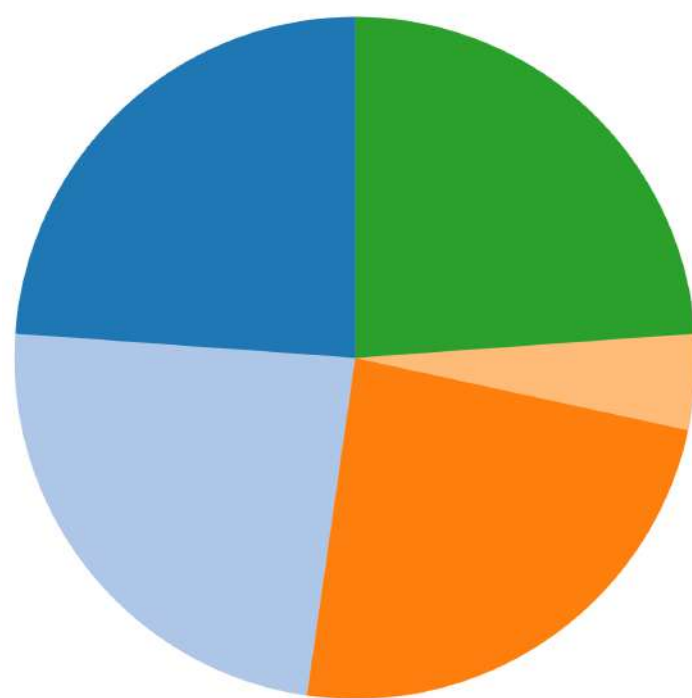


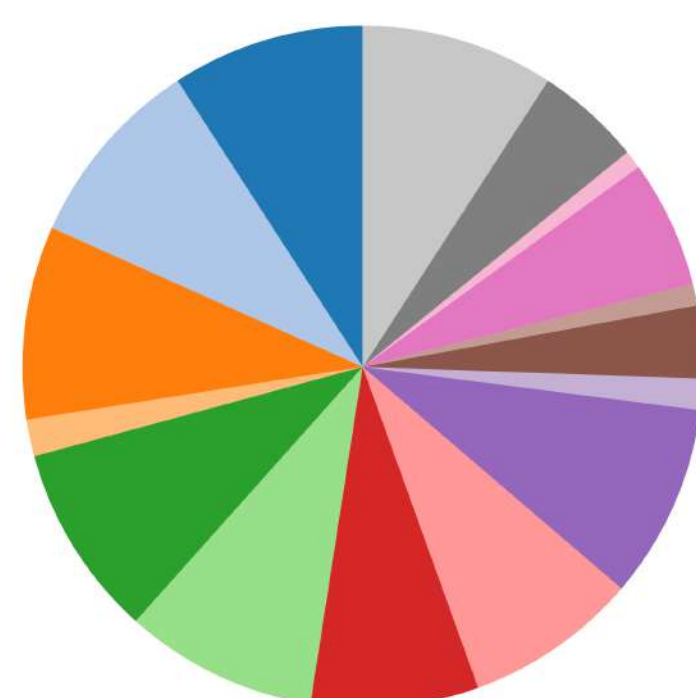
- austin_sailor
- stanford_hydra
- austin_buds
- austin_sirius
- berkeley_mv
- berkeley_rpt
- iamlab_cmu_pickup_insert
- utaustin_mutex
- imperialcollege_sawyer_wrist_cam
- stanford_mask_vit
- language_table
- kuka
- bc_z
- robo_net
- dlr_sara_pour
- stanford_robotcook
- cmu_play_fusion
- bridge
- furniture_bench
- ucsd_pick_and_place
- usc_cloth_sim
- stanford_kuka_multimodal
- roboturk
- kaist_nonprehensile
- asu_table_top
- utokyo_xarm_pick_and_place
- berkeley_cable_routing
- droid
- uiuc_d3field
- robo_set
- qut_dexterous_manipulation
- nyu_door_opening_surprising_effectiveness
- nyu_franka_play
- mimic_play
- maniskill
- columbia_cairlab_pusht_real
- conq_hose_manipulation
- dlr_edan_shared_control
- berkeley_gnm_sac_son
- berkeley_autolab_ur5
- aloha_mobile
- agent_aware_affordances
- human_image_hammer
- human_image_spatula
- epic_kitchen
- drake_tooluse_image
- pybullet_grasping_image
- mujoco_metaworld

5 Datasets
1000 Episode Max



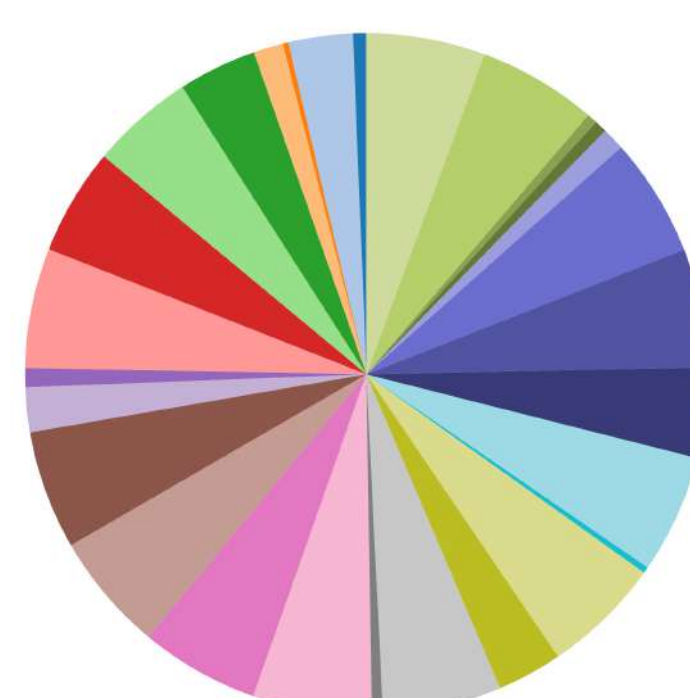
Trajectory

15 Datasets
1000 Episode Max



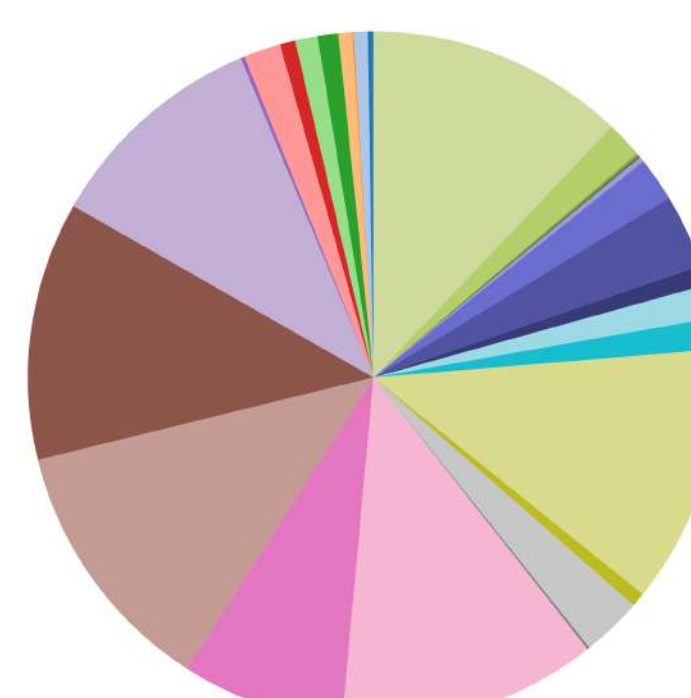
Episode Step

28 Datasets
1000 Episode Max

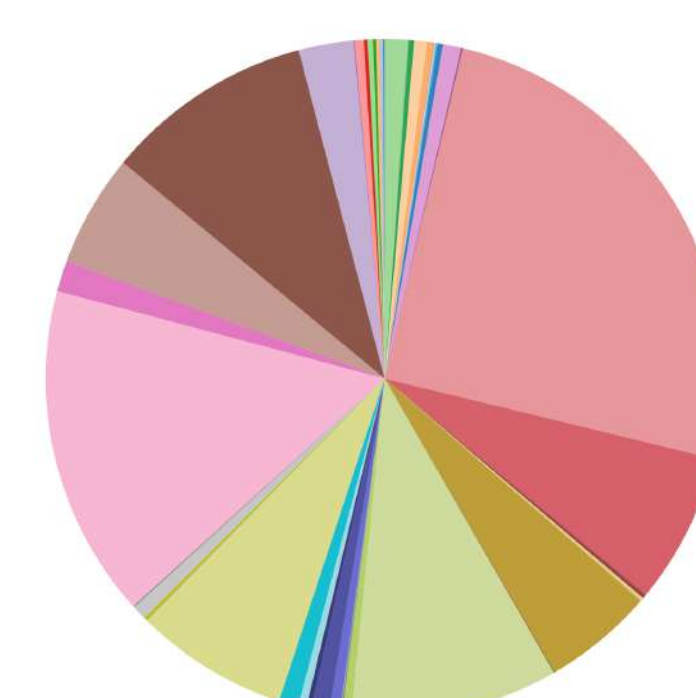


Sample Weight

28 Datasets
10000 Episode Max



50 Datasets
100000 Episode Max



Grouped Sample Weight

