$$f(x) = rac{1}{\sqrt{(2\pi)^k |\Sigma|}} e^{-rac{1}{2}(x-\mu)^T \Sigma^{-1}(x-\mu)},$$

where $x,\mu\in\mathbb{R}^k$, Σ is a k-by-k positive definite matrix and $|\Sigma|$ is its determinant Show that $\int_{\mathbb{R}^k}f(x)\,dx=1.$

Let $y = x - u \Rightarrow dy = dx$ Then

: L is a k-by-k positive definite matrix

... By Cholesky decomposition, we can get $E = LL^T$, where L is an invertible lower triangular matrix.

Then $|E| = |LL^T| = |L||L^T| = |L|^2 = 3 |L| = |E|^{\frac{1}{2}}$

Let $y = L^{-1}(x-x) = 0$ x = u+Ly, dx = |L| dy.

And $(x-u)^T \Sigma'(x-u) = (x-u)^T (LL^T)^{-1} (x-u)$ = $(x-u)^T (L^{-1}L^{-1}) (x-u)$

= (L-(x-u)) T (L-(x-u))

= $y^Ty = ||y||^2$

Hence, $\int_{\mathbb{R}^{k}} \frac{1}{\sqrt{(xx)^{k}|E|}} e^{-\frac{1}{2}(x-u)^{T} E^{-1}(x-u)} dx = \int_{\mathbb{R}^{k}} \frac{1}{\sqrt{(xx)^{k}|E|}} e^{-\frac{1}{2}\|y\|^{2}} |L| dy$

 $= \frac{1}{\{(2\pi)^k} \int_{c=1}^{ca} \left(\int_{-ca}^{ca} e^{-\frac{1}{2}y^2} dy \right) \quad \text{by Gauss integral, } \int_{-ca}^{ca} e^{-\frac{1}{2}x^2} dx = \sqrt{2\pi}$ $= \frac{1}{\{(2\pi)^k} \left(\sqrt{2\pi} \right)^k = 1$

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2. Let A,B be n-by-n matrices and x be a n-by-1 vector. 
 (a) Show that \frac{\partial}{\partial A} {\rm trace}(AB) = B^T.
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(b) Show that
$$x^TAx = \operatorname{trace}(xx^TA)$$
.

(b) Derive the maximum likelihood estimators for a multivariate Gaussian.

(a) Suppose
$$(AB)_{ij} = \stackrel{P}{\underset{k=1}{\mathcal{L}}} A_{ik} B_{kj}$$

trace $(AB) = \stackrel{P}{\underset{k=1}{\mathcal{L}}} (AB)_{ii} = \stackrel{P}{\underset{k=1}{\mathcal{L}}} \stackrel{P}{\underset{k=1}{\mathcal{L}}} A_{ik} B_{ki}$

$$\frac{\partial}{\partial A_{pq}} \operatorname{trace}(AB) = \frac{\partial}{\partial A_{pq}} \left(\sum_{i=1}^{p} \sum_{k=1}^{q} A_{ik} B_{ki} \right) , \quad \frac{\partial A_{ik}}{\partial A_{pq}} = \begin{cases} 1 & \text{if } i=p \text{ and } k=q \\ 0 & \text{o.i.} \end{cases}$$

$$1 \leq p, q \leq n$$

$$= 0 \cdot \sum_{i=p}^{p} \sum_{k=q}^{q} B_{ki} + 1 \cdot B_{qq}$$

Therefore
$$\frac{\partial}{\partial A}$$
 trace $(AB) = B^T$.

(b)
$$x^T A x$$
 is a scalar, $x^T A x = trace(x^T A x)$

Hence, trace
$$(x^TAx) = trace(xx^TA)$$
.

(c) Suppose
$$X_{\bar{i}} \stackrel{\text{lid}}{=} N_n(\mathcal{U}, \mathcal{E})$$
 for $i=1,2,...,m$, where $\mathcal{U} \in \mathbb{R}^n$ and

$$f(x_{\overline{v}}; u, \underline{\Sigma}) = \frac{1}{(2\lambda)^{\frac{n}{2}} |\underline{\Sigma}|^{\frac{1}{2}}} \exp\left(-\frac{1}{2}(x_{\overline{v}} - u)^{T} \underline{\varepsilon}^{-1}(x_{\overline{v}} - u)\right)$$

$$L(u,E) = \prod_{i=1}^{m} f(x_i,u,E) = \frac{1}{(z_i)^{\frac{m}{2}}|E|^{\frac{m}{2}}} \prod_{i=1}^{n} exp(-\frac{1}{z_i}(x_i-u)^T E^{-1}(x_i-u))$$

$$\mathcal{L}(\mathcal{U},\mathcal{E}) = \mathcal{L}_n \mathcal{L}(\mathcal{U},\mathcal{E}) = -\frac{m\pi}{2} \mathcal{L}_n(2z) - \frac{m}{2} \mathcal{L}_n[\mathcal{E}] - \frac{1}{2} \mathcal{L}_n[\chi_{c} - u]^T \mathcal{E}^{-1}(\chi_{c} - u)$$

$$\frac{\partial}{\partial u} l(u, E) = -\frac{1}{2} \sum_{i=1}^{n} \frac{\partial}{\partial u} ((\chi_i - u)^T E^{-1} (\chi_i - u))$$

Let
$$\frac{\partial}{\partial u} \mathcal{L}(u, E) = 0$$
 \Rightarrow $\frac{E}{E}(x_E - u) = 0$ \Rightarrow $\hat{u} = \frac{E}{E}x_E$

Hence,
$$l(u, E) = -\frac{mn}{2} l_n(2x) - \frac{m}{2} l_n(E) - \frac{1}{2} \frac{m}{c} (\chi_c - u)^T E^{-1}(\chi_c - u)$$

Let
$$S = \sum_{i=1}^{n} (\chi_i - u)(\chi_i - u)^T$$

$$\frac{\partial}{\partial \Sigma} \cdot l(u, \Sigma) = \frac{m}{2} \Sigma - \frac{1}{2} \zeta$$
Let
$$\frac{\partial}{\partial \Sigma} \cdot l(u, \Sigma) = 0 \implies \frac{m}{2} \Sigma - \frac{1}{2} \zeta = 0 \implies \hat{\Sigma} = \frac{\zeta}{m} = \frac{1}{m} \cdot \sum_{i=1}^{n} (\chi_i - u)(\chi_i - u)^T$$

#3.

- 1. softmax 的對稱性使不同參數組合給出相同輸出,這會如何影響可 辨識性與正則化設計?
- 2. cross-entropy 對於標註噪聲 (label noise) 敏感度如何?什麼情况需要改用其他損失或加權?