Yujiong Liu

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2013 - 2015

Duluth MN, USA August 2015–June 2017

Harbin, China

September 2013–July 2015

EDUCATION

Virginia Tech Blacksburg VA, USA

Ph.D. in Mechanical Engineering, GPA: 4.00/4.00, Advisor: Prof. Pinhas Ben-Tzvi 2017 - 2022

Duluth MN, USA University of Minnesota, Duluth

M.S. in Applied and Computational Mathematics, GPA: 4.00/4.00, Advisor: Prof. Bruce Peckham 2015-2017

Harbin Institute of Technology Harbin, China

M.S. in Mechatronics Engineering, GPA: 82.5/100, Advisor: Prof. Minxiu Kong

Tongji University Shanghai, China

B.S. in Mechanical Engineering, GPA: 4.11/5.00 2009-2013

Experience

Virginia Tech Blacksburg VA, USA

Graduate Research Assistant and Lab Manager at the Robotics & Mechatronics Lab August 2017-May 2022

Development of a novel quadruped robot with a serpentine robotic tail

- Development of three novel cable/rod driven serpentine mechanisms

University of Minnesota, Duluth

Graduate Teaching Assistant at the Applied Math Department

Investigated the dynamic behaviors of a singular perturbed quadratic map

Harbin Institute of Technology

Graduate Research Assistant at the State Key Laboratory of Robotics and System

- Developed an adaptive controller for the Delta robot

- Developed a novel forward kinematics for the H4 robot

SELECTED PUBLICATIONS

[1] Liu, Y. and Ben-Tzvi, P., "Systematic Development of a Novel, Dynamic, Reduced Complexity Quadruped Robot Platform for Robotic Tail Research", 2022 IEEE International Conference on Robotics and Automation (ICRA), Philadelphia, PA, USA, May 23-27, 2022.

- [2] Liu, Y. and Ben-Tzvi, P., 2021, "Dynamic Modeling, Analysis, and Design Synthesis of a Reduced Complexity Quadruped with a Serpentine Robotic Tail", Integrative and Comparative Biology, 61(2), pp. 464–477
- [3] Liu, Y. and Ben-Tzvi, 2021, "A New Extensible Continuum Manipulator Using Flexible Parallel Mechanism and Rigid Motion Transmission", Journal of Mechanisms and Robotics, Transactions of the ASME, 13(3), p. 031112
- [4] Liu, Y. and Ben-Tzvi, P., 2021, "Dynamic Modeling, Analysis, and Comparative Study of a Quadruped with Bio-inspired Robotic Tails", Multibody System Dynamics, 51(2), pp. 195-219
- [5] Liu, Y., Wang, J. and Ben-Tzvi, P., 2019, "A Cable Length Invariant Robotic Tail Using a Circular Shape Universal Joint Mechanism", Journal of Mechanisms and Robotics, Transactions of the ASME, 11(5), p. 051005
- [6] Ben-Tzvi, P. and Liu, Y., 2021, "Robots With Tails", ASME Mechanical Engineering Magazine, 143(6), pp. 32-37, Read the Story Online

TEACHING

• Graduate Teaching Assistant at Virginia Tech Fall 2018–Spring 2019 Mechanical Engineering Lab I and II (ME4005 and 4006) • Graduate Teaching Assistant at University of Minnesota, Duluth Fall 2015–Spring 2017 Numerical Analysis (MATH3810), Calculus III (MATH3298), Finite Math (MATH1160) Selected Awards • 3rd Place of the 2022 Paul E. Torgersen Graduate Student Research Excellence Award (PhD Category), College of Engineering, Virginia Tech 2022 • Outstanding Graduate Student of the Mechatronics School, Harbin Institute of Technology 2015 • First Class Scholarship, Harbin Institute of Technology 2013, 2014 • First Class Prize of the 5th National College Mechanical Innovation Design Competition 2012 • National Encouragement Scholarship, Ministry of Education, P.R. China 2011 • Outstanding Student of the Mechanical Engineering Department, Tongji University 2011 MENTORSHIP SKILLS • Mathematics: Modeling, Mechanics, Dynamics, • Graduate Students: Shikhar Kashyap, Isaac Control, Optimization Pressgrove • Design and Manufacturing: Mechanical Design, PCB Design, CNC • Integration: Embedded Linux, ARM Mbed, ROS • Undergraduate Students: Alex Broz, Logan Stevenson, One senior design team of 7 students • Coding: C/C++, Matlab ACADEMIC MEMBERSHIPS • American Society of Mechanical Engineers (ASME), Student Member 2019-present • Institute of Electrical and Electronics Engineers (IEEE), Student Member 2019-present References Dr. Pinhas Ben-Tzvi Virginia Tech Professor bentzvi@vt.edu Dr. Bruce Peckham University of Minnesota, Duluth Professor Emeritus bpeckham@d.umn.edu