

微算機系統實習

第 13 組專案報告

LAB 07

實作 Char Device Driver

組別： 13

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日期：2024.06.05

一、實驗內容：

1. lab 7-1

練習撰寫一個可掛載於系統的驅動模組

(1) 項目一：製作簡易驅動程式(30%)

分別在虛擬機和 TX2 上成功執行

需查看系統訊息

(2) 項目二：製作字元驅動程式(40%)

在虛擬機上製作字元驅動程式

需查看系統訊息

2. lab 7-2

練習撰寫一個可掛載於系統的字元驅動

用 C/C++設計另一個程式來控制掛載中的字元驅動

能利用字元驅動來控制 GPIO

使用 Linux Kernel 的檔案存取方式來處理 LED 控制

請編寫一個字元裝置(character device)驅動程式

使用 mknod 指令在/dev/下建立一個名為 demo 的 node

編寫字元驅動需使用 module_init 及 module_exit

模組須使用 Makefile 編譯

(1) 項目一：創建 file_operations 資料結構 (15%)

每個 function 需印出以下規定訊息

Open: Enter Open function

Release: Enter Release function

Read: Enter Read function

Write: Enter Write function

I/O Control: Enter I/O Control function

(2) 項目二：掛載與卸載驅動程式(15%)

初始(掛載)使用 register_chrdev function

離開(卸載)使用 unregister_chrdev function

(3) 項目三：控制裝置驅動 (20%)

必須能讀取命令參數，使指定的 LED 燈點亮或熄滅(on/off)

能分別點亮及熄滅 4 顆 LED 燈，此動作需於驅動程式中完成

Ex: ./Lab7 LED1 on (第一顆燈狀態為亮，其他 LED 狀態不變)

(4) 項目四：讀取裝置驅動狀態 (20%)

必須在終端機上顯示被點亮的燈號

Ex: ./Lab7 LED1 (讀取 LED1 點燈狀態)

顯示 "LED1 Status: 0" (Terminal 回傳 LED1 狀態為 0，表示未亮)

程式於 TX2 嵌入式平台上執行

二、實驗過程及結果：

1. 實驗過程

(1) lab 7-1

(a) 項目一

(i) hellod.c

```
1  #include <linux/kernel.h>
2  #include <linux/module.h>
3
4  static int __init tx2_hello_module_init(void){
5      printk("Hello, TX2 module is installed !\n");
6      return 0;
7  }
8
9  static void __exit tx2_hello_module_cleanup(void){
10     printk("Good-bye, TX2 module was removed!\n");
11 }
12
13 module_init(tx2_hello_module_init);
14 module_exit(tx2_hello_module_cleanup);
15 MODULE_LICENSE("GPL");
```

(ii) Makefile

```
1  obj-m := hellod.o
2
3  kernel_DIR := /usr/src/linux-headers-5.4.0-150-generic
4
5  PWD := $(shell pwd)
6
7  all:
8      make -C $(kernel_DIR) M=$(PWD)
9  clean:
10     rm *.o *.ko *.mod.c
11  .PHONY:
12     clean
```

其中 kernel_DIR 在虛擬機為

/usr/src/linux-headers-5.4.0-150-generic

在 TX2 則為

/usr/src/linux-headers-4.9.201-tegra-ubuntu18.04_aarch64/kernel-4.9/

(b) 項目二

(i) demo.c

實作讀寫等函數

```
1 static ssize_t drv_write(struct file *filp, const char *buf, size_t count, loff_t *ppos){
2     printk("device write\n");
3     printk("%d\n", iCount);
4     printk("W_buf_size: %d\n", (int)count);
5     raw_copy_from_user(userChar, buf, count);
6     userChar[count - 1] = 0;
7     printk("userChar: %s\n", userChar);
8     printk("userChar: %d\n", (int)sizeof(userChar));
9     iCount++;
10    return count;
11 }
12
```

```
1 long drv_ioctl(struct file *filp, unsigned int cmd, unsigned long arg){
2     printk("device ioctl\n");
3     return 0;
4 }
5
6 static int drv_open(struct inode *inode, struct file *filp){
7     printk("device open\n");
8     return 0;
9 }
10
11 static int drv_release(struct inode *inode, struct file *filp){
12     printk("device close\n");
13     return 0;
14 }
15
16 static ssize_t drv_read(struct file *filp, char *buf, size_t count, loff_t *ppos){
17     printk("device read\n");
18     return count;
19 }
```

```
1 struct file_operations drv_fops =
2 {
3     read: drv_read,
4     write: drv_write,
5     unlocked_ioctl: drv_ioctl,
6     open: drv_open,
7     release: drv_release,
8 };
```

實作初始化以及退出函數

```

1 static int demo_init(void){
2     if(register_chrdev(MAJOR_NUM, "demo", &drv_fops)<0){
3         printk("<1>%s: can't get major %d\n", MODULE_NAME, MAJOR_NUM);
4         return (-EBUSY);
5     }
6
7     printk("<1>%s: started\n", MODULE_NAME);
8     return 0;
9 }
10
11 static void demo_exit(void){
12     unregister_chrdev(MAJOR_NUM, "demo");
13     printk("<1>%s: removed\n", MODULE_NAME);
14 }

```

(ii) test.c

控制掛載好的 demo

```

1 #include <stdio.h>
2 int main(){
3     char buf[1024] = "Data Input 123456 hello world";
4     FILE *fp = fopen("/dev/demo", "w+");
5     if(fp == NULL){
6         printf("can't open device!\n");
7         return 0;
8     }
9     fwrite(buf, sizeof(buf), 1, fp);
10    fread(buf, sizeof(buf), 1, fp);
11    fclose(fp);
12    return 0;
13 }

```

(2) lab 7-2

(a) demo.c

實作讀寫函數

```
1 static int driver_open(struct inode *inode, struct file *filp) {
2     printk("Open: Enter Open function\n");
3     return 0;
4 }
5
6 static int driver_close(struct inode *inode, struct file *filp) {
7     printk("Release: Enter Release function\n");
8     return 0;
9 }
10
11 long driver_ioctl(struct file *filp, unsigned int cmd, unsigned long arg)
12 {
13     printk("I/O Control: Enter I/O Control function\n");
14     return 0;
15 }
16
17 static ssize_t driver_read(struct file *filp, char *buf, size_t size, loff_t *f_pos) {
18     printk("Read: Enter Release function\n");
19     return 0;
20 }
```

```
1 static ssize_t driver_write(struct file *filp, const char *buf, size_t size, loff_t *f_pos) {
2     printk("Write: Enter Write function\n");
3     if(copy_from_user(userChar, buf, size) == 0){
4         userChar[size - 1] = '\0';
5         int ledIndex;
6         int pin;
7
8         printk("%s\n", userChar);
9         if(userChar[0] == 'g') {
10             ledIndex = userChar[4] - '1';
11             printk("LED%d Status: %d\n", ledIndex + 1, ledBook[ledIndex]);
12         }
13         else if (userChar[1] == 'n') {
14             ledIndex = userChar[3] - '1';
15             pin = gpioPin[ledIndex];
16             gpio_set_value(pin, 1);
17             ledBook[ledIndex] = 1;
18         }
19         else if (userChar[1] == 'f') {
20             ledIndex = userChar[4] - '1';
21             pin = gpioPin[ledIndex];
22             gpio_set_value(pin, 0);
23             ledBook[ledIndex] = 0;
24         }
25         else {
26             printk("Error: command not found");
27         }
28     } else{
29         printk("Error: Write Error\n");
30     }
31     return size;
32 }
```

實作初始化及退出函數

```
1 static int demo_init(void) {
2     int result;
3     printk("<1>demo: started\n");
4
5     char* ledName[4] = { "LED1", "LED2", "LED3", "LED4" };
6     int i;
7     for (i = 0; i < 4; i++) {
8         if (gpio_is_valid(gpioPin[i]) == 0) {
9             printk("pin %d is no valid\n", gpioPin[i]);
10            return -EBUSY;
11        }
12
13        if (gpio_request(gpioPin[i], ledName[i]) < 0) {
14            printk("pin %d is busy\n", gpioPin[i]);
15            return -EBUSY;
16        }
17
18        gpio_direction_output(gpioPin[i], 0);
19        gpio_export(gpioPin[i], false);
20    }
21
22    result = register_chrdev(DRIVER_MAJOR, DRIVER_NAME, &driver_fops);
23    if (result < 0) {
24        printk("<1>demo: Failed to register character device\n");
25        return result;
26    }
27
28    return 0;
29 }
```

```
1 static void demo_exit(void) {
2     printk("<1>demo: removed\n");
3     int i;
4     for (i = 0; i < 4; i++) {
5         gpio_free(gpioPin[i]);
6     }
7
8     /* Unregister character device */
9     unregister_chrdev(DRIVER_MAJOR, DRIVER_NAME);
10 }
```



```
1 module_init(demo_init);
2 module_exit(demo_exit);
```

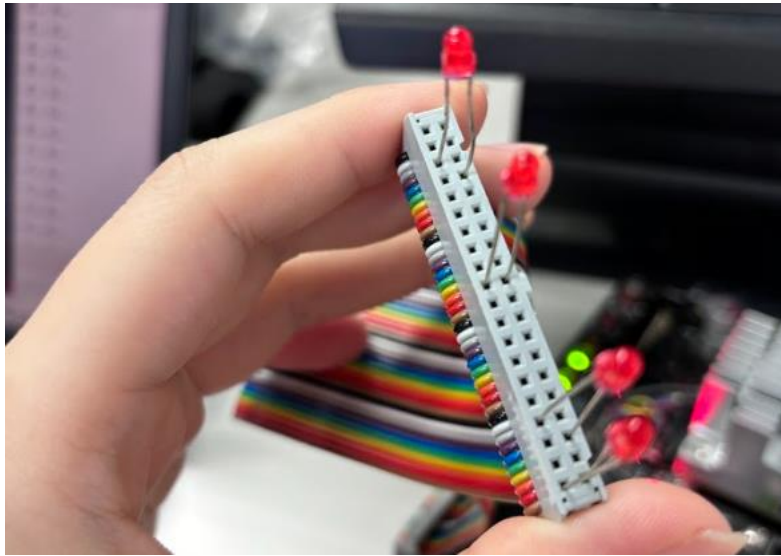
(b) led.cpp

控制 demo



```
1 #include <iostream>
2 #include <cstdio>
3
4 using namespace std;
5
6 int main(int argc, char *argv[]) {
7     char buffer[100] = { 0 };
8     FILE *fp = fopen("/dev/demo", "w+");
9
10    if (fp != NULL) {
11        if (argc == 3) {
12            snprintf(buffer, sizeof(buffer), "%s %c", argv[2], argv[1][3]);
13            fwrite(buffer, sizeof(buffer), 1, fp);
14        } else if (argc == 2) {
15            snprintf(buffer, sizeof(buffer), "get %c", argv[1][3]);
16        } else {
17            cout << "Error: number of arg\n";
18            cout << "number of arg: " << argc << endl;
19        }
20
21        fwrite(buffer, sizeof(buffer), 1, fp);
22    } else {
23        cout << "Error: Failed to open file\n";
24        return 0;
25    }
26
27    fread(buffer, sizeof(buffer), 1, fp);
28    fclose(fp);
29    return 0;
30 }
```


LED 腳位



LED1 : 7(VCC)、6(GND) -> GPIO396
LED2 : 19(VCC)、20(GND) -> GPIO429
LED3 : 35(VCC)、34(GND) -> GPIO395
LED4 : 40(VCC)、39(VCC) -> GPIO393

2. 預期實驗結果

能成功掛載 .ko 並在輸入指令後用 dmesg 查看到對應系統訊息。在 lab7-2 中，輸入 ./led LEDx on 可使 LEDx 亮燈，./led LEDx off 可使 LEDx 變暗，而 ./led LEDx 則會於系統訊息顯示 LEDx 目前的狀態，如亮燈則 state 為 1，暗燈時 state 為 0

3. 實際上的結果

(1) lab 7-1

(a) 項目一

(i) 虛擬機

掛載/卸除

```
LD [M] /home/nvidia/Desktop/lab07/hellod.ko
make[1]: Leaving directory '/usr/src/linux-headers-5.4.0-150-generic'
nvidia@ubuntu:~/Desktop/lab07$ sudo insmod hellod.ko
nvidia@ubuntu:~/Desktop/lab07$ sudo rmmod hellod.ko
nvidia@ubuntu:~/Desktop/lab07$ dmesg
```

系統訊息

```
[ 1683.941673] Hello, TX2 module is installed !
[ 1738.879043] e1000: ens33 NIC Link is Down
[ 1744.932923] e1000: ens33 NIC Link is Up 1000 Mbps Full Duplex, Fl
[ 1842.874089] Good-bye, TX2 module was removed!
nvidia@ubuntu:~/Desktop/lab07$
```

(ii) TX2

掛載/卸除

```
> ^C
nvidia@nvidia-desktop:~/Desktop/lab07$ sudo insmod hellod.ko
[sudo] password for nvidia:
nvidia@nvidia-desktop:~/Desktop/lab07$ dmesg
[ 10403.260428] hellod: loading out-of-tree module taints kernel.
[ 10403.266774] Hello, TX2 module is installed !
nvidia@nvidia-desktop:~/Desktop/lab07$ sudo rmmod hellod.ko
nvidia@nvidia-desktop:~/Desktop/lab07$ dmesg
[ 10403.266774] Good-bye, TX2 module was removed!
```

系統訊息

```
[ 1664.763341] Hello, TX2 module is installed !
[ 1673.172026] Good-bye, TX2 module was removed!
```

查看掛載狀態

```
nvidia@ubuntu:~/Desktop/lab07$ sudo insmod hellod.ko
nvidia@ubuntu:~/Desktop/lab07$ lsmod | grep hellod
hellod                16384  0
nvidia@ubuntu:~/Desktop/lab07$ sudo rmmod hellod.ko
nvidia@ubuntu:~/Desktop/lab07$ dmesg
```

(b) 項目二

make & insmod

```
make: *** [all] Error 2
nvidia@ubuntu:~/Desktop/lab07/2_code$ make
make -C /usr/src/linux-headers-5.4.0-150-generic M=/home/nvidia/Desktop/lab07/2_code
make[1]: Entering directory '/usr/src/linux-headers-5.4.0-150-generic'
CC [M] /home/nvidia/Desktop/lab07/2_code/demo.o
Building modules, stage 2.
MODPOST 1 modules
WARNING: modpost: missing MODULE_LICENSE() in /home/nvidia/Desktop/lab07/2_code/demo.o
see include/linux/module.h for more information
CC [M] /home/nvidia/Desktop/lab07/2_code/demo.mod.o
LD [M] /home/nvidia/Desktop/lab07/2_code/demo.ko
make[1]: Leaving directory '/usr/src/linux-headers-5.4.0-150-generic'
nvidia@ubuntu:~/Desktop/lab07/2_code$ sudo insmod demo.ko
nvidia@ubuntu:~/Desktop/lab07/2_code$
```

mknod

```
nvidia@ubuntu:~$ sudo mknod /dev/demo c 60 0
[sudo] password for nvidia:
nvidia@ubuntu:~$ cd /dev/
nvidia@ubuntu:/dev$ ls -l demo
crw-r--r-- 1 root root 60, 0 May 20 00:26 demo
nvidia@ubuntu:/dev$
```

呼叫 test.o 執行

```
Issing - tainting kernel
[ 4241.768102] <1>demo: started
nvidia@ubuntu:~/Desktop/lab07/2_code$ sudo ./test.o
nvidia@ubuntu:~/Desktop/lab07/2_code$ sudo ./test.o
nvidia@ubuntu:~/Desktop/lab07/2_code$ dmesg
```

```
[ 4292.245509] device read
[ 4292.245512] device close
nvidia@ubuntu:~/Desktop/lab07/2_code$ sudo su
root@ubuntu:/home/nvidia/Desktop/lab07/2_code# echo "test123" >/dev/deno
root@ubuntu:/home/nvidia/Desktop/lab07/2_code#
[ 4342.114863] userChar: 100
[ 4342.114866] device close
root@ubuntu:/home/nvidia/Desktop/lab07/2_code# sudo rmmod demo
root@ubuntu:/home/nvidia/Desktop/lab07/2_code#
```

系統訊息

```
[ 4241.767316] Disabling lock debugging due to kernel taint
[ 4241.767446] demo: module verification failed: signature and/or required key missing - tainting kernel
[ 4241.768102] <1>demo: started
nvidia@ubuntu:~/Desktop/lab07/2_code$
[ 4241.767446] demo: module verification failed: signature and/or required key missing - tainting kernel
[ 4241.768102] <1>demo: started
[ 4284.865423] device open
[ 4284.865428] device ioctl
[ 4284.865436] device write
[ 4284.865437] 0
[ 4284.865438] W_buf_size: 1024
[ 4284.865439] userChar: Data Input 123456 hello world
[ 4284.865440] userChar: 100
[ 4284.865442] device read
[ 4284.865444] device close
[ 4292.245491] device open
[ 4292.245496] device ioctl
[ 4292.245504] device write
[ 4292.245505] 1
[ 4292.245506] W_buf_size: 1024
[ 4292.245507] userChar: Data Input 123456 hello world
[ 4292.245508] userChar: 100
[ 4292.245509] device read
[ 4292.245512] device close
[ 4342.114854] device ioctl
[ 4342.114859] device write
[ 4342.114860] 1
[ 4342.114861] W_buf_size: 8
[ 4342.114862] userChar: test123
[ 4342.114863] userChar: 100
[ 4342.114866] device close
root@ubuntu:/home/nvidia/Desktop/lab07/2_code#
[ 4342.114861] W_buf_size: 8
[ 4342.114862] userChar: test123
[ 4342.114863] userChar: 100
[ 4342.114866] device close
[ 4376.173987] <1>demo: removed
root@ubuntu:/home/nvidia/Desktop/lab07/2_code#
```

(2) lab 7-2

操作影片：[lab7 2. MOV](#)

(a) 掛載 demo.ko，查看系統訊息會顯示 started

```
nvidia@nvidia-desktop:~/Desktop/lab07$ sudo insmod demo.ko
nvidia@nvidia-desktop:~/Desktop/lab07$ lsmod | grep demo
demo                4572  0
[ 2873.879894] <1>demo: started
```

(b) 控制 LED 亮燈

```
[ 3112.197920] <1>demo: started
nvidia@nvidia-desktop:~/Desktop/lab07$ sudo ./led LED1 on
nvidia@nvidia-desktop:~/Desktop/lab07$ sudo ./led LED2 on
nvidia@nvidia-desktop:~/Desktop/lab07$ sudo ./led LED3 on
nvidia@nvidia-desktop:~/Desktop/lab07$ sudo ./led LED4 on
```



```

[ 3132.213324] Open: Enter Open function
[ 3132.217011] I/O Control: Enter I/O Control function
[ 3132.222106] Write: Enter Write function
[ 3132.226296] on 1
[ 3132.228352] Read: Enter Release function
[ 3132.232511] Release: Enter Release function
[ 3137.488616] Open: Enter Open function
[ 3137.492351] I/O Control: Enter I/O Control function
[ 3137.497366] Write: Enter Write function
[ 3137.501454] on 2
[ 3137.503497] Read: Enter Release function
[ 3137.507476] Release: Enter Release function
[ 3142.220897] Open: Enter Open function
[ 3142.224621] I/O Control: Enter I/O Control function
[ 3142.229597] Write: Enter Write function
[ 3142.233450] on 3
[ 3142.235289] Read: Enter Release function
[ 3142.239263] Release: Enter Release function
[ 3145.777080] Open: Enter Open function
[ 3145.780812] I/O Control: Enter I/O Control function
[ 3145.785717] Write: Enter Write function
[ 3145.789569] on 4
[ 3145.791408] Read: Enter Release function
[ 3145.795345] Release: Enter Release function

```

(c) 查看 LED 狀態

```

nvidia@nvidia-desktop:~/Desktop/lab07$ sudo ./led LED4
nvidia@nvidia-desktop:~/Desktop/lab07$ sudo ./led LED3
nvidia@nvidia-desktop:~/Desktop/lab07$ sudo ./led LED2
nvidia@nvidia-desktop:~/Desktop/lab07$ sudo ./led LED1
nvidia@nvidia-desktop:~/Desktop/lab07$ dmesg

```

```

[ 3145.795345] Release: Enter Release function
[ 3156.998470] Open: Enter Open function
[ 3157.002232] I/O Control: Enter I/O Control function
[ 3157.007208] Write: Enter Write function
[ 3157.011097] get 4
[ 3157.013021] LED4 Status: 1
[ 3157.015750] Read: Enter Release function
[ 3157.019706] Release: Enter Release function
[ 3161.832056] Open: Enter Open function
[ 3161.835810] I/O Control: Enter I/O Control function
[ 3161.840718] Write: Enter Write function
[ 3161.844569] get 3
[ 3161.846508] LED3 Status: 0
[ 3161.849244] Read: Enter Release function
[ 3161.853187] Release: Enter Release function
[ 3165.851621] Open: Enter Open function
[ 3165.855349] I/O Control: Enter I/O Control function
[ 3165.860268] Write: Enter Write function
[ 3165.864182] get 2
[ 3165.866127] LED2 Status: 0
[ 3165.868830] Read: Enter Release function
[ 3165.872767] Release: Enter Release function
[ 3167.462251] Open: Enter Open function
[ 3167.465949] I/O Control: Enter I/O Control function
[ 3167.470857] Write: Enter Write function
[ 3167.474705] get 1
[ 3167.476627] LED1 Status: 0
[ 3167.479345] Read: Enter Release function
[ 3167.483278] Release: Enter Release function

```

(d)關閉 LED 燈

```
nvidia@nvidia-desktop:~/Desktop/lab07$ sudo ./led LED1 off
nvidia@nvidia-desktop:~/Desktop/lab07$ sudo ./led LED2 off
nvidia@nvidia-desktop:~/Desktop/lab07$ sudo ./led LED3 off
nvidia@nvidia-desktop:~/Desktop/lab07$ sudo ./led LED4 off
nvidia@nvidia-desktop:~/Desktop/lab07$ dmesg
[ 3185.088180] Open: Enter Open function
[ 3185.091899] I/O Control: Enter I/O Control function
[ 3185.096803] Write: Enter Write function
[ 3185.100651] off 1
[ 3185.102594] Read: Enter Release function
[ 3185.106532] Release: Enter Release function
[ 3189.515356] Open: Enter Open function
[ 3189.519212] I/O Control: Enter I/O Control function
[ 3189.524906] Write: Enter Write function
[ 3189.528823] off 2
[ 3189.530787] Read: Enter Release function
[ 3189.534736] Release: Enter Release function
[ 3193.672630] Open: Enter Open function
[ 3193.676371] I/O Control: Enter I/O Control function
[ 3193.681346] Write: Enter Write function
[ 3193.685277] off 3
[ 3193.687259] Read: Enter Release function
[ 3193.691522] Release: Enter Release function
[ 3196.689252] Open: Enter Open function
[ 3196.692939] I/O Control: Enter I/O Control function
[ 3196.697872] Write: Enter Write function
[ 3196.701747] off 4
[ 3196.703678] Read: Enter Release function
[ 3196.707615] Release: Enter Release function
```

(e) 移除掛載

```
nvidia@nvidia-desktop:~/Desktop/lab07$ sudo rmmod demo
nvidia@nvidia-desktop:~/Desktop/lab07$ dmesg
[ 3209.857373] Release: Enter Release function
[ 3235.599815] <1>demo: removed
nvidia@nvidia-desktop:~/Desktop/lab07$
nvidia@nvidia-desktop:~/Desktop/lab07$ lsmod | grep demo
nvidia@nvidia-desktop:~/Desktop/lab07$
```

4. 遇到的問題&問題怎麼解決

這次主要遇到的問題是 lab7_2 時 LED 燈不會亮，我們使用了以前的程式碼去測試是否能正常開啟燈的狀態，發現是可行的，但使用掛載後卻無法操控對應 gpio。後來我們到 /dev 目錄檢查，才發現在該目錄底下並沒有名稱為 demo 的設備文件，而創立後設備文件的權限也無法進行寫入，所以我們又另外設置權限，最終才可以順利操控 LED 燈。

在 /dev 下以 `ls -l` 查看，發現尚未有 demo

```
crw----- 1 root root    10,  46   五  27 18:32  cpu_freq_min
crw----- 1 root root    10, 203   一  28  2018  cuse
drwxr-xr-x  8 root root    10, 160   五  27 18:32  disk
crw----- 1 root root    10,  44   五  27 18:32  emc_freq_min
```

創建 demo 的 node(沒有權限)


```
crw-rw-rw- 1 root root 10, 40 五 27 18:32 cpu_freq_min
crw-rw-rw- 1 root root 10, 203 一 28 2018 cuse
crw-r--r-- 1 root root 60, 0 五 27 19:35 demo
drwxr-xr-x 8 root root 160 五 27 18:32 disk
crw-rw-rw- 1 root root 10, 44 五 27 18:32 emc_freq_min
crw-rw-rw- 1 root video 20, 0 五 27 18:32 fb0
```

給予 demo 權限

```
nvidia@nvidia-desktop:/dev$ sudo chmod 666 /dev/demo
nvidia@nvidia-desktop:/dev$ ls -l
total 0
crw-rw-rw- 1 root root 10, 235 五 27 18:32 autofs
drwxr-xr-x 2 root root 1340 五 27 18:32 block
crw-rw-rw- 1 root root 10, 234 一 28 2018 btrfs-control
drwxr-xr-x 3 root root 60 一 1 1970 bus
crw-rw-rw- 1 root video 243, 1 五 27 18:32 camchar-dbg
crw-rw-rw- 1 root video 243, 0 五 27 18:32 camchar-echo
crw-rw-rw- 1 root video 250, 0 五 27 18:32 capture-vi-channel0
crw-rw-rw- 1 root video 250, 1 五 27 18:32 capture-vi-channel1
crw-rw-rw- 1 root video 250, 10 五 27 18:32 capture-vi-channel10
crw-rw-rw- 1 root video 250, 11 五 27 18:32 capture-vi-channel11
crw-rw-rw- 1 root video 250, 12 五 27 18:32 capture-vi-channel12
crw-rw-rw- 1 root video 250, 13 五 27 18:32 capture-vi-channel13
crw-rw-rw- 1 root video 250, 14 五 27 18:32 capture-vi-channel14
crw-rw-rw- 1 root video 250, 2 五 27 18:32 capture-vi-channel2
crw-rw-rw- 1 root video 250, 3 五 27 18:32 capture-vi-channel3
crw-rw-rw- 1 root video 250, 4 五 27 18:32 capture-vi-channel4
crw-rw-rw- 1 root video 250, 5 五 27 18:32 capture-vi-channel5
crw-rw-rw- 1 root video 250, 6 五 27 18:32 capture-vi-channel6
crw-rw-rw- 1 root video 250, 7 五 27 18:32 capture-vi-channel7
crw-rw-rw- 1 root video 250, 8 五 27 18:32 capture-vi-channel8
crw-rw-rw- 1 root video 250, 9 五 27 18:32 capture-vi-channel9
drwxr-xr-x 2 root root 6060 五 27 18:32 char
crw-rw-rw- 1 root root 5, 1 五 27 18:32 console
crw-rw-rw- 1 root root 10, 41 五 27 18:32 constraint_cpu_freq
crw-rw-rw- 1 root root 10, 40 五 27 18:32 constraint_gpu_freq
crw-rw-rw- 1 root root 10, 39 五 27 18:32 constraint_online_cpus
crw-rw-rw- 1 root root 10, 54 五 27 18:32 cpu_dma_latency
crw-rw-rw- 1 root root 10, 45 五 27 18:32 cpu_freq_max
crw-rw-rw- 1 root root 10, 46 五 27 18:32 cpu_freq_min
crw-rw-rw- 1 root root 10, 203 一 28 2018 cuse
crw-rw-rw- 1 root root 60, 0 五 27 19:35 demo
drwxr-xr-x 8 root root 160 五 27 18:32 disk
```

三、程式碼

1. lab 7-1

(1) 項目一

hellod.c
<pre>#include <linux/kernel.h> #include <linux/module.h> static int __init tx2_hello_module_init(void){ printk("Hello, TX2 module is installed !\n"); return 0; } static void __exit tx2_hello_module_cleanup(void){ printk("Good-bye, TX2 module was removed!\n"); }</pre>

```
module_init(tx2_hello_module_init);  
module_exit(tx2_hello_module_cleanup);  
MODULE_LICENSE("GPL");
```

Makefile (ubuntu)

```
obj-m := hellod.o  
  
kernel_DIR := /usr/src/linux-headers-5.4.0-150-generic  
  
PWD := $(shell pwd)  
  
all:  
    make -C $(kernel_DIR) M=$(PWD)  
clean:  
    rm *.o *.ko *.mod.c  
.PHONY:  
    clean
```

Makefile (tx2)

```
obj-m := hellod.o  
  
kernel_DIR := /usr/src/linux-headers-4.9.201-tegra-  
ubuntu18.04_aarch64/kernel-4.9/  
  
PWD := $(shell pwd)  
  
all:  
    make -C $(kernel_DIR) SUBDIRS=$(PWD)  
clean:  
    rm *.o *.ko *.mod.c  
.PHONY:  
    clean
```

(2) 项目二

demo.c

```
#include<linux/init.h>  
#include<linux/kernel.h>  
#include<linux/module.h>  
#include<linux/fs.h>  
#include<asm/uaccess.h>  
  
#define MAJOR_NUM 60  
#define MODULE_NAME "demo"
```

```

static int iCount = 0;
static char userChar[100];

static ssize_t drv_write(struct file *flip, const char *buf,
size_t count, loff_t *ppos){
    printk("device write\n");
    printk("%d\n", iCount);
    printk("W_buf_size: %d\n", (int)count);
    raw_copy_from_user(userChar, buf, count);
    userChar[count - 1] = 0;
    printk("userChar: %s\n", userChar);
    printk("userChar: %d\n", (int)sizeof(userChar));
    iCount++;
    return count;
}

long drv_ioctl(struct file *filp, unsigned int cmd, unsigned
long arg){
    printk("device ioctl\n");
    return 0;
}

static int drv_open(struct inode *inode, struct file *filp){
    printk("device open\n");
    return 0;
}

static int drv_release(struct inode *inode, struct file *filp){
    printk("device close\n");
    return 0;
}

static ssize_t drv_read(struct file *flip, char *buf, size_t
count, loff_t *ppos){
    printk("device read\n");
    return count;
}

struct file_operations drv_fops =
{
    read: drv_read,
    write: drv_write,
    unlocked_ioctl: drv_ioctl,
    open: drv_open,
    release: drv_release,
};

static int demo_init(void){

```



```

        if(register_chrdev(MAJOR_NUM, "demo", &drv_fops)<0){
            printk("<1>%s: can't get major %d\n", MODULE_NAME,
MAJOR_NUM);
            return (-EBUSY);
        }

        printk("<1>%s: started\n", MODULE_NAME);
        return 0;
    }

static void demo_exit(void){
    unregister_chrdev(MAJOR_NUM, "demo");
    printk("<1>%s: removed\n", MODULE_NAME);
}

module_init(demo_init);
module_exit(demo_exit);

```

test.c

```

#include <stdio.h>
int main(){
    char buf[1024] = "Data Input 123456 hello world";
    FILE *fp = fopen("/dev/demo", "w+");
    if(fp == NULL){
        printf("can't open device!\n");
        return 0;
    }
    fwrite(buf, sizeof(buf), 1, fp);
    fread(buf, sizeof(buf), 1, fp);
    fclose(fp);
    return 0;
}

```

Makefile (ubuntu)

```

obj-m := hellod.o

kernel_DIR := /usr/src/linux-headers-5.4.0-150-generic

PWD := $(shell pwd)

all:
    make -C $(kernel_DIR) M=$(PWD)

clean:
    rm *.o *.ko *.mod.c

.PHONY:

```

clean

2. lab 7-2

demo.c

```
#include <linux/init.h>
#include <linux/module.h>
#include <linux/fs.h>
#include <linux/gpio.h>
#include <asm/uaccess.h>

MODULE_LICENSE("Dual BSD/GPL");

#define DRIVER_MAJOR 60
#define DRIVER_NAME "demo"

int gpioPin[4] = { 396, 429, 395, 393};
int ledPin[4] = { 7, 12, 18, 37 };
int ledBook[4] = { 0, 0, 0, 0 };
static char userChar[100];

static int driver_open(struct inode *inode, struct file *filp) {
    printk("Open: Enter Open function\n");
    return 0;
}

static int driver_close(struct inode *inode, struct file *filp)
{
    printk("Release: Enter Release function\n");
    return 0;
}

long driver_ioctl(struct file *filp, unsigned int cmd, unsigned
long arg)
{
    printk("I/O Control: Enter I/O Control function\n");
    return 0;
}

static ssize_t driver_read(struct file *filp, char *buf, size_t
size, loff_t *f_pos) {
    printk("Read: Enter Release function\n");
    return 0;
}

static ssize_t driver_write(struct file *filp, const char *buf,
size_t size, loff_t *f_pos) {
    printk("Write: Enter Write function\n");
```

```

if(copy_from_user(userChar, buf, size) == 0){
    userChar[size - 1] = '\0';
    int ledIndex;
    int pin;

    printk("%s\n", userChar);
    if(userChar[0] == 'g') {
        ledIndex = userChar[4] - '1';
        printk("LED%d Status: %d\n", ledIndex + 1,
ledBook[ledIndex]);
    }
    else if (userChar[1] == 'n') {
        ledIndex = userChar[3] - '1';
        pin = gpioPin[ledIndex];
        gpio_set_value(pin, 1);
        ledBook[ledIndex] = 1;
    }
    else if (userChar[1] == 'f') {
        ledIndex = userChar[4] - '1';
        pin = gpioPin[ledIndex];
        gpio_set_value(pin, 0);
        ledBook[ledIndex] = 0;
    }
    else {
        printk("Error: command not found");
    }
} else{
    printk("Error: Write Error\n");
}
return size;
}

static struct file_operations driver_fops = {
    .open = driver_open,
    .release = driver_close,
    .unlocked_ioctl = driver_ioctl,
    .read = driver_read,
    .write = driver_write,
};

static int demo_init(void) {
    int result;
    printk("<1>demo: started\n");

    char* ledName[4] = { "LED1", "LED2", "LED3", "LED4" };
    int i;
    for (i = 0; i < 4; i++) {
        if (gpio_is_valid(gpioPin[i]) == 0) {
            printk("pin %d is no valid\n", gpioPin[i]);
            return -EBUSY;

```

```

    }

    if (gpio_request(gpioPin[i], ledName[i]) < 0) {
        printk("pin %d is busy\n", gpioPin[i]);
        return -EBUSY;
    }

    gpio_direction_output(gpioPin[i], 0);
    gpio_export(gpioPin[i], false);
}

result = register_chrdev(DRIVER_MAJOR, DRIVER_NAME,
&driver_fops);
if (result < 0) {
    printk("<1>demo: Failed to register character
device\n");
    return result;
}

return 0;
}

static void demo_exit(void) {
    printk("<1>demo: removed\n");
    int i;
    for (i = 0; i < 4; i++) {
        gpio_free(gpioPin[i]);
    }

    /* Unregister character device */
    unregister_chrdev(DRIVER_MAJOR, DRIVER_NAME);
}

module_init(demo_init);
module_exit(demo_exit);

```

led.cpp

```

#include <iostream>
#include <cstdio>

using namespace std;

int main(int argc, char *argv[]) {
    char buffer[100] = { 0 };
    FILE *fp = fopen("/dev/demo", "w+");

    if (fp != NULL) {
        if (argc == 3) {

```

```

        snprintf(buffer, sizeof(buffer), "%s %c", argv[2],
argv[1][3]);
        fwrite(buffer, sizeof(buffer), 1, fp);
    } else if (argc == 2) {
        snprintf(buffer, sizeof(buffer), "get %c",
argv[1][3]);
    } else {
        cout << "Error: number of arg\n";
        cout << "number of arg: " << argc << endl;
    }

    fwrite(buffer, sizeof(buffer), 1, fp);
} else {
    cout << "Error: Failed to open file\n";
    return 0;
}

fread(buffer, sizeof(buffer), 1, fp);
fclose(fp);
return 0;
}

```

Makefile

```

obj-m :=demo.o

kernel_DIR :=/usr/src/linux-headers-4.9.201-tegra-
ubuntu18.04_aarch64/kernel-4.9/

PWD := $(shell pwd)

all:
    g++ -o led led.cpp
    make -C $(kernel_DIR) SUBDIRS=$(PWD)
    sudo insmod demo.ko
clean:
    sudo rmmmod demo.ko
    rm *.o *.ko *.mod.c
.PHONY:
    clean

```

四、本次實驗過程說明與解決方法：

1. 實驗過程

撰寫.c 及.cpp 檔及所需 Makefile → 使用 make 指令執行 Makefile →
 在/dev/下新增 node →編寫字元裝置(建立 file_operations 資料結構)
 並編譯出 ko 檔(驅動模組檔案) → 將 ko 檔(驅動模組檔案)掛載並查看
 (dmesg)系統訊息→ 執行 LED 控制程式(呼叫對應驅動模組) → 控制特

定 LED 燈或讀取特定 LED 點燈狀態

2. 解決方法

LED 無法控制狀態，後來發現是/dev 目錄下無對應 demo，使用 mknod 建立 demo node 並給予它權限即可解決問題。

五、分工：

學號、組員	貢獻比例	工作內容
B812110004 葉芸茜	50%	文書處理、實驗設計與實作、程式規劃、測試與除錯
B812110011 湯青秀	50%	文書處理、實驗設計與實作、程式規劃、測試與除錯