YUKI OYAMA

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WORK EXPERIENCE

Associate Professor
Shibaura Institute of Technology
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Research Center for Advanced Science and Technology (RCAST), The University
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Transport and Mobility Laboratory (TRANSP-OR), École Polytechnique Fédérale
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Research Fellow (PD)
Japan Society for the Promotion of Science (JSPS), Tokyo Institute of Technology
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SCIENTIFIC EDUCATION

03/2017	Ph.D in Engineering
	Department of Urban Engineering, The University of Tokyo
03/2014	M.Sc. in Engineering
	Department of Urban Engineering, The University of Tokyo
03/2012	B.Sc. IN ENGINEERING
•	Department of Urban Engineering, The University of Tokyo

PUBLICATIONS

Oyama, Y. (2023) Capturing positive network attributes during the estimation of recursive logit models: A prism-based approach. *Transportation Research Part C: Emerging Technologies* 147: 104014.

Parady, G., Suzuki, K., **Oyama, Y.**, Chikaraishi, M. (2023) Activity detection with Google Maps Location History data: factors affecting joint activity detection probability and its potential application on real social networks. *Travel Behaviour and Society* **30**:344-357.

Oyama, Y., Hara, Y., Akamatsu, T. (2022) Markovian traffic equilibrium assignment based on network generalized extreme value model. *Transportation Research Part B: Methodological* **155**: 135-159.

Oyama, Y., Hato, E. (2019) Prism-based path set restriction for solving Markovian traffic assignment problem. *Transportation Research Part B: Methodological* 122: 528-546.

Oyama, Y., Hato, E. (2018) Link-based measurement model to estimate route choice parameters in urban pedestrian networks. *Transportation Research Part C: Emerging Technologies* **93**: 62-78.

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