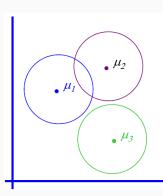
- Each data point is generated according to the following recipe:
- (1) Pick a component at random: choose component i with probability P(y = i)
- (2) Data point $x \sim \mathcal{N}(\mu_i, \sigma^2 \mathbf{I})$



•
$$p(x|y=i) \sim \mathcal{N}(\mu_i, \sigma^2 \mathbf{I})$$

•
$$p(x) = \sum_{i} p(x|y=i)P(y=i)$$

- ▶ Mixture component
- ▶ Mixture proportion



Mixture of K Gaussians distributions: (Multi-model distribution)

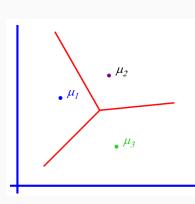
- $p(x|y=i) \sim \mathcal{N}(\mu_i, \sigma^2 \mathbf{I})$
- Gaussian Bayes Classifier:

$$\log \frac{P(y=i|x)}{P(y=j|x)}$$

$$= \log \frac{p(x|y=i)P(y=i)}{p(x|y=j)P(y=j)}$$

$$= \mathbf{w}^{T} x$$

• w depends on $\mu, \sigma^2, P(y)$



"Linear Decision boundary" second-order terms cancel out

Gaussian Mixture Model

EM Algorithm