Coherent Closure on Non-Distance Regular Graphs

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Historical Motivation

Euler's 36 Officers Problem (1782):

- Arrange 36 officers in a 6×6 square.
- 6 ranks × 6 regiments.
- Each row and column must contain exactly one of each rank and regiment.
- Euler conjectured this is impossible (now proven true).

This inspired the study of MOLS, Mutually Orthogonal Latin Squares.



What Are MOLS?

- A Latin square, L of order n is a $n \times n$ grid filled with n symbols, with no repeats per row or column.
- Two Latin squares, $L^{(1)}$ and $L^{(2)}$ are **orthogonal** if pairs $(L_{i,j}^{(1)}, L_{i,j}^{(2)})$ are all distinct.
- A set of Latin squares is **mutually orthogonal** if every pair of Latin squares in the set are orthogonal to each other.

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MOLS(4)

$$L^{(1)} = \begin{bmatrix} 1 & 2 & 3 & 4 \\ 2 & 1 & 4 & 3 \\ 3 & 4 & 1 & 2 \\ 4 & 3 & 2 & 1 \end{bmatrix}, \quad L^{(2)} = \begin{bmatrix} 1 & 2 & 3 & 4 \\ 4 & 3 & 2 & 1 \\ 2 & 1 & 4 & 3 \\ 3 & 4 & 1 & 2 \end{bmatrix}, \quad L^{(3)} = \begin{bmatrix} 1 & 2 & 3 & 4 \\ 3 & 4 & 1 & 2 \\ 4 & 3 & 2 & 1 \\ 2 & 1 & 4 & 3 \end{bmatrix};$$

$$L^{\{1,2\}} = \begin{bmatrix} (1,1) & (2,2) & (3,3) & (4,4) \\ (2,4) & (1,3) & (4,2) & (3,1) \\ (3,2) & (4,1) & (1,4) & (2,3) \\ (4,3) & (3,4) & (2,1) & (1,2) \end{bmatrix}.$$

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MOLS(4)

$$L^{(1)} = \begin{bmatrix} 1 & 2 & 3 & 4 \\ 2 & 1 & 4 & 3 \\ 3 & 4 & 1 & 2 \\ 4 & 3 & 2 & 1 \end{bmatrix}, \quad L^{(2)} = \begin{bmatrix} 1 & 2 & 3 & 4 \\ 4 & 3 & 2 & 1 \\ 2 & 1 & 4 & 3 \\ 3 & 4 & 1 & 2 \end{bmatrix}, \quad L^{(3)} = \begin{bmatrix} 1 & 2 & 3 & 4 \\ 3 & 4 & 1 & 2 \\ 4 & 3 & 2 & 1 \\ 2 & 1 & 4 & 3 \end{bmatrix};$$

$$L^{\{1,3\}} = \begin{bmatrix} (1,1) & (2,2) & (3,3) & (4,4) \\ (2,3) & (1,4) & (4,1) & (3,2) \\ (3,4) & (4,3) & (1,2) & (2,1) \\ (4,2) & (3,1) & (2,4) & (1,3) \end{bmatrix}.$$

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MOLS(4)

$$L^{(1)} = \begin{bmatrix} 1 & 2 & 3 & 4 \\ 2 & 1 & 4 & 3 \\ 3 & 4 & 1 & 2 \\ 4 & 3 & 2 & 1 \end{bmatrix}, \quad L^{(2)} = \begin{bmatrix} 1 & 2 & 3 & 4 \\ 4 & 3 & 2 & 1 \\ 2 & 1 & 4 & 3 \\ 3 & 4 & 1 & 2 \end{bmatrix}, \quad L^{(3)} = \begin{bmatrix} 1 & 2 & 3 & 4 \\ 3 & 4 & 1 & 2 \\ 4 & 3 & 2 & 1 \\ 2 & 1 & 4 & 3 \end{bmatrix};$$

$$L^{\{2,3\}} = \begin{bmatrix} (1,1) & (2,2) & (3,3) & (4,4) \\ (4,3) & (3,4) & (2,1) & (1,2) \\ (2,4) & (1,3) & (4,2) & (3,1) \\ (3,2) & (4,1) & (1,4) & (2,3) \end{bmatrix}.$$

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What is an Orthogonal Array?

Definition: An **orthogonal array** OA(m, n) is an $m \times n^2$ array over [n], such that:

• Every pair of rows contains each tuple of $[n] \times [n]$ exactly once.

We can build OA(m, n) by using a set of m-2 MOLS(n), $\{L^{(1)}, \ldots, L^{(m-2)}\}$, and write their symbols in such a manner:

$$\mathsf{OA}(m,n) = \begin{bmatrix} 1 & 1 & \dots & r & \dots & n & n \\ 1 & 2 & \dots & c & \dots & n-1 & n \\ L_{1,1}^{(1)} & L_{1,2}^{(1)} & \dots & L_{r,c}^{(1)} & \dots & L_{n,n-1}^{(1)} & L_{n,n}^{(1)} \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \\ L_{1,1}^{(m-2)} & L_{1,2}^{(m-2)} & \dots & L_{r,c}^{(m-2)} & \dots & L_{n,n-1}^{(m-2)} & L_{n,n}^{(m-2)} \end{bmatrix}.$$

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Block Graph

Definition: A **block graph** induced by an orthogonal array OA(m, n) is a simple graph G = (V, E) with the following properties:

- $|V| = n^2$;
- Vertices are labeled by tuples (r, c) where $r, c \in [n]$;
- Two vertices (r_1, c_1) and (r_2, c_2) are adjacent, i.e., $(r_1, c_1) \sim (r_2, c_2)$, if and only if:

the tuples
$$(r_1, c_1, L_{r_1, c_1}^{(1)}, \dots, L_{r_1, c_1}^{(m-2)})$$
 and $(r_2, c_2, L_{r_2, c_2}^{(1)}, \dots, L_{r_2, c_2}^{(m-2)})$ agree in exactly one coordinate.

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Example of OA(3,3)

Consider this Latin Square of order 3:

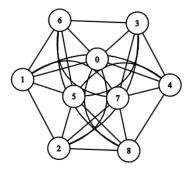
$$L = \begin{bmatrix} 1 & 2 & 3 \\ 3 & 1 & 2 \\ 2 & 3 & 1 \end{bmatrix}.$$

• Construct OA(3,3) with each column: row column

$$OA(3,3) = \begin{bmatrix} 1 & 1 & 1 & 2 & 2 & 2 & 3 & 3 & 3 \\ 1 & 2 & 3 & 1 & 2 & 3 & 1 & 2 & 3 \\ 1 & 2 & 3 & 3 & 1 & 2 & 2 & 3 & 1 \end{bmatrix}.$$

Example of OA(3,3)

OA(3,3) and its block graph



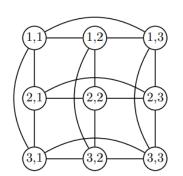
$$\mathsf{OA}(3,3) = \begin{bmatrix} 1 & 1 & 1 & 2 & 2 & 2 & 3 & 3 & 3 \\ 1 & 2 & 3 & 1 & 2 & 3 & 1 & 2 & 3 \\ 1 & 2 & 3 & 3 & 1 & 2 & 2 & 3 & 1 \end{bmatrix}.$$

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Base Case: Block Graph of OA(2,3)

This smaller case of a block graph guides our construction of more complex graphs.

$$OA(2,3) = \begin{bmatrix} 1 & 1 & 1 & 2 & 2 & 2 & 3 & 3 & 3 \\ 1 & 2 & 3 & 1 & 2 & 3 & 1 & 2 & 3 \end{bmatrix}$$



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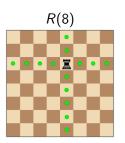
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Rook Graphs: Definition

Definition: The **rook graph** R(n) is the block graph induced by OA(2, n), $n \ge 2$.

- Vertices represent an $n \times n$ chessboard;
- Edges can be interpreted as possible moves for a rook to move on the chessboard.

$$A(R(n)) = \underbrace{\begin{bmatrix} J_n - I & I_n & \cdots & I_n \\ I_n & J_n - I & \cdots & I_n \\ \vdots & \vdots & \ddots & \vdots \\ I_n & I_n & \cdots & J_n - I \end{bmatrix}}_{n \text{ blocks}}.$$



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Coherent Configurations

Let V be a finite set and $\mathcal{R} = \{R_1, \dots, R_r\}$ be a set of binary relations. For each R_i , let $W_i \in \mathsf{Mat}_V(\{0,1\})$ be defined such that its (x,y) entry is 1 if $(x,y) \in R_i$ and 0 otherwise. Suppose the following 4 conditions

- $\sum_{i=1}^{r} W_i = J$;
- For each $i \in [r]$, there exists $j \in [r]$ such that $W_i^T = W_j$;
- There exists a subset $\Delta \subseteq [r]$ such that $\sum_{i \in \Delta} W_i = I$;
- $W_iW_j = \sum_{k=1}^r p_{i,j}^k W_k$ for some constants $p_{i,j}^k \in \mathbb{Z}_{\geq 0}$, for all $i,j \in [r]$.

Then (V, \mathcal{R}) is called a **coherent configuration** of **rank** $|\mathcal{R}| = r$.

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Coherent Algebras

Definition: A matrix algebra $A \subset Mat(\mathbb{C})$ satisfies the following:

- Spanned by unique basis $\{0,1\}$ -matrices: $\{A_1,\ldots,A_r\}$;
- Closed under matrix multiplication, transpose, and Hadamard product;
- $I, J \in \mathcal{A}$.

We say A(G) is a **coherent algebra** containing the adjacency matrix of G when we talk about coherent algebras in this presentation.

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Coherent Algebras

Key Property: If A_1 , A_2 are coherent algebras containing the adjacency matrix of a graph G, then $A' = A_1 \cap A_2$ is also a coherent algebra containing the adjacency matrix of a graph G.

Thus, we are motivated to find the minimal coherent algebra, which we call the coherent closure.

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Coherent Closure, W(G)

Definition: The minimal coherent algebra containing the adjacency matrix of a graph G = (V, E) is called the **coherent closure**, and denoted as $\mathcal{W}(G)$.

Properties:

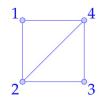
- $A(G) \in \mathcal{W}(G)$;
- Basis matrices, $\{W_1, W_2, \dots, W_r\}$, represent structural relations in the graph;
- The number of basis matrices in the coherent closure is called the coherent rank of G.

$$\operatorname{cr}(G) = |\mathcal{W}(G)| = r.$$

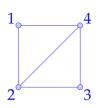
We investigate how this algebra changes under graph operations that disrupt the regularity of a graph.

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$$A_1 = \begin{bmatrix} a & b & c & b \\ b & a & b & b \\ c & b & a & b \\ b & b & b & a \end{bmatrix}$$



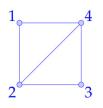
$$A_1 = \begin{bmatrix} a & b & c & b \\ b & a & b & b \\ c & b & a & b \\ b & b & b & a \end{bmatrix}$$



$$A_1^2 = \begin{bmatrix} a^2 + 2b^2 + c^2 & ab + ba + b^2 + cb & ac + 2b^2 + ca & ab + ba + b^2 + cb \\ ab + ba + b^2 + bc & a^2 + 3b^2 & ab + ba + b^2 + bc & ab + ba + 2b^2 \\ ac + 2b^2 + ca & ab + ba + b^2 + cb & a^2 + 2b^2 + c^2 & ab + ba + b^2 + cb \\ ab + ba + b^2 + bc & ab + ba + 2b^2 & ab + ba + b^2 + bc & a^2 + 3b^2 \end{bmatrix}$$

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$$A_1 = \begin{bmatrix} a & b & c & b \\ b & a & b & b \\ c & b & a & b \\ b & b & b & a \end{bmatrix}$$

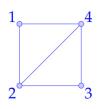


$$A_{1}^{2} = \begin{bmatrix} a^{2} + 2b^{2} + c^{2} & ab + ba + b^{2} + cb & ac + 2b^{2} + ca & ab + ba + b^{2} + cb \\ ab + ba + b^{2} + bc & a^{2} + 3b^{2} & ab + ba + b^{2} + bc & ab + ba + 2b^{2} \\ ac + 2b^{2} + ca & ab + ba + b^{2} + cb & a^{2} + 2b^{2} + c^{2} & ab + ba + b^{2} + cb \\ ab + ba + b^{2} + bc & ab + ba + 2b^{2} & ab + ba + b^{2} + bc & a^{2} + 3b^{2} \end{bmatrix}$$

$$\mathcal{A}_2 = \left[egin{matrix} \mathbf{a} & & \ & \mathbf{a} & \ & & \ & \mathbf{a} & \ \end{array}
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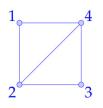
$$A_1 = \begin{bmatrix} a & b & c & b \\ b & a & b & b \\ c & b & a & b \\ b & b & b & a \end{bmatrix}$$



$$A_{1}^{2} = \begin{bmatrix} a^{2} + 2b^{2} + c^{2} & ab + ba + b^{2} + cb & ac + 2b^{2} + ca & ab + ba + b^{2} + cb \\ ab + ba + b^{2} + bc & a^{2} + 3b^{2} & ab + ba + b^{2} + bc & ab + ba + 2b^{2} \\ ac + 2b^{2} + ca & ab + ba + b^{2} + cb & a^{2} + 2b^{2} + c^{2} & ab + ba + b^{2} + cb \\ ab + ba + b^{2} + bc & ab + ba + 2b^{2} & ab + ba + b^{2} + bc & a^{2} + 3b^{2} \end{bmatrix}$$

$$A_2 = \begin{bmatrix} a & b & b \\ & b & a & b \end{bmatrix}$$

$$A_1 = \begin{bmatrix} a & b & c & b \\ b & a & b & b \\ c & b & a & b \\ b & b & b & a \end{bmatrix}$$

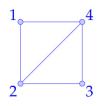


$$A_1^2 = \begin{bmatrix} a^2 + 2b^2 + c^2 & ab + ba + b^2 + cb & ac + 2b^2 + ca & ab + ba + b^2 + cb \\ ab + ba + b^2 + bc & a^2 + 3b^2 & ab + ba + b^2 + bc & ab + ba + 2b^2 \\ ac + 2b^2 + ca & ab + ba + b^2 + cb & a^2 + 2b^2 + c^2 & ab + ba + b^2 + cb \\ ab + ba + b^2 + bc & ab + ba + 2b^2 & ab + ba + b^2 + bc & a^2 + 3b^2 \end{bmatrix}$$

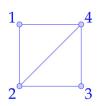
$$A_2 = \begin{bmatrix} a & b & c & b \\ d & e & d & f \\ c & b & a & b \\ d & f & d & e \end{bmatrix}$$

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$$A_2 = \begin{bmatrix} a & b & c & b \\ d & e & d & f \\ c & b & a & b \\ d & f & d & e \end{bmatrix}$$

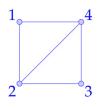


$$A_2 = \begin{bmatrix} a & b & c & b \\ d & e & d & f \\ c & b & a & b \\ d & f & d & e \end{bmatrix}$$



$$A_{2}^{2} = \begin{bmatrix} a^{2} + 2bd + c^{2} & ab + be + bf + cb & ac + 2bd + ca & ab + be + bf + cb \\ da + dc + ed + fd & 2db + e^{2} + f^{2} & da + dc + ed + fd & 2db + ef + fe \\ ac + 2bc + ca & ab + be + bf + cb & a^{2} + 2bd + c^{2} & ab + be + bf + cb \\ da + dc + ed + fd & 2db + ef + fe & da + dc + ed + fd & 2db + e^{2} + f^{2} \end{bmatrix}$$

$$A_2 = \begin{bmatrix} a & b & c & b \\ d & e & d & f \\ c & b & a & b \\ d & f & d & e \end{bmatrix}$$



$$ab + be + bf + cb$$

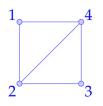
$$2db + ef + fe$$

$$ab + be + bf + cb$$

$$2db + e^{2} + f^{2}$$

$$A_{3} = \begin{bmatrix} a & b & c & b \\ d & e & d & f \\ c & b & a & b \\ d & f & d & e \end{bmatrix}$$

$$A_2 = \begin{bmatrix} a & b & c & b \\ d & e & d & f \\ c & b & a & b \\ d & f & d & e \end{bmatrix}$$



$$A_2^2 = \begin{bmatrix} a^2 + 2bd + c^2 & ab + be + bf + cb & ac + 2bd + ca \\ da + dc + ed + fd & 2db + e^2 + f^2 & da + dc + ed + fd \\ ac + 2bc + ca & ab + be + bf + cb & a^2 + 2bd + c^2 \\ da + dc + ed + fd & 2db + ef + fe & da + dc + ed + fd \end{bmatrix}$$

$$ab + be + bf + cb$$

 $2db + e^2 + f^2$
 $ab + be + bf + cb$
 $2db + ef + fe$

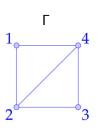
$$a^{2} + 2bd + c^{2}$$

$$da + dc + ed + fc$$

$$ab + be + bf + cb$$
$$2db + ef + fe$$
$$ab + be + bf + cb$$
$$2db + e^{2} + f^{2}$$

$$A_{3} = \begin{bmatrix} a & b & c & b \\ d & e & d & f \\ c & b & a & b \\ d & f & d & e \end{bmatrix} = A_{2}$$

$$\mathcal{W}(\Gamma) = \begin{bmatrix} a & b & c & b \\ d & e & d & f \\ c & b & a & b \\ d & f & d & e \end{bmatrix}$$



We say " Γ has **coherent rank** 6".

Choice of Base Graph

We want graphs with a known coherent rank, such as strongly regular graphs.

Strongly regular graphs are a class of simple graphs G = (V, E), with the following properties.

- Total vertices: |V| = v;
- Each vertex has degree k;
- ullet For every pair of adjacent vertices, they share λ common adjacent vertices;
- ullet For every pair of non-adjacent vertices, they share μ common adjacent vertices;
- Known coherent rank of 3, with the coherent closure having basis matrices $\langle I, A, J I A \rangle$.

From here, we refer to such strongly regular graphs with the parameters above as $SRG(v, k, \lambda, \mu)$.

Choice of Base Graph

Base Graph: The Rook graph R(n), induced from OA(2,n).

Properties

- $|V| = n^2, |E| = 2(n-1);$
- Strongly regular with parameters $SRG(n^2, 2(n-1), n-2, 2)$;
- Interpreted as the possible moves of a Rook on a $n \times n$ chessboard.

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Graph Operations Studied

We investigate how the coherent closure W containing the adjacency matrix of a graph G = (V, E) evolves under two structural graph modifications:

- 1. Vertex Deletion.
- 2. Seidel Switching.

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Graph Operation: Vertex Deletion

Vertex Deletion:

- Choose a vertex $v \in V$,
- Remove v and all edges incident to it,
- The resulting graph is $G' = (V \setminus \{v\}, E')$.

Adjacency Matrix Perspective:

$$A(G) = \begin{bmatrix} 0 & \vec{a}^T \\ \vec{a} & A_{11} \end{bmatrix} \quad \Rightarrow \quad A(G') = A_{11}$$

where A_{11} is the adjacency matrix of the resulting graph, and \vec{a} represents the adjacency between v and $V \setminus \{v\}$.

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Graph Operation: Seidel Switching

Seidel Switching:

- Choose a subset $S \subseteq V$,
- Flip adjacency between S and $V \setminus S$,
- Edges within S and within $V \setminus S$ are unchanged.

Adjacency Matrix Perspective:

$$A(G) = \begin{bmatrix} A(G^S) & C \\ C^T & A(G^{V \setminus S}) \end{bmatrix} \quad \Rightarrow \quad A(G') = \begin{bmatrix} A(G^S) & J - C \\ J - C^T & A(G^{V \setminus S}) \end{bmatrix}$$

where $A(G^S)$ represents edges in the set S, $A(G^{V\setminus S})$ represents edges in the set $V\setminus S$, and C represents the adjacency between vertices in sets S and $V\setminus S$.

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Theorem (Wielandt's Principle)

Let A be a coherent algebra and let $A \in A$. For $b \in \mathbb{C}$, define the matrix B such that

$$[B]_{xy} = \begin{cases} 1, & \text{if } [A]_{xy} = b; \\ 0, & \text{otherwise.} \end{cases}$$

then, $B \in A$.

Process of finding coherent closure

Showing upper bound:

- ① Use 2-WL refinement algorithm for small n,
- ② Notice pattern and generalise into a set of basis matrices and show they form a coherent algebra, A.

Showing Lower bound:

- Use the Wielandt's Principle to show that a certain number of basis matrices need to exist in the coherent closure,
- ② Show that the minimum number of basis matrices is equal to $|\mathcal{A}|$, and thus $\mathcal{W} = \mathcal{A}$.

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Summary of Coherent Rank and Types

Graph Operation	Coherent Rank	Туре
Vertex Deletion	10	$\begin{bmatrix} 3 & 2 \\ 2 & 3 \end{bmatrix}$
Switching on 1 Vertex	15	$ \begin{bmatrix} 1 & 1 & 1 \\ 1 & 3 & 2 \\ 1 & 2 & 3 \end{bmatrix} $
Switching on 1 <i>n</i> -clique	10	$\begin{bmatrix} 2 & 2 \\ 2 & 4 \end{bmatrix}$
Switching on $1 < k < \frac{n}{2}$ <i>n</i> -cliques	12	[4 2] 2 4]
Switching on $\frac{n}{2}$ <i>n</i> -cliques	6	[6]

$$A(R(n)) = \begin{bmatrix} J_n - I & I_n & \cdots & I_n \\ I_n & J_n - I & \cdots & I_n \\ \vdots & \vdots & \ddots & \vdots \\ I_n & I_n & \cdots & J_n - I \end{bmatrix}$$

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Interpreting Coherent Rank Patterns

Other graphs considered:

Block Graph of OA(3, n)

Triangular Graph, T(n)

Paley Graph, P(n)

```
n:3, rank 7
n:4, rank 24
n:5, rank 28
n:6, rank 116
n:7, rank 74
n:8, rank 200
n:9. rank 194
n:10. rank 430
n:11, rank 250
n:12, rank 974
n:13, rank 412
n:14, rank 1090
n:15, rank 1112
n:16, rank 1516
n:17, rank 880
n:18, rank 3024
n:19, rank 1230
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n:3, rank 2 n:4, rank 6 n:5, rank 10 n:6, rank 11 n:7, rank 11 n:8, rank 11 n:9, rank 11 n:10, rank 11 n:11, rank 11 n:12, rank 11 n:13, rank 11 n:14, rank 11 n:15, rank 11 n:16, rank 11 n:17, rank 11 n:18, rank 11 n:19, rank 11

n:5, rank 8 n:13, rank 24 n:17, rank 32 n:29, rank 56 n:37, rank 72 n:41, rank 80 n:53, rank 104 n:61, rank 120 n:73, rank 144 n:89, rank 176 n:97, rank 192 n:101, rank 200 n:109, rank 216 n:113, rank 224

Conclusion and Future Directions

Summary:

- Studied coherent closures of modified rook graphs;
- Applied vertex deletion and Seidel switching;
- Observed fixed coherent rank and algebraic structure under graph operations.

Future Work:

- Extend analysis to larger k, higher-order OA(k, n);
- Extend analysis to other strongly regular graphs, such as Triangular graphs or Paley graphs.

Thank you! I welcome your questions.