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# CS2040 Data Structures and Algorithms

## Lecture Note #11 – Part 2

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### Graphs

### Part 2: Traversal Algorithms

# Review – Binary Tree Traversal

In a binary tree, there are three standard traversal:

- Preorder
- Inorder**
- Postorder

```
pre(u)
  visit(u);
  pre(u->left);
  pre(u->right);
```

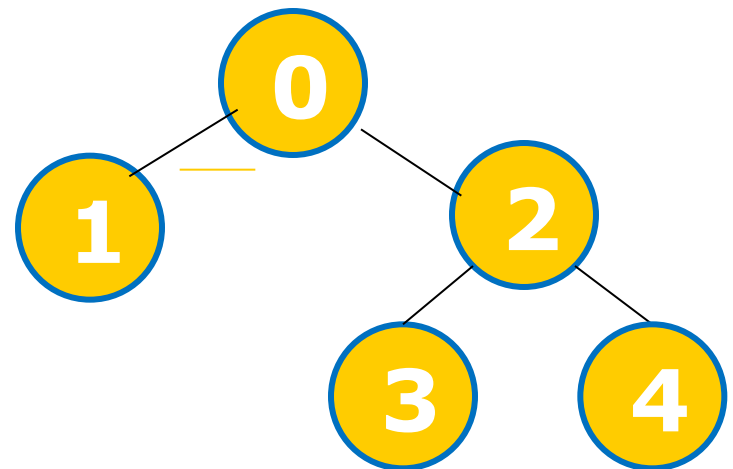
```
in(u)
  in(u->left);
  visit(u);
  in(u->right);
```

```
post(u)
  post(u->left);
  post(u->right);
  visit(u);
```

- (Note: "level order" is just BFS which we will see next)

We start binary tree traversal from root:

- pre(root)/in(root)/post(root)
  - pre = 0, 1, 2, 3, 4
  - in = 1, 0, 3, 2, 4
  - post = 1, 3, 4, 2, 0



# What is the PostOrder Traversal of this Binary Tree?

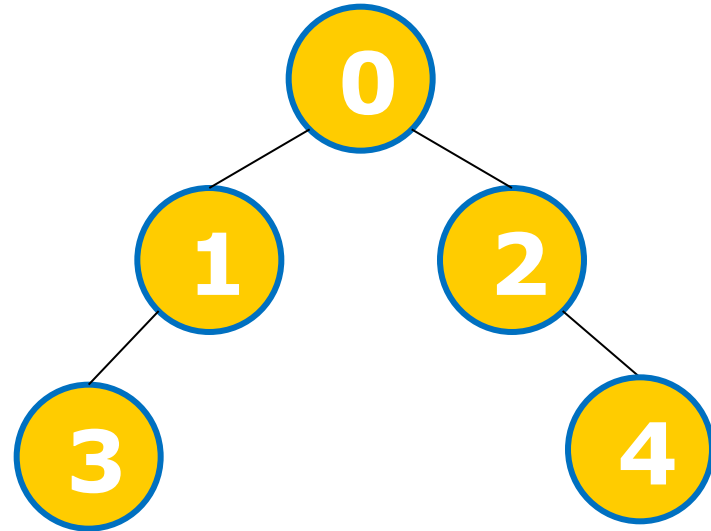
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1. 0 1 2 3 4

2. 0 1 3 2 4

3. 3 4 1 2 0

😊 3 1 4 2 0



# Traversing a Graph (1)

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Two ingredients are needed for a **traversal**:

1. The start
2. The movement

## Defining the start ("source")

- ▣ In tree, we *normally* start from root
  - Note: Not all tree are rooted though!
    - ▣ In that case, we have to select one vertex as the "source", see below
- ▣ In general graph, we do not have the notion of root
  - Instead, we start from a distinguished vertex
    - ▣ We call this vertex as the "**source**" **s**

# Traversing a Graph (2)

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Defining the movement:

- In (binary) tree, we only have (at most) two choices:
  - Go to the **left subtree** or to the **right subtree**
- In general graph, we can have more choices:
  - If **vertex u** and **vertex v** are adjacent/connected with edge **(u, v)**;  
and we are now in **vertex u**; then we can also go to **vertex v** by traversing that edge **(u, v)**
- In (binary) tree, there is **no cycle**
- In general graph, we **may have (trivial/non trivial) cycles**
  - We need a way to avoid revisiting  **$u \rightarrow v \rightarrow w \rightarrow u \rightarrow v$**   
... indefinitely

# Traversing a Graph (2)

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## **Solution: BFS and DFS**

**Idea:** If a vertex **v** is reachable from **s**, then  
all neighbors  
of **v** will also be reachable from **s**  
(recursive definition)

# Breadth-First Search



Traversing a Graph

# Breadth First Search (BFS) – Ideas

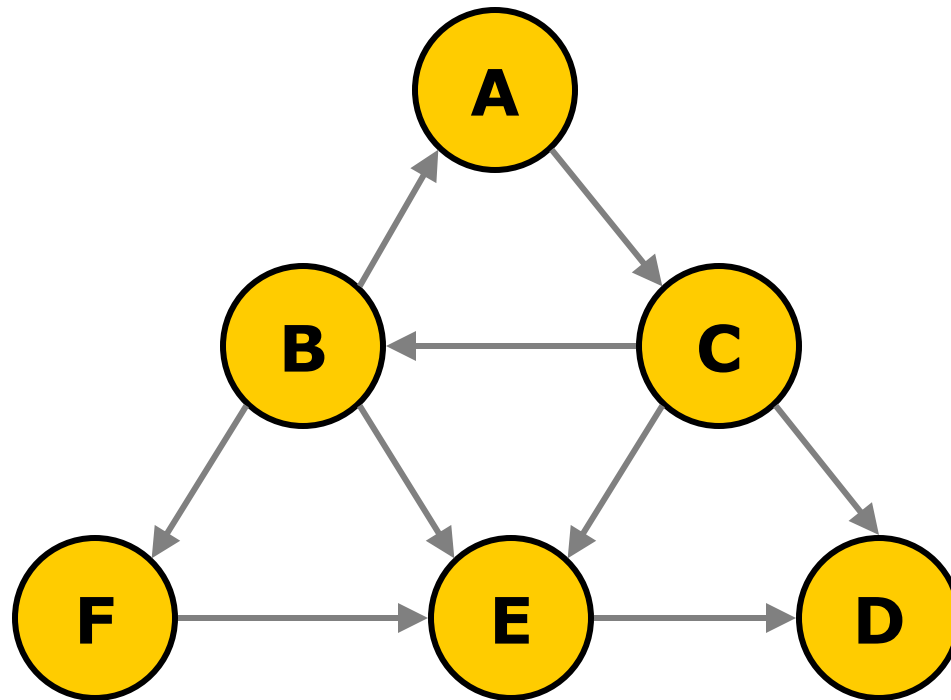


- Start from **s**
- BFS visits vertices of  $G$  in *breadth-first* manner (when viewed from source vertex  $s$ )
  - Q: How to maintain such order?
    - A: Use queue **Q**, initially, it contains only **s**
  - Q: How to differentiate visited vs unvisited vertices (to avoid cycle)?
    - A: 1D array/Vector **visited** of size  $V$ , **visited[v] = 0** initially, and **visited[v] = 1** when **v** is visited
  - Q: How to memorize the path?
    - A: 1D array/Vector **p** of size  $V$ , **p[v]** denotes the **p**redecessor (or **p**arent) of **v**
- Edges used by BFS in the traversal will form a BFS “spanning” tree of  $G$  (tree that includes all



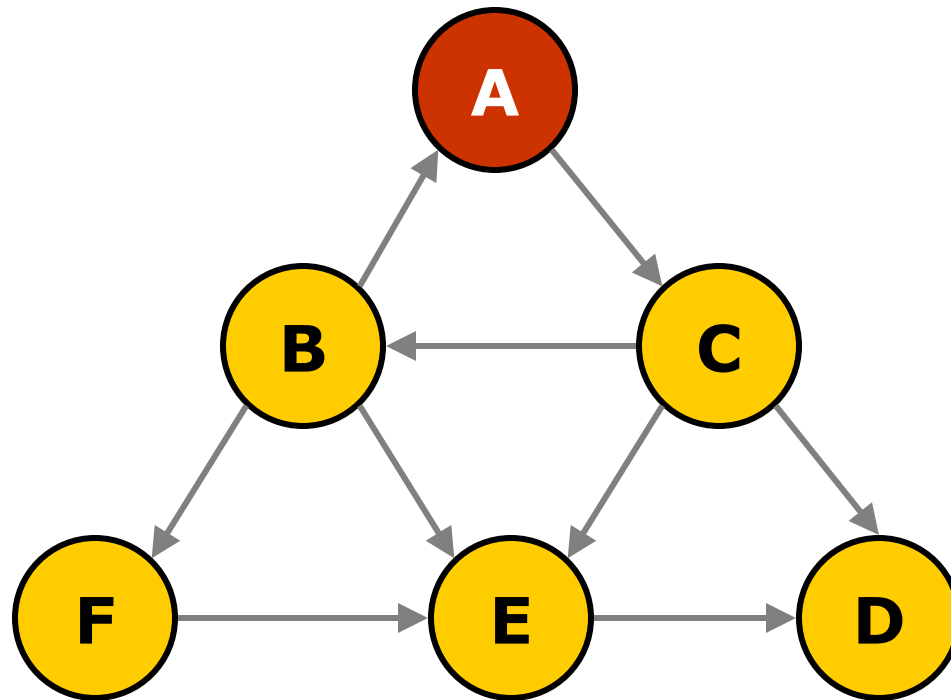
# Breadth-first search

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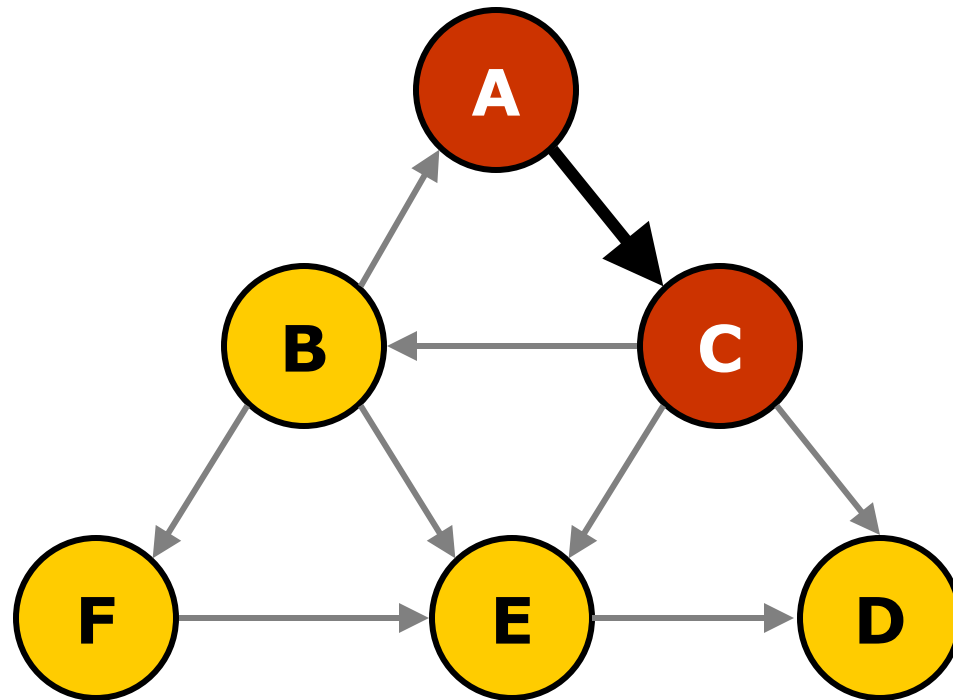
# Breadth-first search

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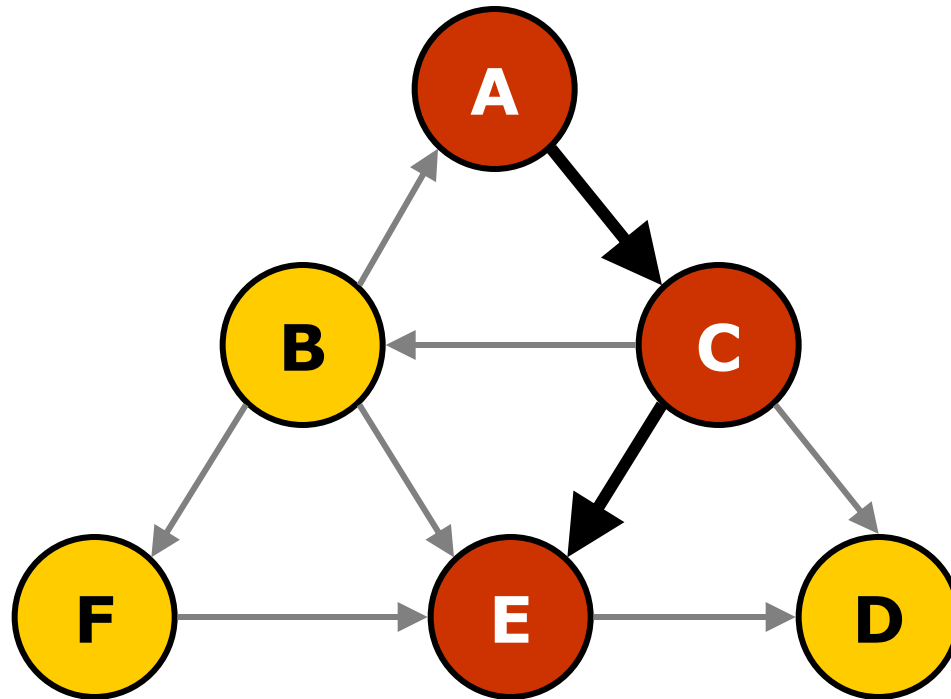
# Breadth-first search

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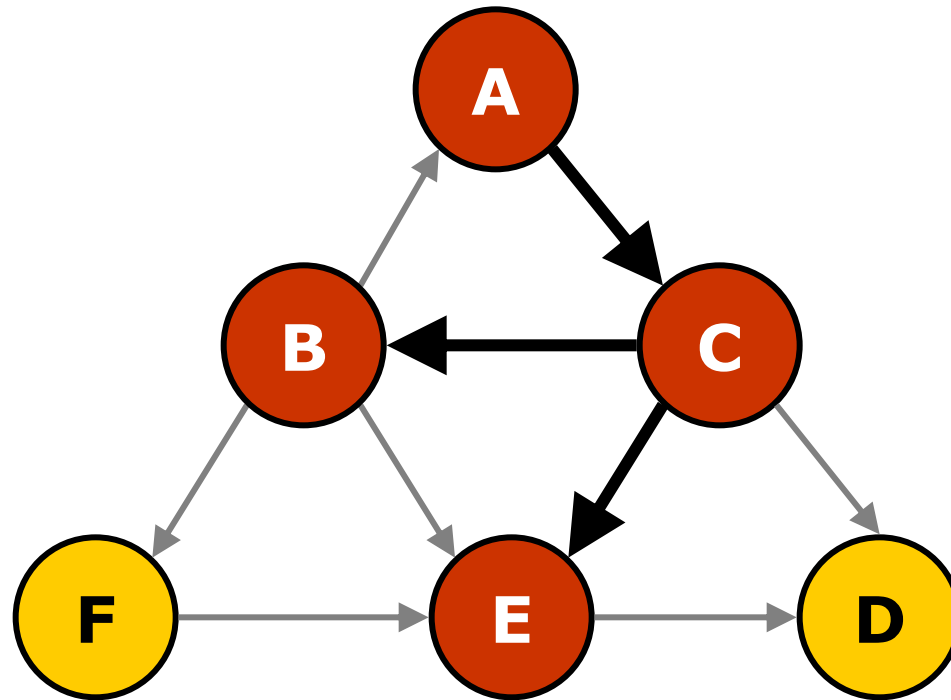
# Breadth-first search

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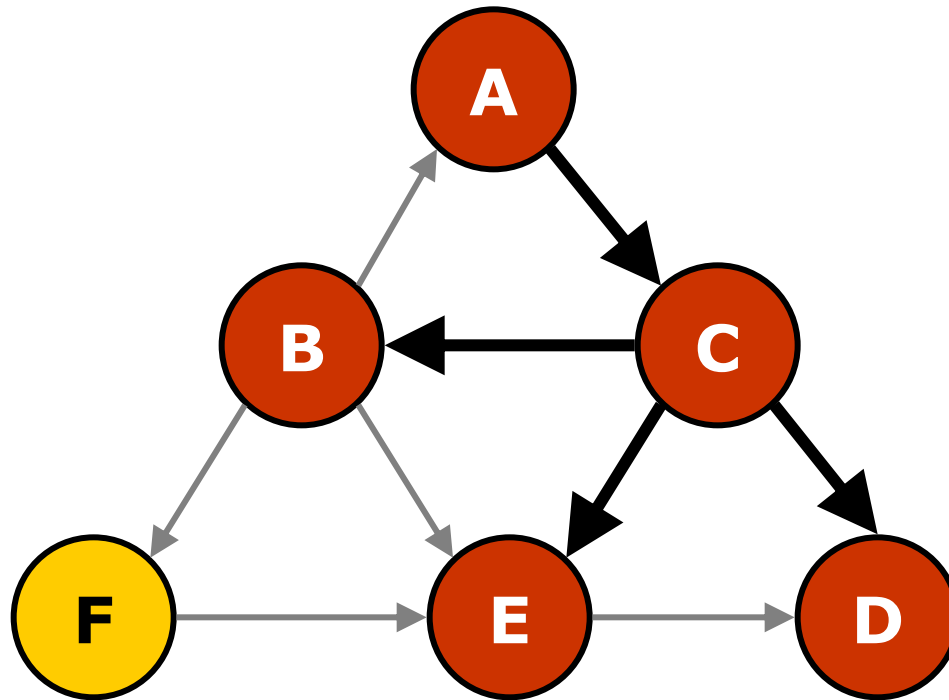
# Breadth-first search

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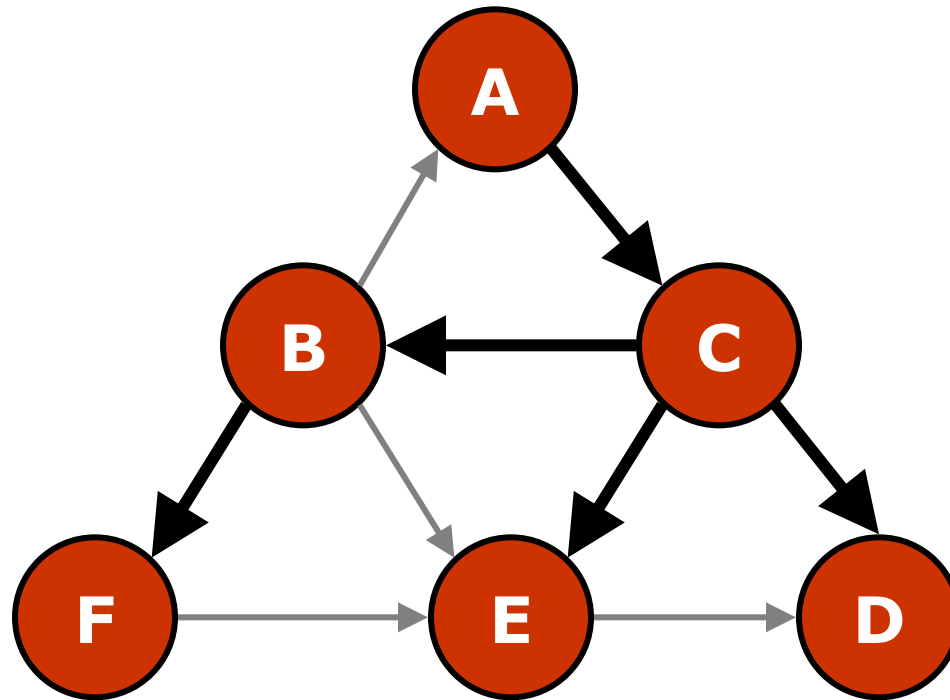
# Breadth-first search

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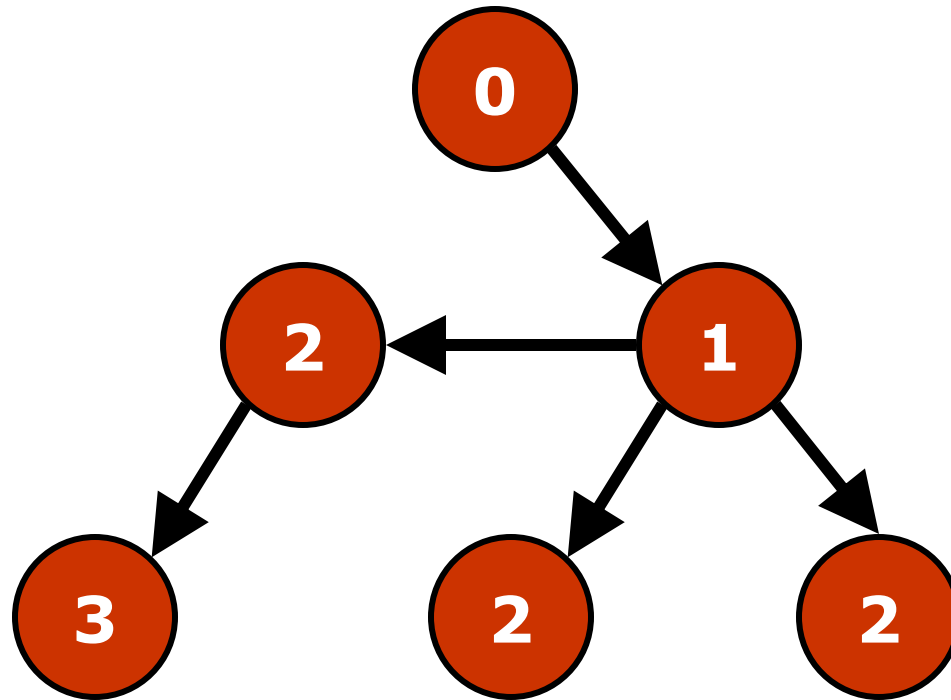
# Breadth-first search

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# Breadth-first search

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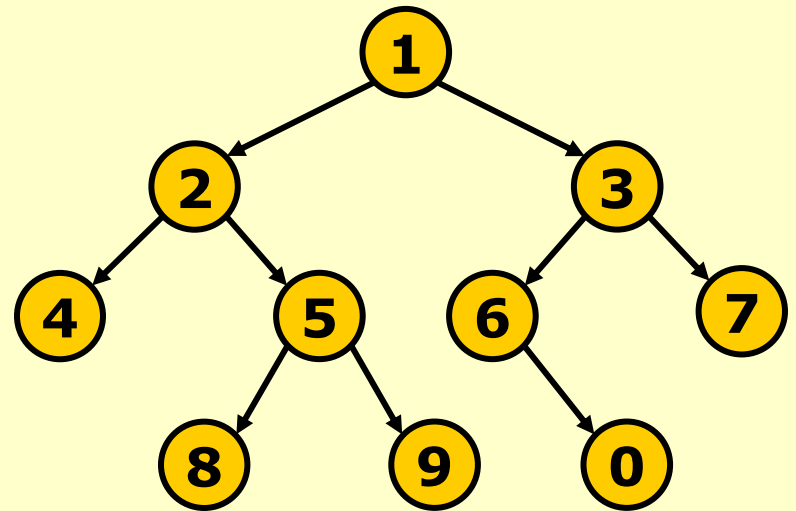




# Level-Order on Tree

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```
if T is empty return  
Q = new Queue  
Q.enq(T)  
while Q is not empty  
    curr = Q.deq()  
    print curr.element  
    if T.left is not empty  
        Q.enq(curr.left)  
    if curr.right is not empty  
        Q.enq(curr.right)
```



# BFS(v)

---

Q = **new** Queue

Q.enq (v)

**mark v as visited**

**while** Q is not empty

    curr = Q.deq()

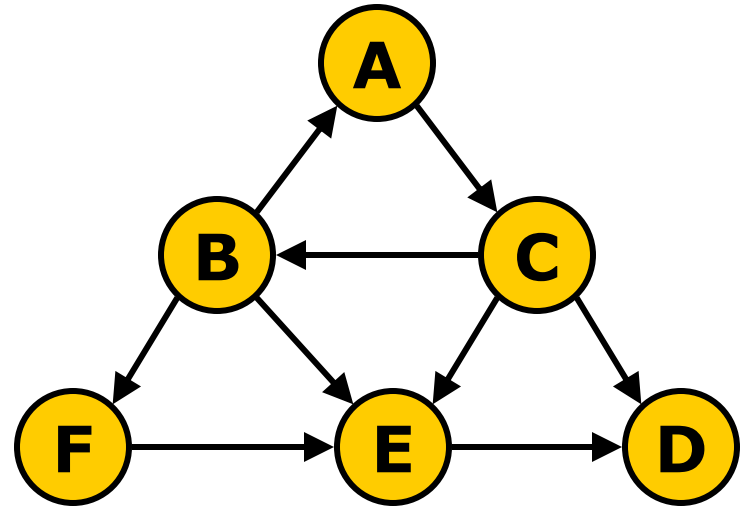
    print curr

**foreach** w in adj(curr)

**if w is not visited**

            Q.enq(w)

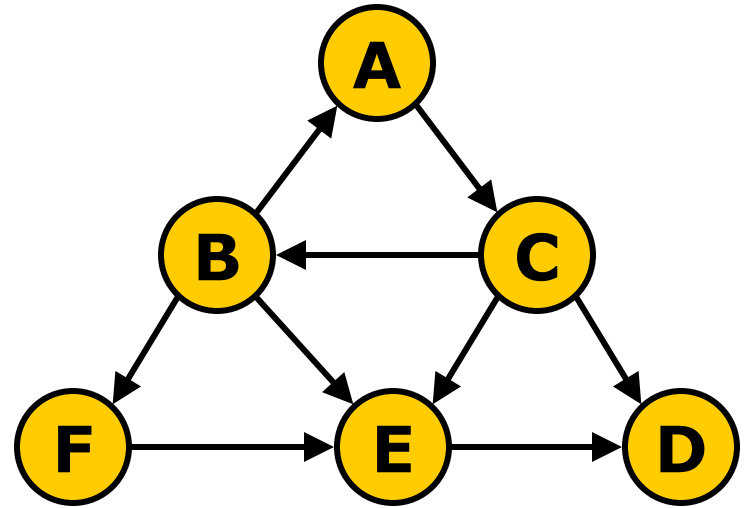
**mark w as visited**



# Building the BFS Tree

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```
Q = new Queue
Q.enq (v)
mark v as visited
while Q is not empty
    curr = Q.deq()
    print curr
    foreach w in adj(curr)
        if w is not visited
            Q.enq(w)
            w.parent = curr
            mark w as visited
```



# Calculating Level

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Q = **new** Queue

Q.enq (v)

mark v as visited

**v.level = 0**

**while** Q is not empty

    curr = Q.deq()

    print curr

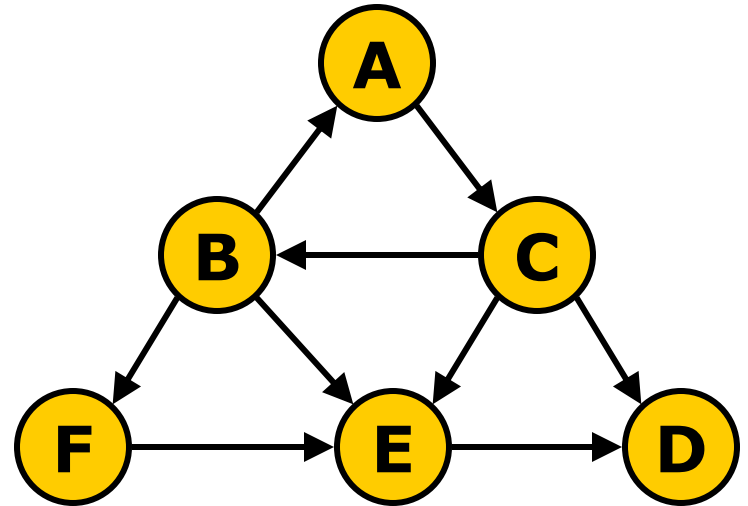
**foreach** w in adj(curr)

**if** w is not visited

            Q.enq(w)

**w.level = curr.level + 1**

            mark w as visited



# Search all vertices

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**Search(G)**

**foreach** vertex  $v$

    mark  $v$  as unvisited

**foreach** vertex  $v$

**if**  $v$  is not visited

      BFS( $v$ )

# Running time

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```
Q = new Queue
Q.enq (v)
mark v as visited
while Q is not empty
    curr = Q.deq()
    print curr
    foreach w in adj(curr)
        if w is not visited
            Q.enq(w)
            mark w as visited
```

Main Loop

$$O\left(\sum_{curr \in V} adj(curr)\right) = O(E)$$

Initialization

$$O(V)$$

Total Running Time

$$O(V + E)$$

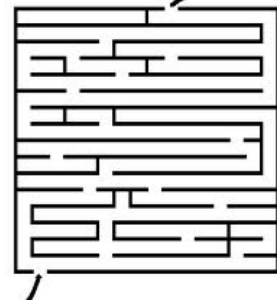
# Depth-First Search



Traversing a Graph

# Depth First Search (DFS)

## – Ideas

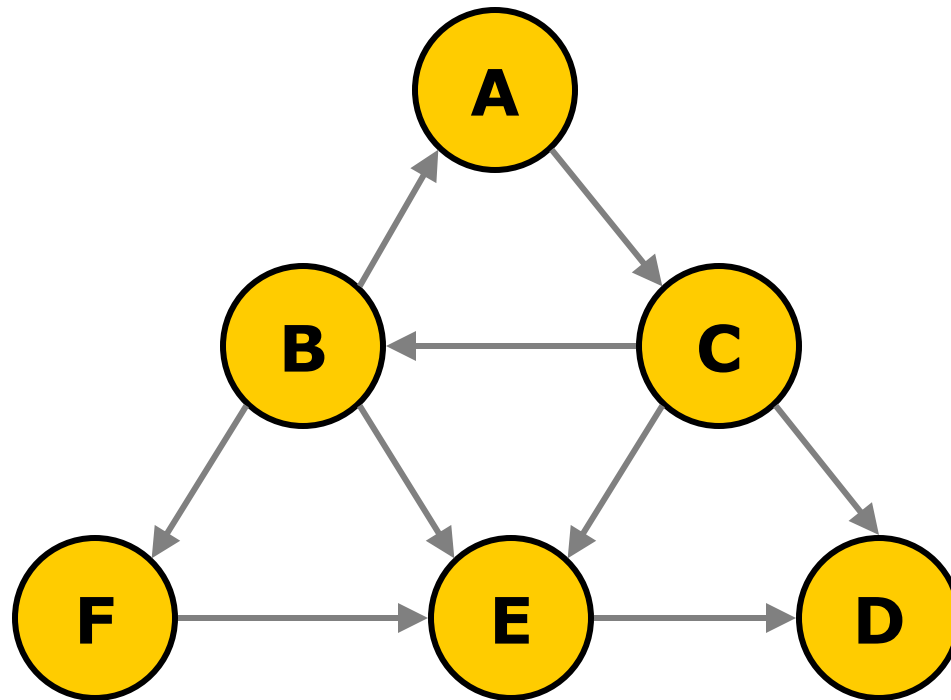


- Start from **s**
- **DFS** visits vertices of  $G$  in *depth-first* manner (when viewed from source vertex  $s$ )
  - Q: How to maintain such order?
    - A: Stack **S**, but we will simply use recursion (an implicit stack)
  - Q: How to differentiate visited vs unvisited vertices (to avoid cycle)?
    - A: 1D array/Vector **visited** of size  $V$ ,  
**visited**[**v**] = **0** initially, and **visited**[**v**] = **1** when **v** is visited
  - Q: How to memorize the path?
    - A: 1D array/Vector **p** of size  $V$ ,  
**p**[**v**] denotes the predecessor (or parent) of **v**
- Edges used by DFS in the traversal will form a DFS “spanning” tree of  $G$  (tree that includes all vertices of  $G$ ) stored in **p**



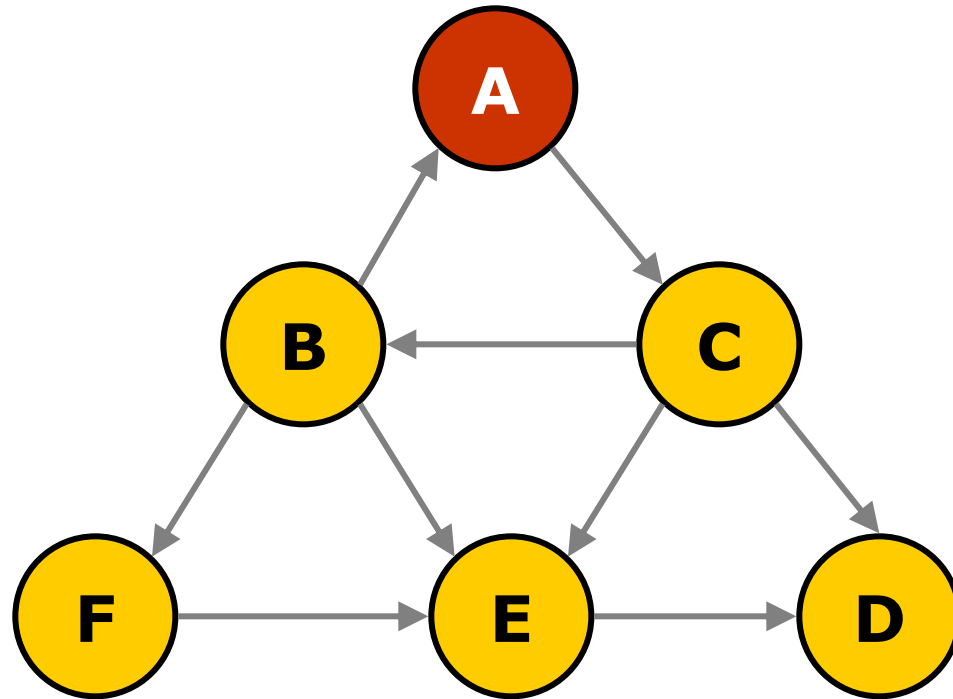
# Depth-first search

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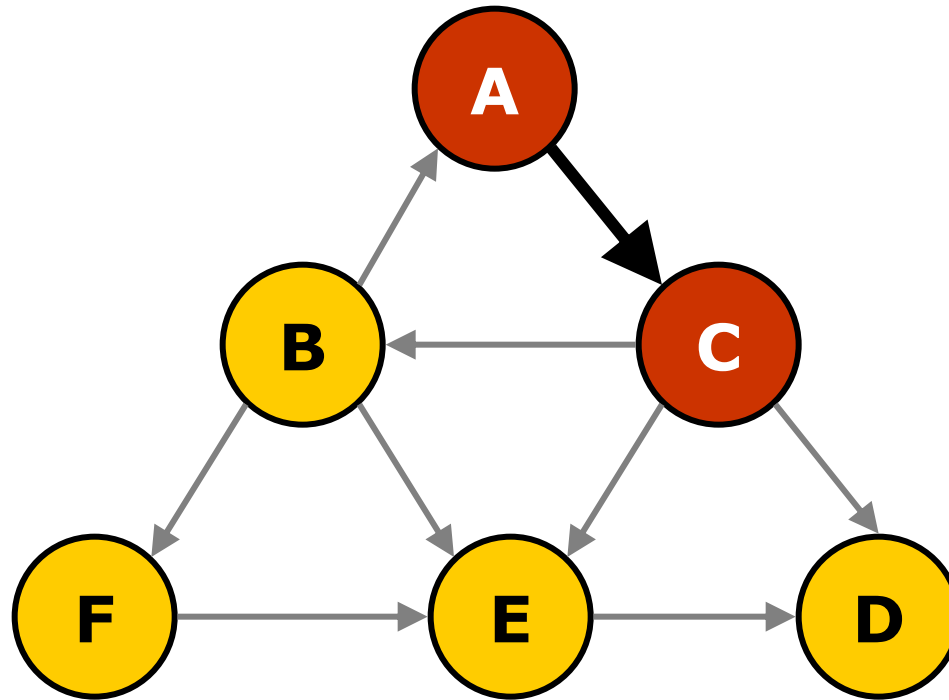
# Depth-first search

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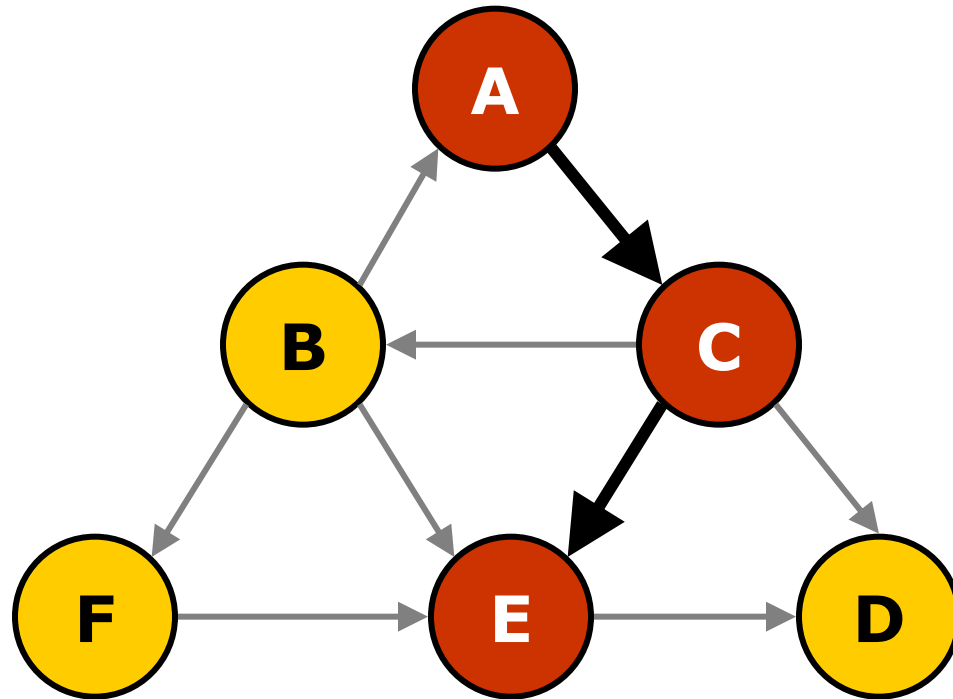
# Depth-first search

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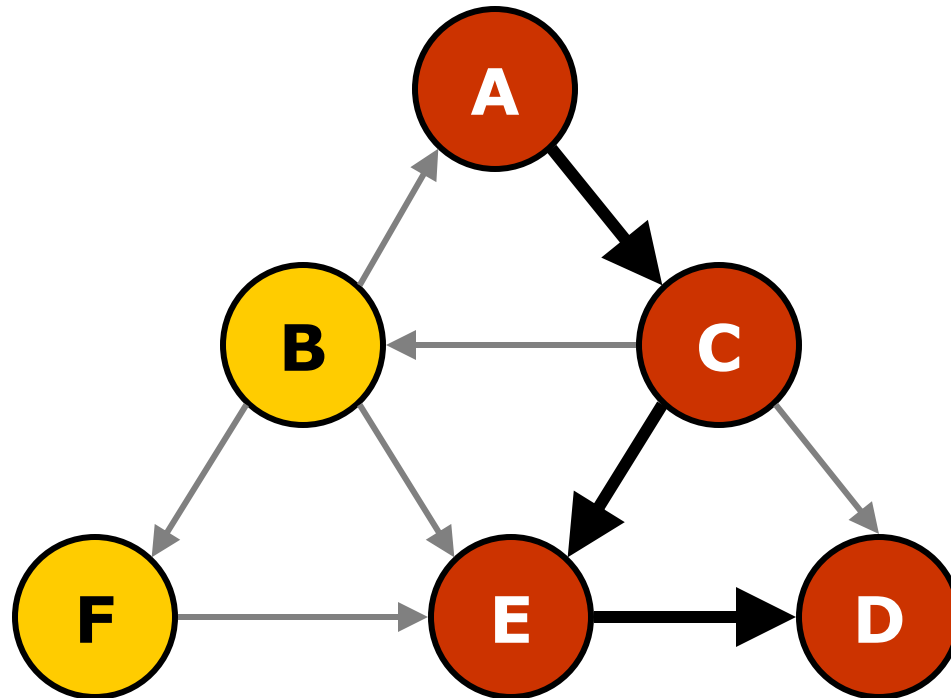
# Depth-first search

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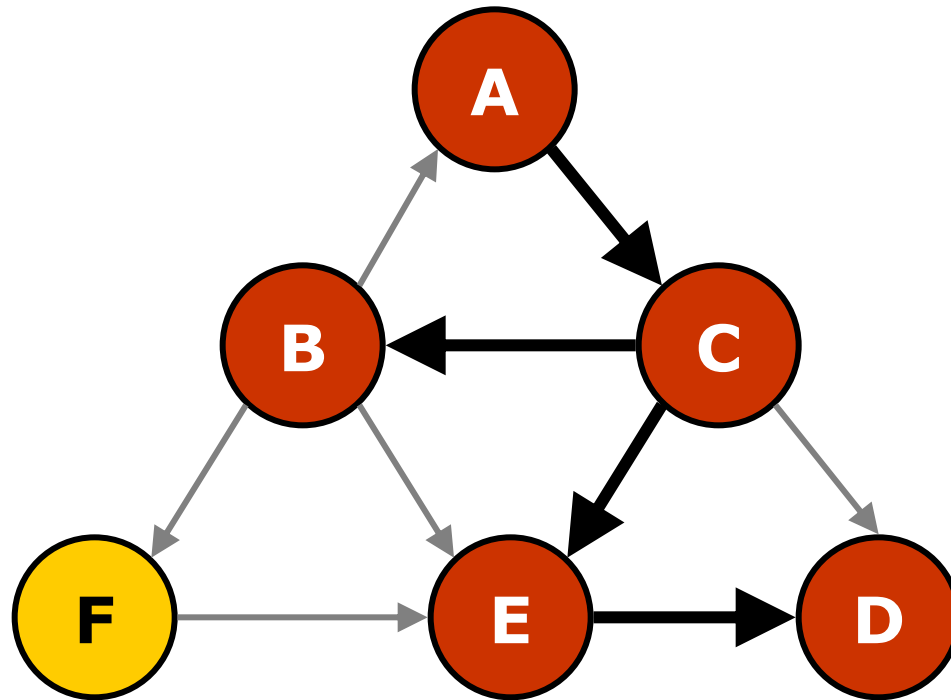
# Depth-first search

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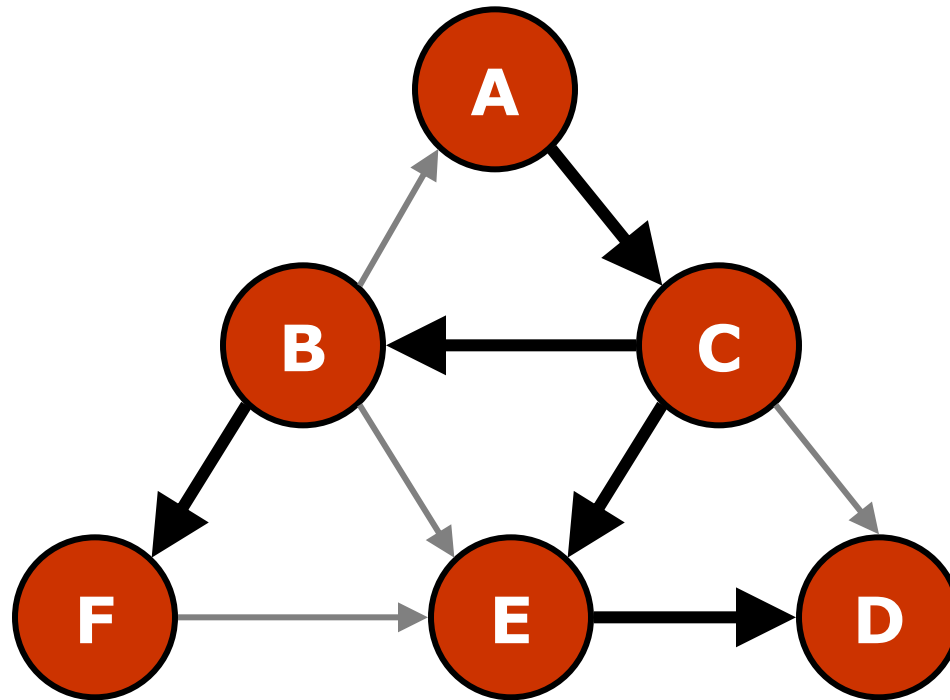
# Depth-first search

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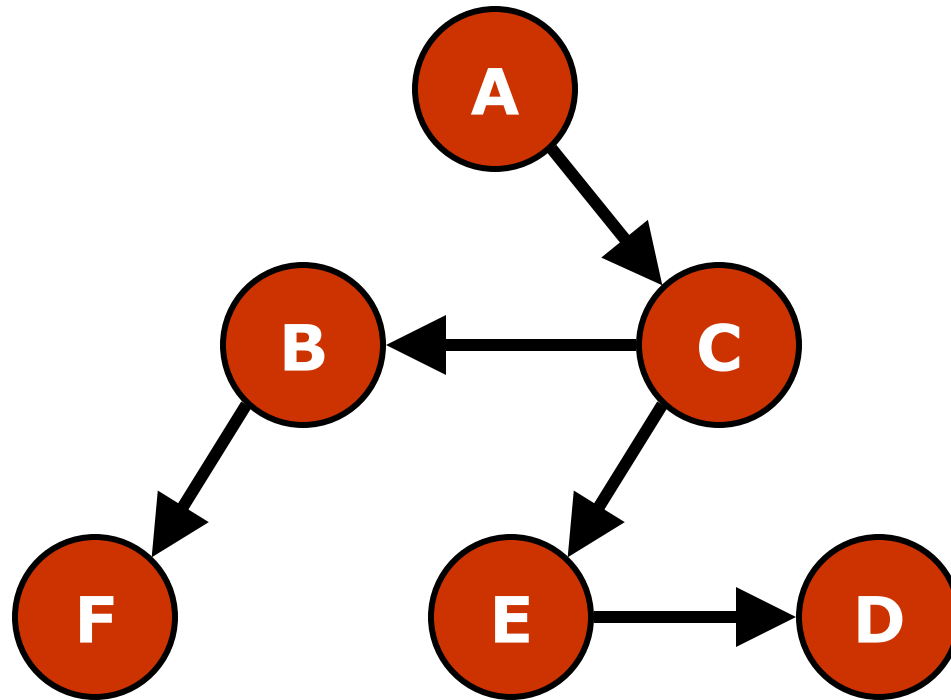
# Depth-first search

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# Depth-first search

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# DFS(v)

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S = **new** Stack

S.push (v)

Print and mark v as visited

**while** S is not empty

    curr = S.top()

**if** every vertex in adj(curr)  
        is visited

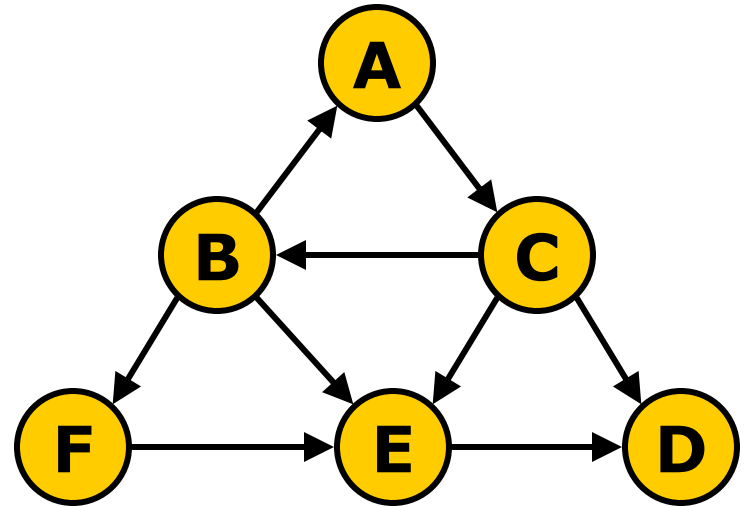
        S.pop()

**else**

**let** w be an unvisited vertex in adj(curr)

        S.push(w)

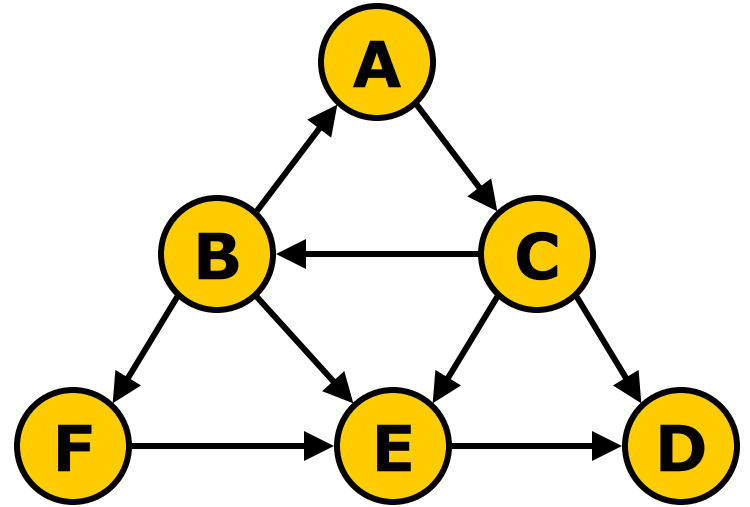
        print and mark w as visited



# Recursive version: DFS(v)

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```
print v  
marked v as visited  
foreach w in adj(v)  
  if w is not visited  
    DFS(w)
```



# Search all vertices

---

**Search(G)**

**foreach** vertex  $v$

mark  $v$  as unvisited

**foreach** vertex  $v$

**if**  $v$  is not visited

DFS( $v$ )

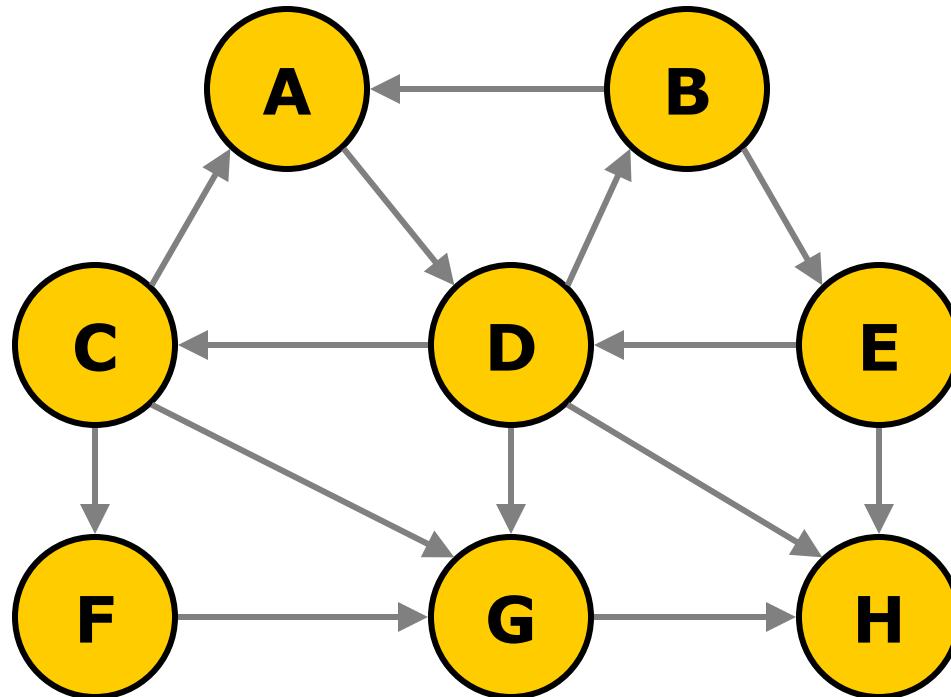
# Running time

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▣ DFS:  $\Theta(V + E)$

# Two more times!

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# What can we do with BFS/DFS? (1)

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Several tasks, let's see *some of them*:

## ▣ Reachability test

- Test whether vertex **v** is reachable from vertex **u**?
- Start BFS/DFS from **s = u**
- If **visited[v] = 1** after BFS/DFS terminates, then **v** is *reachable* from **u**; otherwise, **v** is *not reachable* from **u**

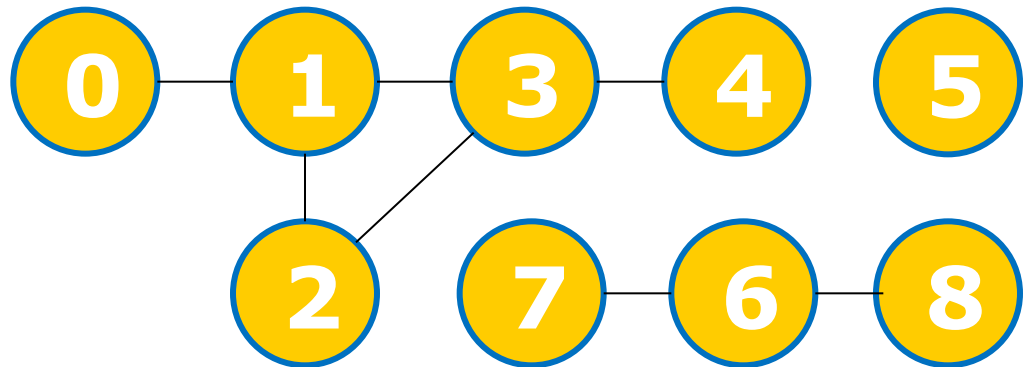
```
BFS(u)  // DFSrec(u)
```

```
if visited[v] == 1
```

```
    Output "Yes"
```

```
else
```

```
    Output "No"
```



# What can we do with BFS/DFS? (2)

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- 📁 Find Shortest Path between 2 vertices in an unweighted graph/graph where edges have same weight
  - When the graph is **unweighted\*/edges have same weight**, shortest path between any 2 vertices **u,v** is finding the **least number of edges** traversed from u to v
  - The  $O(V+E)$  Breadth First Search (BFS) traversal algorithm precisely measures this
    - ▣ Run BFS from u as source
    - ▣ Construct shortest path from u to v from **p** after BFS finishes
    - ▣ Cost of shortest path from u to v is (number of edges in the path)×(edge weight for weighted edges)

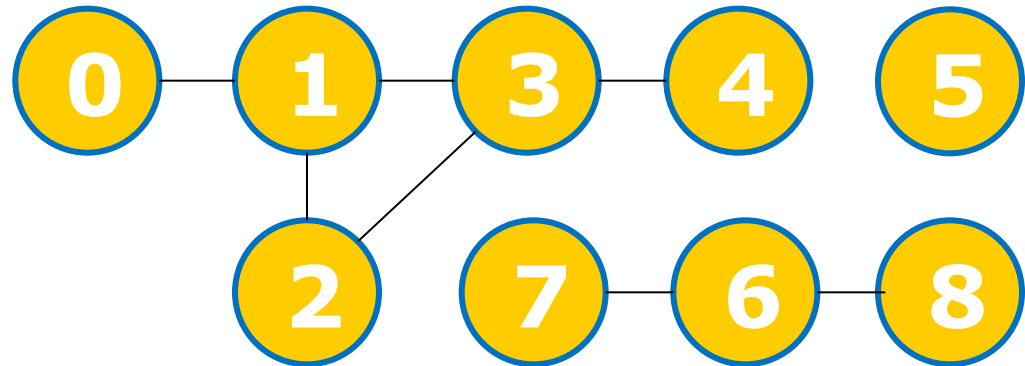
\* Can treat the edge weight as 1

# What can we do with BFS/DFS? (3)

## ▣ Identifying component(s)

- Component is sub graph containing 1 or more vertices in which any 2 vertices are connected to each other by at least one path, and is connected to no additional vertices
- With BFS/DFS, we can identify components by labeling/counting them in graph G
- Solution:

```
cc ← 0
for all v in V
    visited[v] ← 0
for all v in V // O(V)?
    if visited[v] == 0
        cc ← cc + 1
        DFSrec(v) // O(V+E)?
        // BFS from v
        // is also OK
```



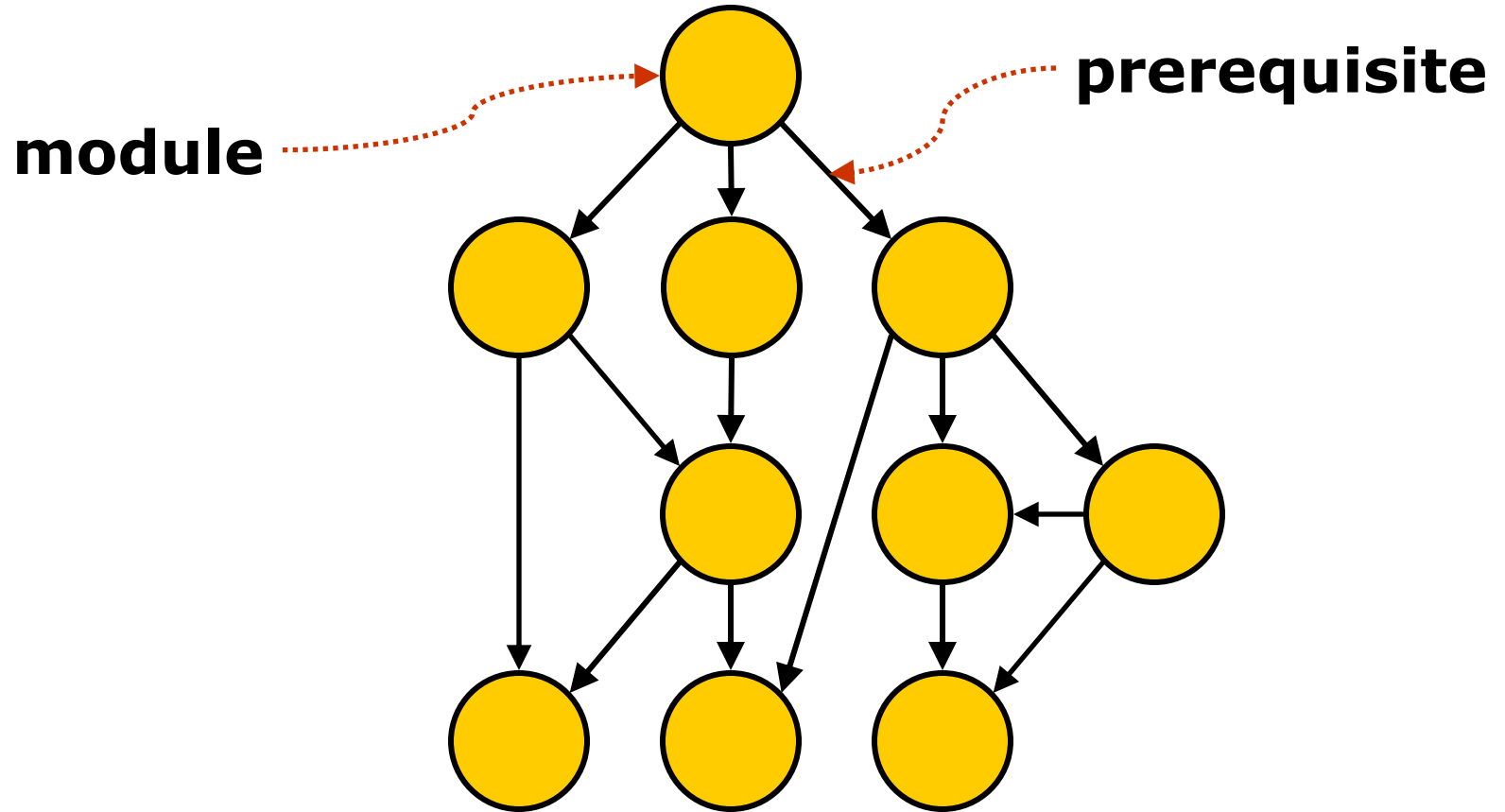


# Topological Sort



# Module selection

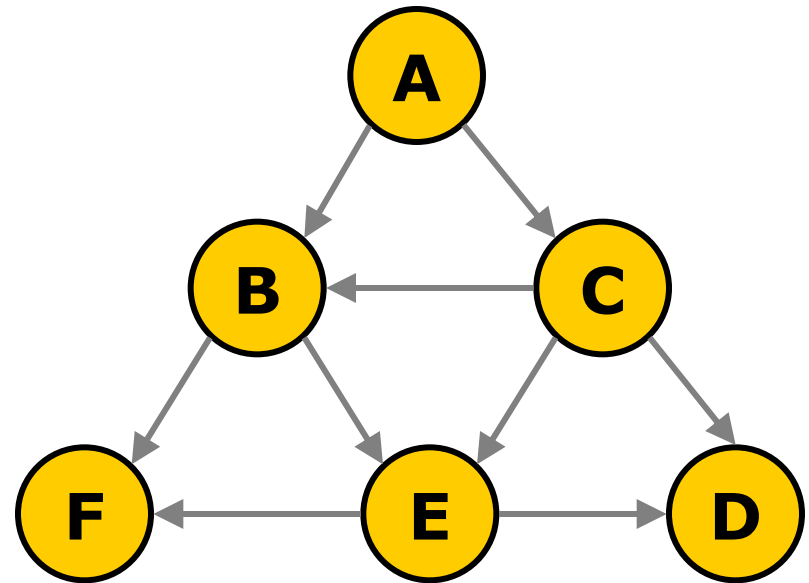
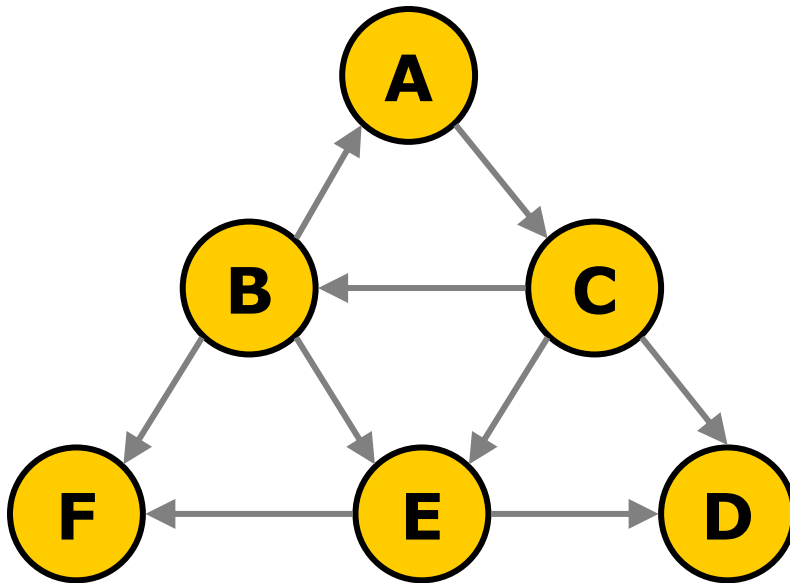
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# Definition

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- ▣ Directed Acyclic Graph (DAG): A directed graph with no cycle.



# Definition

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- in-degree of a vertex
  - number of incoming edges
- out-degree of a vertex
  - number of outgoing edges

# Topological sort

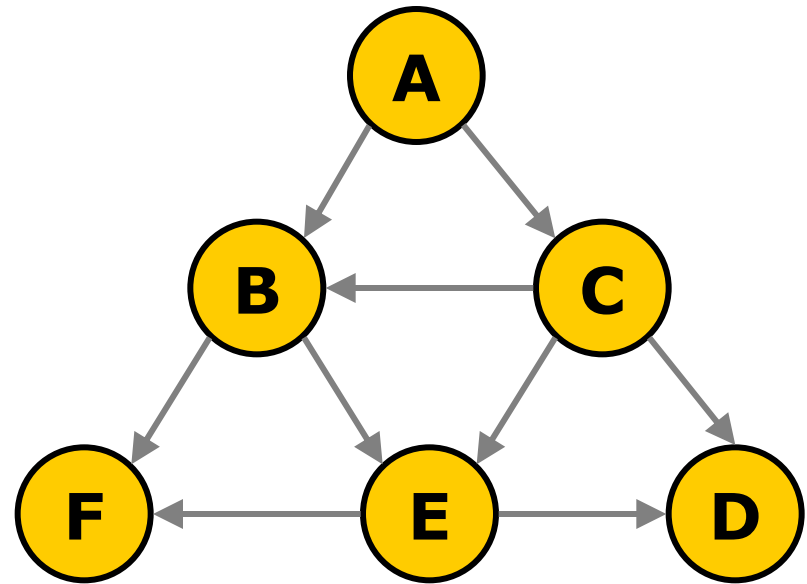
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- Goal: Order the vertices, such that if there is a path from  $u$  to  $v$ ,  $u$  appears before  $v$  in the output.

# Topological sort

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- ❑ ACBEFD
- ❑ ACBEDF
- ❑ ACDBEF



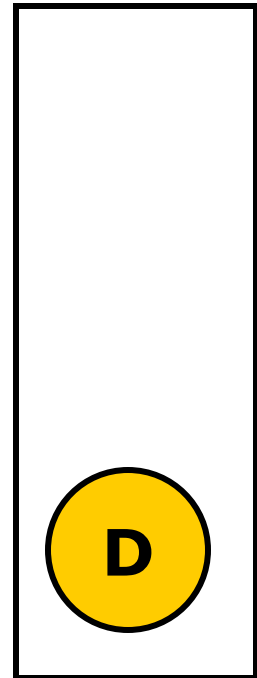
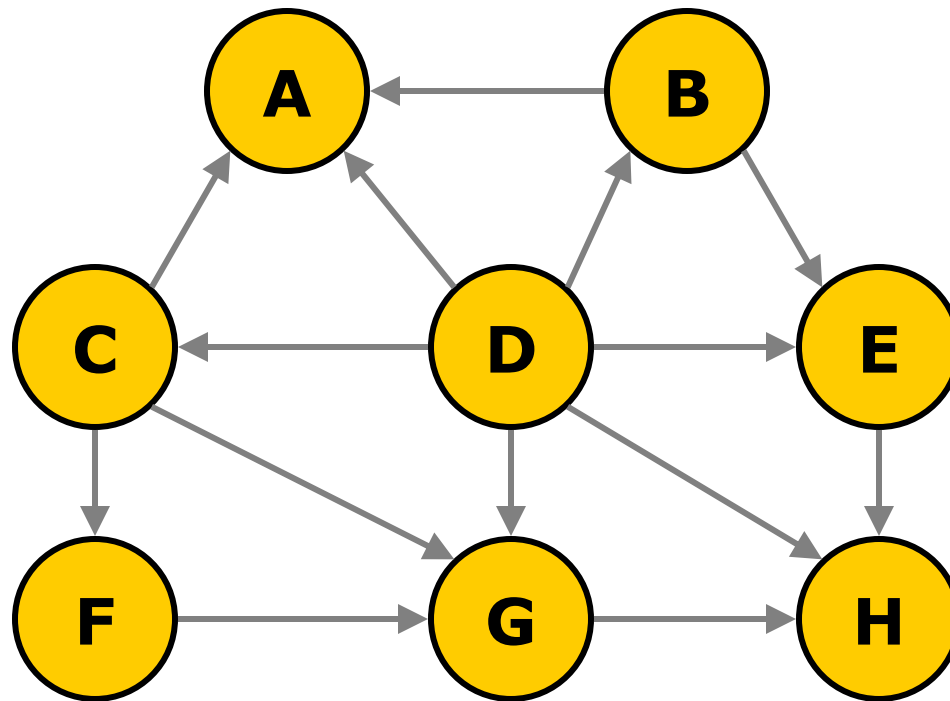
# Pseudocode for Toposort

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```
q = new Queue()
put all vertices with in-degree 0 into q
while q is not empty
    v = q.deq()
    print v
    remove v from G
    enqueue neighbours of v with in-degree 0
```

# Example

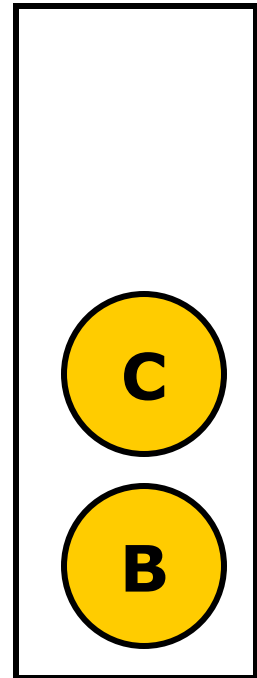
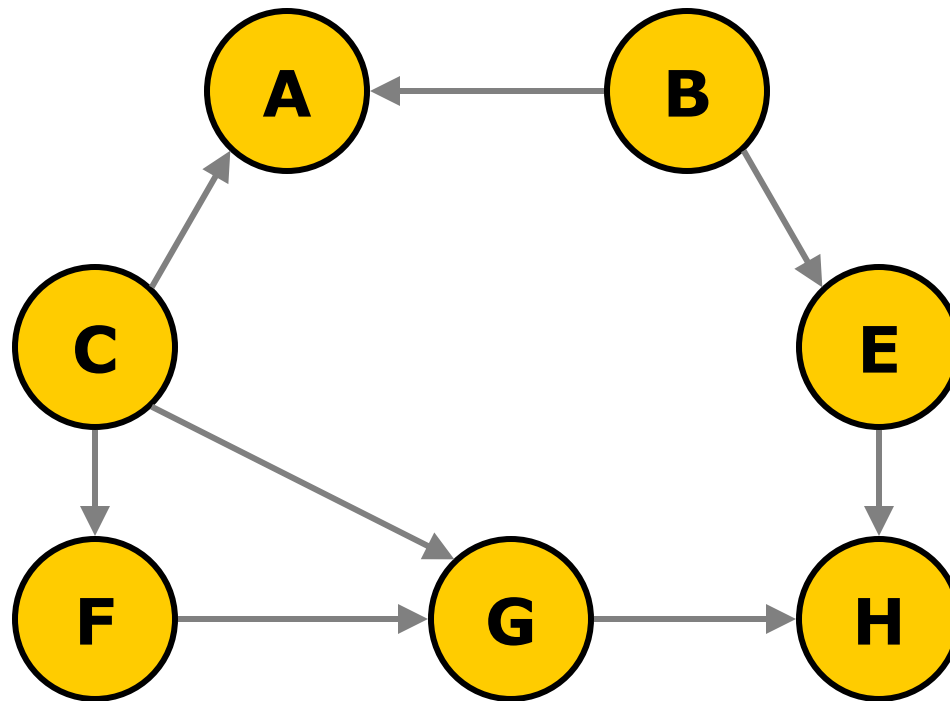
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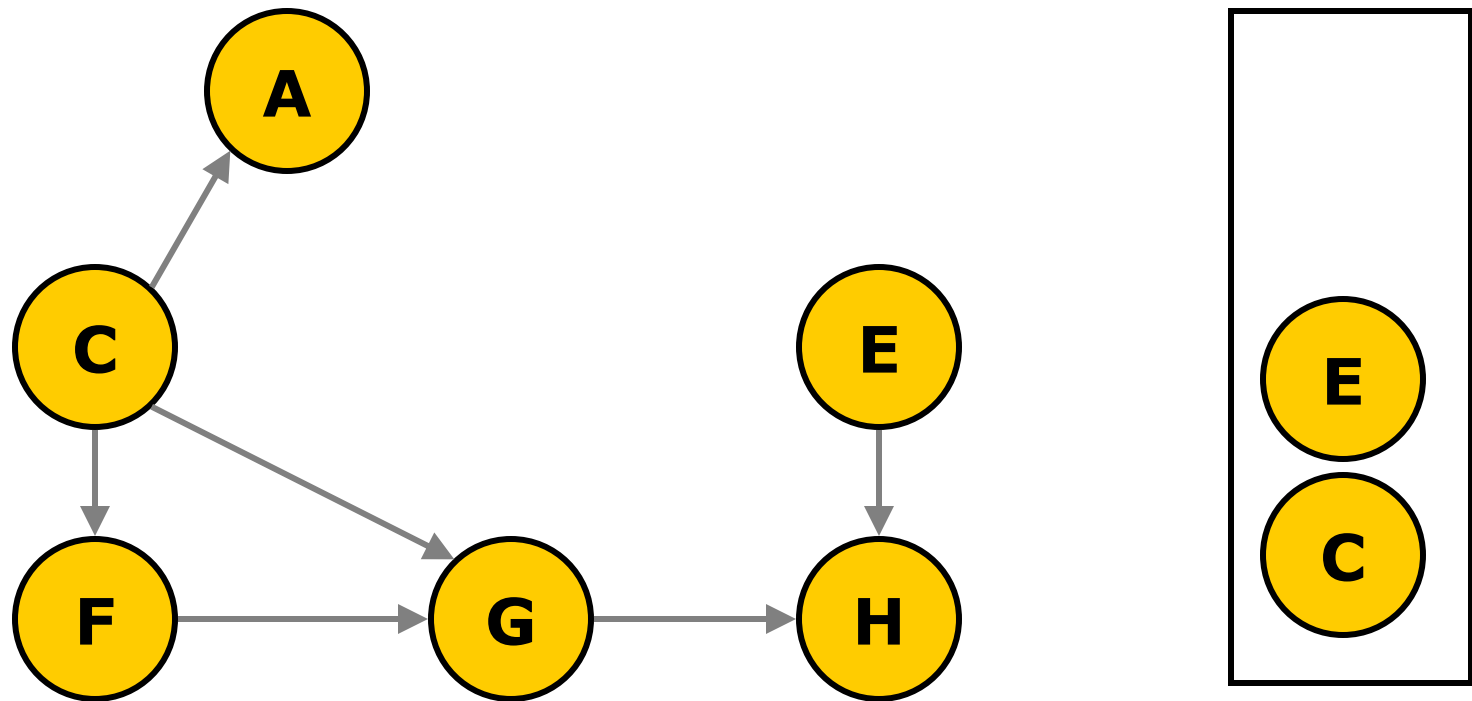
# Output: D

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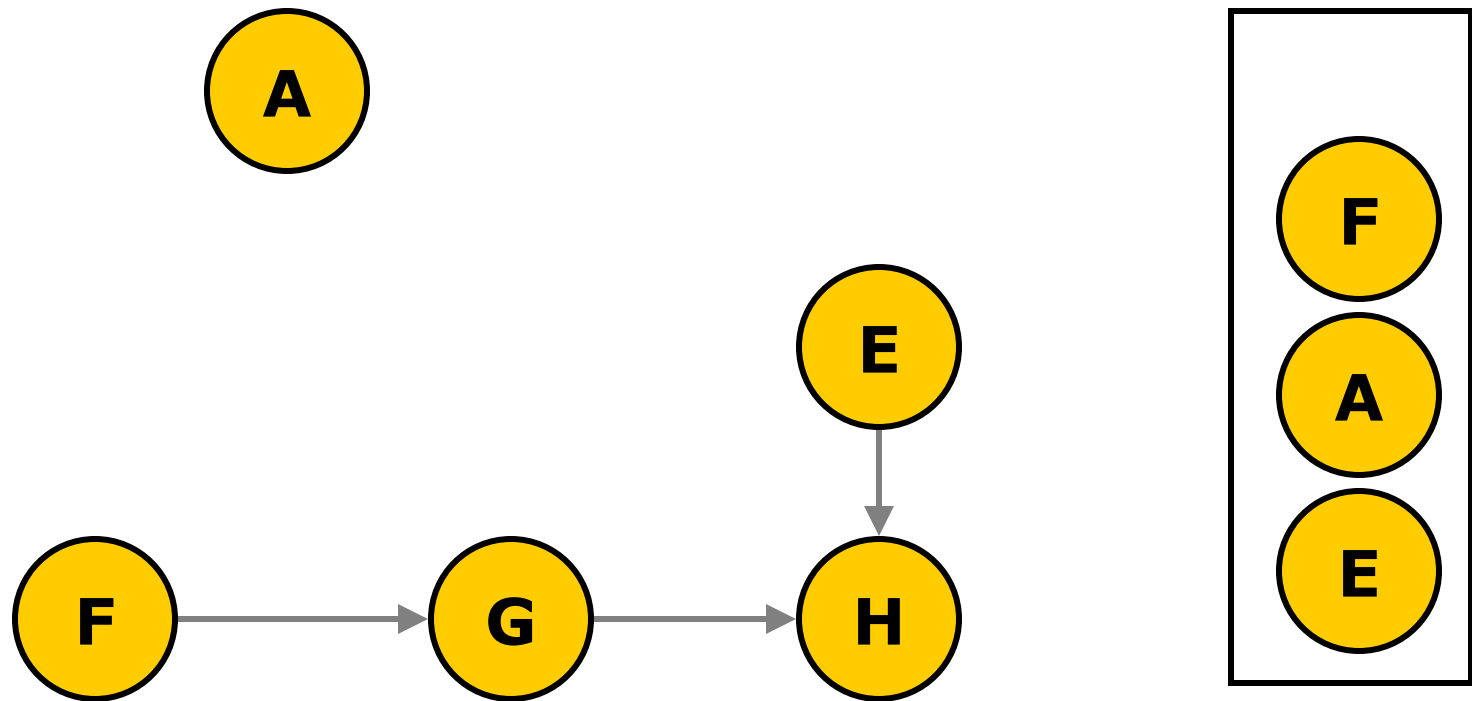
# Output: DB

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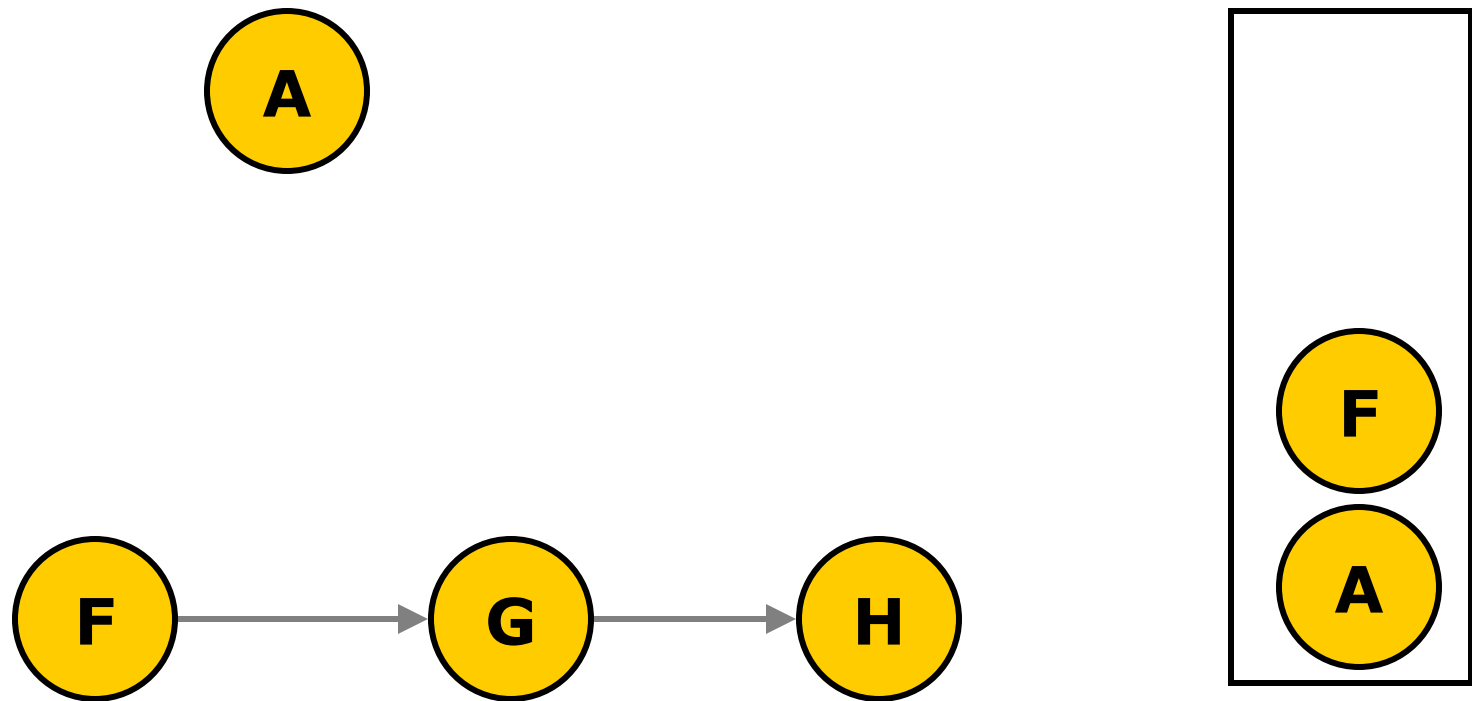
# Output: DBC

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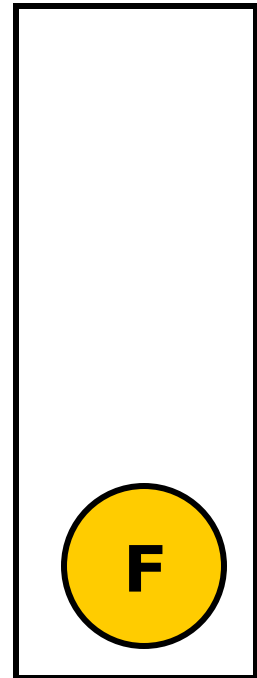
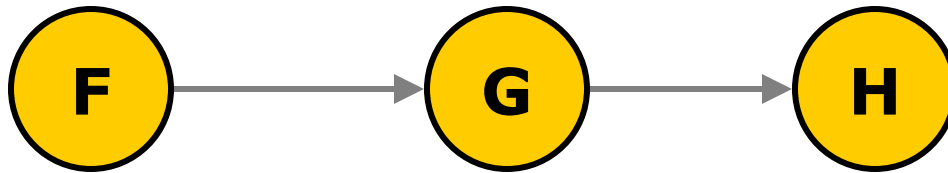
# Output: DBCE

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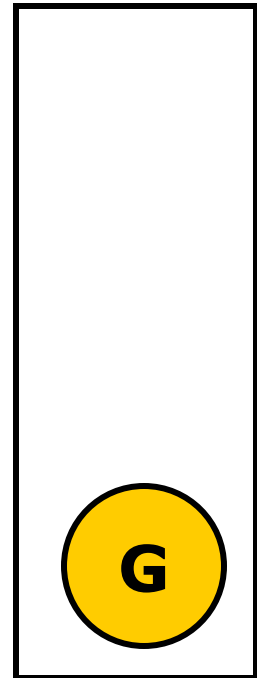
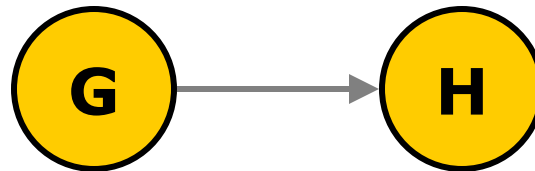
# Output: DBCEA

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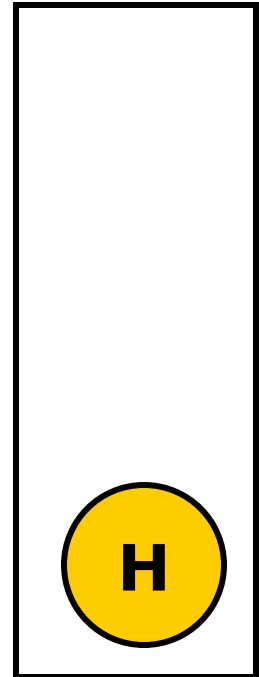
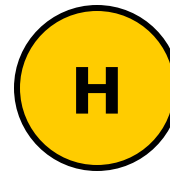
# Output: DBCEAF

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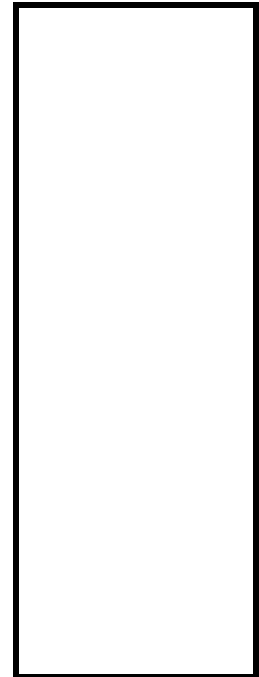
# Output: DBCEAFG

---



# Output: DBCEAFGH

---





# Pseudocode for Toposort

---

```
q = new Queue()
put all vertices with in-degree 0 into q
while q is not empty
    v = q.deq()
    print v
    remove v from G
    enqueue neighbours of v with in-degree 0
```

**Which DS to use?**

**What is the pre-process?**

**What is the complexity?**