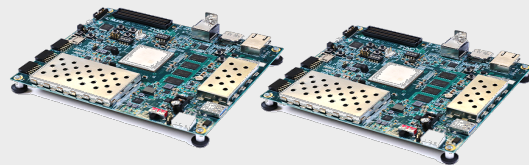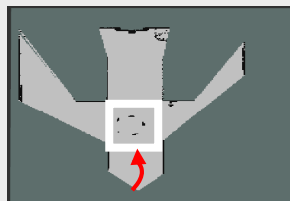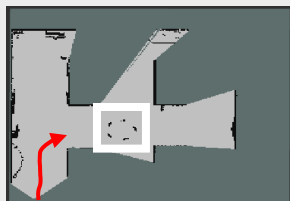Evaluation System with Multi-robot ROS

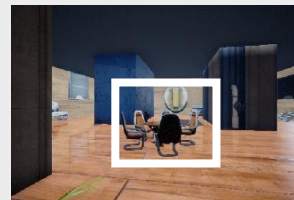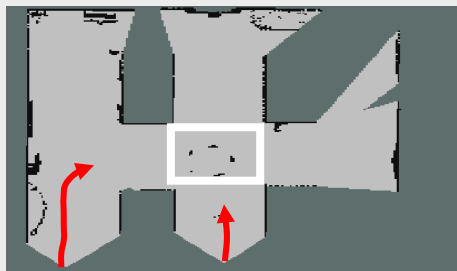AirSim simulator with ROS

ZCU102 board with ROS and INCA

Communicate with ROS

VO results with SuperPoint
(Local map and trajectory)

Input images for PR of the same scene (chairs in white boxes)

Merged Map → Robot Tasks on :
Exploration/
Navigation/
...