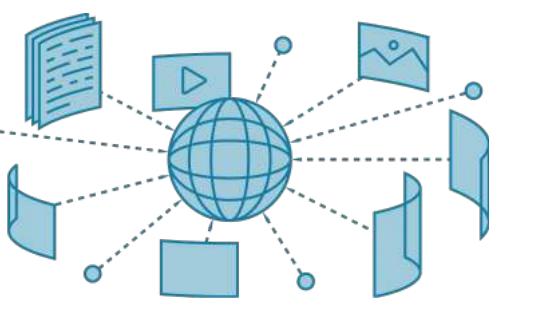


π cross-embodiment robot dataset



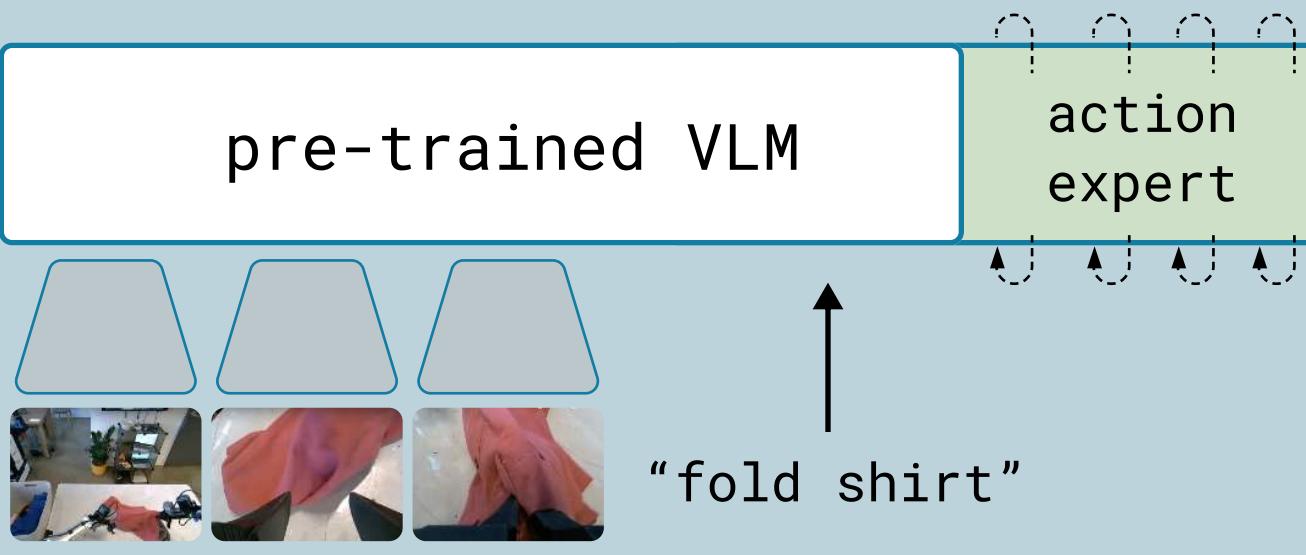
Internet-scale pre-training



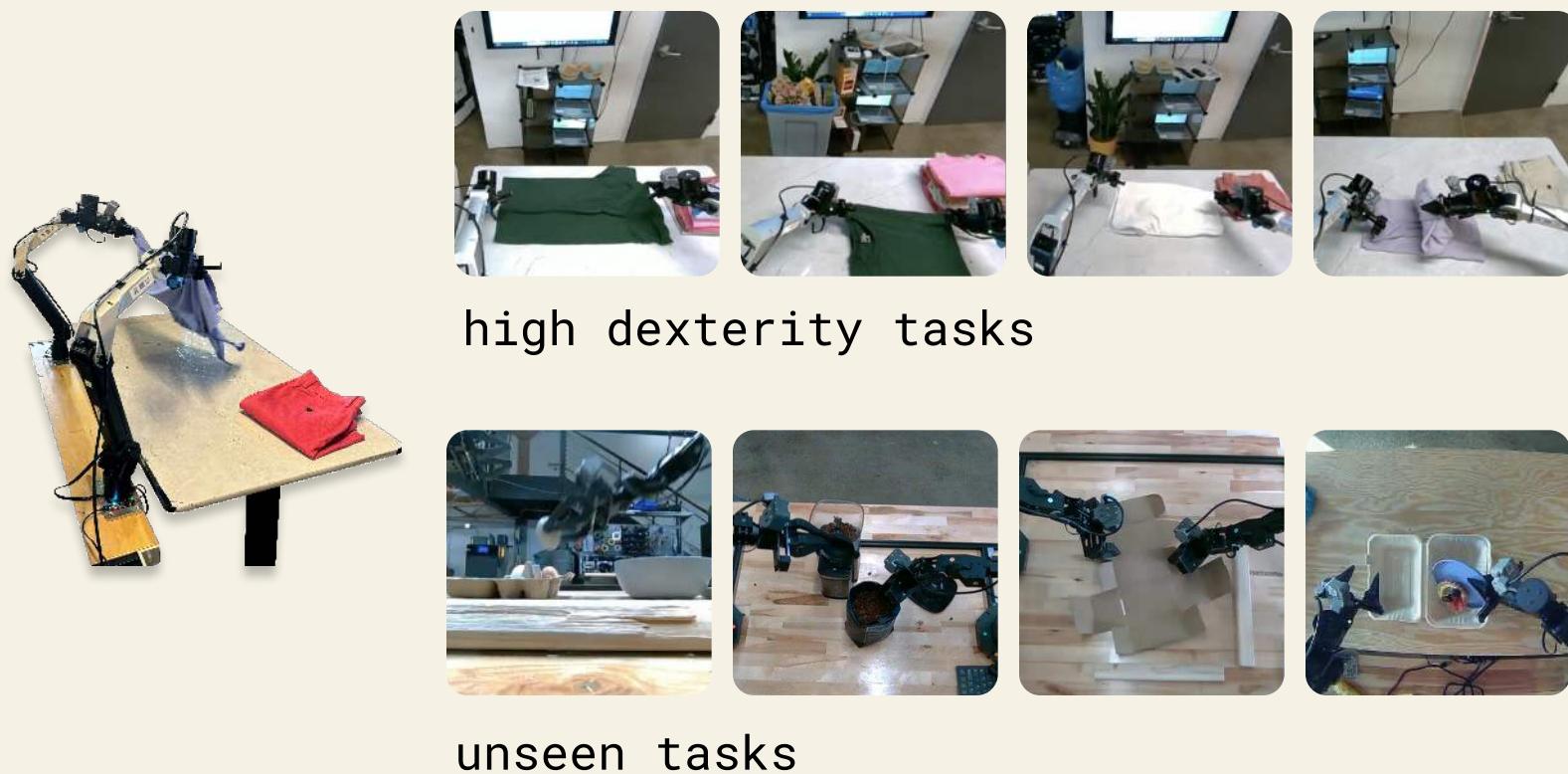
Open X-Embodiment Dataset



π_0 vision-language-action model



High-quality post-training data



Zero-shot in-distribution tasks



Specialized post-training to difficult tasks



Efficient post-training to unseen tasks

