```
In [1]:  #Import necessary programs
   import os
   import pandas as pd
   import numpy as np
   import math
   import matplotlib.pyplot as plt

   import json
   import csv

   import os,glob
   import statsmodels.api as sm
```

The data that is used in this model is from the free data source provided by StatsBomb



```
In [2]: #Read through all json files in folder and combine them
myList = []
folder_path = r'C:\Users\Yuma\Desktop\Sport Analytics\StatsBomb Data\open-dat
for filename in glob.glob(os.path.join(folder_path,'*.json')):
    with open(filename,'r',encoding='utf-8') as f:
        myList += json.load(f)
print(len(myList))
```

1904058

12826

In [4]: print(shot_data[162])

{'id': '423171d3-ff73-400c-9ff6-669ccf35f2ac', 'index': 2507, 'period': 2, 'timestamp': '00:16:49.931', 'minute': 61, 'second': 49, 'type': {'id': 16, 'name': 'Shot'}, 'possession': 127, 'possession_team': {'id': 217, 'name': 'Barcelona'}, 'play_pattern': {'id': 4, 'name': 'From Throw In'}, 'team': {'id': 217, 'name': 'Barcelona'}, 'player': {'id': 5246, 'name': 'Luis Albe rto Suárez Díaz'}, 'position': {'id': 23, 'name': 'Center Forward'}, 'locat ion': [115.7, 39.3], 'duration': 1.335006, 'related events': ['28820abd-b16 0-4729-b2f0-cf7bde32b8c0'], 'shot': {'open_goal': True, 'statsbomb_xg': 0.6 45913, 'end_location': [118.8, 39.7], 'first_time': True, 'outcome': {'id': 101, 'name': 'Wayward'}, 'type': {'id': 87, 'name': 'Open Play'}, 'body_par t': {'id': 37, 'name': 'Head'}, 'technique': {'id': 95, 'name': 'Volley'}, 'freeze_frame': [{'location': [105.0, 40.9], 'player': {'id': 6396, 'name': 'Beñat Etxebarria Urkiaga'}, 'position': {'id': 15, 'name': 'Left Center Mi dfield'}, 'teammate': False}, {'location': [103.6, 36.0], 'player': {'id': 6775, 'name': 'Daniel García Carrillo'}, 'position': {'id': 13, 'name': 'Ri ght Center Midfield'}, 'teammate': False}, {'location': [110.0, 51.0], 'pla yer': {'id': 3023, 'name': 'Yuri Berchiche Izeta'}, 'position': {'id': 21, 'name': 'Left Wing'}, 'teammate': False}, {'location': [108.3, 55.1], 'play er': {'id': 6789, 'name': 'Mikel Balenziaga Oruesagasti'}, 'position': {'i d': 6, 'name': 'Left Back'}, 'teammate': False}, {'location': [107.0, 26. 0], 'player': {'id': 6390, 'name': 'Markel Susaeta Laskurain'}, 'position': {'id': 17, 'name': 'Right Wing'}, 'teammate': False}, {'location': [119.6, 36.3], 'player': {'id': 11748, 'name': 'Unai Simón Mendibil'}, 'position': {'id': 1, 'name': 'Goalkeeper'}, 'teammate': False}, {'location': [114.3, 4 0.1], 'player': {'id': 11744, 'name': 'Peru Nolaskoain Esnal'}, 'position': {'id': 5, 'name': 'Left Center Back'}, 'teammate': False}, {'location': [11 2.2, 32.1], 'player': {'id': 6877, 'name': 'Yeray Álvarez López'}, 'positio n': {'id': 3, 'name': 'Right Center Back'}, 'teammate': False}, {'locatio n': [113.8, 30.8], 'player': {'id': 6649, 'name': 'Óscar de Marcos Arana'}, 'position': {'id': 2, 'name': 'Right Back'}, 'teammate': False}, {'locatio n': [94.7, 32.9], 'player': {'id': 5470, 'name': 'Ivan Rakitić'}, 'positio n': {'id': 15, 'name': 'Left Center Midfield'}, 'teammate': True}, {'locati on': [106.6, 34.6], 'player': {'id': 5503, 'name': 'Lionel Andrés Messi Cuc cittini'}, 'position': {'id': 13, 'name': 'Right Center Midfield'}, 'teamma te': True}, {'location': [107.4, 60.2], 'player': {'id': 5477, 'name': 'Ous mane Dembélé'}, 'position': {'id': 17, 'name': 'Right Wing'}, 'teammate': T rue}, {'location': [115.3, 49.2], 'player': {'id': 6374, 'name': 'Nélson Ca bral Semedo'}, 'position': {'id': 2, 'name': 'Right Back'}, 'teammate': Tru e}, {'location': [112.1, 37.3], 'player': {'id': 5213, 'name': 'Gerard Piqu é Bernabéu'}, 'position': {'id': 3, 'name': 'Right Center Back'}, 'teammat e': True}, {'location': [115.0, 28.5], 'player': {'id': 3501, 'name': 'Phil ippe Coutinho Correia'}, 'position': {'id': 21, 'name': 'Left Wing'}, 'team mate': True}, {'location': [95.4, 20.6], 'player': {'id': 5211, 'name': 'Jo rdi Alba Ramos'}, 'position': {'id': 6, 'name': 'Left Back'}, 'teammate': T rue}]}}

```
In [5]:
            #Display elements of shot data
            for i in range(len(shot data)):
                print(shot_data[i]['shot']['statsbomb_xg'])
            0.35517353
            0.2932451
            0.074154906
            0.05818526
            0.017370177
            0.092796184
            0.645913
            0.043115344
            0.025119951
            0.062046476
            0.12498811
            0.044921484
            0.032342415
            0.110647604
            0.09387077
            0.03721017
            0.020380031
            0.46143624
            0.41998687
In [6]:
            new_shot_data = []
        for i in range(len(shot_data)):
                #Get rid of PK shots because we already know PKs have a 0.76 xG
                if 'statsbomb xg' in shot data[i]['shot']:
                     if not (shot_data[i]['shot'].get('statsbomb_xg') == 0.76):
                         Dict = dict({'id': shot_data[i]['id'], 'play_pattern': shot_data[
                                  shot_data[i]['location'], 'statsbomb_xg': shot_data[i][
                                  shot_data[i]['shot']['end_location'], 'body_part': shot_
                                  'technique': shot_data[i]['shot']['technique']['name'],
                                  shot_data[i]['shot']['outcome']['name'], 'under_pressure
                         if 'under pressure' in shot data[i].keys():
                             Dict.update(under_pressure = shot_data[i]['under_pressure'])
                         if 'first time' in shot data[i]['shot'].keys():
                             Dict.update(first_time = shot_data[i]['shot']['first_time'])
                         new_shot_data.append(Dict)
            print(len(new shot data))
            12610
```

```
In [7]:  print(new_shot_data[174])
```

```
{'id': 'ceec9e87-df47-4b25-a784-3b4b41606599', 'play_pattern': 'From Corne
r', 'location': [119.1, 42.6], 'statsbomb_xg': 0.90241957, 'end_location':
[120.0, 42.9, 0.1], 'body_part': 'Right Foot', 'technique': 'Normal', 'outc
ome': 'Goal', 'under_pressure': False, 'first_time': True}
```

```
In [8]:
          print(new_shot_data[i]['location'])
             #print(new_shot_data[130]['location'])
             [111.7, 51.7]
             [114.0, 27.0]
             [92.0, 34.5]
             [109.1, 38.7]
             [107.0, 25.0]
             [108.1, 27.4]
             [112.0, 43.7]
             [97.0, 54.0]
             [112.3, 41.4]
             [102.5, 29.2]
             [109.3, 29.7]
             [106.5, 33.5]
             [116.9, 31.2]
             [106.0, 23.0]
             [111.1, 24.1]
             [94.4, 24.5]
             [107.4, 25.9]
             [100.1, 58.1]
             [100.2, 27.7]
 In [9]:
         print(new_shot_data[0]['location'])
             [111.7, 51.7]
In [10]:
            #Calculate 'distance' data from 'location' data
             distance = []
             goal = [120,40]
             for i in range(len(new shot data)):
                 point = new_shot_data[i]['location']
                 calculation = math.sqrt(((point[0]-goal[0])**2) + ((point[1]-goal[1])**2)
                 distance.append(calculation)
             print(distance[10000])
```

11.36353818139403

[54.64804531609818, 65.22485943116808, 11.113040535948294, 6.80131482398 1564, 49.08561677997488, 46.63657704161671, 24.820541335489118, 31.32869 2867804165, 10.304846468766009, 31.680513712958646, 43.9087837747374, 2 5.709953780811272, 70.59402924599885, 50.527540151656176, 60.76214776397 254, 31.193595102442714, 48.21548399174822, 42.28801653255506, 31.849051 31905529, 12.045632385265794, 27.057552910841316, 5.111893990013171, 42. 247514599731296, 44.56263613247929, 53.44036527550666, 30.8505239136548 1, 23.694216382171234, 34.01934998982646, 86.47854662307778, 50.16224027 094536, 19.430335187247493, 22.048829574925662, 14.406685156436867, 50.8 5601358542897, 29.97289058597137, 49.236394799058836, 4.43266846868991, 51.556946498163384, 57.79587107933758, 49.67416371113079, 23.67863263321 3386, 9.090276920822351, 25.324181401947186, 41.84515713520801, 24.11101 950255092, 36.86989764584398, 41.05481377096251, 50.84892164592895, 14.9 54646765153033, 47.617413363264426, 29.054604099077164, 9.86580694308436 5, 0.9669255716442647, 75.84658741214857, 36.006207601244455, 10.6387666 09506805, 12.587693381648801, 61.76808174133644, 74.19748604606447, 67.5 4306100005792, 39.50767544287257, 34.33021719550333, 58.53049310232291, 7.507346666949624, 75.37912601136831, 12.787972654802287, 45.75716886505 853, 58.33924890336339, 59.52014901853704, 31.60750224624893, 20.7990284

```
In [12]:
         #Create a different json for the linear regression model
             # 0 means false, 1 meeans true
             new shot data 2 = []
             for i in range(len(new shot data)):
                 Dict_2 = dict({'id': new_shot_data[i]['id'] , 'location': new_shot_data[i]
                                 'angle': angle[i], 'isFoot': 0, 'isHead': 0, 'isVolley': (
                                 'isCorner': 0, 'isRegularPlay': 0, 'isFreeKick': 0, 'isThr
                                 'fromGK': 0, 'first time': 0, 'under pressure': 0, 'isGoal
                                 'statsbomb xg': new shot data[i]['statsbomb xg']})
                 if new shot data[i]['body part'] == 'Right Foot':
                     Dict 2.update(isFoot = 1)
                 elif new_shot_data[i]['body_part'] == 'Left Foot':
                     Dict 2.update(isFoot = 1)
                 else:
                     Dict_2.update(isFoot = 0)
                 if new_shot_data[i]['body_part'] == 'Head':
                     Dict 2.update(isHead = 1)
                 else:
                     Dict 2.update(isHead = 0)
                 if new shot data[i]['technique'] == 'Half Volley':
                     Dict 2.update(isVolley = 1)
                 elif new shot data[i]['technique'] == 'Volley':
                     Dict 2.update(isVolley = 1)
                 else:
                     Dict 2.update(isVolley = 0)
                 if new shot data[i]['technique'] == 'Normal':
                     Dict 2.update(isNormalShot = 1)
                 else:
                     Dict 2.update(isNormalShot = 0)
                 if new_shot_data[i]['technique'] == 'Lob':
                     Dict 2.update(isLobShot = 1)
                 else:
                     Dict 2.update(isLobShot = 0)
                 if new_shot_data[i]['play_pattern'] == 'From Corner':
                     Dict_2.update(isCorner = 1)
                 else:
                     Dict 2.update(isCorner = 0)
                 if new shot data[i]['play pattern'] == 'Regular Play':
                     Dict 2.update(isRegularPlay = 1)
                 if new_shot_data[i]['play_pattern'] == 'From Free Kick':
                     Dict 2.update(isFreeKick = 1)
                 else:
                     Dict 2.update(isFreeKick = 0)
                 if new_shot_data[i]['play_pattern'] == 'From Throw In':
                     Dict 2.update(isThrowIn = 1)
                 else:
                     Dict_2.update(isThrowIn = 0)
```

```
if new_shot_data[i]['play_pattern'] == 'From Counter':
                     Dict 2.update(isCounter = 1)
                 else:
                     Dict 2.update(isCounter = 0)
                 if new shot data[i]['play pattern'] == 'From Keeper':
                     Dict 2.update(fromKeeper = 1)
                 else:
                     Dict 2.update(fromKeeper = 0)
                 if new_shot_data[i]['play_pattern'] == 'From Goal Kick':
                     Dict 2.update(fromGK = 1)
                 else:
                     Dict 2.update(fromGK = 0)
                 if new shot data[i]['under pressure'] == True:
                     Dict_2.update(under_pressure = 1)
                 else:
                     Dict 2.update(under pressure = 0)
                 if new shot data[i]['first time'] == True:
                     Dict 2.update(first time = 1)
                 else:
                     Dict_2.update(first_time = 0)
                 if new shot data[i]['outcome'] == 'Goal':
                     Dict 2.update(isGoal = 1)
                 else:
                     Dict 2.update(isGoal = 0)
                 new shot data 2.append(Dict 2)
             print(new shot data 2[10000])
             {'id': 'dbf2d5a1-1817-4fb4-8a79-381e9de3bac0', 'location': [108.7, 38.8],
             'distance': 11.36353818139403, 'angle': 6.061788788728689, 'isFoot': 1, 'is
             Head': 0, 'isVolley': 0, 'isNormalShot': 1, 'isLobShot': 0, 'isCorner': 0,
             'isRegularPlay': 0, 'isFreeKick': 0, 'isThrowIn': 1, 'isCounter': 0, 'fromK
             eeper': 0, 'fromGK': 0, 'first time': 0, 'under pressure': 1, 'isGoal': 0,
             'statsbomb_xg': 0.14499828}
In [13]:
          #Save data as a csv file so we don't have to parse through original data over
             headers = ['id', 'location', 'distance', 'angle', 'isFoot', 'isHead', 'isVol]
                         'isRegularPlay', 'isFreeKick', 'isThrowIn', 'isCounter', 'fromKeer
                        'isGoal', 'statsbomb xg']
             filename = "shot_data.csv"
             with open(filename, 'w') as csvfile:
                 writer = csv.DictWriter(csvfile, fieldnames = headers)
                 writer.writeheader()
                 writer.writerows(new shot data 2)
```

```
#Read json through pandas dataframe
In [14]:
              df = pd.DataFrame(new_shot_data_2, columns=['id','location','distance', 'ang]
                                                               'isLobShot', 'isCorner','isRegula
                                                              'fromKeeper', 'fromGK', 'first tin
              print(df)
                                                           id
                                                                    location
                                                                                distance
              0
                      65f16e50-7c5d-4293-b2fc-d20887a772f9
                                                               [111.7, 51.7]
                                                                               14.345034
                                                               [114.0, 27.0]
              1
                      b0f73423-3990-45ae-9dda-3512c2d1aff3
                                                                               14.317821
              2
                      13b1ddab-d22e-43d9-bfe4-12632fea1a27
                                                                [92.0, 34.5]
                                                                               28.535066
              3
                      391bfb74-07a6-4afe-9568-02a9b23f5bd4
                                                               [109.1, 38.7]
                                                                               10.977249
              4
                      5e55f5a5-954f-4cc4-ba6e-a9cf6d6e249e
                                                               [107.0, 25.0]
                                                                               19.849433
              . . .
                                                               [100.5, 39.8]
                      c0090be3-7f39-4653-b535-dbaa01b5639a
              12605
                                                                               19.501026
              12606
                     786c2e5c-7a14-407c-81cb-16bf3e4ec34b
                                                                [91.8, 53.6]
                                                                               31.308146
              12607
                      31b998c0-f889-43ee-a215-0f1e1273c76b
                                                               [103.1, 47.2]
                                                                               18.369812
              12608
                      a586c569-474f-4c70-a7de-0364824de189
                                                               [104.8, 51.7]
                                                                               19.181502
              12609
                      b642d77d-582e-4ebb-849e-44202b65df1a
                                                               [106.9, 60.1]
                                                                               23.992082
                                          isHead
                                                   isVolley
                                                              isNormalShot isLobShot isCorn
              er
              0
                      54.648045
                                       1
                                                0
                                                           1
                                                                          0
                                                                                      0
              0
              1
                      65.224859
                                       1
                                                                                      0
                                                           1
              0
              2
                                                           0
                                                                          1
                                                                                      0
                      11.113041
                                       1
              0
              3
                                                                                      0
                       6.801315
                                                1
                                                           0
                                                                          1
              0
              4
                      49.085617
                                       1
                                                           0
                                                                          1
                                                                                      0
              1
              . . .
              . . .
                                                                                      0
              12605
                       0.587628
                                       1
                                                0
                                                           1
                                                                          a
              1
              12606
                      25.746596
                                       1
                                                           0
                                                                          1
                                                                                      0
              1
              12607
                                                                          1
                                                                                      0
                      23.075726
                                       1
              0
              12608
                     37.586804
                                       1
                                                           0
                                                                          1
                                                                                      0
              0
              12609
                     56.906052
                                       1
                                                           1
                                                                                      0
                      isRegularPlay
                                      isFreeKick isThrowIn isCounter
                                                                          fromKeeper
                                                                                        fromGK
                                                                                     0
              0
                                   1
                                                0
                                                            0
                                                                        0
                                                                                             0
              1
                                   1
                                                0
                                                            0
                                                                        0
                                                                                     0
                                                                                             0
              2
                                                                                     1
                                                                                             0
              3
                                   1
                                                0
                                                            0
                                                                        0
                                                                                     0
                                                                                             0
              4
                                                            0
                                                                                     0
                                                                                             0
                                   0
                                                a
                                                                        0
              12605
                                   0
                                                0
                                                            0
                                                                        0
                                                                                     0
                                                                                             0
              12606
                                                0
                                                            0
                                                                        0
                                                                                     0
                                                                                             0
                                   0
```

12608		1 0		0 0	0	0
12609		0 1		0 0	0	0
	first_time	under_pressure	isGoal	statsbomb_xg		
0	1	0	0	0.095480		
1	1	0	0	0.047924		
2	0	0	0	0.018477		
3	0	1	0	0.137954		
4	0	0	0	0.036229		
	• • •	• • •		• • •		
12605	1	0	0	0.038873		
12606	0	1	0	0.017531		
12607	1	0	0	0.079473		
12608	0	0	0	0.145874		
12609	0	0	0	0.020496		

```
In [15]: #Eliminate duplicate data
df.drop_duplicates(subset = 'id', keep = False, inplace = True)
print(len(df))
```

12610

```
In [16]: M print(df[['isFoot', 'isVolley']])
```

	isFoot	isVolley
0	1	1
1	1	1
2	1	0
3	0	0
4	1	0
• • •		• • •
12605	1	1
12606	1	0
12607	1	0
12608	1	0
12609	1	1

[12610 rows x 20 columns]

[12610 rows x 2 columns]

```
In [17]:
            #Logistic Regression Calculation
            #Got rid of 'isNormalShot', 'isCounter', 'fromKeeper', 'fromGK' because the p
            x = df[['distance', 'angle', 'isHead', 'isVolley', 'isLobShot', 'isNormalShot
                    'under pressure', 'first time']]
            y = df['isGoal']
            model = sm.Logit(y,x).fit()
            predictions = model.predict(x)
            print(model.summary2())
            Optimization terminated successfully.
                    Current function value: 0.310837
                    Iterations 7
                                   Results: Logit
            ______
            Model:
                              Logit
                                              Pseudo R-squared: 0.163
            Dependent Variable: isGoal
                                              AIC:
                                                               7859.3028
                              2020-09-02 12:13 BIC:
                                                               7933.7252
            Date:
            No. Observations:
                              12610
                                              Log-Likelihood:
                                                               -3919.7
            Df Model:
                                              LL-Null:
                                                               -4682.0
                                              LLR p-value:
            Df Residuals:
                             12600
                                                               0.0000
            Converged:
                              1.0000
                                              Scale:
                                                               1.0000
            No. Iterations: 7.0000
                           Coef. Std.Err.
                                                   P > |z| [0.025 0.975]
```

The next two sets of code are taken from Peter McKeever's Expected Goals Model program. It can be found here: http://petermckeever.com/2019/01/building-an-expected-goals-model-in-python/)

0.0052 -31.4653 0.0000 -0.1742 -0.1538

0.0015 -8.7771 0.0000 -0.0158 -0.0100

0.1068 -12.7052 0.0000 -1.5665 -1.1478

Log Regression test set accuracy 0.889

-0.1640

-0.0129

-1.3571

distance

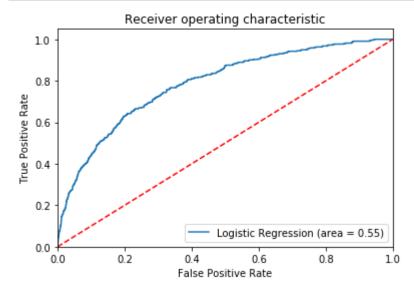
angle

isHead

C:\Users\Yuma\Anaconda3\lib\site-packages\sklearn\linear_model\logistic.py:
432: FutureWarning: Default solver will be changed to 'lbfgs' in 0.22. Spec
ify a solver to silence this warning.
FutureWarning)

The below program comes from Susan Li's article on "Building A Logistic Regression in Python, Step by Step" and can be found here: https://towardsdatascience.com/building-a-logistic-regression-in-python-step-by-step-becd4d56c9c8 (https://towardsdatascience.com/building-a-logistic-regression-in-python-step-by-step-becd4d56c9c8)

```
In [20]:
             #Draw a ROC curve to better understand our logistic regression model
             from sklearn.metrics import roc auc score
             from sklearn.metrics import roc curve
             logit roc auc = roc auc score(y test, log r.predict(x test))
             fpr, tpr, thresholds = roc_curve(y_test, log_r.predict_proba(x_test)[:,1])
             plt.figure()
             plt.plot(fpr, tpr, label='Logistic Regression (area = %0.2f)' % logit roc aud
             plt.plot([0, 1], [0, 1], 'r--')
             plt.xlim([0.0, 1.0])
             plt.ylim([0.0, 1.05])
             plt.xlabel('False Positive Rate')
             plt.ylabel('True Positive Rate')
             plt.title('Receiver operating characteristic')
             plt.legend(loc="lower right")
             plt.savefig('Log_ROC')
             plt.show()
```



```
In [21]:
             #Output of xG values
             xg_model = log_r.predict_proba(x)
             for i in range(len(xg_model)):
                 print(xg_model[i][1])
             0.06085157840353018
             0.06444000103209123
             0.29530300648422597
             0.10972257129266423
             0.06916560895578812
             0.07243000286101878
             0.13604853657170463
             0.0914299495383149
             0.10804098400383186
             0.22455177696200465
             0.0725760143905931
             0.42687777680821876
             0.051747318758124536
             0.1934598829008563
             0.14548176145360356
             0.07391687562182615
             0.15426284319756012
             0.32053178334575116
             0.014773122559248454
             0.03488243689810308
```

Below is where you can apply the expected goals model to new datasets.

```
In [22]:
             #Import dataset and calculate distance and angle
             test df = pd.read csv(r'C:\Users\Yuma\Desktop\Sport Analytics\xG Model Data.d
             distance = []
             goal = [120,40]
             for i in range(len(test df)):
                 point_x = test_df.loc[i]['x_location']
                 point_y = test_df.loc[i]['y_location']
                 calculation = math.sqrt((point_x-goal[0])**2) + ((point_y-goal[1])**2)
                 distance.append(calculation)
             angle = []
             pen_vect_pt = [12,0]
             for i in range(len(test df)):
                 shot_vector = [120-test_df.loc[i]['x_location'],abs(40-test_df.loc[i]['y]
                 unit vector 1 = pen vect pt / np.linalg.norm(pen vect pt)
                 unit_vector_2 = shot_vector / np.linalg.norm(shot_vector)
                 dot product = np.dot(unit vector 1, unit vector 2)
                 current_angle = math.degrees(np.arccos(dot_product))
                 angle.append(current angle)
             test df['distance'] = distance
             test_df['angle'] = angle
             print(test df)
                x location y location isHead isVolley isLobShot
                                                                     isNormalShot
             0
                     114.0
                                  40.0
                                             0
                isFreeKick isCorner
                                      under pressure first time distance
                                                                             angle
             0
                                   0
                                                   0
                                                                               0.0
                         0
                                                                        6.0
          M test_x = test_df[['distance', 'angle', 'isHead', 'isVolley', 'isLobShot', 'is
In [23]:
                      'under_pressure', 'first_time']]
             test_xG = log_r.predict_proba(test_x)
             print("The probability that the shot is a goal is: ")
             print(test xG[0][1])
             The probability that the shot is a goal is:
```

0.4285524750325052