Fast and Accurate Text Classification: Skimming, Rereading and Early Stopping

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Introduction

Motivations: For text classification, reading the entire input is not always necessary in practice & we do not have to treat each individual word equally.

Goal: Augment existing RNN models to realize efficient classification, while maintaining a higher or comparable accuracy compared to reading the full text.

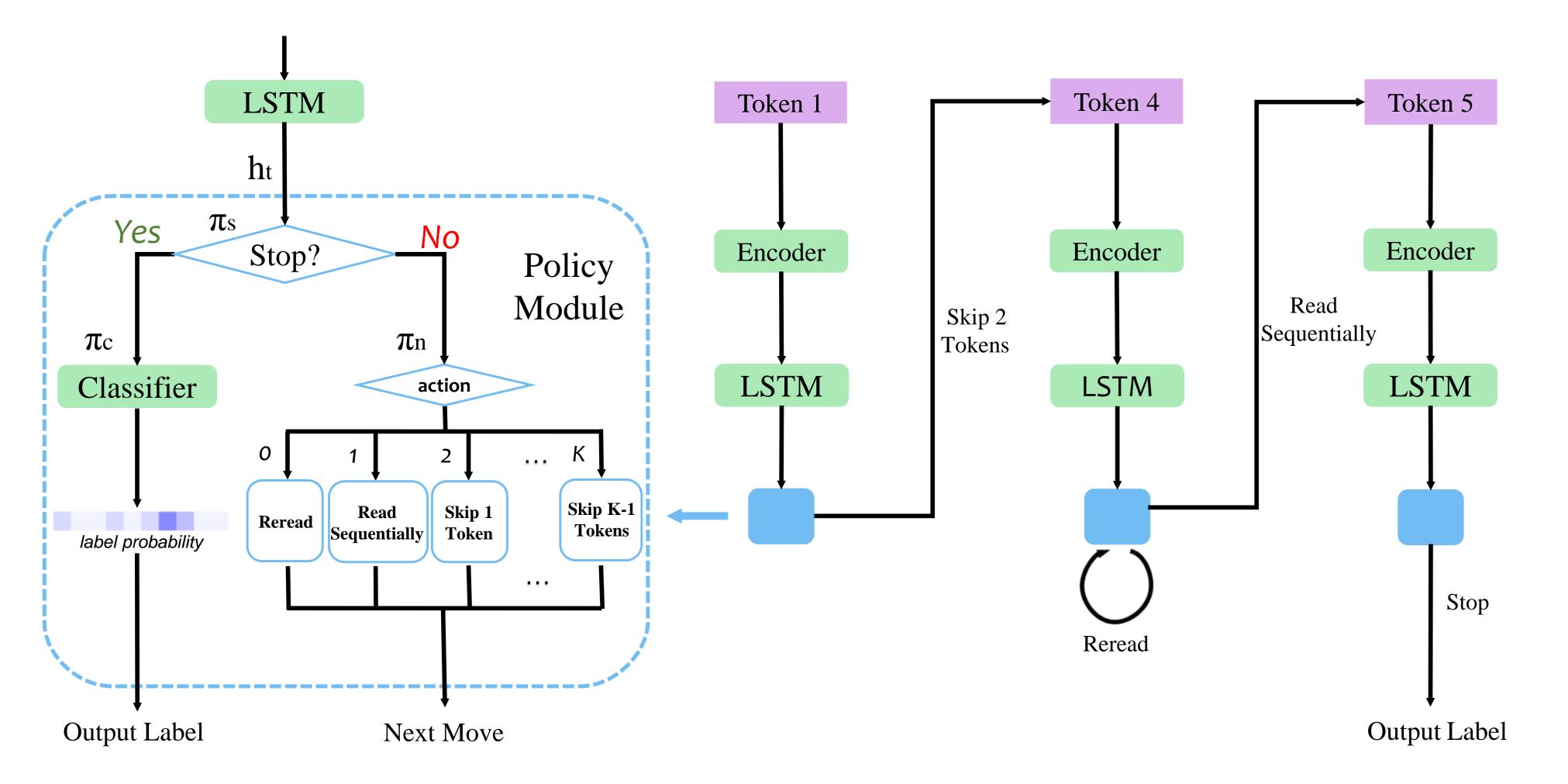
Contributions:

- ► Proposed an end-to-end trainable approach for skimming, rereading and early stopping mimicking human fast reading, which is applicable to classification tasks.
- ▶ Realized the control of trade-off between accuracy and energy cost with single parameter.
- ▶ Proved the the effectiveness of each component in our approach and their combinations.

Model Architecture

Model Overview

- ▶ Given an input sequence $x_{1:T}$ with length T, our model aims to predict a single label y for the entire sequence.
- ➤ Develop a technique for skimming, re-reading, early stopping and prediction, with the goal of skipping irrelevant information and reinforcing the important parts.



Model Specification

- ► At each time step t, policy module Π takes hidden state h_t of an encoder, which summarizes the text read before and the current token x_{i_t} . Outputs a probability distribution π_t defined over actions.
- ▶ A sequence of actions are generated by first sampling a stopping decision in the form of a binary variable s from a Bernoulli distribution $\pi_S(\cdot|h_t)$.
- ▶ If s=1, the model stops and draws a label \hat{y} from a conditional multinomial distribution specified by a classifier $\pi_{\mathcal{C}}(\cdot|h_t,s=1)$
- ▶ Otherwise, the model draws a step size $k \in \{0, ..., K\}$ from another conditional multinominal distribution $\pi_N(\cdot|h_t, s=0)$ to jump to the token $x_{i_{t+1}=i_t+k}$.

Joint Training Method

Joint Distribution:

 \blacktriangleright We are modeling the possibility of given label \hat{y} as:

$$\Pi(X_{i_1:i_t},\hat{y})=\pi_{\mathcal{S}}(s=1|h_t)\pi_{\mathcal{C}}(\hat{y}|h_t,s=1)\prod_{j=1}^{t-1}\pi_{\mathcal{S}}(s=0|h_j)\pi_{\mathcal{N}}(k_j=i_{j+1}-i_j|h_j,s=0),$$

▶ It could be simplified as:

$$\Pi(X_{i_1:i_t},\hat{y}) = \pi_S(1|h_t)\pi_C(\hat{y}|h_t,1)\prod_{j=1}^{t-1}\pi_S(0|h_j)\pi_N(k_j|h_j,0).$$
(2)

Reward Design:

We want to combine the accuracy between predicted label \hat{y} and true label y as well as computational cost \mathcal{F} , with single trade-off parameter α

$$r_{j} = \begin{cases} -\mathcal{L}(\hat{y}, y) - \alpha \mathcal{F}_{t} & \text{if } j = t \text{ is the final time step} \\ -\alpha \mathcal{F} & \text{otherwise} \end{cases}$$
(3)

Joint Training:

► Our final goal is to find the optimal $\theta = \{\theta^{\pi_S}, \theta^{\pi_C}, \theta^N, \theta^{RNN}\}$, which maximize the expected return defined by:

$$J(heta) = \mathbb{E}_{(x,y)\sim\mathcal{D}}\left[\sum_t \mathbb{E}_{(X_{i_1:i_t},\hat{y})\sim\Pi} \sum_{j=1}^t \gamma^{j-1} r_j
ight],$$
 (4)

▶ The REINFORCE policy gradient of the objective on data (x, y) can be derived as follows:

$$\widehat{\nabla_{\theta} J} = \nabla_{\theta} [\log \pi_{S}(1|h_{t}) + \log \pi_{C}(\hat{y}|h_{t}, 1) + \sum_{j=1}^{t-1} (\log \pi_{S}(0|h_{j}) + \log \pi_{N}(k_{j}|h_{j}, 0))] \sum_{j=1}^{t} \gamma^{j-1} r_{j}.$$
 (5)

Fit a value function as the baseline for accumulative reward to handle large variance.

Ablation Analysis

► **Target:** We aim to demonstrate the effectiveness of each action mechanism in our method: skimming, rereading and early-stopping.

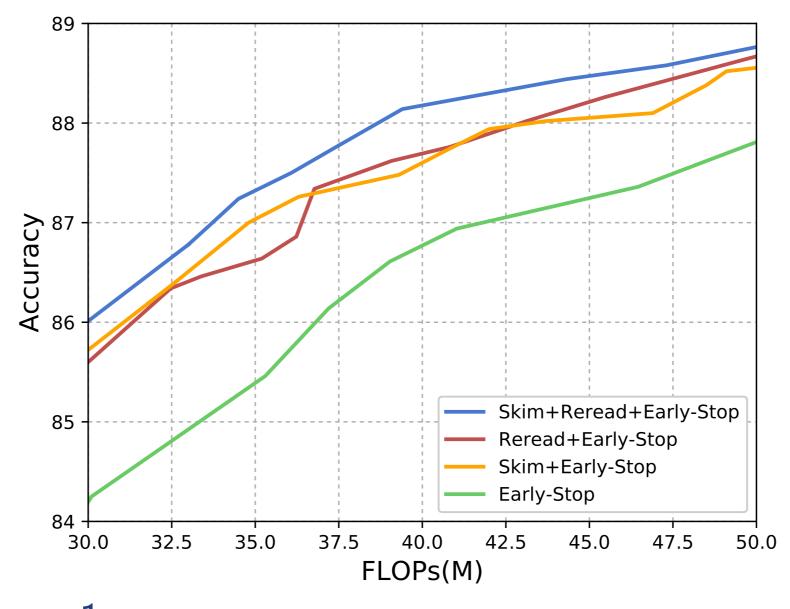


Figure 1: Comparison between different action combination sett

► Notation:

- Blue: Our model (all actions)
- Orange: Skimming and early-stopping (No rereading)
- ► Red: Rereading and early-stopping (No Skimming)
- ► Green: Only an early-stopping module
- ► Analysis & Conclusion:

► Performance of green curve is the worst, indicating that rereading and skimming mechanisms are useful.

► Performance of blue curve is better than all other ones, indicating that combining skimming and rereading together can further improve performance.





Experiment Results

- Datasets: IMDB(Word level), AG_news/DBpedia(Character level), Yelp(Sentence level)
- Baselines:
- ► Whole Reading: A classifier use whole corpus as training data.
- ► Partial Reading: Only a stopping module to decide when to terminate reading the paragraph.
- ► Early Stopping: Whole Reading model trained on the truncated sentences decided by the stopping model.

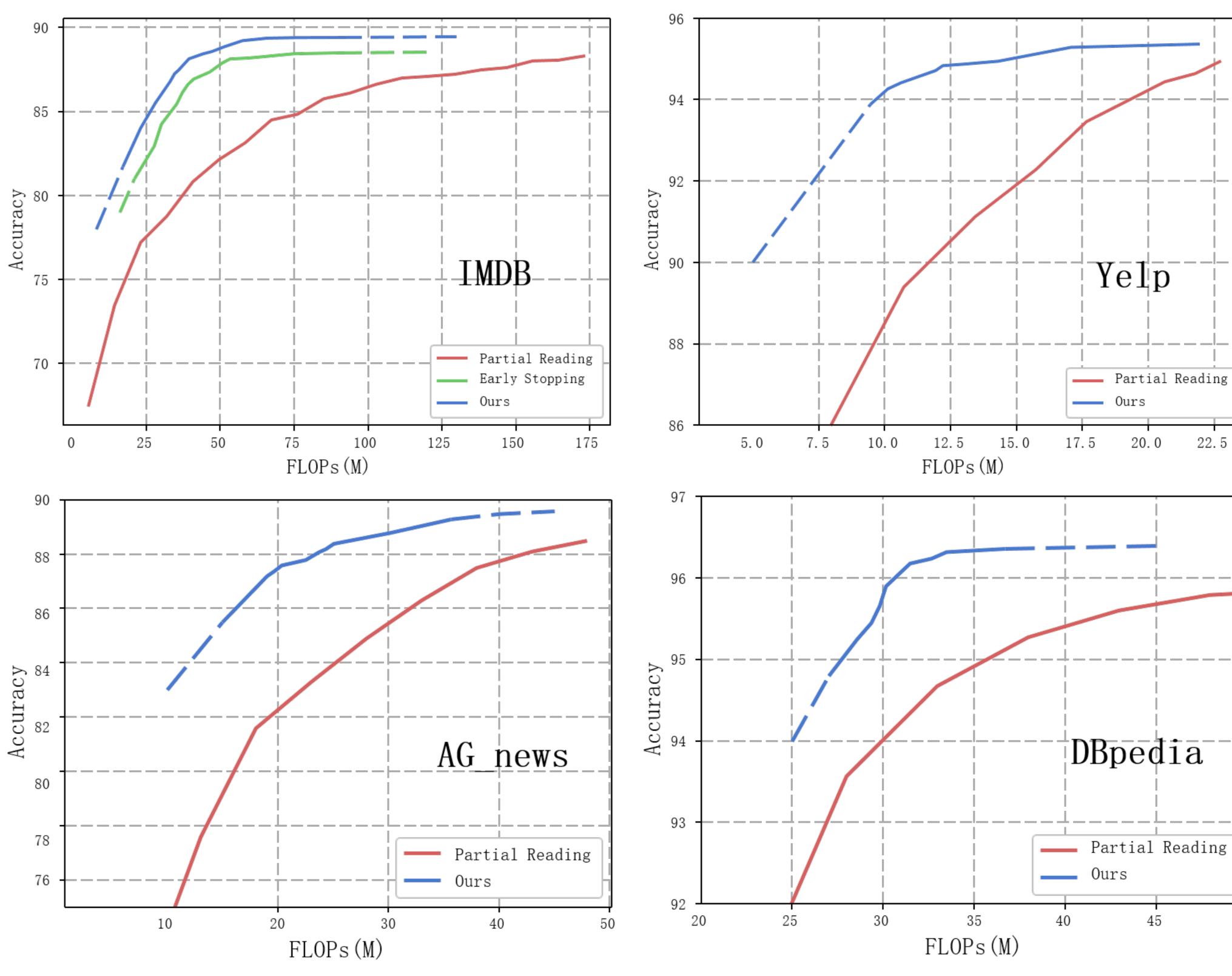


Figure 2: The x-axis and y-axis are representing FLOPs and accuracy, respectively. Curves are obtained by changing the computational budget for each method. Especially, for Ours and Early Stopping model, we adjust the parameter α .

Metrics:

- ► Accuracy: Obtained by whole reading model.
- ► Speedup: Speedups of our model compared to whole-reading baseline at the same accuracy level.
- ▶ Relative PR Accuracy: Relative performance of the partial reading baseline with the same computational cost as our model.

Dataset	Speedup	Accuracy	Relative PR Accuracy
IMDB	4.11x	88.32%	-7.19%
AG_news	1.85x	88.50%	-4.42%
DBpedia	2.42x	95.99%	-1.94%
Yelp	1.58x	94.95%	-3.38%

Table 1: Summary of our results on four datasets. Training the classifier jointly with the policy model improves both computational efficiency and accuracy.

► **Conclusion:** We observe that our proposed model can achieve superior performance while being significantly faster.

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