

## Lecture 2: Conditioning, Bayes' Rule, and Independence

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EE210: Probability and Introductory Random Processes  
KAIST EE

MONTH DAY, 2021

- Conditional Probability
- Bayes' Rule
- Bayesian Inference: Sneak Peek
- Independence, Conditional Independence

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    - $\mathbb{P}(\Omega|B) = 1$ ?
    - $\mathbb{P}(B|B) = 1$  from our common sense. True?

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- All other properties of the law  $\mathbb{P}(\cdot)$  is applied to the conditional law  $\mathbb{P}(\cdot|B)$ .
- For example, finite additivity. For two disjoint events  $A$  and  $C$ ,

$$\mathbb{P}(A \cup C \mid B) = \mathbb{P}(A \mid B) + \mathbb{P}(C \mid B)$$



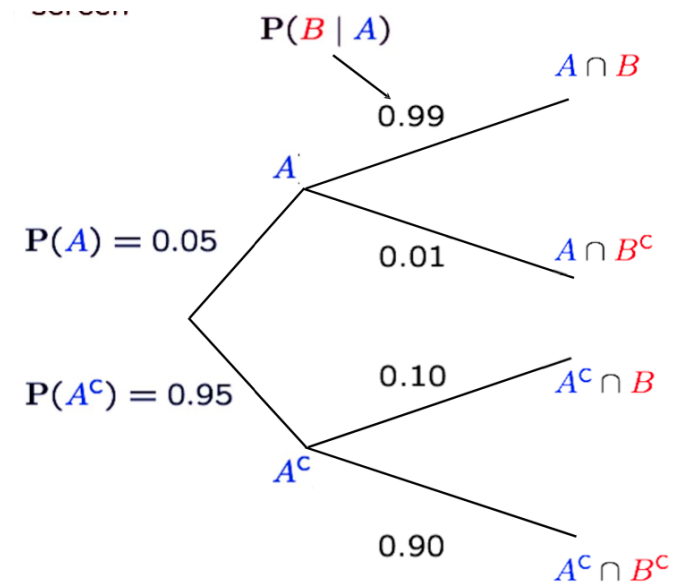
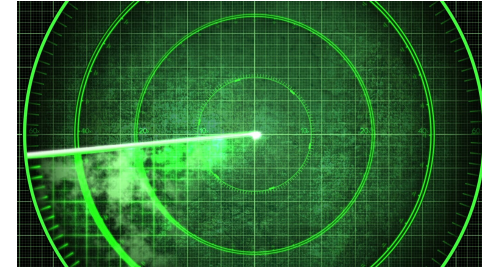
# Example: Conditional Probability

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$$=$$

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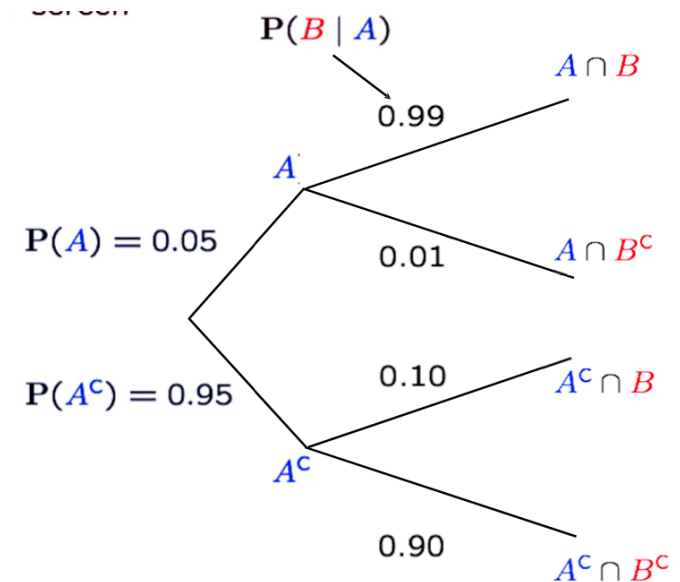
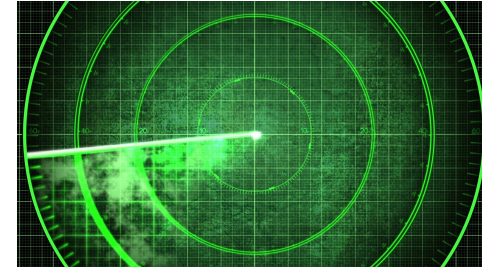
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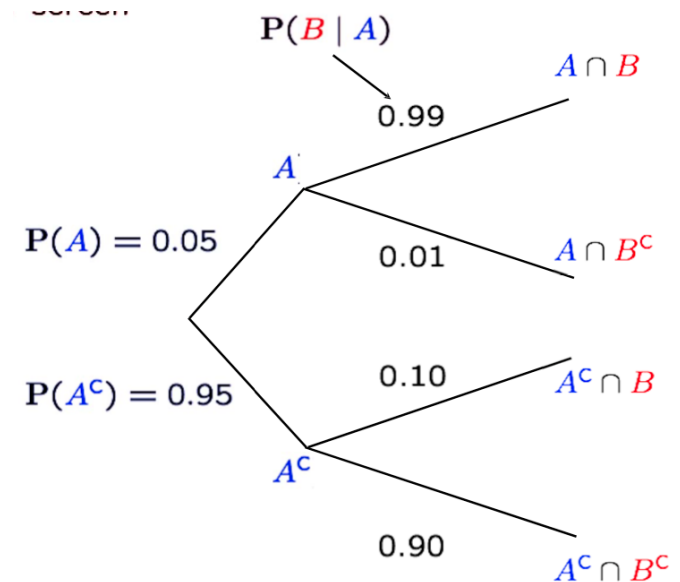
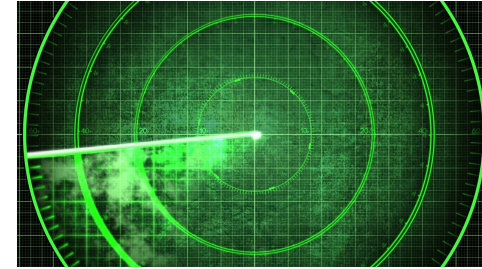
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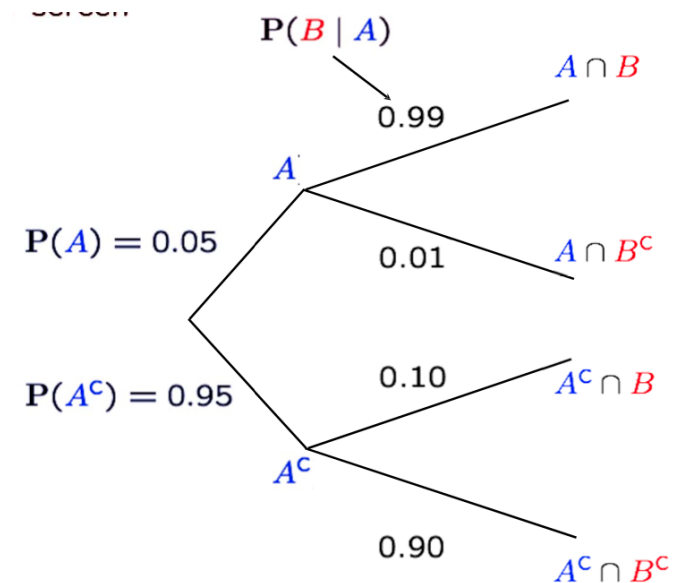
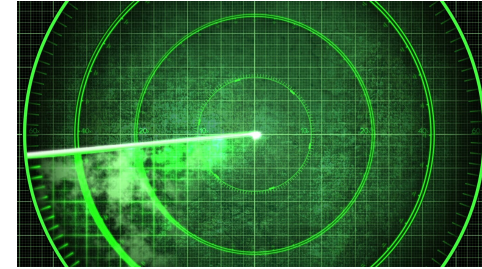
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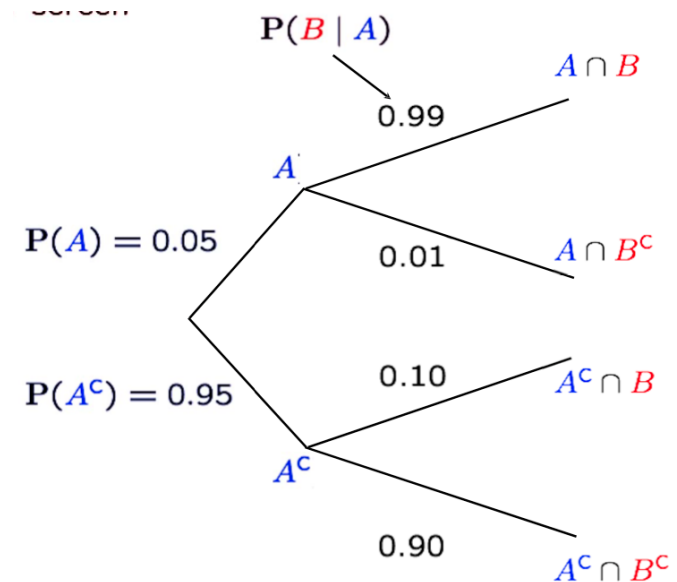
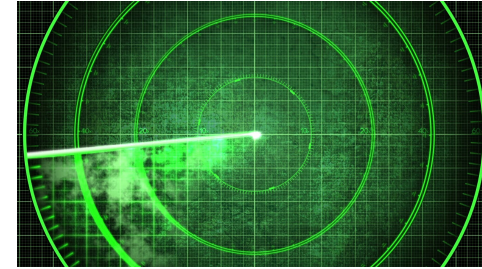
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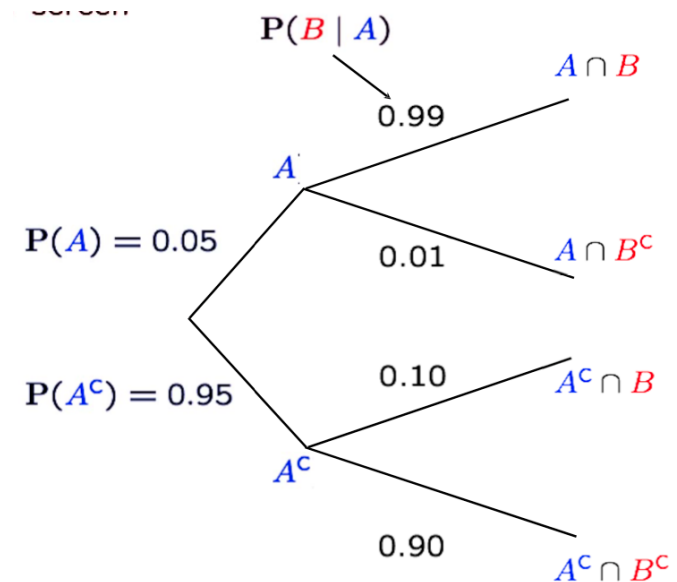
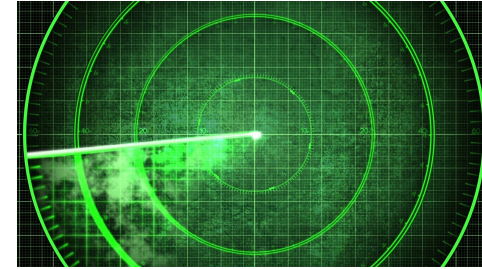
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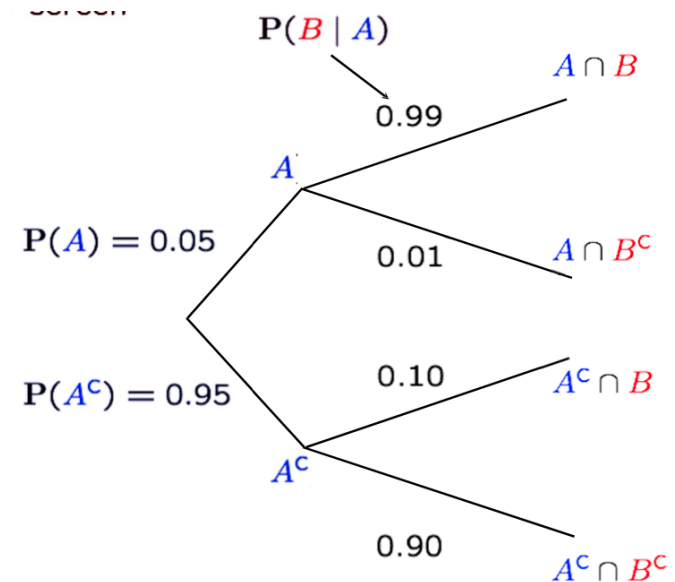
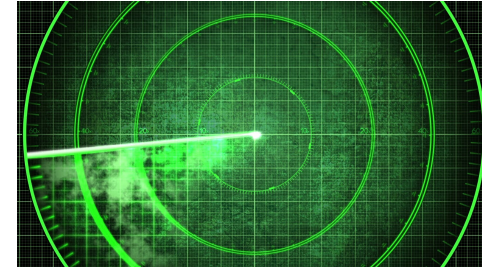
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$$\mathbb{P}(A|B) = \frac{\mathbb{P}(A \cap B)}{\mathbb{P}(B)} = \frac{0.0495}{0.1445} \approx 0.34$$



From now on, using the theory of probability and conditional probability constructed so far, we will develop interesting properties and theorems which are very useful to answer some exciting questions.

That is *Bayes' Rule* to make some *inference* (추론).





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We will study this topic rigorously later in this class (chapter 8).



## KAIST EE

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- A probability tree diagram illustrating the joint and conditional probabilities for three events:  $A$ ,  $B$ , and  $C$ .
- The tree starts with a root node branching into  $A$  and  $A^c$ .
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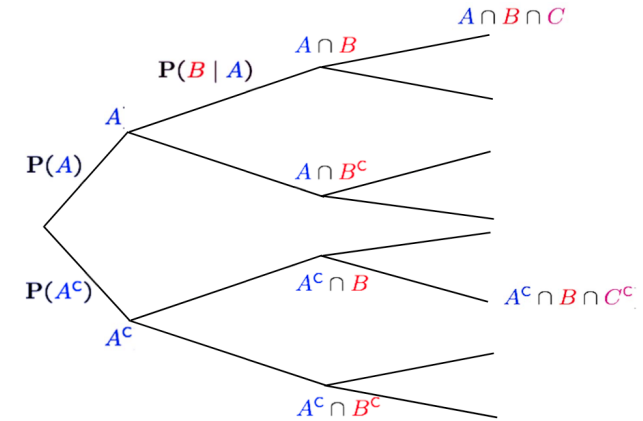
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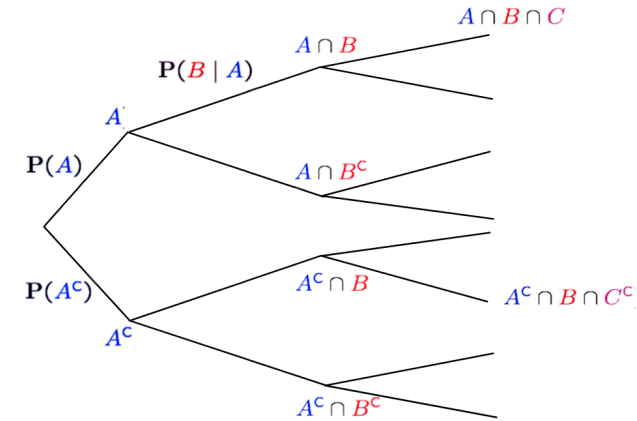


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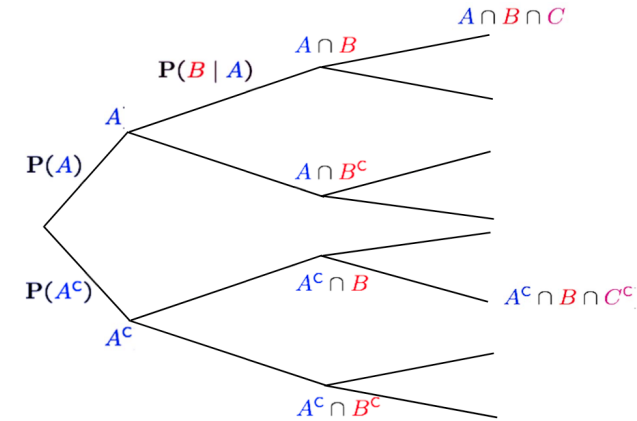


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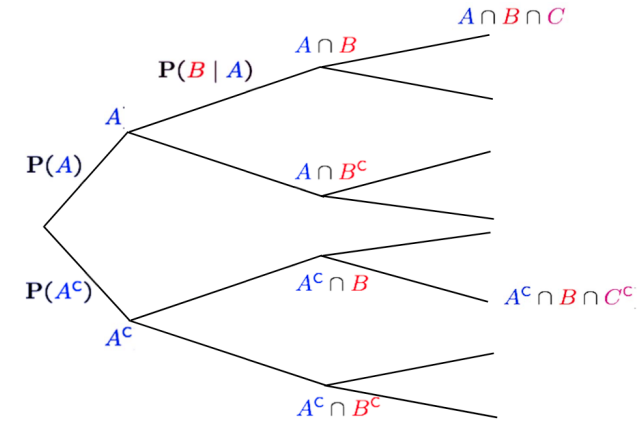


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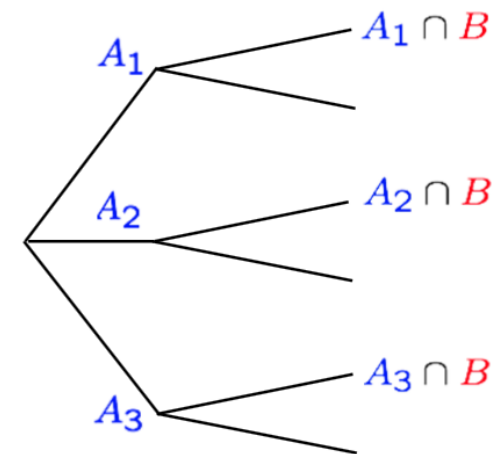
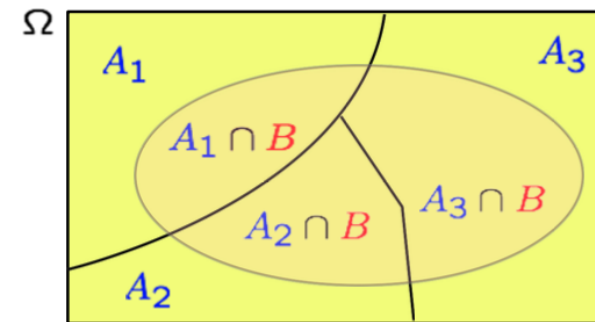
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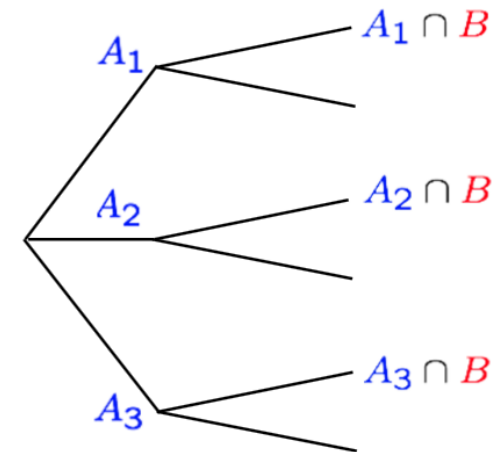
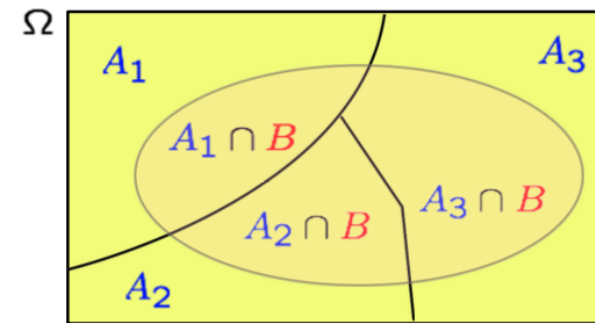
$$\mathbb{P}(A_1 \cap A_2 \cap \cdots \cap A_n) = \mathbb{P}(A_1) \cdot \mathbb{P}(A_2|A_1) \cdot \mathbb{P}(A_3|A_1, A_2) \cdots \mathbb{P}(A_n|A_1, A_2, \dots, A_{n-1})$$

# Total Probability Theorem



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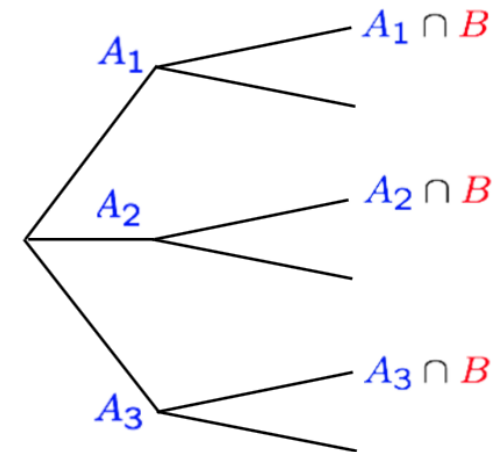
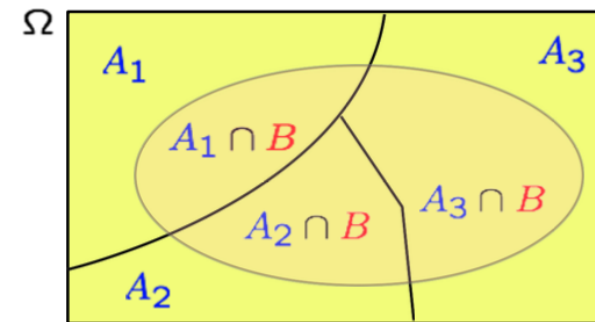
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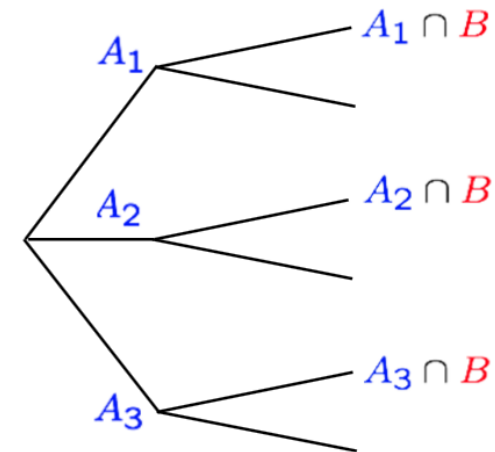
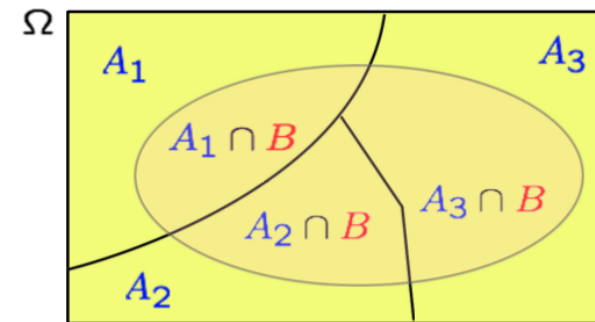
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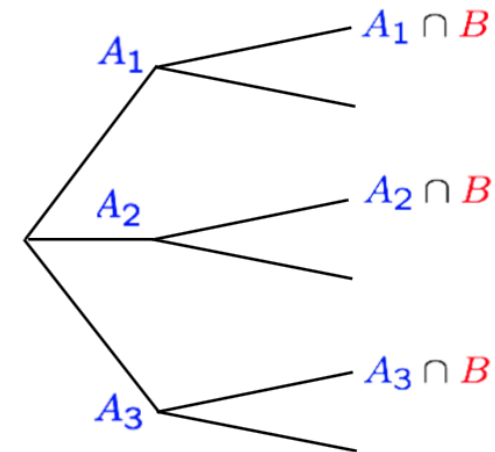
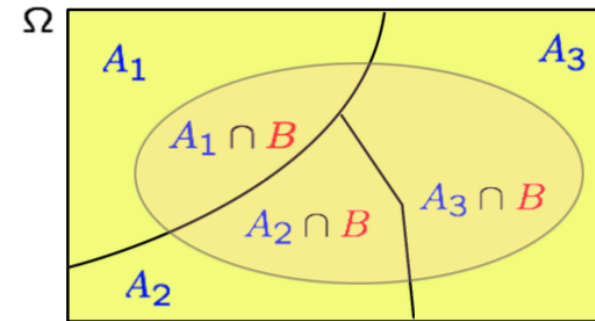
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$$\mathbb{P}(B) = \sum_i \mathbb{P}(A_i) \mathbb{P}(B|A_i)$$

- $\mathbb{P}(A_i \cap B) = \mathbb{P}(A_i) \mathbb{P}(B|A_i)$



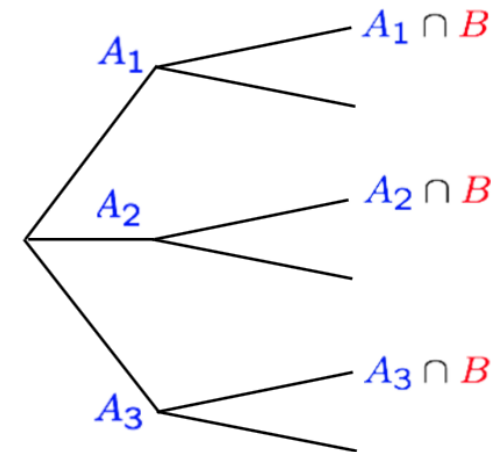
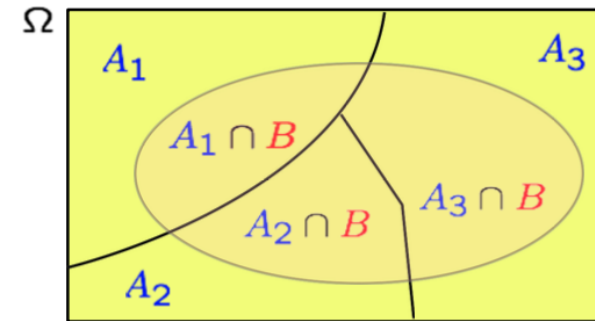
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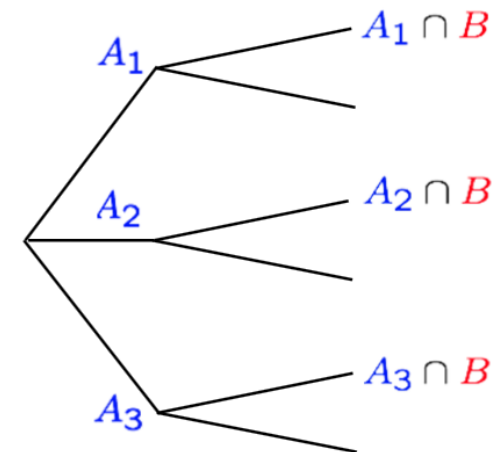
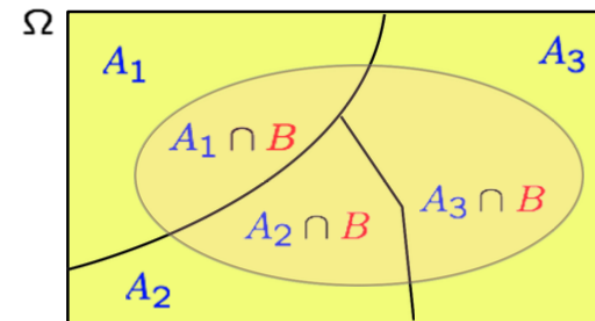
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- $\mathbb{P}(A_i \cap B) = \mathbb{P}(A_i) \mathbb{P}(B|A_i)$
- Weighted average from the point of  $A_i$  knowledge.



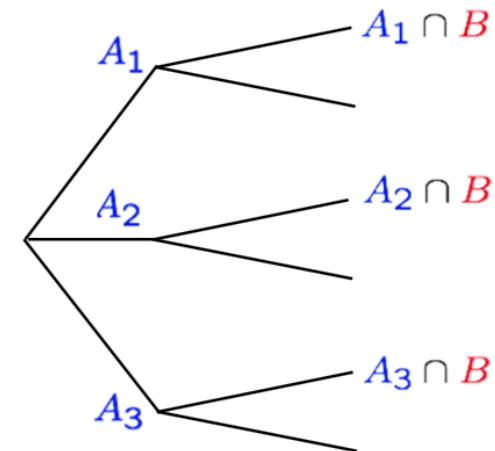
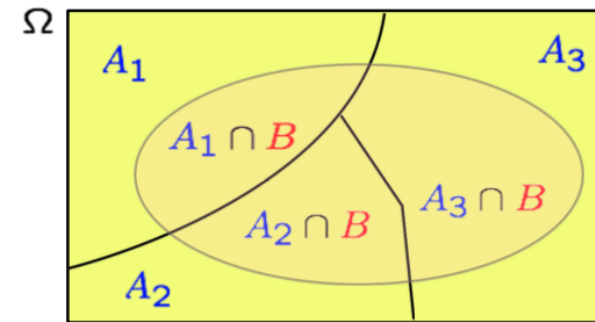
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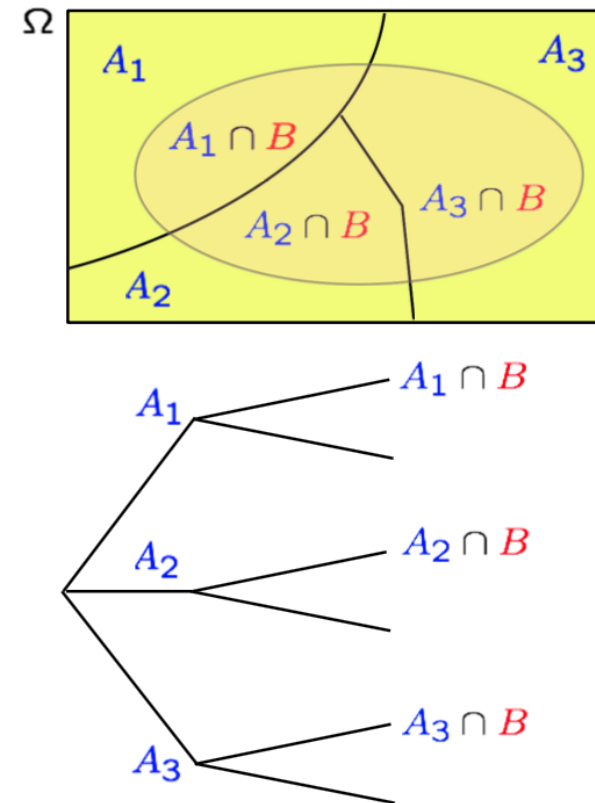


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## Bayes' Rule

$$\mathbb{P}(A_i|B) = \frac{\mathbb{P}(A_i)\mathbb{P}(B|A_i)}{\sum_j \mathbb{P}(A_j)\mathbb{P}(B|A_j)}$$



- $A_1$ : you are happy,  $A_2$ : you are sad
- $B$ : you shout.
- Assume:

$$\mathbb{P}(A_1) = 0.7, \mathbb{P}(A_2) = 0.3,$$

$$\mathbb{P}(B|A_1) = 0.3, \mathbb{P}(B|A_2) = 0.5.$$

- Calculate  $\mathbb{P}(A_1|B)$  and  $\mathbb{P}(A_2|B)$ .

$$\mathbb{P}(A_1)\mathbb{P}(B|A_1) = 0.7 \times 0.3 = 0.21$$

$$\mathbb{P}(A_2)\mathbb{P}(B|A_2) = 0.3 \times 0.5 = 0.15$$

$$\mathbb{P}(B) = 0.21 + 0.15 = 0.36$$

$$\mathbb{P}(A_1|B) = \frac{0.21}{0.36} \approx 0.583$$

$$\mathbb{P}(A_2|B) = \frac{0.15}{0.36} \approx 0.417$$



Bayesian inference was really fun.

Now, let's develop a new concept from conditioning.

That is *Independence*.

# Why We Care Independence?



- Event  $A$ : I get the grade A in the probability class (my interest).
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- Independence makes our analysis and modeling much simpler, because I can remove independent events in my analysis.

- Occurrence of  $A$  provides no new information about  $B$ . Thus, knowledge about  $A$  does not change my belief about  $B$ .
- Using  $\mathbb{P}(B|A) = \mathbb{P}(B \cap A)/\mathbb{P}(A)$ ,

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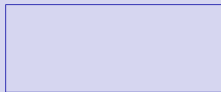
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  - $H_1$ : 1st toss is a head
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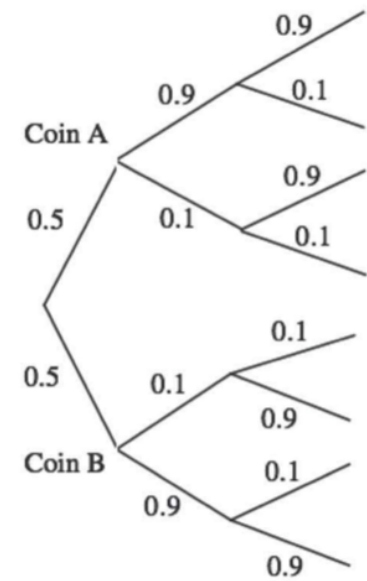
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- $\mathbb{P}(H_1 \cap H_2|D) = 0,$
- No.



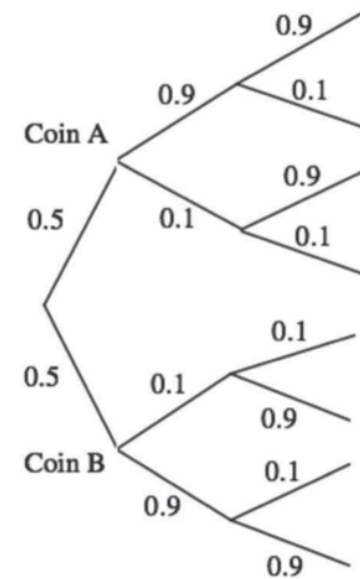
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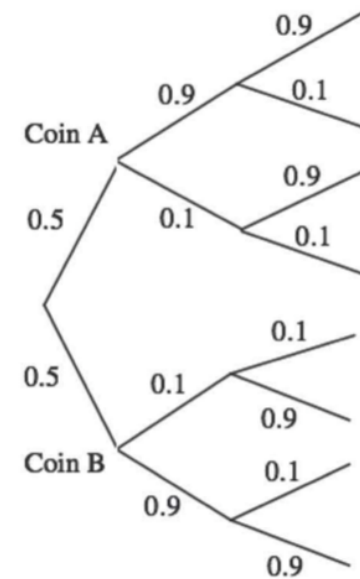
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- $H_1 \perp\!\!\!\perp H_2|B$ ? Yes

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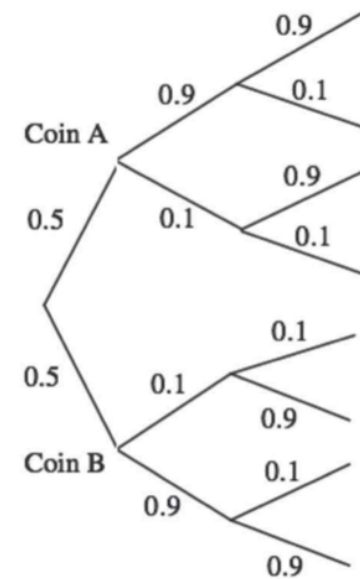


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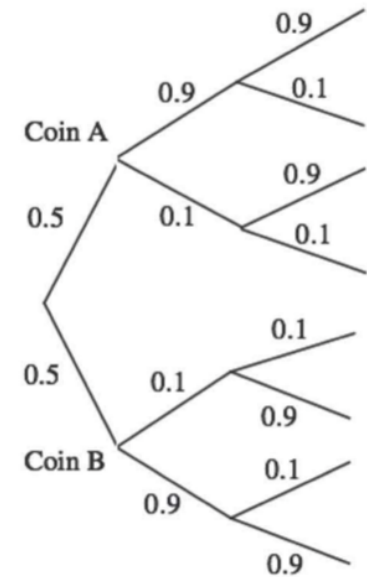
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$$\mathbb{P}(H_1) = \mathbb{P}(B)\mathbb{P}(H_1|B) + \mathbb{P}(B^c)\mathbb{P}(H_1|B^c)$$

$$= \frac{1}{2}0.9 + \frac{1}{2}0.1 = \frac{1}{2}$$

$$\mathbb{P}(H_2) = \mathbb{P}(H_1) \quad (\text{because of symmetry})$$



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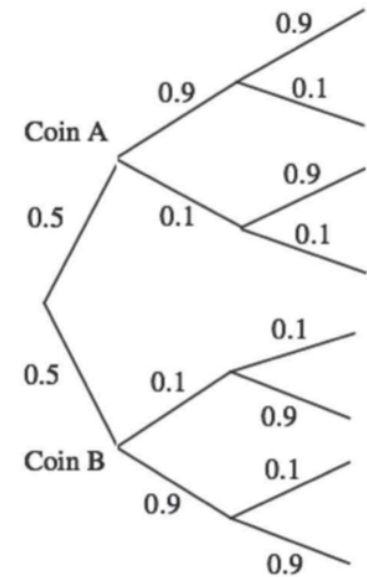
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$$= \frac{1}{2}(0.9 \times 0.9) + \frac{1}{2}(0.1 \times 0.1) \neq \frac{1}{2}$$



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## Independence of Multiple Events

The events  $A_1, A_2, \dots, A_n$  are said to be independent if

$$\mathbb{P}\left(\bigcap_{i \in S} A_i\right) = \prod_{i \in S} \mathbb{P}(A_i), \quad \text{for every subset } S \text{ of } \{1, 2, \dots, n\}$$

Questions?

- 1) What is conditional probability? Why do we need it?
- 2) Explain the overall framework of Bayesian inference.
- 3) What is the total probability theorem?
- 4) What is Bayes' rule? What does it can give us?
- 5) What's the difference between independence and conditional independence?