

# Yuhao Zhang

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1513 University Ave, Room 3158, Madison, WI 53706

## EDUCATION

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### University of Wisconsin-Madison

*Doctor of Philosophy in Mechanical Engineering*

- Advisor: Prof. Xiangru Xu

Madison, WI

Sep 2020 – Present

### University of Michigan-Ann Arbor

*Master of Science in Engineering in Mechanical Engineering*

- Advisor: Prof. Necmiye Ozay and Prof. Jean-Baptiste Jeannin

Ann Arbor, MI

Sep 2017-May 2019

### Peking University

*Bachelor of Engineering in Energy and Power Engineering*

- Advisor: Prof. Jianchun Mi
- Thesis: Experimental and Simulation Research on MILD Combustion Properties in Methanol Boilers
- Double Degree in Economics

Beijing, China

Sep 2013-Jun 2017

## EXPERIENCE

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### University of Wisconsin-Madison

*Research Assistant at Autonomous & Resilient Controls Lab*

- Designed controller for safety-critical systems with measurement and actuation uncertainties, and tested it in both simulations and quadcopter experiments.
- Proposed provable stability conditions for Neural Network Control Systems with dynamics uncertainties.
- Developed optimization-based techniques for formal safety verification and reachability analysis of controlled systems with Artificial Neural Network components.

Madison, WI

Sep 2020-Present

### University of Michigan-Ann Arbor

*Research Associate*

- Designed a high-level software architecture for autonomous taxiing and landing of aircraft.
- Implemented separate modules for the proposed architecture, including a path-finding algorithm, a taxi-way waypoint generator, and a low-level tracking controller.
- Employed falsification techniques to evaluate the performance of the designed controllers.

Ann Arbor, MI

Sep 2018-Jun 2020

### University of Michigan-Ann Arbor

*Grader - EECS 560 "Linear Systems Theory"*

- Helped the course instructor with assignment grading.

Ann Arbor, MI

Jan 2019-May 2019

### University of Michigan-Ann Arbor

*Course Project - Self-driving Cars: Perception and Control*

- Designed a controller for a bicycle model to follow a pre-defined track as rapidly as possible.
- Developed a control algorithm based on MPC to avoid obstacles known only at run-time.

Ann Arbor, MI

Sep 2017-Dec 2017

### Peking University

*Undergraduate Research Assistant at Laboratory of Turbulence & Complex Systems*

- Simulated combustion in traditional boilers and summarize the environmental influence of pollution.
- Experimental and simulation study of methanol MILD combustion in boilers.

Beijing, China

Feb 2016-Jun 2017

### The Chinese University of Hong Kong

*Summer Research Intern at Department of Mechanical and Automation Engineering*

- Worked on harvesting kinetic energy from human motion and vibrations, advised by Prof. Wei-Hsin Liao.

Hong Kong

Jul 2016-Aug 2016

## REPRESENTATIVE PUBLICATIONS

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- Yuhao Zhang**, Xiangru Xu, “*Robust Stability of Neural Feedback Systems with Interval Matrix Uncertain-ties*”, Automatica, 2024. (Provisionally accepted)
- Yuhao Zhang**, Hang Zhang, Xiangru Xu, “*Reachability Analysis of Neural Network Control Systems with Tunable Accuracy and Efficiency*”, IEEE Control Systems Letters, 8: 1697-1702, 2024.
- Yuhao Zhang**, Hang Zhang, Xiangru Xu, “*Backward Reachability Analysis of Neural Feedback Systems Using Hybrid Zonotopes*”, IEEE Control Systems Letters, 7: 2779-2784, 2023.
- Yuhao Zhang**, Xiangru Xu, “*Safety Verification of Neural Feedback Systems Based on Constrained Zono-topes*”, IEEE Conference on Decision and Control, Cancun, Mexico, page 2737-2744, 2022.
- Yuhao Zhang**, Sequoyah Walters, Xiangru Xu, “*Control Barrier Function Meets Interval Analysis: Safety-Critical Control with Measurement and Actuation Uncertainties*”, American Control Conference, Atlanta, GA, USA, page 3814–3819, 2022.
- Sara Shoouri, Shayan Jalili, Jiahong Xu, Isabelle Gallagher, **Yuhao Zhang**, Joshua Wilhelm, Jean-Baptiste Jeannin, Necmiye Ozay, “*Falsification of a Vision-based Automatic Landing System*”, AIAA SciTech Forum, 2021.
- Yuhao Zhang**, Guillaume Poupart-Lafarge, Huaiyuan Teng, Joshua Wilhelm, Jean-Baptiste Jeannin, Necmiye Ozay, Eelco Scholte, “*A software architecture for autonomous taxiing of a*”, AIAA SciTech Forum, 2020.

## SKILLS

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**Software/Programming:** MATLAB, Python, C++, C, Simulink, SolidWorks, PyTorch, Linux, CUDA, FEM  
**Hardware:** Crazyflie quadrotor, Raspberry Pi, Arduino

## LEADERSHIP AND COMMUNITY SERVICE

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| <b>Engineering EXPO</b><br><i>Student Exhibitor</i>  | Madison, WI<br><i>Apr 2023</i>             |
| <ul style="list-style-type: none"><li>Demonstrated quadrotor experiments to middle school students, earning the Honorable Mention Award.</li></ul> |  |
| <b>Practice Department in College of Engineering</b><br><i>Vice President</i>  | Beijing, China<br><i>Sep 2014-Jun 2015</i> |
| <ul style="list-style-type: none"><li>Organized summer-vacation internship programs and scheduled local company visits.</li></ul>                  |  |
| <b>Student Life Department in College of Engineering</b><br><i>Core Member</i>   | Beijing, China<br><i>Sep 2013-Jun 2014</i> |
| <ul style="list-style-type: none"><li>Organized festival celebration activities.</li></ul>   |  |

## AWARDS AND ACHIEVEMENTS

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| <b>Student Research Grants Competition Award</b><br><i>University of Wisconsin-Madison Graduate School</i> | <i>Apr 2023</i> |
| <b>LeRoy Fellowship</b><br><i>Department of Mechanical Engineering, University of Wisconsin-Madison</i>    | <i>Sep 2023</i> |
| <b>XIA Shouyu and HUANG Yuqin Scholarship</b><br><i>College of Engineering, Peking University</i>          | <i>May 2016</i> |
| <b>Community Service Award</b><br><i>College of Engineering, Peking University</i>                         | <i>Dec 2015</i> |
| <b>Second prize in National High School Mathematics Competition</b><br><i>Chinese Mathematical Society</i> | <i>Nov 2012</i> |

## COURSES

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Nonlinear Optimization, Dynamic Programming, High Performance Computing, Advanced Computational Dynamics, Linear System Theory, Robot Kinematics and Dynamics, Self-Driving Cars: Perception and Control