#### Al and Deep Learning

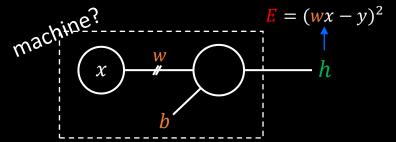
# Multi-Layer Neural Networks and Non-linear Decision Boundary

Jeju National University Yungcheol Byun

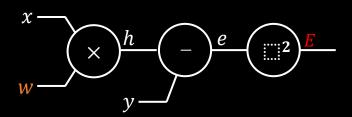
# Agenda

- Machine Learning revisited
- Linear decision boundary
- XOR problem
- Non-linearity and multi-layer neural networks
- Complex nonlinear boundary as you like

# Machine Learning

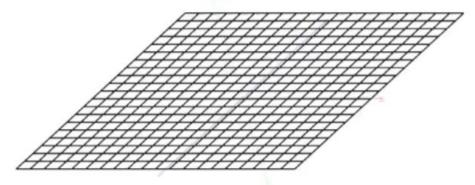


- Parameters(w, b) initialization randomly
- ② Building computation graph of E by TensorFlow framework
- $\bigcirc$  Foreword propagation by putting values into the graph and calculate E
- Back-propagation to get the influence of w, b on the error (applying chain rules)
- Update w, b to adjust a decision boundary
- 6 go to 3



### How to change the decision boundary

 $\begin{array}{ccc} & & \text{sigmoid(w1\cdot length} + \text{w2\cdot width} + \text{b)} \\ \text{db slope} & & \text{db shift} \\ w_1x_1 + w_2x_2 + b = 0 \\ & & \text{db rotation} \end{array}$ 



```
slope
rotation
shift
w1 = 0.00
w2 = 0.00
b = 0.00
```

# Machine Learning

```
import tensorflow as tf
#---- training data
x data = [-2, -1, 1, 2]
y data = [0, 0, 1, 1]
#---- a neuron
w = tf.Variable(tf.random normal([1]))
hypo = tf.sigmoid(x data * w)
#----- learning
cost = -tf.reduce_mean(y_data * tf.log(hypo) +
       tf.subtract(1., y_data) * tf.log(tf.subtract(1., hypo)))
train =
tf.train.GradientDescentOptimizer(learning rate=0.01).
minimize(cost)
```

# Machine Learning

```
sess = tf.Session()
sess.run(tf.global variables initializer())
for i in range(1001):
  sess.run(train) (3)(4)(5)
                                                    Learning finished after
                                                      1001 times updates
  if i % 100 == 0:
     print( ' w: ' , sess.run(w), ' cost: ' , sess.run(cost))
#---- test (classification)
x data = [-2, 4]
print(sess.run(hypo))
```

hypo = tf.sigmoid(x data \* w)

# Testing new data

- After learning,
- a neuron can classify new input data correctly.

```
#---- test (classification)
x_data = [-2, 4]
print(sess.run(hypo))
```

- When the computation graph is created, data is set only one time.
- Still old data in the computation graph.
- No feeding the new data[-2,4] into the precreated computational graph
- Therefore, not working!

- Marking certain place holders in a computational graph
- and then replace it with new data when it <u>runs</u>(evaluation).

sess.run()

import tensorflow as tf

```
#---- training data

x_data = [[-2], [-1], [1], [2]]

y_data = [[0], [0], [1], [1]]
```

- X = tf.placeholder (tf.float32)
- Y = tf.placeholder (tf.float32)

- 1. Place holders: X, Y
- 2.  $x_{data} \rightarrow X$ ,  $y_{data} \rightarrow Y$
- 3. Feeding real data when hypo, cost, and train operations are executed.

```
#---- a neuron
w = tf.Variable (tf.random_normal([1]))
hypo = tf.sigmoid(X * w)
```

```
\frac{\mathbf{X}}{\mathbf{W}} \times \frac{h}{\mathbf{Y}} \frac{e}{\mathbf{W}} \frac{e}{\mathbf{W}}
```

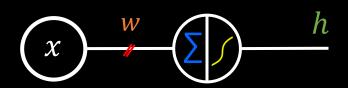
```
#----- learning
cost = -tf.reduce mean(Y * tf.log(hypo) +
    tf.subtract(1., Y) * tf.log(tf.subtract(1., hypo)))
train =
tf.train.GradientDescentOptimizer(learning rate=0.01).minimize(cost)
sess = tf.Session()
sess.run(tf.global variables initializer())
for i in range(1001):
  sess.run(train, feed dict={X:x data, Y:y data})
  if i % 100 == 0:
    print(sess.run(w), sess.run(cost feed_dict={X:x_data, Y:y_data}))
```

```
#---- testing(classification)
x_data = [-2, 4]
result = sess.run(hypo, feed_dict={X: x_data})
print(result)
```

# Lab 15.py

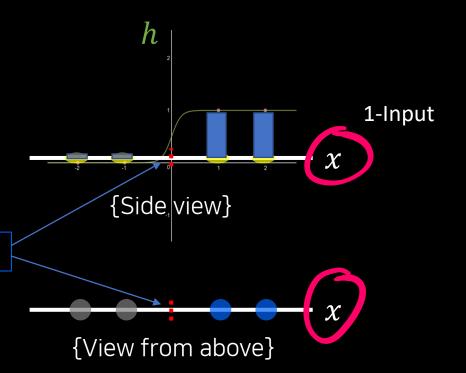
- Classification into one of four classes
- Using placeholders

# 1-Input Neuron

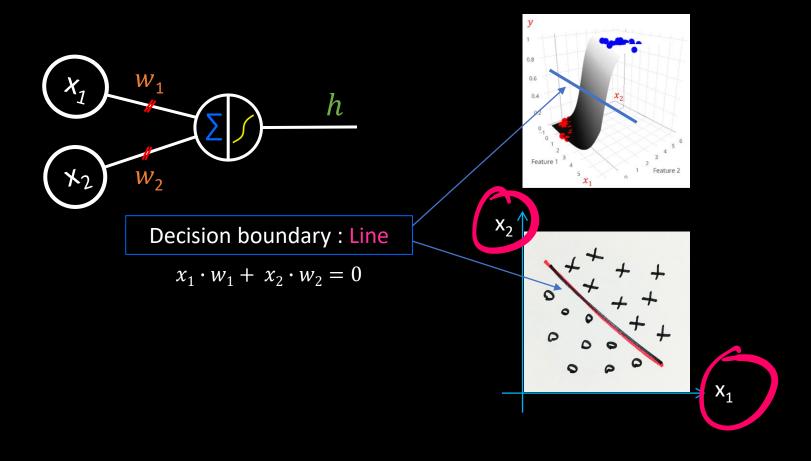


Decision boundary : Value

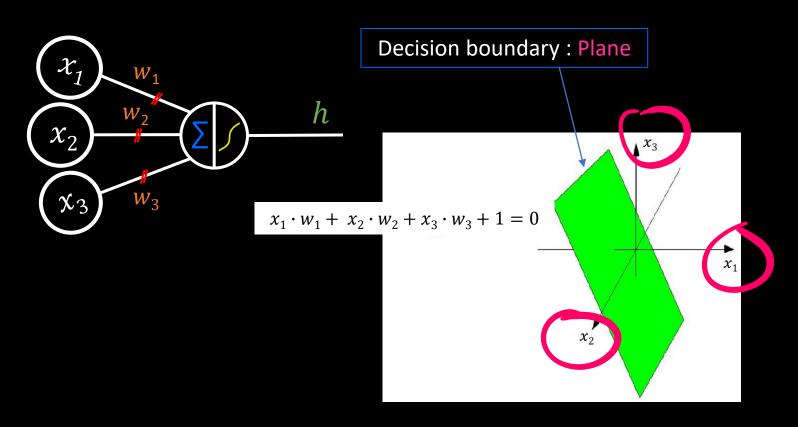
$$w \cdot x = 0$$
$$x = 0$$



# 2-Input Neuron



# 3-Input Neuron



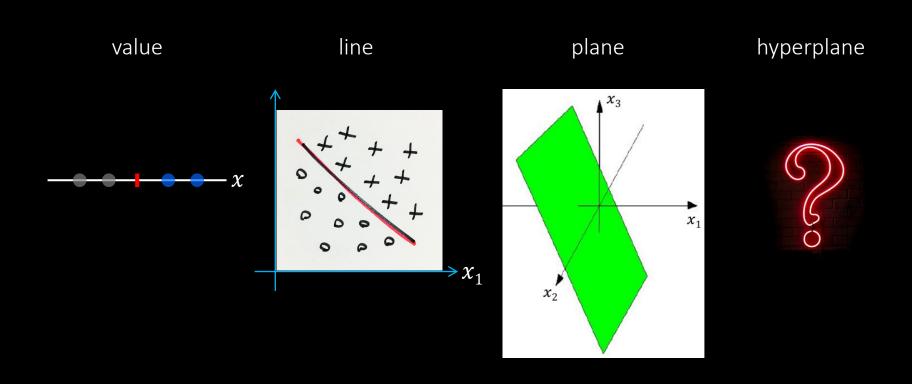
### More than 4 inputs?

$$x_1 w_1 + x_2 w_2 + x_3 w_3 + x_4 w_4 + b = 0$$

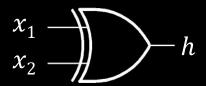
→ hyperplane

초평면

# Linear Decision Boundary



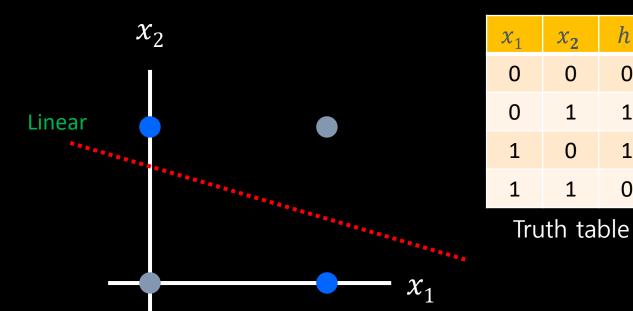
# XOR



0

1

0



View from above

### **XOR**

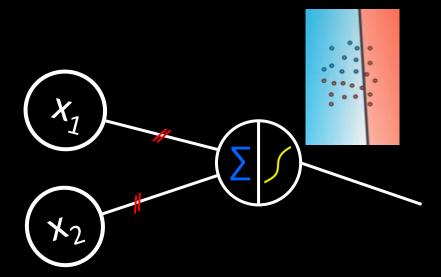
#### **Binary Cross-Entropy Loss**

- Number of class: 2 (0 or 1)
- 1-decision boundary for 2-class classification
- However, impossible to classify using a single linear decision boundary

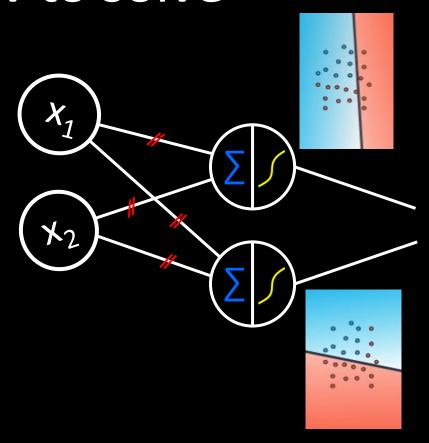
# Lab 16.py

- XOR problem
- A neuron, 1 linear decision boundary
- Cannot be solved!

# How to solve

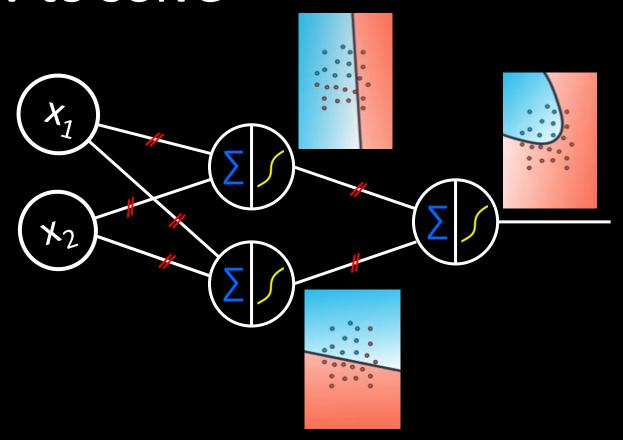


# How to solve



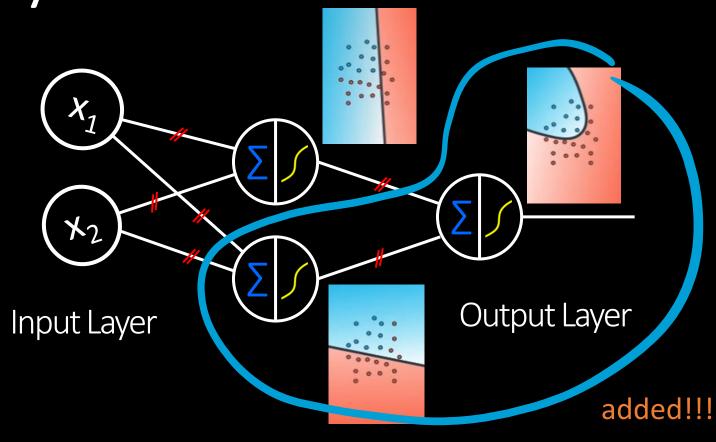
by Luis Serrano, A friendly introduction to Deep Learning, UDACITY

# How to solve

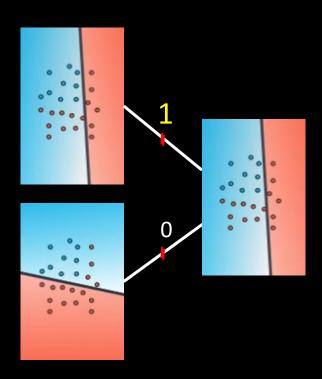


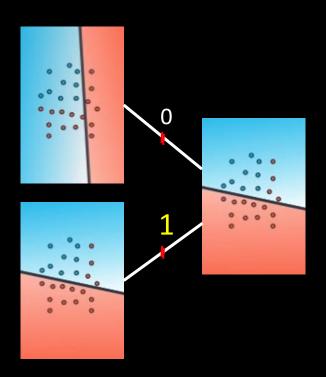
by Luis Serrano, A friendly introduction to Deep Learning, UDACITY

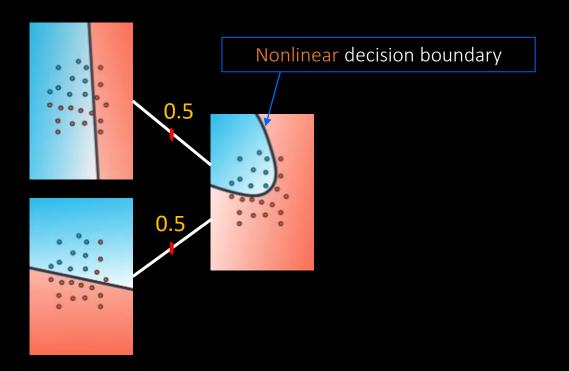
3-layer Neural Network



Hidden Layer





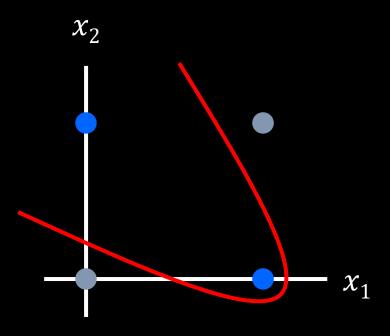


What is a linear decision boundary?

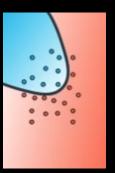
# 3-layer NN for <u>nonlinear</u> decision boundary

#### View from above

# XOR

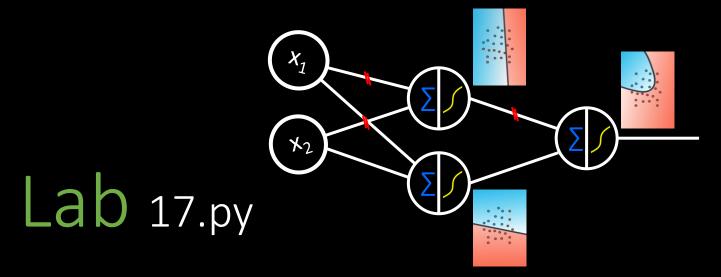




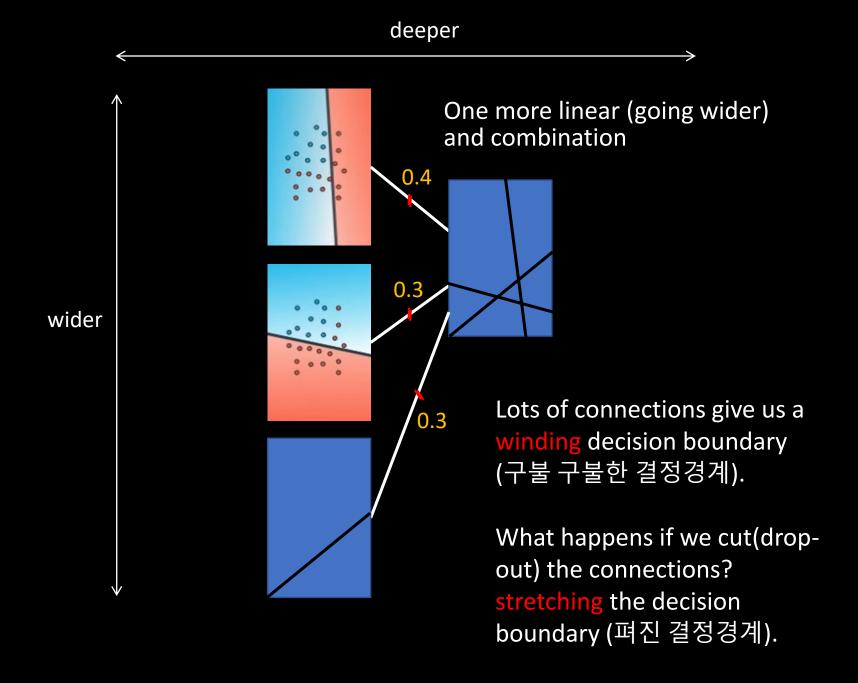




Side view



- Solving XOR gate problem using 3-layer neural network
- The way to create nonlinear decision boundary



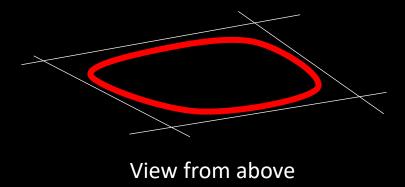
# Nonlinear Decision Boundary

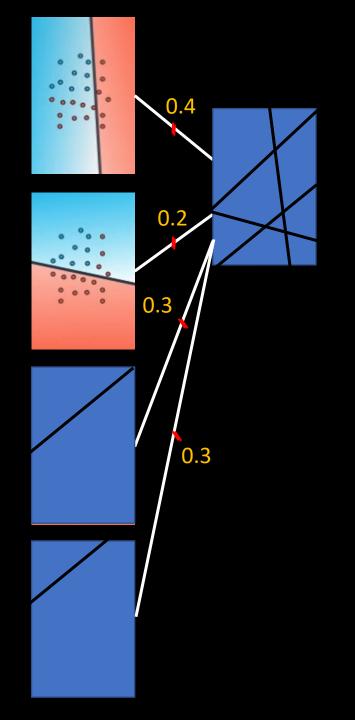
 Combination of three linear decision boundaries



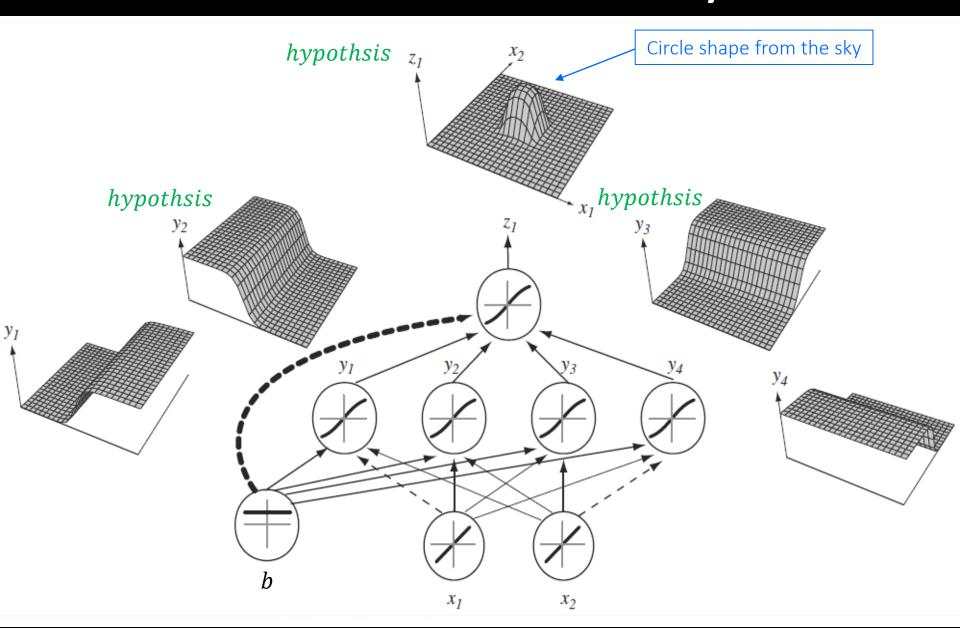
# Nonlinear Decision Boundary

Merging four linear decision boundaries





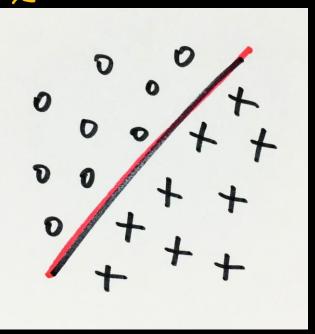
# Nonlinear Decision Boundary

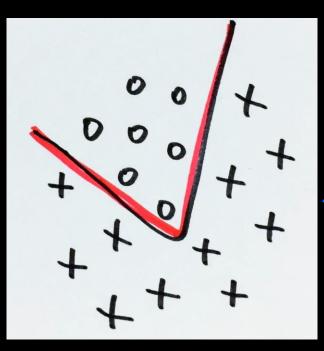


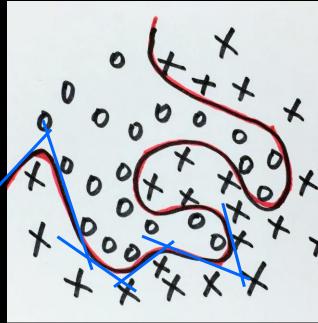


Side view

# As you wish (2 classes)



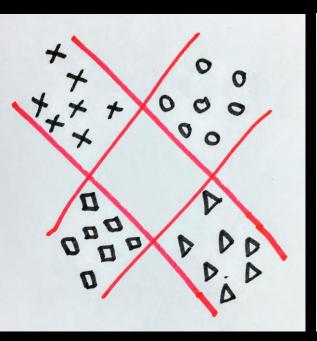


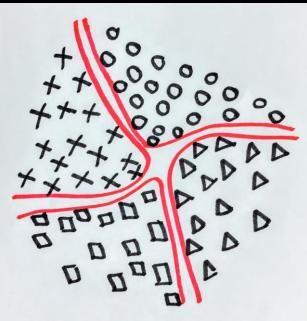


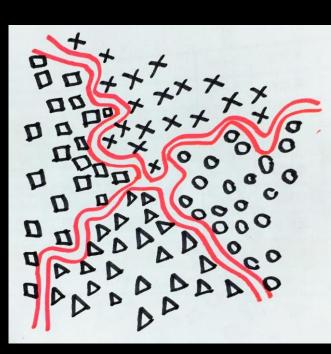
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View from above

# As you wish (4 classes)



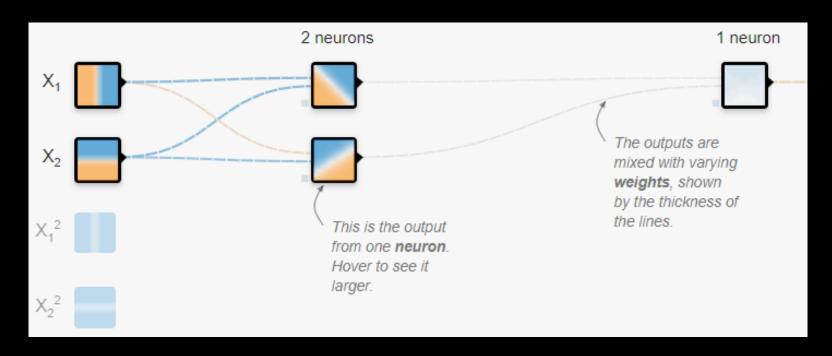




From the above

# More neurons (wider & deeper), more complex(detail) decision boundary

## http://playground.tensorflow.org



# As you wish

### go wider & deeper

- to make more complex nonlinear decision boundaries.
- We can classify anything we imagine.

# The way of machine learning

- Learning over and over again just like human being
- If it misrecognizes, just say 'Nope, you were wrong', which makes it update its weights to do better next time.
- Try it over and over again just like a child.

# Learning or Programming?

"This (machine learning) is the next transformation...the programming paradigm is changing. Instead of programming a computer, you teach a computer to learn something and it does what you want"

Eric Schmidt, Google



# Change of Paradigm

Not programming, but data-driven learning (parameter tuning)