

# Constraining the outputs of ReLU neural networks

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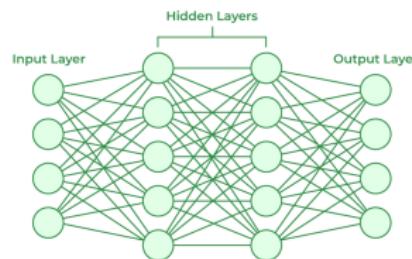
# Neural networks

Any feedforward neural network with an activation function  $\sigma$  gives rise to

$$f_{\theta} : x \mapsto g_L \circ \sigma \circ g_{L-1} \dots \sigma \circ g_1(x)$$

where each layer has linear map  $g_\ell : y \mapsto W_\ell y$  with parameter  $\theta_\ell = W_\ell$ .

The dimension of the input space  $n_0$  and the layer widths  $n_\ell$  determine the network's architecture.



For a dataset  $X = [x_1, x_2, \dots, x_m]$  and unknown parameters  $\theta$  we are interested in describing the **constraints** between the coordinates of the array of model outputs  $F_X(\theta) = [f_{\theta}(x_1), f_{\theta}(x_2), \dots, f_{\theta}(x_m)]$ .

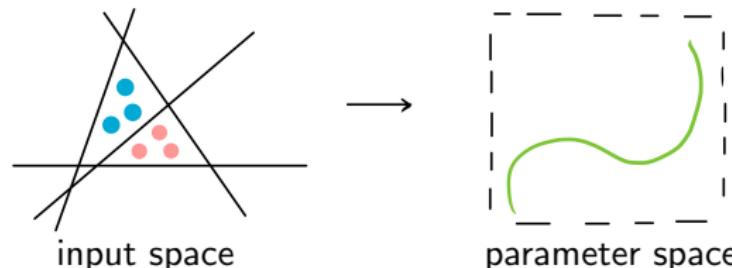
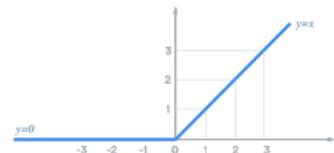
# ReLU networks

A *ReLU network* is given by the activation function

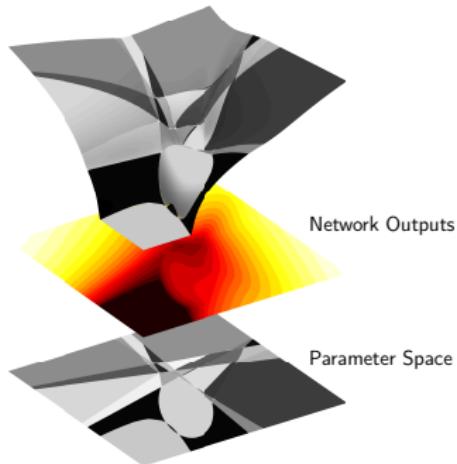
$$\sigma : y = (y_1, \dots, y_{n_\ell}) \mapsto (\max\{0, y_1\}, \dots, \max\{0, y_{n_\ell}\})$$

at each layer of the neural network.

- this makes  $f_\theta(x)$  piece-wise linear
  - ▶ natural subdivision of the **input space** into regions
  - ▶  $f_\theta(x)$  is a linear function of  $x$  in each region
- now consider multiple data points  $X = [x_1, \dots, x_m]$ 
  - ▶ this subdivision extends to the **parameter space**
  - ▶  $F_x(\theta)$  is multi-linear in  $\theta$  in each **activation region**

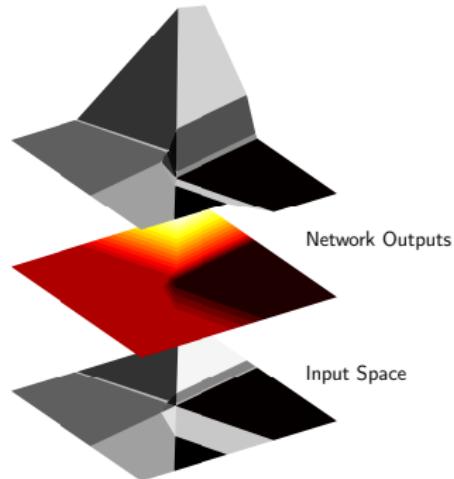


# Fixed data vs. fixed parameters



Fixed Input Data

$$\begin{matrix} n_0 & n_1 & n_2 & n_3 \\ \vdots & \begin{array}{c|c} \bullet & \\ \hline \bullet & \end{array} & \begin{array}{c|c} \bullet & \\ \hline \bullet & \end{array} & \vdots \\ \vdots & \begin{array}{c|c} \bullet & \\ \hline \bullet & \end{array} & \begin{array}{c|c} \bullet & \\ \hline \bullet & \end{array} & \vdots \end{matrix}$$



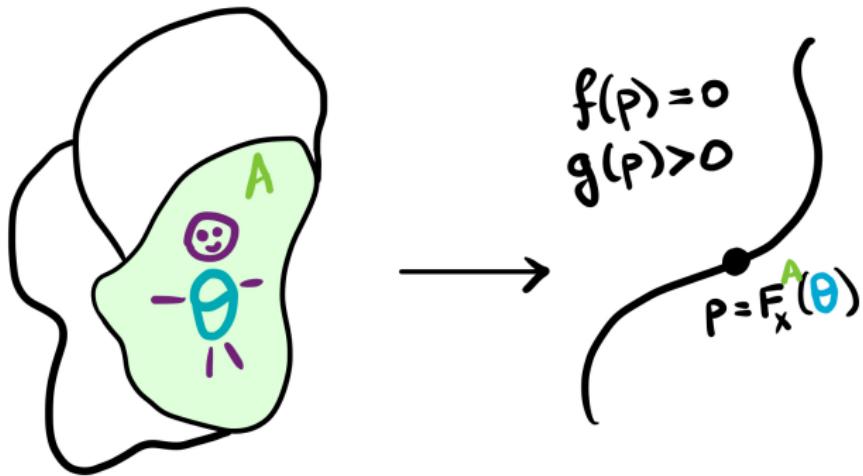
Fixed Parameters

$$\begin{aligned} X &= [\textcolor{magenta}{x_1}, \textcolor{magenta}{x_2}] \\ A_1 &= [(\textcolor{magenta}{1}, 1, 0), (1, 0)] \\ A_2 &= [(\textcolor{blue}{0}, 1, 1), (\textcolor{blue}{1}, 1)] \end{aligned}$$

# The main question

## Problem

Describe the equations and inequalities that define the image of  $F_X^A(\theta)$  as the parameter  $\theta$  varies over an arbitrary activation region  $A$  in the parameter space.



# Implicitization

Given a model, parametrized by

$$\varphi : \theta = (\theta_1, \dots, \theta_n) \mapsto (f_1(\theta), f_2(\theta), \dots, f_m(\theta)),$$

we are interested in describing the polynomials defining  $\overline{\text{image}}(\varphi)$ . This process is called *implicitization*.

# Implicitization

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## Example (The independence model.)

Parametrization:

$$(\theta_1, \theta_2) \mapsto \left( \underbrace{\theta_1 \theta_2}_{p_1}, \underbrace{\theta_1(1 - \theta_2)}_{p_2}, \underbrace{(1 - \theta_1)\theta_2}_{p_3}, \underbrace{(1 - \theta_1)(1 - \theta_2)}_{p_4} \right).$$

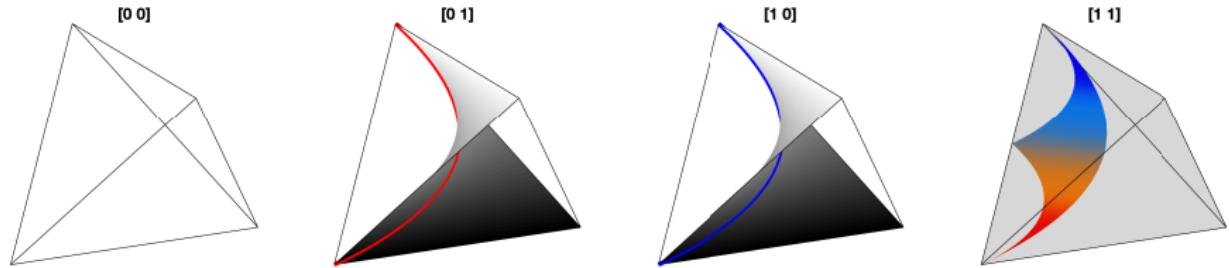
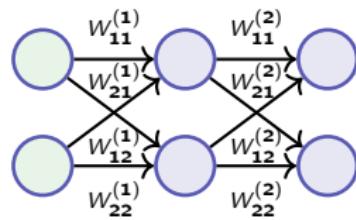
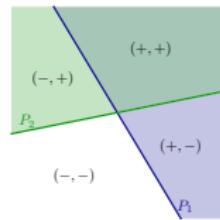
Implicit ideal:  $I = \langle p_1 p_4 - p_2 p_3, p_1 + p_2 + p_3 + p_4 - 1 \rangle$ .



The generators of the ideal  $I$  are called *model invariants*.

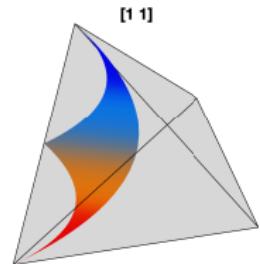
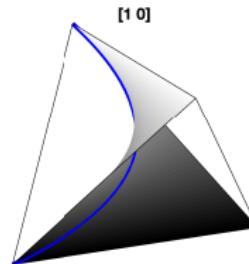
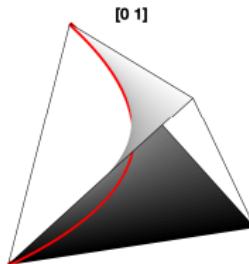
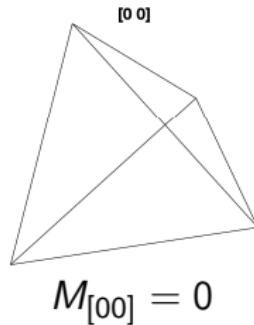
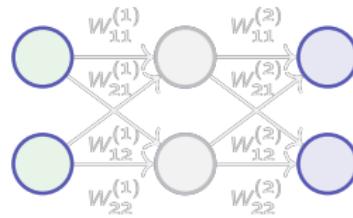
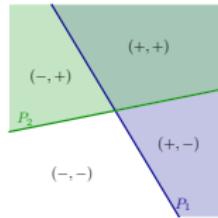
# Parametrization

- The number of linear pieces over the input space can be enormous.
- The linear pieces share parameters and are **not independent**.
- We investigate the relationships between the linear pieces.



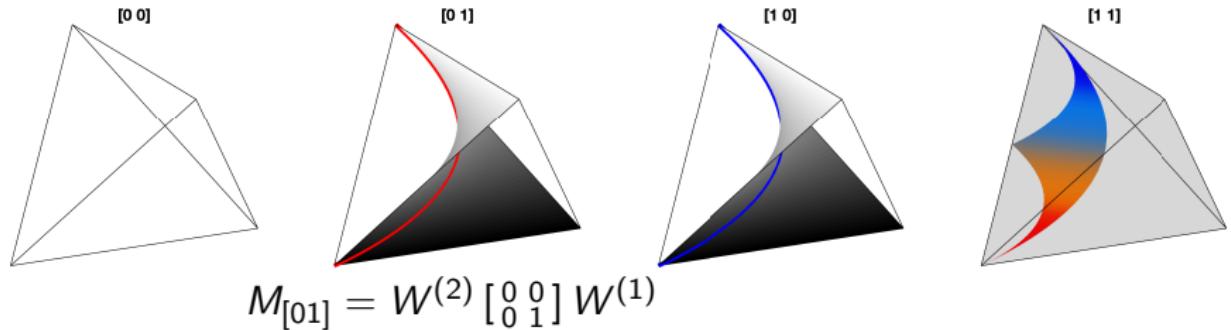
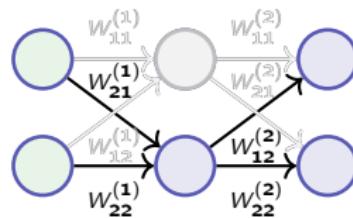
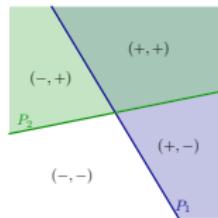
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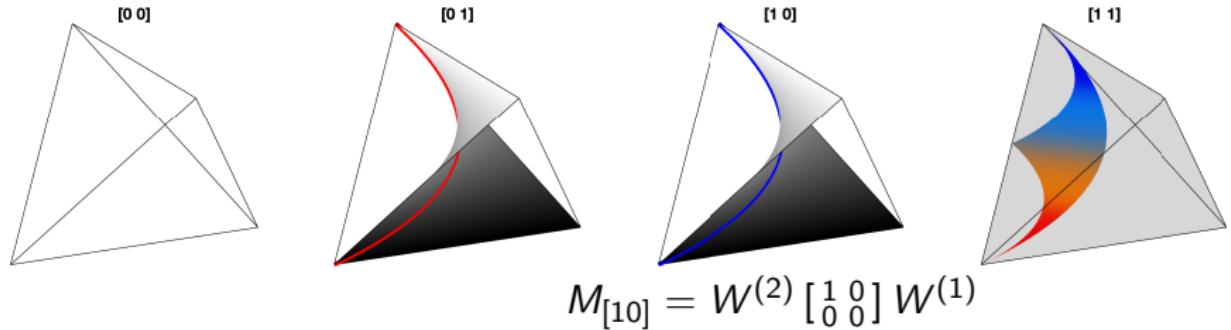
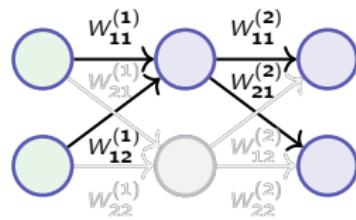
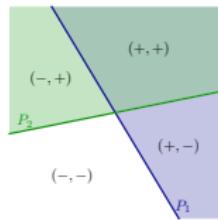
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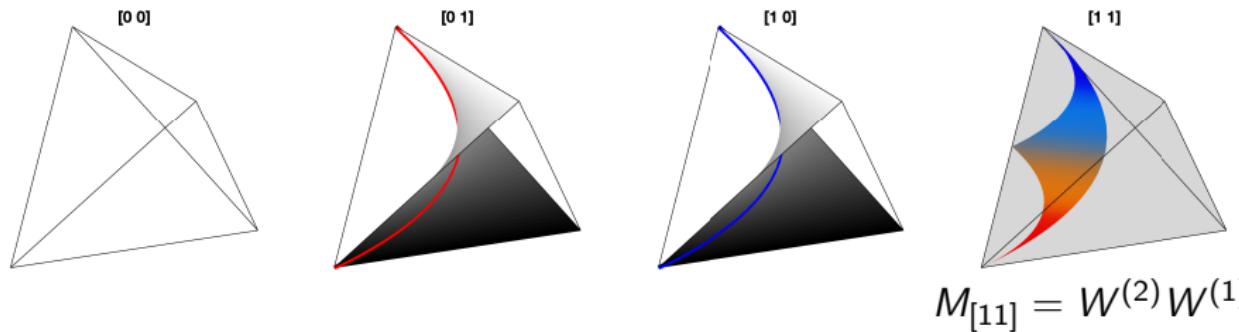
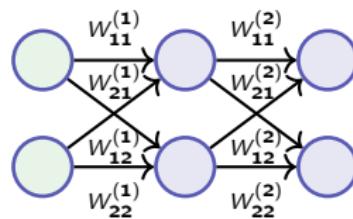
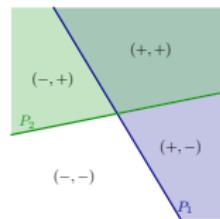
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## Mathematical setup

**Question:** What constraints do the outputs of a ReLU network satisfy?

- Let  $X = [x_1, \dots, x_m]$  define the activation region  $A = [a_1, \dots, a_m]$ .
- Split  $X$  into blocks  $[X_1, \dots, X_k]$  such where  $X_i$  contains data points that follow the same activation pattern.
- Consider the parametrization  $\varphi_X^A : \mathbb{R}^p \rightarrow \mathbb{R}^{n_L \times m} : \theta \mapsto F_X^A(\theta)$ .
- Within each block, this parametrization can be written  $\theta \mapsto M_i(\theta)X_i$ , where  $M(\theta)$  is a matrix dependent on the activation pattern and  $\theta$ .
- So, over all blocks, the parametrization is

$$\boxed{\varphi_X^A : \theta \mapsto [M_1(\theta)X_1 \mid M_2(\theta)X_2 \mid \cdots \mid M_k(\theta)X_k].}$$

Define the *ReLU output variety* as  $\overline{\text{im}(\varphi_X^A)}$ . Denote it by  $V_X^A$ .

**Question:** What are the generators of  $I_X^A := I(V_X^A)$ ? Dimension? Degree?

## Single block

When all data points in  $X$  follow the same activation pattern  $A$ , the map is

$$\varphi_X^A : \theta \mapsto M(\theta)X.$$

### Example

Let  $n_0 = n_1 = n_2 = 2$  and let  $A = [1, 0]$ . Then for any  $X \in \mathbb{R}^{2 \times m}$ ,

$$\varphi_X^A : (W^{(1)}, W^{(2)}) \mapsto M(\theta)X = \begin{pmatrix} w_{11}^{(1)}w_{11}^{(2)} & w_{12}^{(1)}w_{11}^{(2)} \\ w_{11}^{(1)}w_{21}^{(2)} & w_{12}^{(1)}w_{21}^{(2)} \end{pmatrix} [x_1 \dots x_m].$$

The polynomials defining the image are:

- ① one quadratic polynomial induced by  $\det M$
- ② linear polynomials induced by linear dependencies of  $X$ .

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# Single block

Let  $r = \text{rank } M(\theta)$  for generic  $\theta$ .

## Proposition (A.-Montúfar, 2025+)

The ideal  $I_X^A$  is generated by  $n_L \cdot \min\{m - n_0, 0\}$  linear polynomials and  $\binom{n_L}{r+1} \binom{\min\{n_0, m\}}{r+1}$  homogeneous polynomials of degree  $r + 1$ .

- linear polynomials  $\rightarrow$  linear dependencies between data points in  $X$
- degree  $r + 1$  polynomials  $\rightarrow$  certain minors of  $MX$ , which do not depend on the dataset  $X$

# The pattern variety

We consider the parametrization

$$\varphi^A : \theta \mapsto [M_1(\theta) \mid M_2(\theta) \mid \cdots \mid M_k(\theta)].$$

Define the *ReLU pattern variety* to be  $\overline{\text{im}(\varphi^A)}$ .

For each  $i \in [k]$ , we assume that:

- $|X_i| = n_0$ ,
- all points in  $X_i$  follow the same activation pattern,
- all points in  $X_i$  are linearly independent.

## Proposition (A.-Montúfar, 2025+)

Any polynomial  $f \in J^A$  gives rise to a unique polynomial  $g = \psi^{-1}f \in I_X^A$ , where  $\psi$  is a linear change of coordinates dependent on  $X$ .

So, we can study the ideal  $J^A$  of the pattern variety instead!

## Example: 2 blocks

Consider a general dataset  $X = [x_1, x_2, x_3, x_4]$ .

- $X_1 = [x_1, x_2]$  follow the pattern  $(1, 0)$ .
- $X_2 = [x_3, x_4]$  follow the pattern  $(1, 1)$ .

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ReLU output variety:  $\theta \mapsto [M_1(\theta)X_1 \mid M_2(\theta)X_2]$  with  $\theta = (W^{(1)}, W^{(2)})$

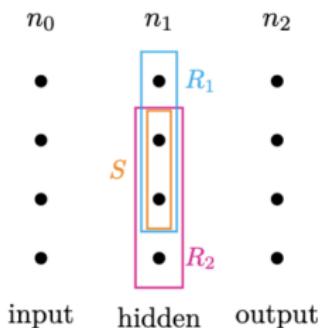
$$M_1(\theta) = \begin{pmatrix} w_{11}^{(1)}w_{11}^{(2)} & w_{12}^{(1)}w_{11}^{(2)} \\ w_{11}^{(1)}w_{21}^{(2)} & w_{12}^{(1)}w_{21}^{(2)} \end{pmatrix}, M_2(\theta) = \begin{pmatrix} w_{11}^{(1)}w_{11}^{(2)} + w_{21}^{(1)}w_{12}^{(2)} & w_{12}^{(1)}w_{11}^{(2)} + w_{22}^{(1)}w_{12}^{(2)} \\ w_{11}^{(1)}w_{21}^{(2)} + w_{21}^{(1)}w_{22}^{(2)} & w_{12}^{(1)}w_{21}^{(2)} + w_{22}^{(1)}w_{22}^{(2)} \end{pmatrix}.$$

ReLU pattern variety:  $\theta \mapsto [M_1(\theta) \mid M_2(\theta)] = (\frac{m_1}{m_2} \frac{m_3}{m_4} \frac{m_5}{m_6} \frac{m_7}{m_8})$

$$J^A = \langle \det \left( \begin{smallmatrix} m_1 & m_3 \\ m_2 & m_4 \end{smallmatrix} \right) \rangle, \quad \det \left( \begin{smallmatrix} m_1 - m_5 & m_3 - m_7 \\ m_2 - m_6 & m_4 - m_8 \end{smallmatrix} \right) \rangle.$$

The ideal  $I_X^A$  is obtained from  $J^A$  in terms of fixed but arbitrary data  $X_1, X_2$ .

## Two blocks, shallow networks



Let  $|R_1| = r_1$ ,  $|R_2| = r_2$ ,  $|S| = s$ .  
Let  $t = r_1 + r_2 - 2s$ .

### Theorem (A.-Montúfar, 2025+)

The ideal  $J^A$  contains:

- ①  $(r_1 + 1)$ -minors of  $M_1$ ;
- ②  $(r_2 + 1)$ -minors of  $M_2$ ;
- ③  $(n_1 + 1)$ -minors of  $[M_1 \mid M_2]$  and  $[M_1^T \mid M_2^T]$ ;
- ④  $(t + 1)$ -minors of  $M_1 - M_2$ .

**Conjecture:** no other polynomials are needed to generate the ideal.

# Sufficiency

Consider the map

$$\mathcal{M}_a \times \mathcal{M}_b \times \mathcal{M}_c \rightarrow \mathbb{R}^{n_2 \times 2n_0} : (A, B, C) \mapsto [M_1 = A + C | M_2 = B + C]$$

where  $\mathcal{M}_r = \{X \in \mathbb{R}^{n_2 \times n_0} : \text{rank}(X) \leq r\}$ .

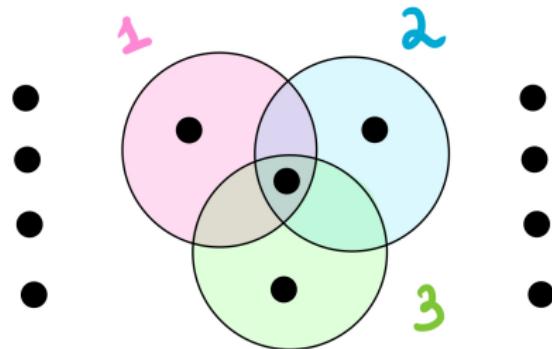
**Question:** Given two matrices  $M_1, M_2 \in \mathbb{R}^{n_2 \times n_0}$  satisfying:

- ①  $\text{rank } M_1 \leq a + c$ ;
- ②  $\text{rank } M_2 \leq b + c$ ;
- ③  $\text{rank}[M_1 | M_2]$  and  $\text{rank}[M_1^T | M_2^T] \leq a + b + c$ ;
- ④  $\text{rank}(M_1 - M_2) \leq a + b$ ,

can we find  $A, B, C$  such that:

- $M_1 = A + C$  and  $M_2 = B + C$ ;
- $\text{rank } A \leq a, \text{ rank } B \leq b, \text{ rank } C \leq c$ ?

## Example: 3 blocks



- 48 cubics: 3-minors of  $M_1$ ,  $M_2$ , and  $M_3$ ;
- 48 cubics: 3-minors of  $M_1 - M_2$ ,  $M_2 - M_3$ , and  $M_2 - M_3$ ;
- 120 quartics: 4-minors of  $[M_i \mid M_j]$  and  $[M_i^T \mid M_j^T]$ ;
- 40 quartics: 4-minors of  $[M_1 - M_2 \mid M_2 - M_3]$  and  $\begin{bmatrix} M_1 - M_2 \\ M_2 - M_3 \end{bmatrix}$ ;
- 2000 quintics: algebraically independent 5-minors of  $\begin{bmatrix} M_1 & M_2 \\ M_3 & M_2 \end{bmatrix}$ ,  $\begin{bmatrix} M_1 & M_2 \\ M_3 & M_3 \end{bmatrix}$ ,  $\begin{bmatrix} M_2 & M_3 \\ M_1 & M_1 \end{bmatrix}$ ,  $\begin{bmatrix} M_2 & M_3 \\ M_1 & M_3 \end{bmatrix}$ ,  $\begin{bmatrix} M_3 & M_1 \\ M_2 & M_2 \end{bmatrix}$ ,  $\begin{bmatrix} M_3 & M_1 \\ M_2 & M_1 \end{bmatrix}$ .

# Many blocks, shallow networks

## Linear combinations:

- Each  $M_i(\theta) = W^{(2)} \text{diag}(A_i) W^{(1)}$  is a sum of rank-one matrices.
- For  $\lambda \in \mathbb{Z}^k$ ,

$$\text{rank} \left( \sum_i \lambda_i M_i(\theta) \right) \leq \left| \text{supp} \left( \sum_i \lambda_i A_i \right) \right|.$$

- Polynomial constraints from minors:

$$(|\text{supp}(\sum_i \lambda_i A_i)| + 1)\text{-minors} \in J^A.$$

**Question:** Which  $\lambda$  give rise to minimal generators?

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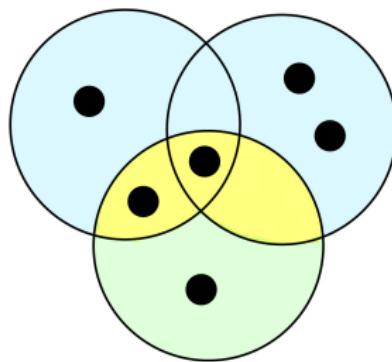
Blocks of linear combinations...

## Shallow networks, dimension

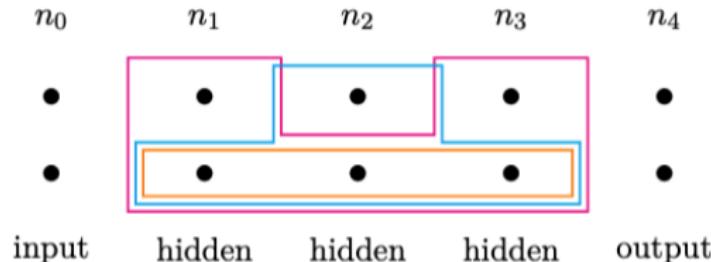
**Two blocks:** If  $n_0 \geq n_1 \leq n_2$  then the ideal  $J^A$  has the expected dimension, namely

$$\dim(\mathcal{M}_a) + \dim(\mathcal{M}_b) + \dim(\mathcal{M}_c).$$

**Many blocks:** If  $n_0 \geq n_1 \leq n_2$  then the ideal  $J^A$  has the expected dimension.



## Two blocks, deep networks



$$\begin{aligned}R_1 &= \{(1, 2, 1), (2, 2, 1), \\&\quad (1, 2, 2), (2, 2, 2)\} \\R_2 &= \{(2, 1, 2), (2, 2, 2)\} \\S &= \{(2, 2, 2)\}\end{aligned}$$

The *path network* determined by  $R_1 \setminus S$  has rank 2, even though all three paths pass through the same neuron in the middle layer. Let

- $r_a$  = rank of the path network on  $R_1 \setminus S$ ;
- $r_b$  = rank of the path network on  $R_2 \setminus S$ ;
- $r_c$  = rank of the fully connected network on  $S$ .

Let  $t = r_a + r_b$ .

# Deep networks

Two blocks:

Theorem (A.-Montúfar, 2025+)

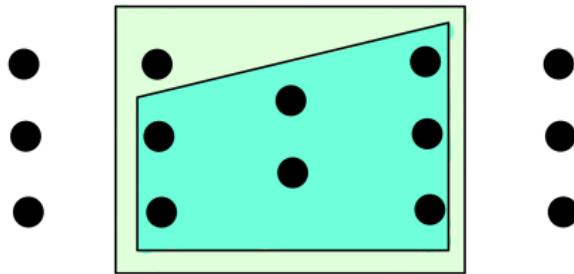
The ideal  $J^A$  contains:

1.  $(r_1 + 1)$ -minors of  $M_1$ ;
2.  $(r_2 + 1)$ -minors of  $M_2$ ;
- 3a.  $(n_{\min} + 1)$ -minors of  $[M_1 \mid M_2]$  if  $A_1^\ell = A_2^\ell$  for all  $\ell > \ell_{\min}$ .
- 3b.  $(n_{\min} + 1)$ -minors of  $[M_1^T \mid M_2^T]$  if  $A_1^\ell = A_2^\ell$  for all  $\ell < \ell_{\min}$ .
4.  $(t + 1)$ -minors of  $M_1 - M_2$ .

Many blocks: Similar to shallow networks, except:

- have to consider rank-1 matrices determined by *paths*;
- get looser rank bounds.

## Example: 2 blocks, deep network



$J^A$  is generated by:

- 9 quadratics: 2-minors of  $M_1 - M_2$ ;
- 10 cubics:  $3 \times 3$  minors of  $[M_1 \mid M_2]$ .

Thank you!

## Questions?

