

CS 217 – Algorithm Design and Analysis

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You will receive feedback from the TA.

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7 Farkas Lemma and LP Duality

7.1 Different Versions of Farkas Lemma

In the following, let $A \in \mathbb{R}^{m \times n}$ and $\mathbf{b} \in \mathbb{R}^m$, and let $\mathbf{x} = (x_1, \dots, x_n)^T$ be a column vector of n variables and $\mathbf{y} = (y_1, \dots, y_m)$ be a row vector of m variables.

Exercise 1. Show that the three versions of Farkas Lemma presented in class are all equivalent (I actually did not present the third version in class):

$$(\neg \exists \mathbf{x} : A\mathbf{x} \leq \mathbf{b}) \iff (\exists \mathbf{y} \geq \mathbf{0} : \mathbf{y}^T A = \mathbf{0}, \mathbf{y}^T \mathbf{b} < 0) . \quad (1)$$

$$(\neg \exists \mathbf{x} \geq \mathbf{0} : A\mathbf{x} \leq \mathbf{b}) \iff (\exists \mathbf{y} \geq \mathbf{0} : \mathbf{y}^T A \geq \mathbf{0}, \mathbf{y}^T \mathbf{b} < 0) . \quad (2)$$

$$(\neg \exists \mathbf{x} \geq \mathbf{0} : A\mathbf{x} = \mathbf{b}) \iff (\exists \mathbf{y} : \mathbf{y}^T A \geq \mathbf{0}, \mathbf{y}^T \mathbf{b} < 0) . \quad (3)$$

Note that the direction “ \Leftarrow ” is easy in each case. We will show the “ \Rightarrow ” of (1) in class using a technique called *Fourier-Motzkin Elimination*. This exercise is actually not that hard. The hardest part is keeping track of what you want to prove and what you can assume.

7.2 A Linear Program for, well, for what?

Let $G = (V, E)$ be a directed graph, $s, t \in V$, and $c : E \rightarrow \mathbf{R}^+$ be a cost function. We want to find an $s - t$ -flow f of value 1. Every edge e generates cost $f(e) \cdot c(e)$, and we want to minimize the overall cost. There are no capacity constraints. We can easily write this as a linear program MCF (Minimum Cost Flow):

$$\begin{aligned} & \text{minimize} && \sum_{e \in E} c(e)f(e) \\ \text{MCF}(G, s, t, c) : & \text{subject to} && \sum_{v \in V} f(v, t) = 1 \\ & && \sum_{u \in V} f(u, v) - \sum_{w \in V} f(v, w) = 0 \quad \forall v \in V \setminus \{s, t\} \\ & && f(e) \geq 0 \quad \forall e \in E \end{aligned}$$

Note that we have m variables, one variable $f(e)$ for each edge e . The first constraint says that the value of the flow should be 1. The other constraints say that the inflow at v should equal the outflow.

Exercise 2. Let d be the shortest path distance from s to t in the directed graph G , where distance means sum of the $c(e)$ along the path. Show that $\text{opt}(MCF) = d$. **Hint.** Make sure you show both \leq and \geq .

Proof. To prove $\text{opt}(MCF) \leq d$, we just need to prove that the shortest path is a solution to MCF . We set $f(e) = 1$ along all edges in the shortest path, since there is only one path with flow 1. The constraints are obviously satisfied. So it is a solution of MCF , and its value is $1 * d = d$, so $\text{opt}(MCF) \leq d$.

To prove $\text{opt}(MCF) \geq d$, we need to prove that all solutions of MCF is not better than d . We try to improve the value of all possible solutions to d .

Suppose we have a solution with x different $s - t$ path. Define $b(\text{path})$ be the smallest flow in all edges of path , $d(\text{path})$ be the length of path . Let sp be the shortest $s - t$ path. We do as follows, choose any path p besides sp , put $b(p)$ units of flow on p to sp . Repeat it until there is only 1 unit flowing through sp .

We need to show in each turn, $\text{val}(MCF)$ is not worse than previous and no constraints are broke. We first prove $\text{val}(MCF)$ is not worse. In each turn, $\text{val}(MCF)' = \text{val}(MCF) + d * b(p) - d(p) * b(p)$, $d \leq d(p)$, so $\text{val}(MCF)' \leq \text{val}(MCF)$. As for the constraints, inflow of t remains to be 1 since we just move $b(p)$ units between two different paths. Flow constraints

remains since we modify the flow in one path, which means we move inflow and outflow of a single vertex at the same time. Since we only have x different $s - t$ path, and the flow value on each path is finite, the process terminates. So $val(MCF) \geq d$

In all $val(MCF) = d$ \square

Exercise 3. Write down the dual of MCF. This will be a maximization problem. Don't use any matrix notation.

Proof. We introduce a dual coefficient $g_v, v \in V$. The dual program is:

- Maximize g_t , subject to:
- $g_v - g_u \leq c(u, v), \forall (u, v) \in E$
- $g_v \in \mathbb{R}, v \in V$

\square

Exercise 4. Interpret the dual. Show that it is the LP formulation of a “natural” maximization problem on G .

Proof. If we set $g_s = 0$, then the g_v can be thought as the cost of some $s - t$ -path. Since each edge (u, v) must satisfy $g_v - g_u \leq c(u, v)$, we can not just choose the maximal $s - t$ -path as solution. Under this constraint, we can see that the solution must at first be a **safe** path, so the program is actually the shortest path problem. \square

Exercise 5. Describe an optimal solution of the dual program.

Proof. The optimal solution is the shortest $s - t$ -path sp , and for each vertex along the path, we must set $g_v = g_u$ for $(u, v), u \in sp, v \notin sp$ accordingly to $g_v - g_u$ constraints. \square