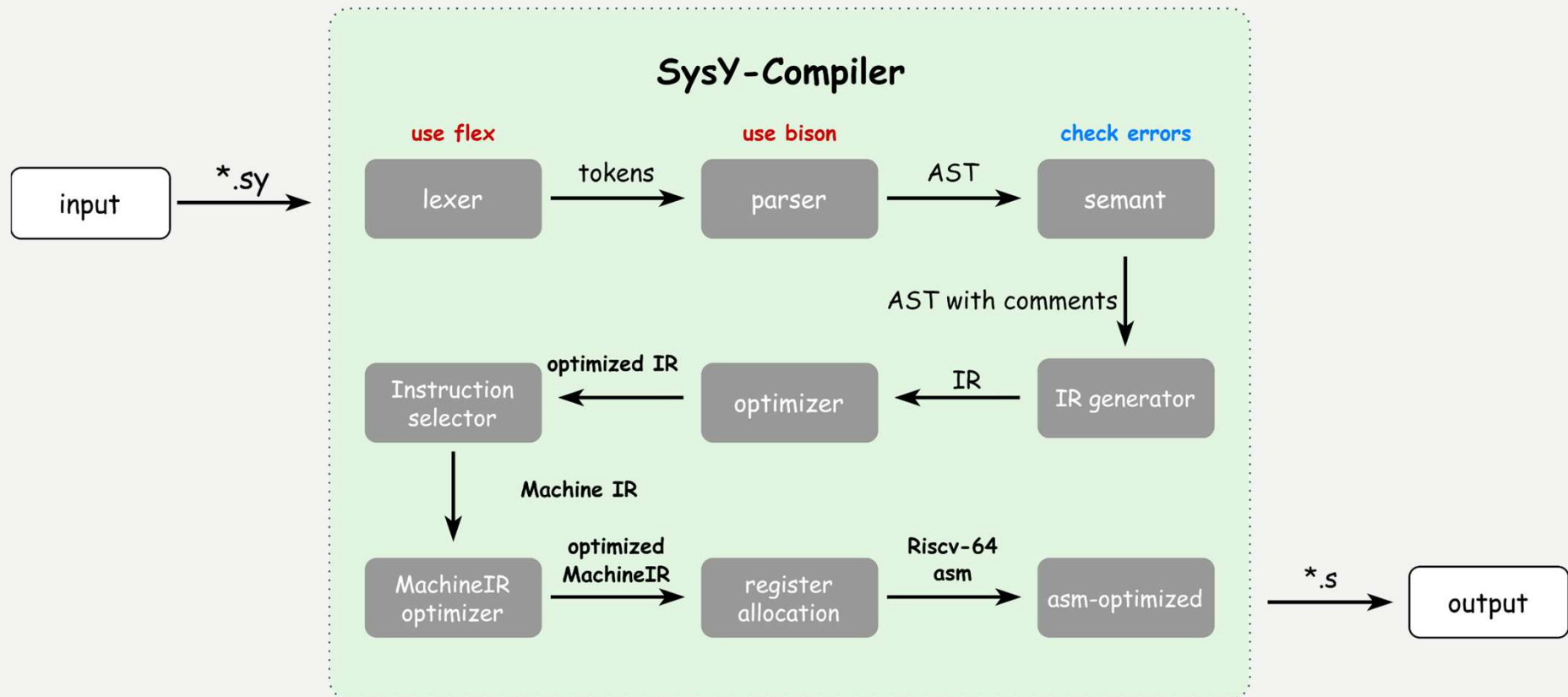


编译器架构



词法分析

```
1  int a = 5;
2  int main()
3  {
4      printf("hello world\n");
5      return 0;
6  }
```

使用flex辅助生成tokens



1	Token	Lexeme	Property	Line	Column
2	INT	int		1	0
3	IDENT	a	a	1	4
4	ASSIGN	=		1	6
5	INT_CONST	5	5	1	8
6	SEMICOLON	;		1	9
7	INT	int		2	0
8	IDENT	main	main	2	4
9	LPAREN	(2	8
10	RPAREN)		2	9
11	LBRACE	{		3	0
12	IDENT	printf	printf	4	4
13	LPAREN	(4	8
14	STR_CONST	"	hello world\n	4	23
15	RPAREN)		4	24
16	SEMICOLON	;		4	25
17	RETURN	return		5	4
18	IDENT	a	a	5	11
19	SEMICOLON	;		5	12
20	RBRACE	}		6	0

语法分析

```
1  int a = 5;  
2  int main()  
3  {  
4      printf("hello world\n");  
5      return 0;  
6  }
```

使用Bison辅助生成语法树



```
1  Program  
2  |  VarDecls  Type: Int  
3  |  |  VarDef  name:a  scope:-1  
4  |  |  |  init:  
5  |  |  |  |  VarInitVal_exp  
6  |  |  |  |  |  Intconst  val:5  Type: Void  
7  |  FuncDef  Name:main  Return Type: Int  
8  |  Block  Size:2  
9  |  |  ExpressionStmt:  Type: Void  
10 |  |  |  FuncCall  name:printf  Type: Void  
11 |  |  |  |  FuncRParams:  
12 |  |  |  |  |  StringConst  type:string  val:hello world\n  
13 |  |  ReturnStmt:  
14 |  |  |  Lval  Type: Void  name:a  scope:-1
```

语义分析

1	Program			
2	VarDecls	Type: Int		
3	VarDef	name:a	scope:-1	
4	init:			
5	VarInitVal_exp			
6	Intconst	val:5	Type: Void	
7	FuncDef	Name:main	ReturnType: Int	
8	Block	Size:2		
9	ExpressionStmt:	Type: Void		
10	FuncCall	name:putf	Type: Void	
11	FuncRParams:			
12	StringConst	type:string	val:hello world	
13	ReturnStmt:			
14	Lval	Type: Void	name:a	scope:-1

1	int a = 5;
2	int main()
3	{
4	putf("hello world\n");
5	return 0;
6	}

1	Program			
2	VarDecls	Type: Int		
3	VarDef	name:a	scope:0	
4	init:			
5	VarInitVal_exp			
6	Intconst	val:5	Type: Int	ConstValue: 5
7	FuncDef	Name:main	ReturnType: Int	
8	Block	Size:2		
9	ExpressionStmt:	Type: Void		
10	FuncCall	name:putf	Type: Void	
11	FuncRParams:			
12	StringConst	type:string	val:hello world\n	
13	ReturnStmt:			
14	Lval	Type: Int	name:a	scope:0

- 识别每个中间变量的类型
- 判断每个变量的作用域
- 预先计算所有常量表达式
- 语义错误检查
 - 使用未定义变量
 - *continue*出现在循环外

中端优化

Mid-End optimizations

Analysis Pass

ControlFlowGraph

DomTree

AliasAnalysis

MemoryDependencyAnalysis

LoopCarriedDependencyAnalysis

LoopBasicInformation

ScalarEvolution

Transform Pass

Redundent-elimination

AggressiveDeadCodeElimination

CommonSubexpressionElimination

DeadStoreElimination

RedundantBranchElimination

loop-optimization

LoopSimplify

LCSSA

LoopInvariantCodeMotion

LoopFullUnroll

LoopIdomRecognize

LoopInvariantCodeMotion

LoopFusion

LoopParallel

LoopStrengthReduce

LoopUnroll

others

Mem2reg

SparseConditionalConstantProagation

Reassociate

FunctionInline

TailRecursiveEliminate

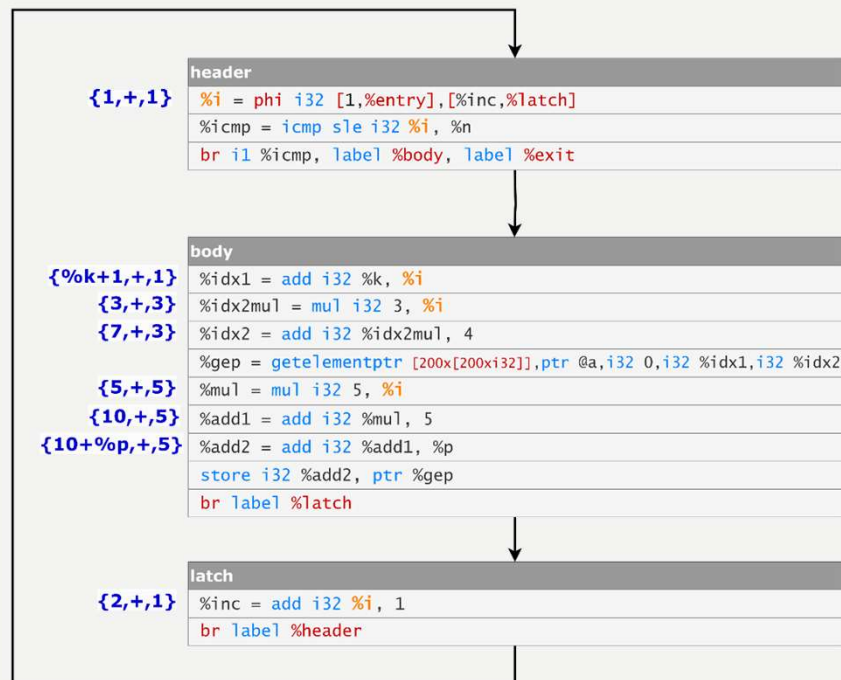
SimplifyCFG

InstSimplify

InstCombine

ScalarEvolution

```
int i = 1;
while(i <= n){
    a[k+i][3*i+4] = 5*i+5+p;
    i = i+1;
}
```



1. 寻找基本归纳变量： 查找header中的phi

`%i = phi i32 [1,%entry],[%inc,%latch]`

2. 识别间接归纳变量： 反复遍历循环每条指令进行判断

`%idx1 = add i32 %k, %i`

3. 判断简单的 for 循环：

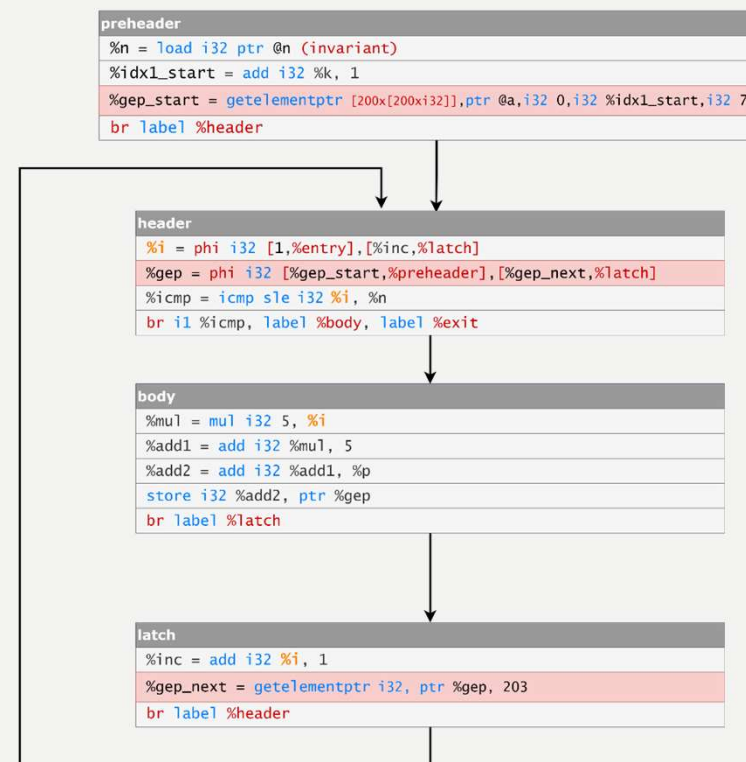
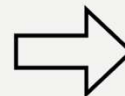
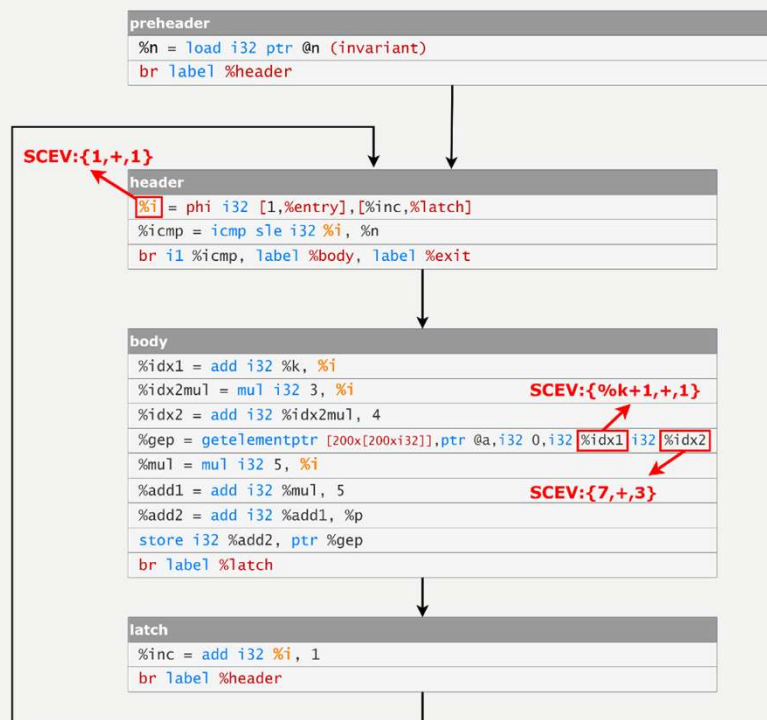
(1) 只有一个exit

(2) 只有一个exiting

(3) exiting分支判断中有一个是归纳变量，另一个是循环不变量

循环强度削弱

```
int a[200][200] = {};  
int i = 1;  
while(i <= n){  
    a[k+i][3*i+4] = 5*i+5+p;  
    i = i+1;  
}
```



循环不变量外提

- ptr 是循环不变量
- 循环中的 store, load, call 不影响 ptr

```
int k = 0;
while(k < n){
    c[i][j] += a[i][k] * b[k][j];
    k = k + 1;
}
```

```
preheader
%gepc = getelementptr [100x[100x132]], ptr @c, i32 0, i32 %i, i32 %j
br label %body
```

```
body
%k = phi i32 [0, %preheader], [%inc, %latch]
%c = load i32 ptr, %gepc
%gepa = getelementptr [100x[100x132]], ptr @a, i32 0, i32 %i, i32 %j
%a = load i32 ptr, %gepa
%gepb = getelementptr [100x[100x132]], ptr @b, i32 0, i32 %i, i32 %j
%b = load i32 ptr, %gepb
%mul = mul i32 %a, %b
%add = add i32 %c, %mul
store i32 %add, ptr %gepc
%inc = add i32 %k, 1
%icmp = icmp slt i32 %inc, %n
br i1 %icmp, label %Label1, label %Label2
```

```
latch
br label %body
```

```
exit
...
```



```
CFG_entry
%tempc_ptr = alloca i32
...
```

some blocks

```
preheader
%gepc = getelementptr [100x[100x132]], ptr @c, i32 0, i32 %i, i32 %j
%c = load i32 ptr, %gepc
store i32 %c, ptr %tempc_ptr
br label %body
```

```
body
%k = phi i32 [0, %preheader], [%inc, %latch]
%tempc = load i32 ptr, %tempc_ptr
%gepa = getelementptr [100x[100x132]], ptr @a, i32 0, i32 %i, i32 %j
%a = load i32 ptr, %gepa
%gepb = getelementptr [100x[100x132]], ptr @b, i32 0, i32 %i, i32 %j
%b = load i32 ptr, %gepb
%mul = mul i32 %a, %b
%add = add i32 %tempc, %mul
store i32 %add, ptr %tempc_ptr
%inc = add i32 %k, 1
%icmp = icmp slt i32 %inc, %n
br i1 %icmp, label %Label1, label %Label2
```

```
latch
br label %body
```

```
exit
%tempc = load i32 ptr, %tempc_ptr
store i32 %tempc, ptr %gepc
...
```

SSAUpdate



```
CFG_entry
(No more alloca for c)
...
```

some blocks

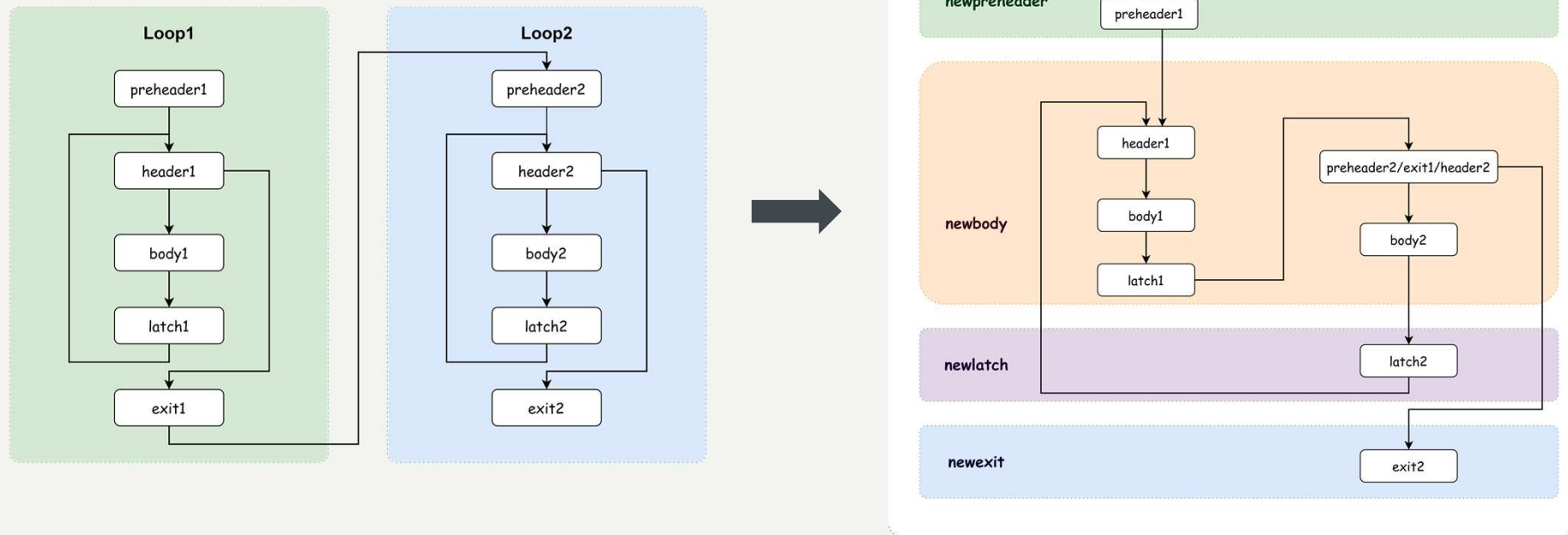
```
preheader
%gepc = getelementptr [100x[100x132]], ptr @c, i32 0, i32 %i, i32 %j
br label %body
```

```
body
%c = phi i32 [0, %preheader], [%inc, %latch]
%k = phi i32 [0, %preheader], [%inc, %latch]
%gepa = getelementptr [100x[100x132]], ptr @a, i32 0, i32 %i, i32 %j
%a = load i32 ptr, %gepa
%gepb = getelementptr [100x[100x132]], ptr @b, i32 0, i32 %i, i32 %j
%b = load i32 ptr, %gepb
%mul = mul i32 %a, %b
%add = add i32 %c, %mul
%inc = add i32 %k, 1
%icmp = icmp slt i32 %inc, %n
br i1 %icmp, label %Label1, label %Label2
```

```
latch
%c = load i32 ptr, %gepc
br label %body
```

```
exit
store i32 %add, ptr %gepc
...
```


循环合并



- 循环步长和上下界相同
- Loop1支配Loop2, Loop2后向支配Loop1
- 循环需要相邻或中间指令可外提至Loop1的preheader
- 合并后不存在后向数据依赖

自动并行化

判断循环能否
自动并行化

使用SCEV
循环内不存在前后依赖
普通循环

并行库
libloop_parallel

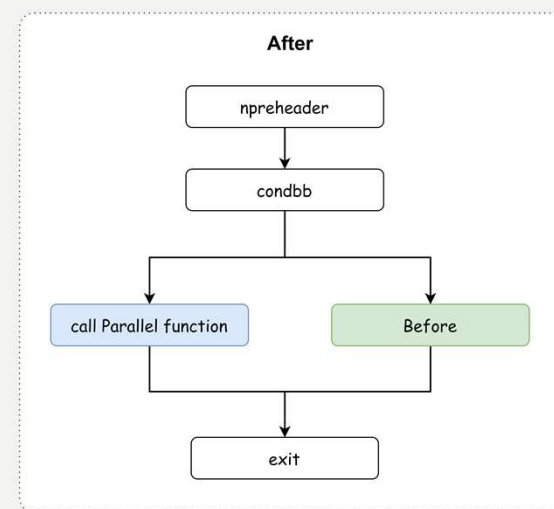
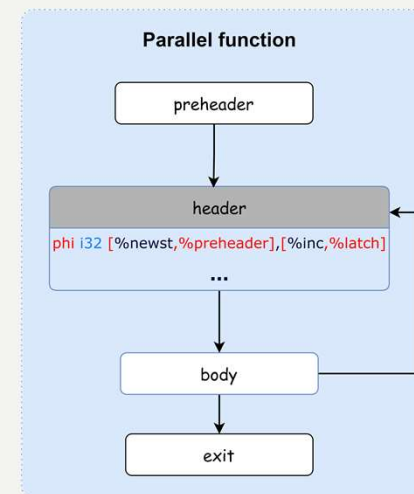
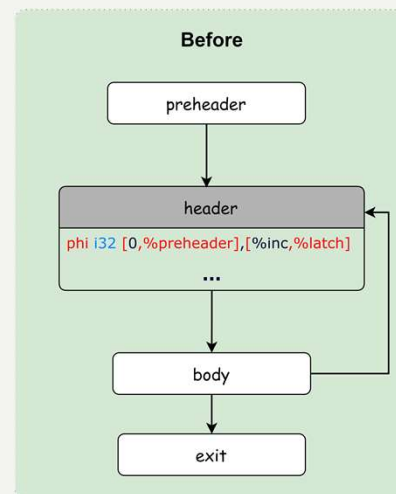
使用pthread
可变参数
步长为常数

循环自动并行化

启发式判断优化条件
循环转为函数
多线程计算

```
void __parallel_loop_constant_100(void *fn, int st, int ed, int len1, int len2, ...)
```

- fn - 并行函数 st - 循环起点 ed - 循环终点
- len1 - 4字节参数数量 len2 - 8字节参数数量
- 按字节读取可变参数: va_start, va_arg, va_end
- pthread创建四线程: pthread_create, pthread_join



其他优化

- 交换运算次序

将 $(a+b)+c$ 转化为 $a+(b+c)$

当 $(b+c)$ 已经计算或为循环不变量时可以优化

Before

```
int b = getint();
int c = getint();
int i = 1;
while(i <= n){
    int t1 = i + b;
    int t2 = t1 + c;
    putint(t2);
    i = i+1;
}
```



After

```
int b = getint();
int c = getint();
int i = 1;
int t1 = b + c;
while(i <= n){
    int t2 = t1 + i;
    putint(t2);
    i = i+1;
}
```

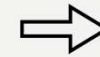
- 模2判断转与判断

将条件判断中的 $\%2$ 转化为 $\&$

有符号不能只与1

Before

```
if(n%2 == 1){
    ...
}
if(n%2 != 1){
    ...
}
if(n%2 == 0){
    ...
}
if(n%2 != 0){
    ...
}
```



After

```
if(n&-2147483647 == 1){
    ...
}
if(n&-2147483647 != 1){
    ...
}
if(n&1 == 0){
    ...
}
if(n&1 != 0){
    ...
}
```

其他优化

- Min-Max识别

识别可以转化为Min-Max的判断语句
变量和数组之间在实现上略有不同

```
Before
if(b > c){
    b = c;
}
if(a[i][j] >= a[i-1][j-1]){
    a[i][j] = a[i-1][j-1];
}
```



```
After
b=min(b,c);
a[i][j]=min(a[i][j],a[i-1][j-1]);
```

- 常量除法判断转乘法判断

在条件判断中，将常量除法的大小判断
转化为常量乘法的大小判断

```
Before
const int c1 = 15;
const int c2 = 25;
if(n / c1 > c2){
    ...
}
if(n / c1 >= c2){
    ...
}
if(n / c1 < c2){
    ...
}
if(n / c1 <= c2){
    ...
}
```



```
After
const int c1 = 15;
const int c2 = 25;
if(n > (c2+1)*c1-1){
    ...
}
if(n >= c2 * c1){
    ...
}
if(n < c2 * c1){
    ...
}
if(n <= (c2+1)*c1-1){
    ...
}
```

后端总体流程

- 指令选择
- Phi消除前代码优化
 - 乘除模常量优化
 - SSA窥孔优化
 - 公共子表达式消除
 - 循环不变量外提
- Phi消除
- 指令调度
- 寄存器分配
- 寄存器分配后的窥孔优化
- 插入ld/sd
- 软件分支预测

指令选择

- 基于窥孔的指令选择
 - 分两次pass进行, 第一个pass翻译函数内IR
 - 第二个pass在开头插入实参

```
define void @fillline(ptr %r0, ptr %r1, i32 %r2)
{
L0: ;
    %r5 = getelementptr i32, ptr %r1, i32 0
    store i32 1, ptr %r5
    %r9 = icmp eq i32 %r2, 1
    br i1 %r9, label %L3, label %L1
L1: ;
    %r14 = add i32 %r2, -1
    %r44 = getelementptr i32, ptr %r0, i32 0
    store i32 1, ptr %r44
    %r45 = icmp eq i32 %r14, 1
    br i1 %r45, label %L7, label %L5
```

```
fillline:
.fillline_0:
    %2 = COPY a2, i64
    %1 = COPY a1, i64
    %0 = COPY a0, i64
    %4 = COPY %1, i64
    %6 = COPY 1, i64
    sw      %6, 0(%4)
    %8 = COPY 1, i64 # Can't schedule
    beq     %2, %8, .fillline_3 # Can't schedule
.fillline_1:
    addiw   %9, %2, -1
    %11 = COPY %0, i64
    %13 = COPY 1, i64
    sw      %13, 0(%11)
    %15 = COPY 1, i64 # Can't schedule
    beq     %9, %15, .fillline_7 # Can't schedule
```

SSA窥孔优化

- Phi消除前代码优化
 - 乘除模常量优化
 - SSA窥孔优化
 - 公共子表达式消除
 - 循环不变量外提

```
%2 = COPY 8, i64
mulw    %1,%0,%2
%4 = COPY 2, i64
divw    %3,%0,%4
addw    %5,%1,%3
%7 = COPY 3, i64
divw    %6,%0,%7
addw    %8,%5,%6
```

```
%2 = COPY 8, i64
slliw   %1,%0,3
%4 = COPY 2, i64
srliw   %37,%0,31
add     %38,%0,%37
sraiw   %3,%38,1
addw    %5,%1,%3
%7 = COPY 3, i64
%39 = COPY 1431655766, i64
mul     %40,%0,%39
srli    %41,%40,63
srli    %42,%40,32
add     %6,%42,%41
addw    %8,%5,%6
```

```
%2 = COPY 8, i64
slliw   %1,%0,3
%4 = COPY 2, i64
srliw   %37,%0,31
add     %38,%0,%37
sraiw   %3,%38,1
sh3add.uw %5,%0,%3
%7 = COPY 3, i64
%39 = COPY 1431655766, i64
mul     %40,%0,%39
srli    %41,%40,63
srli    %42,%40,32
add     %6,%42,%41
addw    %8,%5,%6
```


指令调度

- 实例：减少RAW阻塞
- 只考虑块内的指令调度

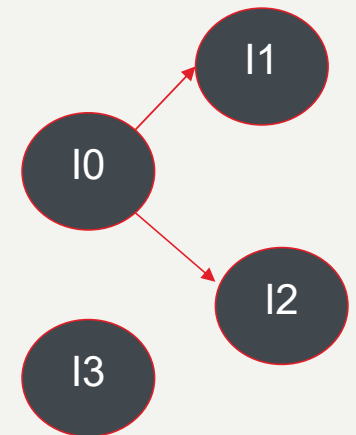
```
addw    %3,%1,%2
addw    %4,%0,%3
addw    %5,%4,%3
addw    %6,%0,%2
```

```
addw    %3,%1,%2
addw    %6,%0,%2
addw    %4,%0,%3
addw    %5,%4,%3
```

指令调度

- 算法: List scheduling
- ①建立数据优先图 (有向无环)
- ②找到更好的拓扑序
- 模拟指令的发射与延迟
 - 模拟处理器状态, 维护指令执行完成的倒计时; 模拟双发射
 - 指令发射后, 数据优先图不会立即删除相应结点, 而是等指令倒计时结束才删除
- 尽可能先发射最长路径更长的指令 (以指令延迟为路径长度)
- 如果发现发射某条指令后, 寄存器压力过大以致溢出, 会尝试发射其它指令, 如果可发射的任意指令发射完都会溢出, 仍选择最长路径更长的指令发射

I0	addw	%3,%1,%2
I1	addw	%4,%0,%3
I2	addw	%5,%4,%3
I3	addw	%6,%0,%2



寄存器分配

- 算法：线性扫描；活跃区间可以是不连续的多段
- 溢出权重：被指令引用的总次数/区间总长；优先溢出权重低的
- 循环外，每遇到一个被引用的操作数，引用次数+1
- 循环内，每遇到一个被引用的操作数，引用次数+ $2^{\min(5, loopdepth)} + loopdepth + 1$
- 溢出处理
- 在溢出的位置插入ld/sd，重新分配，迭代至不动点
- 区间合并 (Coalesce)
- 采用激进的合并策略（只要不冲突并且有COPY语句连接，就合并）
- 分配时，如果有类似%0 = COPY a0的语句，会优先尝试给%0分配a0

活跃区间分段的例子

- 多个def会导致分段
- 在不连续的基本块内活跃也会导致分段
- 活跃区间分段可以大大减少实际上不存在的区间冲突

1 7 [11,12) [13,35) [42,43) Ref: 42

```
main:
.main_0:
    lui        %2,%hi(A)
    addi       %3,%2,%lo(A)
    addi       %1,%3,12
.main_7:
    %202 = COPY %1, i64
    addiw      %203,x0,0
    lui        %206,24 # Can't schedule
    addiw      %38,%206,1688 # Can't schedule
    %5 = COPY %202, i64 # Can't schedule
    %7 = COPY %203, i64 # Can't schedule
```

```
.main_5:
    addi       %6,%5,160
    %5 = COPY %6, i64 # Can't schedule
    %7 = COPY %8, i64 # Can't schedule
    jal        x0,.main_1 # Can't schedule
```

区间合并 (Coalesce) 的例子

- 激进的合并策略
- 其中一个例子: 41个区间->30个区间
- 其中一个区间合并的实例

```
%5 = COPY %202, i64
```

```
%5 = COPY %6, i64
```

```
1 Check Intervals main Before Coalesce
2 0 0 [4,4) [5,7) [12,12) [38,38) [43,43)
3 0 1 [0,4) [5,12) [13,38) [39,43) [44,44)
4 0 10 [70,71) Ref: 4
5 1 1 [3,4) [5,6) Ref: 4
6 1 2 [1,2) Ref: 4
7 1 3 [2,4) [5,12) [13,38) [39,43) [44,44)
8 1 5 [10,12) [13,38) [39,40) [41,43) Ref: 4
9 1 6 [40,41) Ref: 8
34 1 50 [46,47) Ref: 4
35 1 51 [45,46) Ref: 4
36 1 52 [47,48) Ref: 4
37 1 202 [6,10) Ref: 4
38 1 203 [7,11) Ref: 4
```

```
44 Check Intervals main After Coalesce
45 0 0 [4,4) [5,7) [12,12) [38,38) [43,43)
46 0 1 [0,4) [5,12) [13,38) [39,43) [44,44)
47 0 10 [70,71) Ref: 4
48 1 2 [1,2) Ref: 4
49 1 3 [2,4) [5,12) [13,38) [39,43) [44,44)
50 1 5 [3,4) [5,6) [6,10) [10,12) [13,38)
51 1 7 [7,11) [11,12) [13,35) [35,38) [39,43)
```

寄存器分配

- 避免WAW冲突
- 检查虚拟寄存器被def的语句的周围(同一个基本块内 $[-10, +latency]$)
- 优先分配指令附近没有被def的物理寄存器

```
t4 = 3
t1 = t2 + t3
%3 = t2 / t3 // %3 应当最后才尝试分配到t1或t5
// ...
t5 = ... // %3 指令latency范围以内
```

- 窥孔优化: 删除冗余的读溢出语句

```
addi    t2,t0,16
# Write Spill
sd       t2,304(sp)
# store i32 %r314, ptr %r318
# Read Spill
ld       t2,304(sp)
sw       t3,0(t2)
```

寄存器分配之后的优化

- 插入s寄存器的ld/sd
- 有时，会存在部分控制流，这些控制流不经过部分s寄存器的def。这时，我们不需要将sd语句插入一开头的位置，ld语句也不需要插入结尾的位置，这样可以减少sd/ld的执行次数
- 对于一个s寄存器，找到所有出现的块，在前向/后向支配树求取LCA
- 先在后向支配树的LCA上插入ld，后在前向支配树的LCA上插入sd
- 软件分支预测
- 为了让指令cache能更好地加速取指，高概率进入的分支应当是false分支，否则true和false分支要反转
- 我们认为，凡是进入循环的分支，都是高概率的分支。如果进入循环的分支是true分支，则分支要反转，否则分支不反转。
- 因为while转do-while和循环展开都会生成大量的大概率是true分支的代码，所以我们认为检测不到循环的情况下仍然是进入true分支的几率大