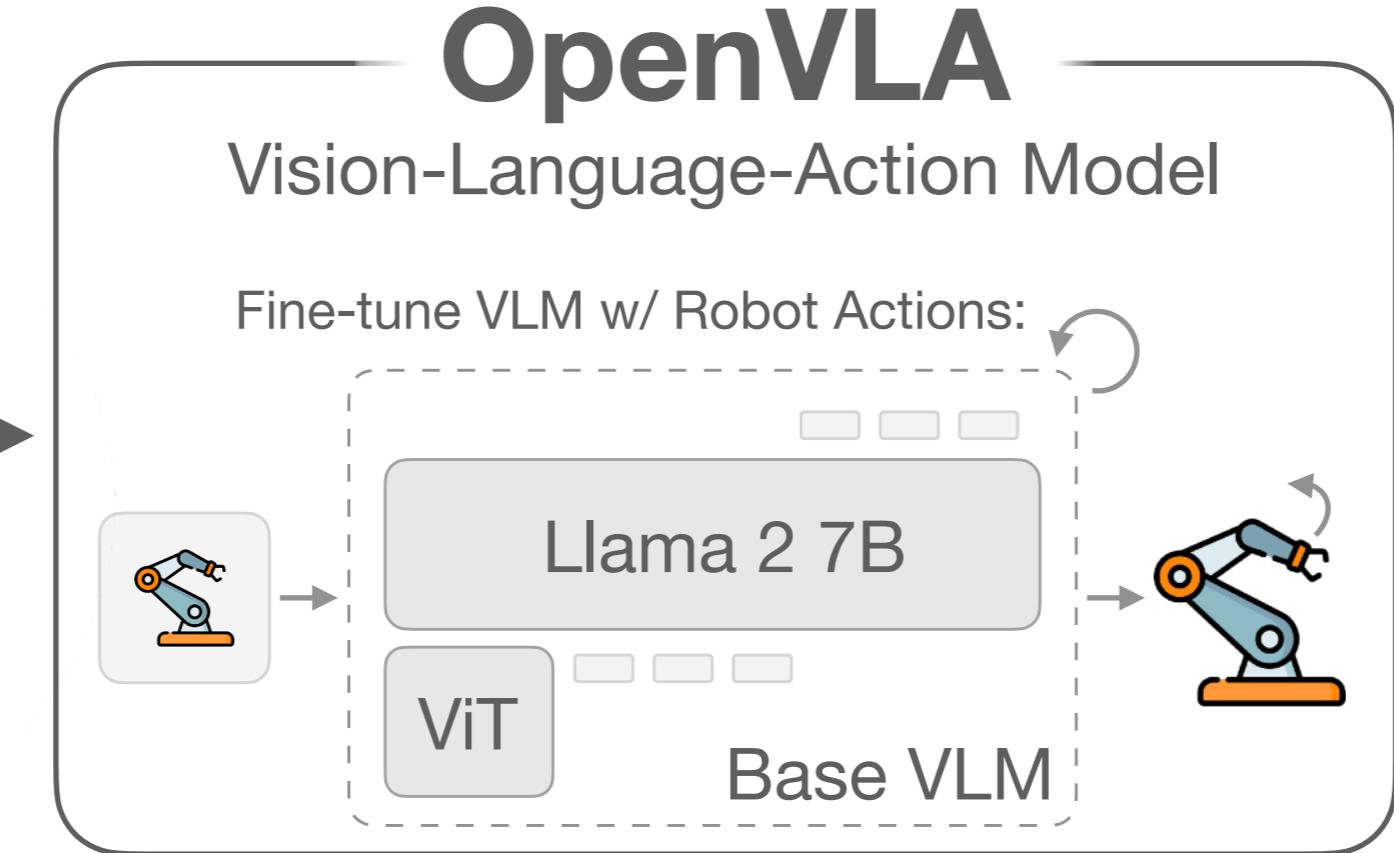


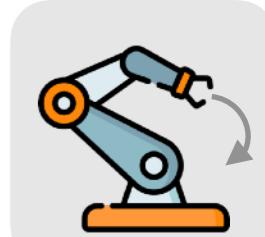
Large-Scale Robot Training Data



Closed-Loop Robot Control Policy

User: Wipe the table.

OpenVLA:
 $[\Delta x, \Delta \theta, \Delta \text{Grip}] = \dots$



Fully Open-Source

- Data
- Weights
- Code

Multi-Robot Control & Efficient Fine-Tuning

