

MUX Definitions:

```
package forwardmux;
typedef enum bit [1:0] {
    rs_out    = 2'b00,
    ex_mem_out = 2'b01,
    mem_wb_out = 2'b10
} forwardmux_sel_t;
endpackage
```

Forwarding Unit:

Below is the pseudo code for the forwarding unit shown in the datapath.

```
// source register 1 conflicts
forward1 = forwardmux::rs_out; // Output from register unit
if (id_ex.rs1 != 0)
    if (ex_mem.ctrl.load_regfile & (ex_mem.rd == id_ex.rs1))
        forward1 = forwardmux::ex_mem_out; // ex_mem.ex_data_out
    else if (mem_wb.ctrl.load_regfile) & (mem_wb.rd == id_ex.rs1)
        forward1 = forwardmux::mem_wb_out; // mem_wb.rd_data_in

// source register 2 conflicts (same as above but for second mux)
forward2 = forwardmux::rs_out;
if (id_ex.rs2 != 0)
    if (ex_mem.ctrl.load_regfile) & (ex_mem.rd == id_ex.rs2)
        forward2 = forwardmux::ex_mem_out;
    else if (mem_wb.ctrl.load_regfile) & (mem_wb.rd == id_ex.rs2)
        forward2 = forwardmux::mem_wb_out;
```

Hazard Detection Unit:

```
hz_pc_ld = 1;
hz_if_id_ld = 1;
hz_if_id_rst = 0;
hz_id_ex_rst = 0;
hz_ex_mem_rst = 0;

// Data hazard
no_sr1 = [op_auipc, op_lui, op_jal] // Instr which don't read sr1
no_sr2 = [op_auipc, op_lui, op_jal, op_load, op_imm]
```

```

if (id_ex.opcode == op_load
& id_ex.rd != 0
& ((if_id.opcode not in no_sr1) & (id_ex.rd == if_id.sr1))
| (if_id.opcode not in no_sr2) & (id_ex.rd == if_id.sr2)))
    // Stall pipeline and insert nop in ex stage
    hz_pc_ld = 0      // no load pc
    hz_if_id_ld = 0 // no load if_id
    hz_id_ex_rst = 1 // Insert nop

// Control hazard
if ((ex_mem.opcode == op_br & br_en) | ex_mem.opcode == op_jal |
ex_mem.opcode == op_jalr)
    hz_if_id_rst = 1 // Reset if_id
    hz_id_ex_rst = 1
    hz_ex_mem_rst = 1

```

Arbiter Design

The interface for the arbiter is as follows:

```
module arbiter
(
    input clk,
    input rst,

    /* Instruction memory signals */
    input  logic [31:0]  imem_address,
    output logic [255:0] imem_rdata,
    input  logic [255:0] imem_wdata,
    input  logic        imem_read,
    input  logic        imem_write,
    output logic        imem_resp,

    /* Data memory signals */
    input  logic [31:0]  dmem_address,
    output logic [255:0] dmem_rdata,
    input  logic [255:0] dmem_wdata,
    input  logic        dmem_read,
    input  logic        dmem_write,
    output logic        dmem_resp,

    /* Physical memory signals */
    output logic [31:0]  pmem_address,
    input  logic [255:0] pmem_rdata,
    output logic [255:0] pmem_wdata,
    output logic        pmem_read,
    output logic        pmem_write,
    input  logic        pmem_resp
);
```

The arbiter itself can be described entirely by its state machine.

Controller Description:

Default signals:

pmem_address = dmem_address;

pmem_wdata = dmem_wdata;

pmem_read = 1'b0;

pmem_write = 1'b0;

dmem_resp = 1'b0;

dmem_rdata = pmem_rdata;

imem_resp = 1'b0;

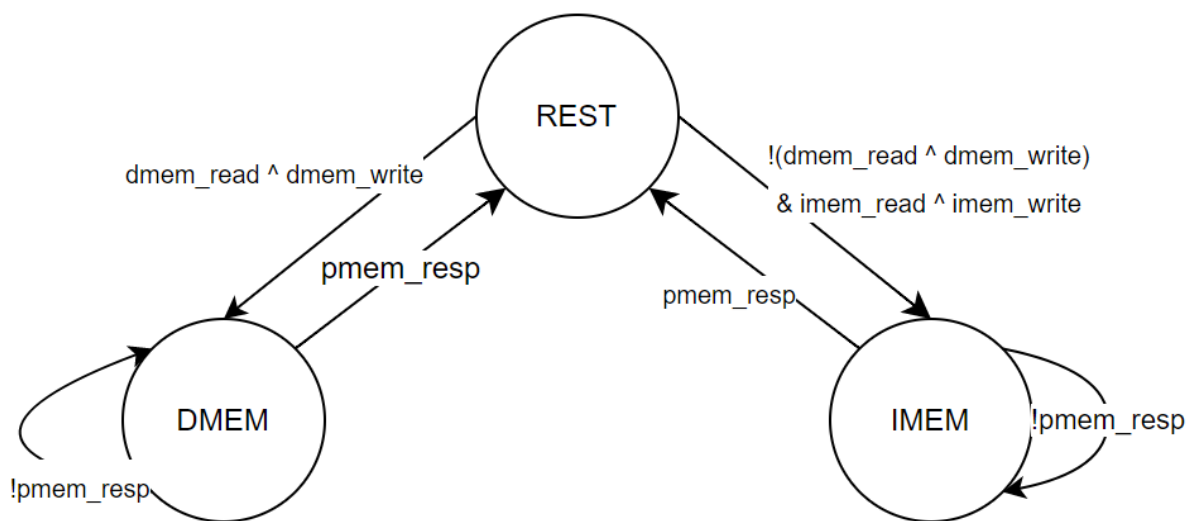
imem_rdata = pmem_rdata;

State Name	Description	Transition Conditions	Outputs
REST	Rest state. No physical memory read/writes in progress.	if (dmem_read ^ dmem_write) DMEM else if (imem_read ^ imem_write) IMEM else REST	if (dmem_read ^ dmem_write) pmem_read = dmem_read; pmem_write = dmem_write; dmem_resp = pmem_resp; else if (imem_read ^ imem_write) pmem_read = imem_read; pmem_write = imem_write; imem_resp = pmem_resp; pmem_address = imem_address; pmem_wdata = imem_wdata;
DMEM	Accessing physical memory for data.	if (pmem_resp) REST else DMEM	pmem_read = dmem_read; pmem_write = dmem_write; dmem_resp = pmem_resp;

IMEM	Accessing physical memory for instruction.	if (pmem_resp) -> REST else -> IMEM	pmem_read = imem_read; pmem_write = imem_write; imem_resp = pmem_resp; pmem_address = imem_address; pmem_wdata = imem_wdata;
------	--	--	--

Note that this design assumes that main memory accesses take at least 2 cycles to complete.

State Diagram:



Arbiter Integration:

In order to integrate the multicycle memory system with the processor, the processor must be able to be stalled. In this design, whenever there is a cache miss on either the instruction or data cache, the entire pipeline will be stalled by pausing loads on the pc and the four pipeline registers. Note that these load signals will override the reset signals generated by the hazard detection unit. This stalling logic is contained in the datapath but is replicated here for clarity.

```
instr_stall = !instruction_cache.mem_resp
```

```
data_stall = (ex_mem.ctrl.mem_write | ex_mem.ctrl.mem_read) &
!data_cache.mem_resp
```

```
pipeline_stall = instr_stall | data_stall
```

```
pc.load = !pipeline_stall & hz_pc_ld
```

```
if_id.load = !pipeline_stall & hz_if_id_ld
id_ex.load = !pipeline_stall
ex_mem.load = !pipeline_stall
mem_wb.load = !pipeline_stall
if_id.rst = !pipeline_stall & hz_if_id_rst // or main reset
id_ex.rst = !pipeline_stall & hz_id_ex_rst // or main reset
ex_mem.rst = !pipeline_stall & hz_ex_mem_rst // or main reset
```

Progress Report (3/10-3/29)

Over the last two weeks, we completed the requirements for Checkpoint 1 as well as parts of checkpoint 2.

For checkpoint 1 content, the basic division of labor was as follows:

- Implementation of basic RV32I pipelined datapath: Mitchell
- Arbiter, hazard detection, and forwarding design: Neha
- Arbiter, hazard detection, and forwarding design verification: Mitchell
- Pipeline implementation verification: Yu

The basic pipelined datapath was initially tested and debugged using the mp4-cp1.s test code provided by the TA's. Once this test successfully passed, the design was further tested by writing extra assembly code, which tested each instruction independently, and inspecting the waveform to check if the outcome matches the expectation.

For checkpoint 2 content that was implemented, the division of labor was as follows:

- Integration of caches, arbiter, hazard detection, forwarding, and static branch prediction: Neha
- RVFI + verification: Yu

First, hazard detection, forwarding, and static branch prediction were implemented and tested using the magic memory from checkpoint 1. Assembly test code was written to test each of the different forwarding, data hazard, and control hazard possibilities. To ensure correct behavior of this test code, Verdi was used to trace the timing for each of the instructions. Once this part of the design was verified, the arbiter was implemented and integrated with the given cache. From here, the same testing procedure was repeated, and we ensured that the mp4-cp2.s test code also passed. Finally, once the RVFI was correctly hooked up, the test code was rerun to ensure that our design matches the specifications.

The fmax and total power for our design as of now is given below. The full timing and power reports are at the end of this document.

slack = 5.15

fmax = $1/(10\text{-slack}) * 1000 = 206.2 \text{ MHz}$

total power = 1.78e+03 uW

A datapath for our design up to this point is given at the end of this document.

Roadmap (3/29-4/12)

As our next step, we plan to start working on designing the advanced features. The following is a list of advanced features we are planning to look into:

Cache organization and design

L2+ cache system[2]

4-way set associative cache[2]

Parameterized cache[points up to TA discretion]

Branch prediction

Local branch history table[2]

Global 2-level branch history table[3]

Tournament branch predictor[5]

Software branch predictor model [2]

Advanced cache

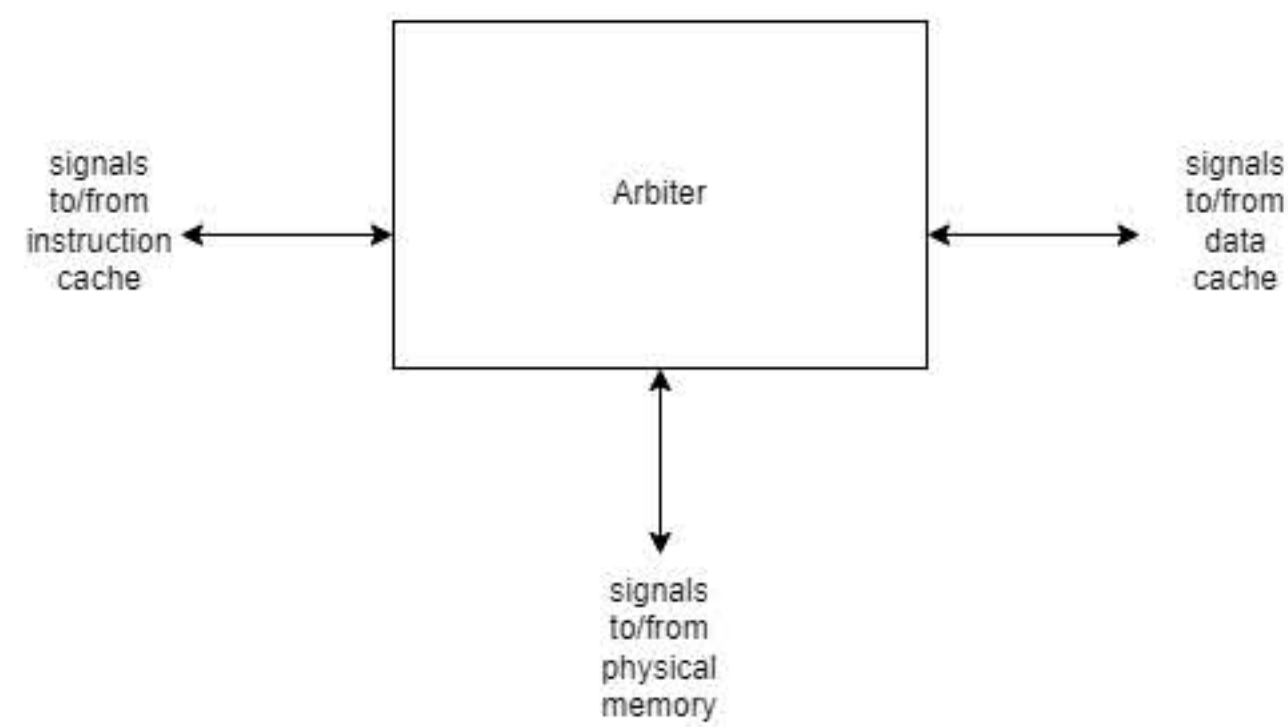
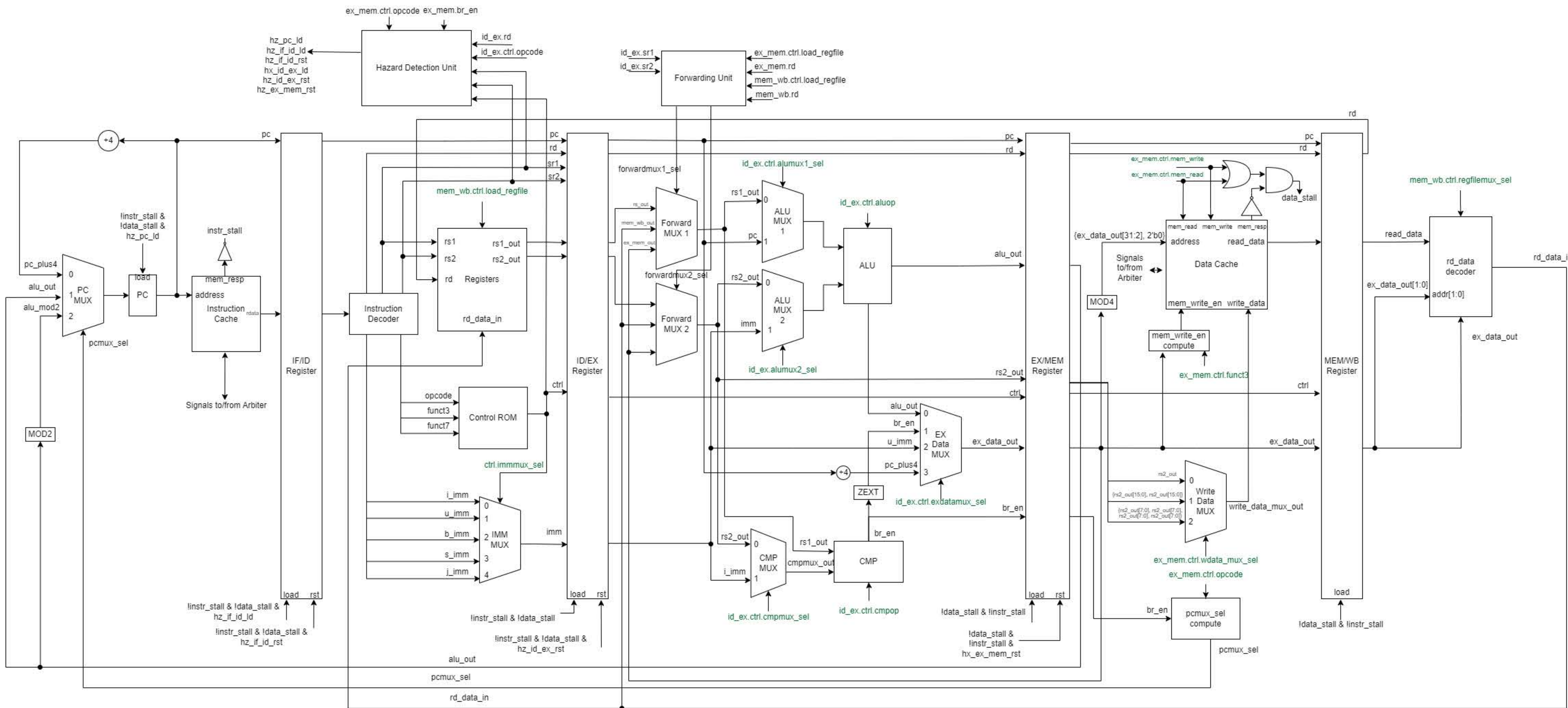
Victim Cache[6]

Other than the advanced features, we are also looking for a more efficient branch stall design and adding the instruction for execution of coremark.

The work division for now is as follows:

- Cache organization and design options: Neha
- More efficient control hazard handling & victim cache: Mitchell
- Branch prediction & coremark: Yu

Each member is responsible for the design, implementation, and verification of their respective part. Our main goal for the next two weeks will be to do the design component.



Information: Updating design information... (UID-85)
Warning: There are 291 switching activity information conflicts. (PWR-19)
Information: Propagating switching activity (high effort zero delay simulation). (PWR-6)
Warning: Design has unannotated sequential cell outputs. (PWR-415)

Report : power
 -hier
 -analysis_effort high
Design : mp4
Version: R-2020.09-SP4
Date : Mon Mar 27 19:37:58 2023

Library(s) Used:

NangateOpenCellLibrary (File: /class/ece411/freepdk-45nm/stdcells.db)

Operating Conditions: typical Library: NangateOpenCellLibrary
Wire Load Model Mode: top

Design	Wire Load Model	Library
mp4	5K_hvratio_1_1	NangateOpenCellLibrary

Global Operating Voltage = 1.1
Power-specific unit information :
Voltage Units = 1V
Capacitance Units = 1.000000ff
Time Units = 1ns
Dynamic Power Units = 1uW (derived from V,C,T units)
Leakage Power Units = 1nW

Hierarchy		Switch Power	Int Power	Leak Power	Total
Power %					
mp4		272.791	757.822	7.49e+05	
1.78e+03	100.0				
cacheline_adaptor (cacheline_adaptor)		20.161	45.124	3.70e+04	
102.238	5.7				
arbiter (arbiter)		5.671	4.263	9.83e+03	
19.767	1.1				
dcache (cache_0)		64.613	186.456	2.43e+05	
493.621	27.7				

bus (line_adapter_0)	0.242	0.175	6.12e+03
6.533 0.4			
datapath (cache_datapath_0)	64.307	185.684	2.36e+05
486.095 27.3			
dirty (array_width1_0)	1.341	6.092	1.60e+03
9.036 0.5			
valid (array_width1_1)	0.121	0.696	1.53e+03
2.345 0.1			
tag (array_width24_0)	0.368	5.493	1.92e+04
25.065 1.4			
DM_cache (data_array_0)	61.554	172.762	1.98e+05
432.111 24.3			
control (cache_control_0)	6.33e-02	0.598	332.251
0.993 0.1			
icache (cache_1)	76.643	202.565	2.48e+05
526.882 29.6			
bus (line_adapter_1)	1.285	0.641	4.24e+03
6.161 0.3			
datapath (cache_datapath_1)	75.290	201.421	2.43e+05
520.000 29.2			
valid (array_width1_3)	0.139	0.822	1.59e+03
2.553 0.1			
tag (array_width24_1)	0.979	6.006	1.94e+04
26.418 1.5			
DM_cache (data_array_1)	72.738	193.807	2.14e+05
480.348 27.0			
control (cache_control_1)	6.90e-02	0.503	149.170
0.721 0.0			
cpu (cpu)	105.293	319.292	2.10e+05
634.864 35.7			
datapath (datapath)	105.293	319.292	2.10e+05
634.864 35.7			
rd_data_decoder (rd_data_decoder)			
	0.424	0.173	2.78e+03
3.378 0.2			
forwarding_unit (forwarding)	0.234	0.318	1.19e+03
1.746 0.1			
CMP (cmp)	0.347	0.473	4.42e+03
5.234 0.3			
ALU (alu)	0.891	0.938	2.26e+04
24.441 1.4			
hazard_detection (hazard_detection)			
	0.141	0.223	995.991
1.360 0.1			
control_rom (control_rom)	0.518	0.247	2.41e+03
3.180 0.2			
regfile (regfile)	6.089	29.810	1.12e+05
147.573 8.3			
instr_decoder (instr_decoder)	0.000	0.000	0.000
0.000 0.0			
PC (pc_register)	1.476	3.919	3.24e+03
8.632 0.5			
mem_wb_reg (mem_wb_reg)	14.230	41.075	7.27e+03
62.572 3.5			

ex_mem_reg (ex_mem_reg)	27.057	80.468	1.18e+04
119.314 6.7			
id_ex_reg (id_ex_reg)	38.577	118.398	1.68e+04
173.765 9.8			
if_id_reg (if_id_reg)	14.090	42.505	6.39e+03
62.983 3.5			
1			

Report : timing

-path full

-delay max

-max_paths 1

Design : mp4

Version: R-2020.09-SP4

Date : Mon Mar 27 19:36:14 2023

Operating Conditions: typical Library: NangateOpenCellLibrary

Wire Load Model Mode: top

Startpoint: cpu/datapath/mem_wb_reg/data_reg[rd][0]

(rising edge-triggered flip-flop clocked by my_clk)

Endpoint: cpu/datapath/ex_mem_reg/data_reg[ex_data_out][31]

(rising edge-triggered flip-flop clocked by my_clk)

Path Group: my_clk

Path Type: max

Des/Clust/Port

Wire Load Model

Library

mp4

5K_hvratio_1_1

NangateOpenCellLibrary

Point

Incr

Path

clock my_clk (rise edge)

0.00

0.00

clock network delay (ideal)

0.00

0.00

cpu/datapath/mem_wb_reg/data_reg[rd][0]/CK (DFF_X1)

0.00

0.00

r

cpu/datapath/mem_wb_reg/data_reg[rd][0]/Q (DFF_X1)

0.10

0.10

f

cpu/datapath/mem_wb_reg/out[rd][0] (mem_wb_reg)

0.00

0.10

f

cpu/datapath/forwarding_unit/wb_rd[0] (forwarding)

0.00

0.10

f

cpu/datapath/forwarding_unit/U20/ZN (INV_X1)

0.06

0.15

r

cpu/datapath/forwarding_unit/U21/ZN (OAI22_X1)

0.04

0.19

f

cpu/datapath/forwarding_unit/U22/ZN (AOI221_X1)

0.09

0.28

r

cpu/datapath/forwarding_unit/U24/ZN (NAND4_X1)

0.05

0.33

f

cpu/datapath/forwarding_unit/U25/ZN (NOR3_X1)

0.07

0.40

r

cpu/datapath/forwarding_unit/forward2[1] (forwarding)

0.00

0.40

r

cpu/datapath/U36/ZN (INV_X1)

0.03

0.42

f

r	cpu/datapath/U40/ZN (NOR2_X1)	0.16	0.58
r	cpu/datapath/U41/Z (CLKBUF_X1)	0.19	0.77
f	cpu/datapath/U42/ZN (NOR2_X1)	0.11	0.88
f	cpu/datapath/U43/Z (CLKBUF_X1)	0.17	1.05
r	cpu/datapath/U224/ZN (AOI22_X1)	0.10	1.15
f	cpu/datapath/U225/ZN (OAI21_X1)	0.04	1.19
r	cpu/datapath/U227/ZN (INV_X1)	0.04	1.23
f	cpu/datapath/U229/ZN (AOI22_X1)	0.03	1.26
f	cpu/datapath/U230/Z (CLKBUF_X1)	0.13	1.39
f	cpu/datapath/ALU/b[2] (alu)	0.00	1.39
r	cpu/datapath/ALU/U37/ZN (INV_X1)	0.15	1.54
f	cpu/datapath/ALU/U25/ZN (INV_X1)	0.10	1.64
f	cpu/datapath/ALU/U113/Z (XOR2_X1)	0.11	1.75
f	cpu/datapath/ALU/U186/CO (FA_X1)	0.11	1.86
f	cpu/datapath/ALU/U255/CO (FA_X1)	0.09	1.95
f	cpu/datapath/ALU/U360/CO (FA_X1)	0.09	2.04
f	cpu/datapath/ALU/U382/CO (FA_X1)	0.09	2.13
f	cpu/datapath/ALU/U400/CO (FA_X1)	0.09	2.22
f	cpu/datapath/ALU/U673/CO (FA_X1)	0.09	2.31
f	cpu/datapath/ALU/U415/CO (FA_X1)	0.09	2.40
f	cpu/datapath/ALU/U429/CO (FA_X1)	0.09	2.49
f	cpu/datapath/ALU/U450/CO (FA_X1)	0.09	2.58
f	cpu/datapath/ALU/U469/CO (FA_X1)	0.09	2.67
f	cpu/datapath/ALU/U483/CO (FA_X1)	0.09	2.76
f	cpu/datapath/ALU/U500/CO (FA_X1)	0.09	2.86
f	cpu/datapath/ALU/U519/CO (FA_X1)	0.09	2.95
f	cpu/datapath/ALU/U557/CO (FA_X1)	0.09	3.04

f	cpu/datapath/ALU/U687/CO (FA_X1)	0.09	3.13
f	cpu/datapath/ALU/U700/CO (FA_X1)	0.09	3.22
f	cpu/datapath/ALU/U713/CO (FA_X1)	0.09	3.31
f	cpu/datapath/ALU/U725/CO (FA_X1)	0.09	3.40
f	cpu/datapath/ALU/U736/CO (FA_X1)	0.09	3.49
f	cpu/datapath/ALU/U746/CO (FA_X1)	0.09	3.58
f	cpu/datapath/ALU/U763/CO (FA_X1)	0.09	3.67
f	cpu/datapath/ALU/U775/CO (FA_X1)	0.09	3.76
f	cpu/datapath/ALU/U576/CO (FA_X1)	0.09	3.85
f	cpu/datapath/ALU/U600/CO (FA_X1)	0.09	3.94
f	cpu/datapath/ALU/U786/CO (FA_X1)	0.09	4.03
f	cpu/datapath/ALU/U798/CO (FA_X1)	0.09	4.12
f	cpu/datapath/ALU/U617/CO (FA_X1)	0.09	4.22
f	cpu/datapath/ALU/U639/CO (FA_X1)	0.09	4.31
f	cpu/datapath/ALU/U660/CO (FA_X1)	0.09	4.40
f	cpu/datapath/ALU/U663/Z (XOR2_X1)	0.07	4.46
f	cpu/datapath/ALU/U664/ZN (AND2_X1)	0.04	4.50
f	cpu/datapath/ALU/U665/ZN (OR2_X1)	0.06	4.56
f	cpu/datapath/ALU/f[31] (alu)	0.00	4.56
f	cpu/datapath/U652/ZN (AOI22_X1)	0.06	4.62
r	cpu/datapath/U653/ZN (OAI21_X1)	0.03	4.65
f	cpu/datapath/ex_mem_reg/in[ex_data_out][31] (ex_mem_reg)	0.00	4.65
f	cpu/datapath/ex_mem_reg/U102/ZN (AND2_X1)	0.05	4.70
f	cpu/datapath/ex_mem_reg/data_reg[ex_data_out][31]/D (DFF_X1)	0.01	4.71
f	data arrival time		4.71
	clock my_clk (rise edge)	10.00	10.00
	clock network delay (ideal)	0.00	10.00

clock uncertainty	-0.10	9.90
cpu/datapath/ex_mem_reg/data_reg[ex_data_out][31]/CK (DFF_X1)	0.00	9.90
r		
library setup time	-0.04	9.86
data required time		9.86

data required time		9.86
data arrival time		-4.71

slack (MET)		5.15

1