#### Al and Deep Learning

# Linear Regression & Back-propagation

Jeju National University Yungcheol Byun

## Agenda

- Neuron and Regression
- Loss/Error/Cost Function
- Learning and Updating Weights
- Gradient/Slope
- Computation Graph
- Forward Propagation
- Backpropagation





After spending most of the ocean life, salmons go back home(river) where they were born.

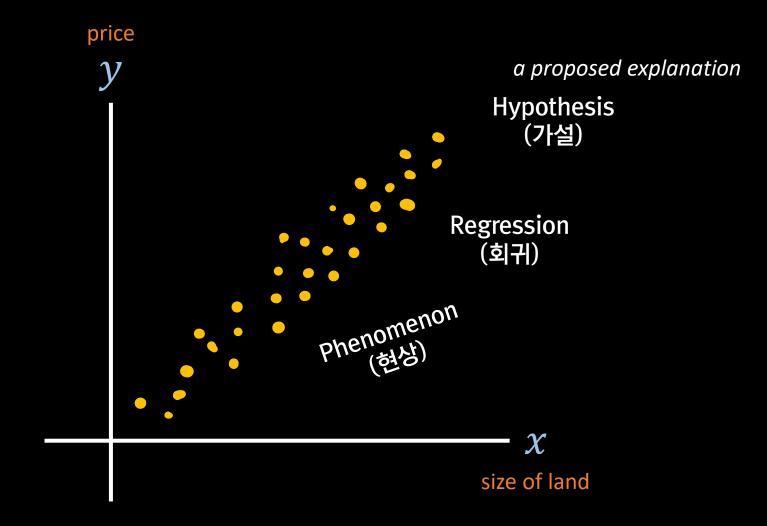
## Regression(회귀)

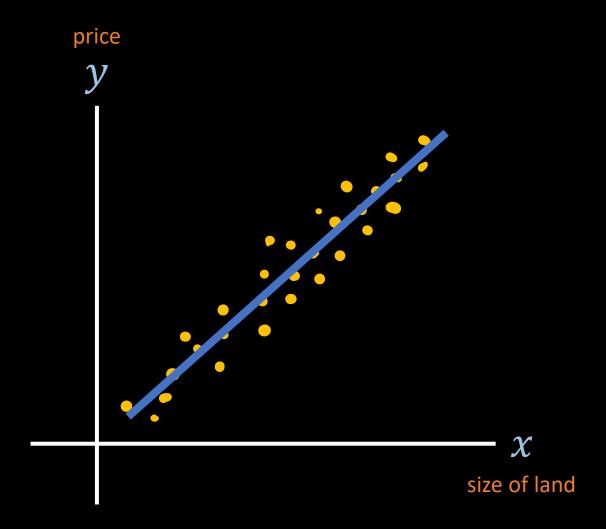
- Going back again.
- To describe a natural phenomena
- A term frequently used in anthropology(인류학) to present a natural tendency

What is 'a proposed <u>explanation</u> for a <u>phenomenon</u>'?

## Regression(회귀)

 Something (statistical measure) to determine the relationship between one dependent variable (usually denoted by Y, 종속변수) and a series of other independent variables X 독립변수 .







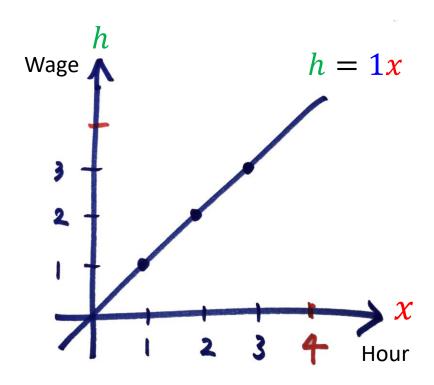
## Lab Linear Regression



#### www.desmos.com

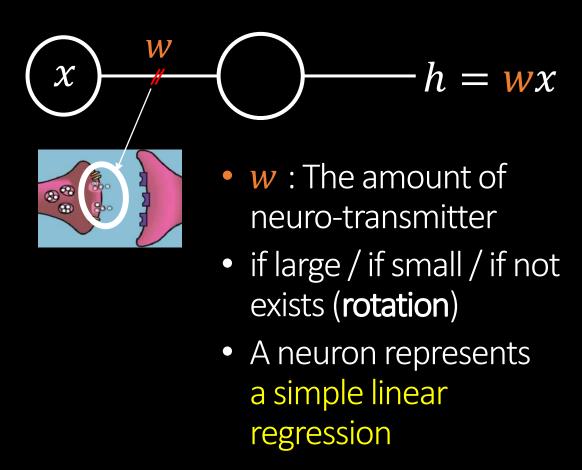
- 1. Draw a point(data) (1, 1)
- 2. Add (2, 2), (-1, -1), (-2, -2)
- 3. h = x
- 4. h = 2x
- 5. h = wx (rotation)
- 6. Move all of the points by adding 1 to y
- 7. h = wx + 1 (shifting)
- 8. h = wx + b (rotation and shifting)

#### www.desmos.com



## h = wx

## Neuron and regression



## Hypothesis

$$h = wx$$

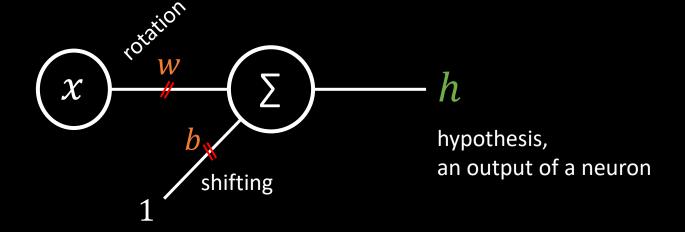
$$h = wx + b$$

An answer by a neuron

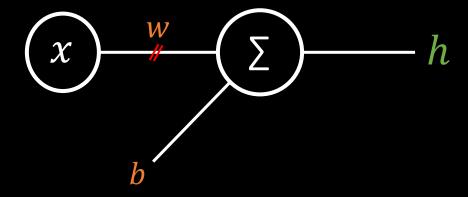


- hypothesis: a proposed explanation for a phenomenon (regression).
- Not proved yet, but it can represents the regression correctly after updating w.
- b? for better linear regression

#### The role of w and b



$$h = wx + b$$



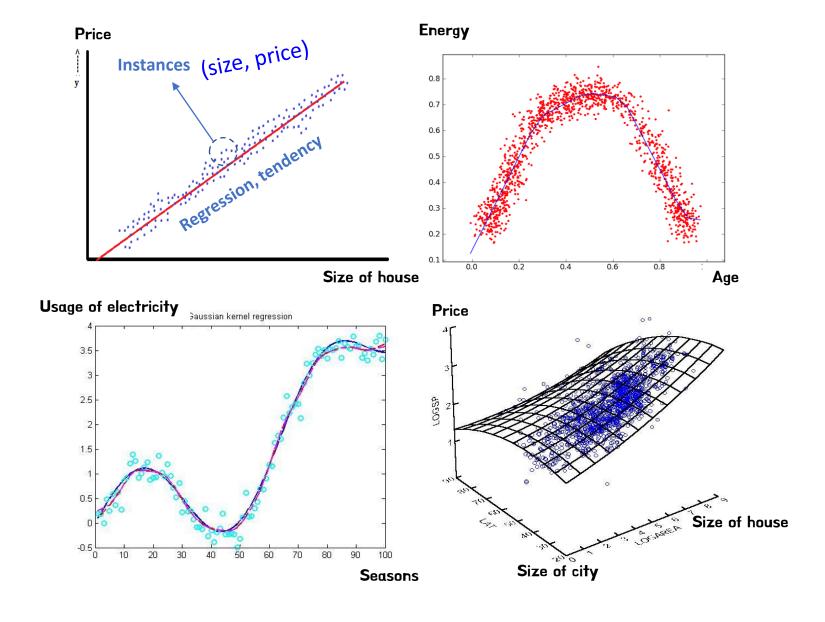
#### Linear Regression

# A regression expressed by linear combination of coefficients

$$h = wx + b$$

linear?
non-linear?
$$h = \frac{b}{-x}$$

### Examples of Linear Regression

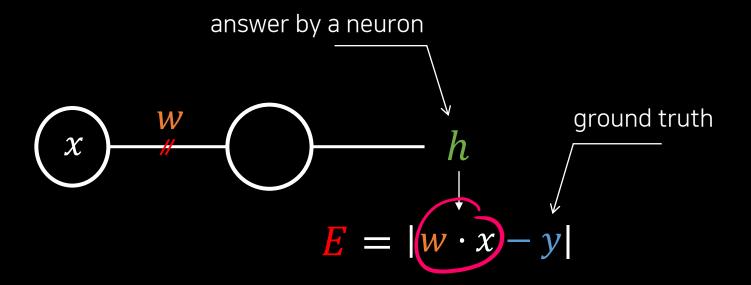


## How to learn (update w, b)

- Scolding or blaming the neuron if its answer is wrong.
- The neuron gets stress and automatically updates w and b to answer well next time so that the error(difference, stress) decreases.
- How can we measure the error?

#### Error function

loss function difference function stress function



#### Why absolute?

ex) age difference

#### Error function

The error is the difference between a neuron's answer and it's ground truth.

$$E = |hypothesis - y|$$
 $E = |w \cdot x - y|$ 

a.csv

'1 hour, then 1 USD' 
$$\longrightarrow$$
  $\begin{bmatrix} x_i & y_i \\ 1 & 1 \end{bmatrix}$  data, experience

$$E = |w \cdot 1 - 1|$$

Supervised Learning

지도학습

#### www.desmos.com

```
1. Plot (1, 1)

2. h = w \cdot x

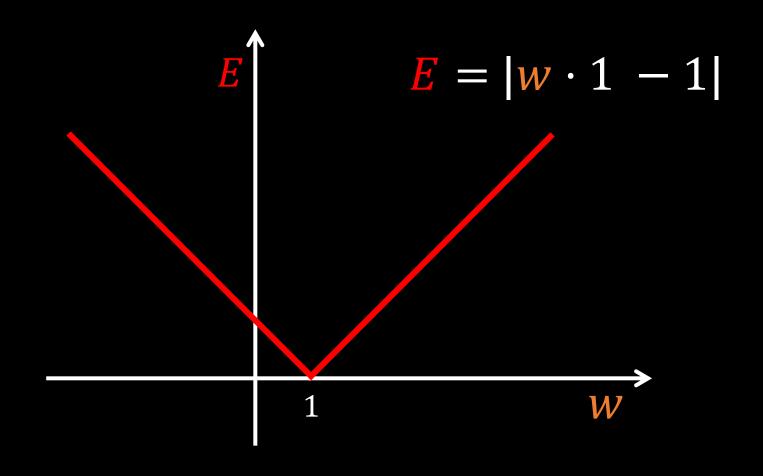
3. E = w \cdot 1 - 1

4. E = |w \cdot 1 - 1|

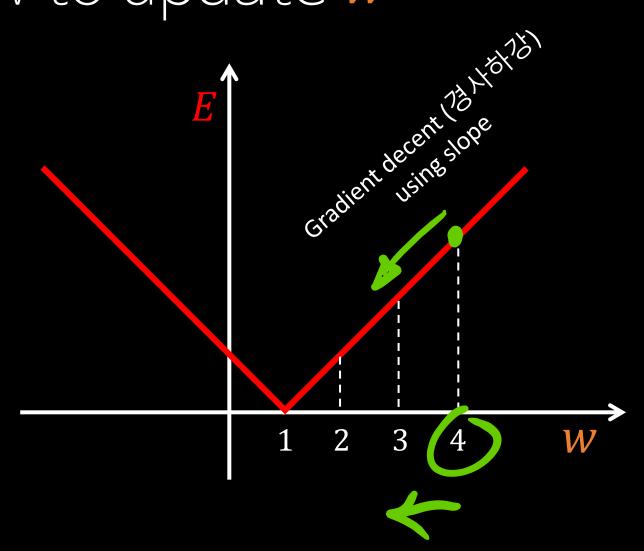
5. (w, E)
```



### Error Function of w



## How to update w



## How to update w learning rate (ex, 1) $w = w - \alpha \cdot \text{Slope}$ $\Delta E$ $\Delta E$ $\Delta w$ $\int_{1}^{1} \Delta w$

## How to update w learning rate (ex, 1) $w = w - \alpha \cdot Slope$ $-2 - 1 \cdot (-1)$ $\Delta E$ $\Delta E$ $\Delta w$ 0 1

$$w = 4, \alpha = 1, Slope = 1$$

$$w = w - \alpha \cdot \text{Slope}$$

$$4 - 1 \cdot 1 \longrightarrow 3 \qquad \text{Error } E = 2$$

$$3 - 1 \cdot 1 \longrightarrow 2 \qquad \text{Error } E = 1$$

$$2 - 1 \cdot 1 \longrightarrow 1 \qquad \text{Error } E = 0$$

$$w = -2, \alpha = 1, Slope = -1$$

$$w = w - \alpha \cdot \text{Slope}$$

$$-2 - 1 \cdot (-1) \longrightarrow -1 \quad \text{Error } E = 2$$

$$-1 - 1 \cdot (-1) \longrightarrow 0 \quad \text{Error } E = 1$$

$$0 - 1 \cdot (-1) \longrightarrow 1 \quad \text{Error } E = 0$$

$$w = -2, \alpha = 2, Slope = -1$$

$$w = w - \alpha \cdot \text{Slope}$$

$$-2 - 2 \cdot (-1) \longrightarrow 0 \qquad \text{Error } E = 1$$

$$0 - 2 \cdot (-1) \longrightarrow 2 \qquad \text{Error } E = 1$$

$$2 - 2 \cdot (1) \longrightarrow 0 \qquad \text{Error } E = 1$$

$$0 - 2 \cdot (-1) \longrightarrow 2 \qquad \text{Error } E = 1$$

$$2 - 2 \cdot (1) \longrightarrow 0 \qquad \text{Error } E = 1$$

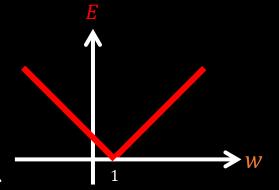
$$E = |w \cdot x - y|$$

Absolute Error

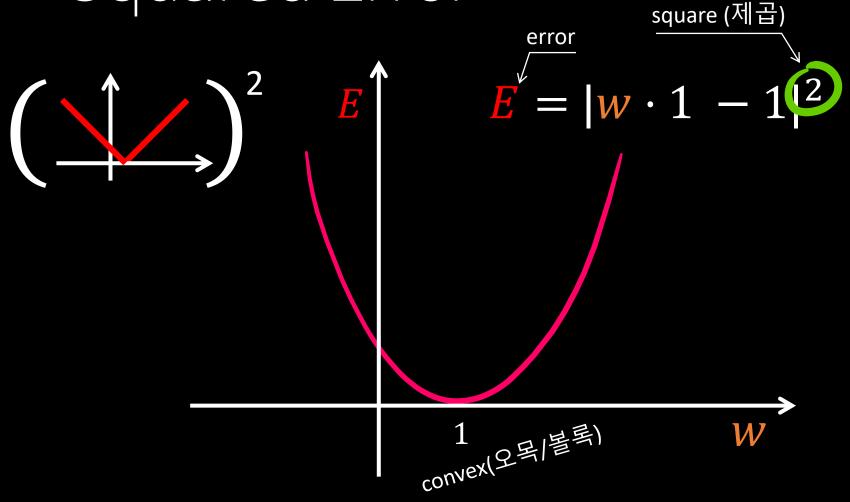
#### L1 Loss function

#### <u>Issues</u> in the absolute error

- Always the slope is 1 or -1 regardless of the value of w
- Therefore, the same speed in movement
- No guarantee for convergence of the value of w which gives 0 or almost 0 in the error.

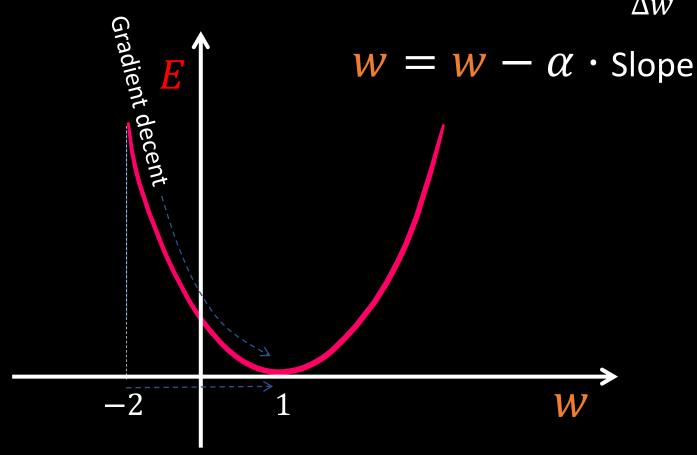


## Squared Error

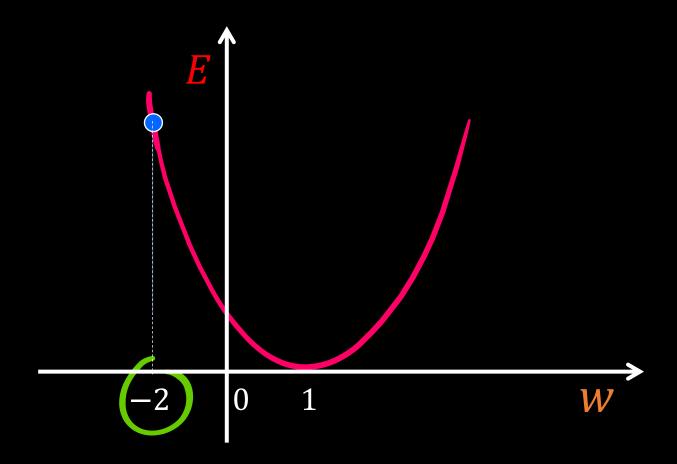


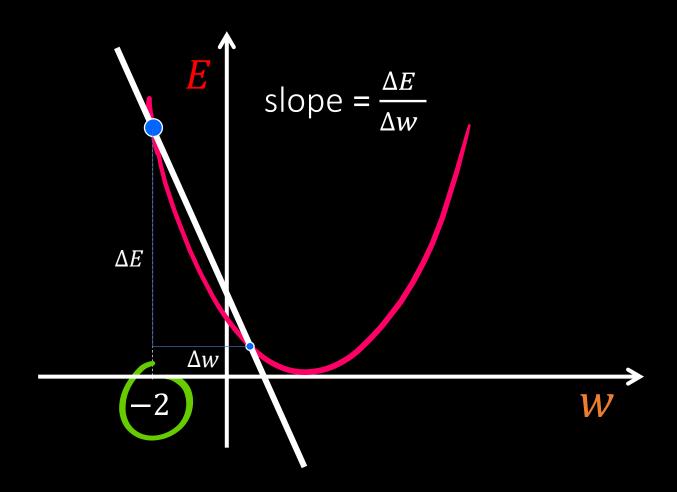
## How to update w

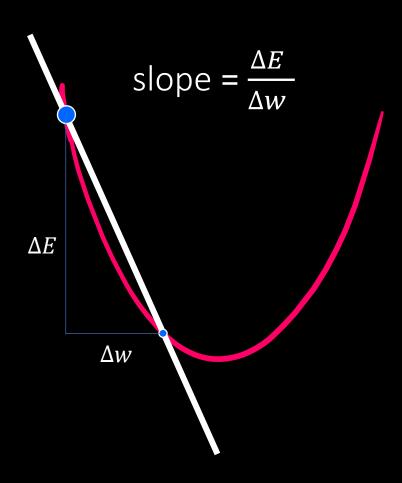
 $\frac{\Delta E}{\Delta w}$ 

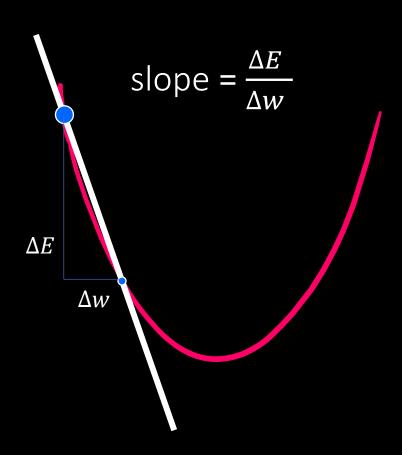


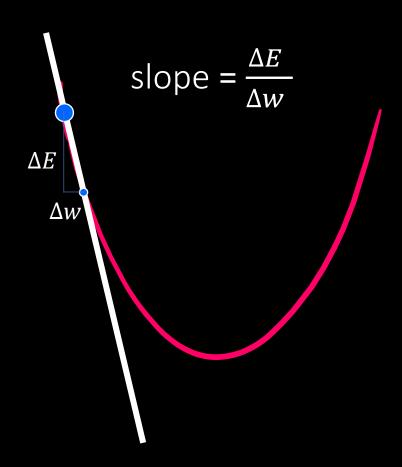
## How to update w



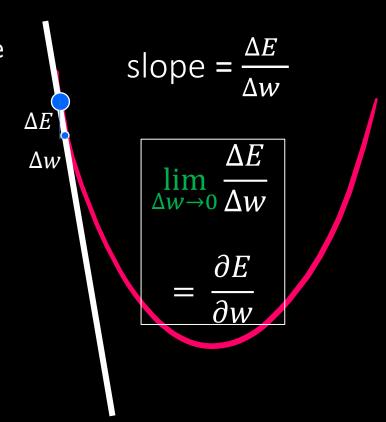


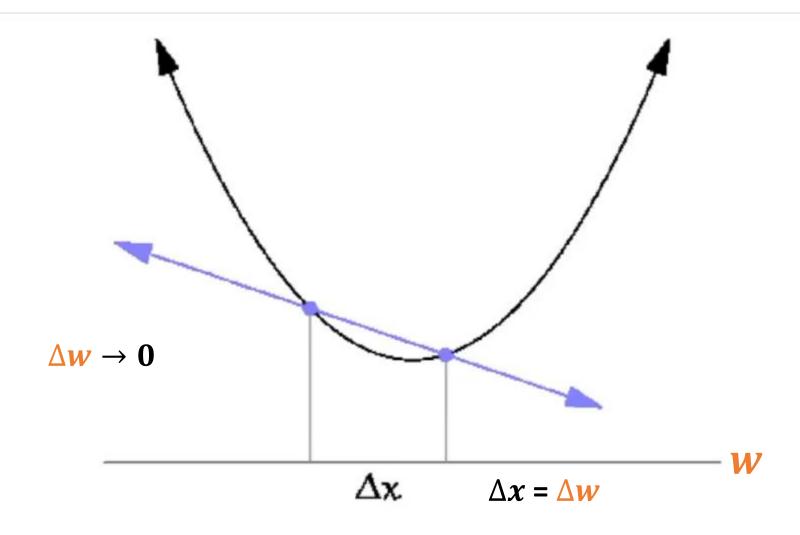






접선·Tangent line





#### Numerical differentiation

- ① cutting into a number of minute lines (미분)
- ② drawing a line connection both ends of a line → a tangent line

$$\lim_{\Delta w \to 0} \frac{\Delta E}{\Delta w}$$

$$=\frac{\partial E}{\partial w}$$

= 미분 (잘게 나누다.)

$$w = w - \alpha * Slope$$

$$w = w - \alpha \frac{\partial E}{\partial w}$$

 $\alpha$  = learning rate(ex, 0.1)

$$E = |w \cdot 1 - 1|^2$$

Squared Error

#### L2 Loss function

# Advantages

- Fast movement from both sides and fine(slow) tuning at the valley(center) area
- Different slope/gradient according to the value of w
- Steep slope means that the error is big and w is far from the optimal value.
- We can get the slope(gradient) at any place(differentiable).

#### In case of L1 Loss

- Always the same slope in the error graph regardless of the value of w
- Therefore, the same speed in the movement
- Not sure to get the w value which gives 0 error or almost 0
- No way to guess the current value of w
- Not differentiable when w is 1

# Multiple Data

a.csv

For 3 instances of data

x <sub>i</sub>	y <sub>i</sub>
1	1
2	2
3	3

data, experience



Add (2, 2), (3, 3)

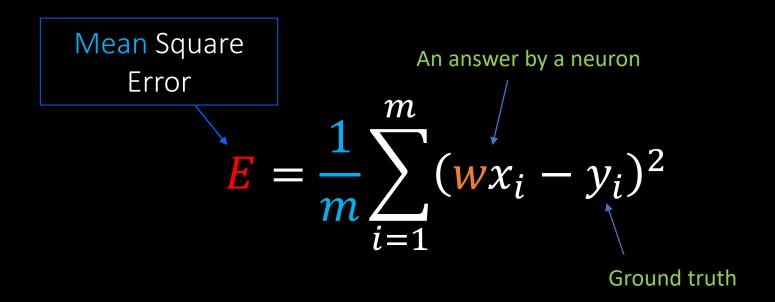
$$E = \frac{1}{3} \sum_{i=1}^{3} (wx_i - y_i)^2$$

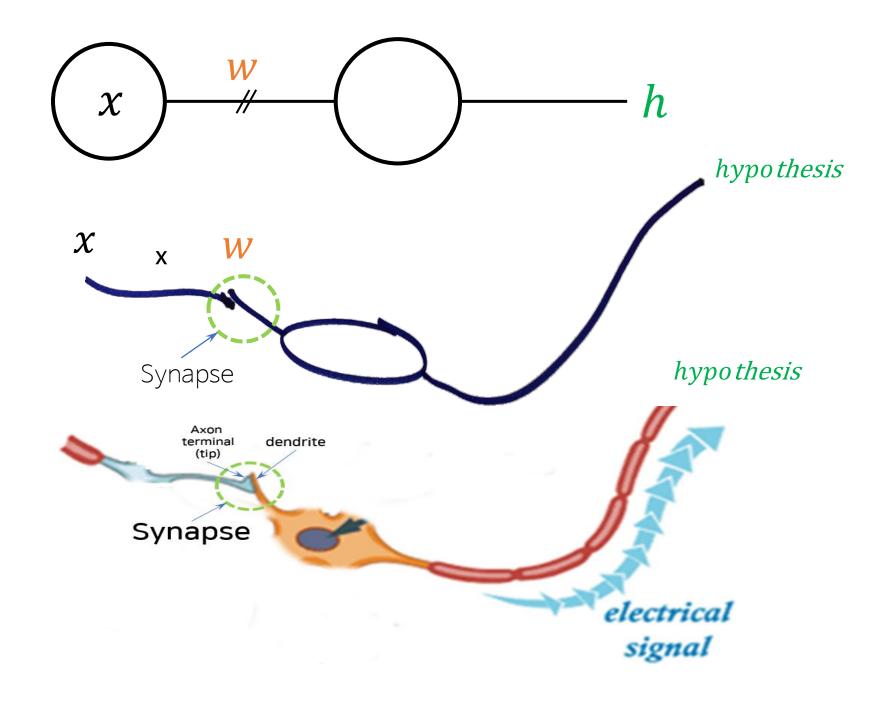
Draw (w, E)

$$E = \frac{1}{3} ((w \cdot 1 - 1) + (w \cdot 2 - 2) + (w \cdot 3 - 3))$$

# Multiple Data

In case of m instances,





# The meaning of slope

Steep slope

$$\frac{\Delta E}{\Delta w}$$

The error E will change drastically when we change w.

.....

Gentle slope

$$\frac{\Delta E}{\Delta w}$$

The error E changes just a little bit when we change w.

 $\lim_{\Delta w \to 0} \frac{\Delta E}{\Delta w} \to \frac{\partial E}{\partial w}$ 

Therefore,

# Slope/Gradient

means the influence of w change on error E.

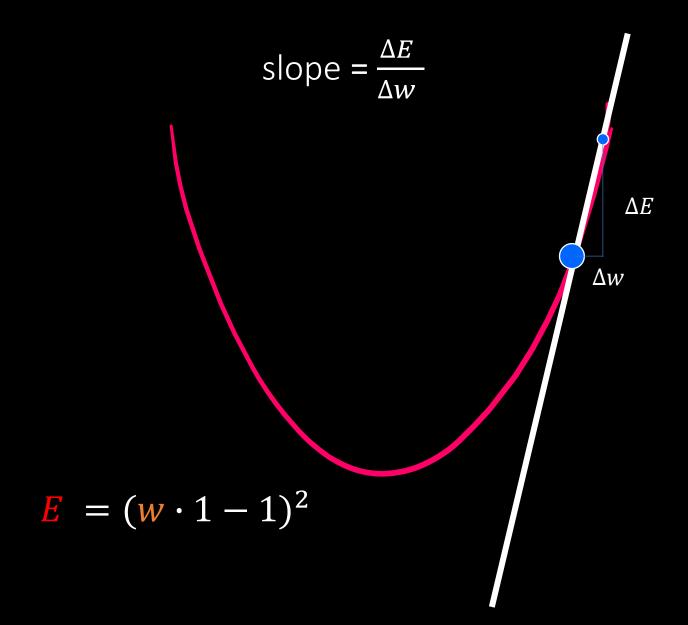
따라서 경사/기울기는 ₩ 의 변화가 오류(E)에 얼마나 영향을 미치는지 의미(□치는 영향력)

얼굴에 기미

### (Q) Compute the influence

$$E = (wx - y)^2$$

Let's assume that data (x, y) is (1, 1), then compute the influence of w change on E when the current w is equal to 3.



#### Method 1 numerical gradient

$$E = (w \cdot 1 - 1)^2$$

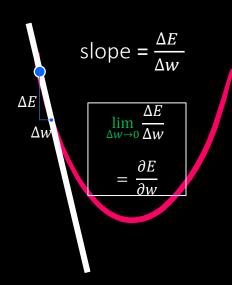
w: 3 -> E: 4

w: 3.00001 -> E: 4.00004

 $\Delta w = 0.00001$ 

 $\Delta E = 0.00004$ 

$$\frac{\Delta E}{\Delta w} = \frac{0.00004}{0.00001} = 4$$



Slope = Influence of 
$$w$$
 change = 4

#### Method2 derivative, differential equation

$$E = (w \cdot 1 - 1)^{2}$$

$$\lim_{\Delta w \to 0} \frac{\Delta E}{\Delta w} = \frac{\partial E}{\partial w} = \frac{\partial}{\partial w} (w \cdot 1 - 1)^{2}$$

$$= 2(w \cdot 1 - 1)$$

Therefore, when 
$$w = 3$$
, the gradient is  $2(3 - 1) = 4$ 

#### How to update w (Learning)

- 1. Initialize w with a random value (ex,3)
- 2. Get the influence(slope) of w change on E
- 3. Update w using below eq:

Parameter Tuning

$$\mathbf{w} = \mathbf{w} - \alpha * slope$$

4. Go to step 2

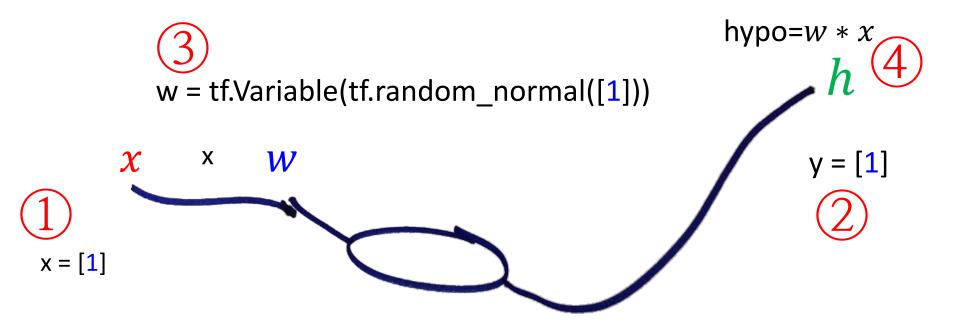
Loop

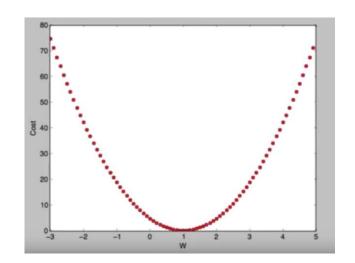
# TensorFlow Google



- Machine learning framework by Google
- Tuning parameters including w automatically instead of us
- Define w inside of TensorFlow to be tuned (managed) by it
- Hypothesis and cost\_function(E)

#### Linear Regression using TF





cost\_function = (hypo – y) \*\* 2
$$E = (\text{hypo} - y)^2$$

## Download myml.git

https://github.com/yungbyun/myml.git

- 1) Run DOS prompt
- 2) git clone https://github.com/yungbyun/myml.git
- 3) Open using PyCharm (File | Open...)

# Lab o1.py Finding w in linear regression

```
import tensorflow as tf
                                                         E = |w \cdot x - y| ** 2
#---- training data
x data = [1]
y_{data} = [1]
                                                               train operation to
#---- a neuron / neural network
w = tf.Variable(tf.random_normal([1]))
                                                              update w to minimize
hypo = w * x_data
                                                                    error(E)
#---- learning
cost = (hypo - y_data) ** 2
train = tf.train.GradientDescentOptimizer(learning_rate=0.01).minimize(cost)
sess = tf.Session()
sess.run(tf.global_variables_initializer())
for i in range(1001):
    sess.run(train) #1-run, 1-update of w \rightarrow 1001 updates
    if i % 100 == 0:
        print('w:', sess.run(w), 'cost:', sess.run(cost))
#---- testing(prediction)
```

 $x_{data} = [2]$ 

print(sess.run(x\_data \* w))

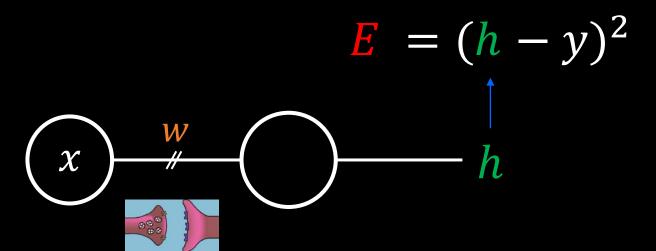
#### import tensorflow as tf

import tensorflow.compat.v1 as tf
tf.disable\_v2\_behavior()

sess.run(train)

# How to update w in TensorFlow

**Error Computation Graph** 



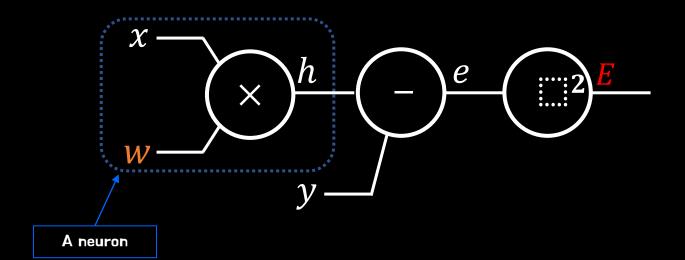
$$E = (wx - y)^2$$

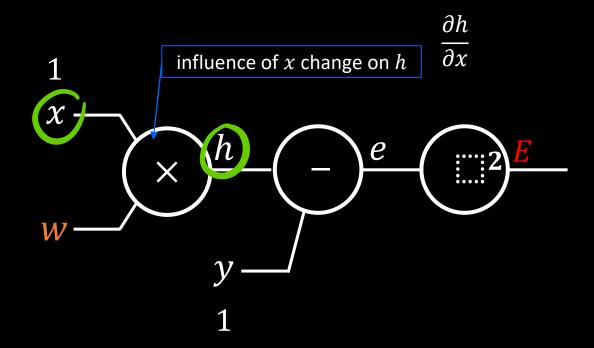
# Loss/error function (L2)

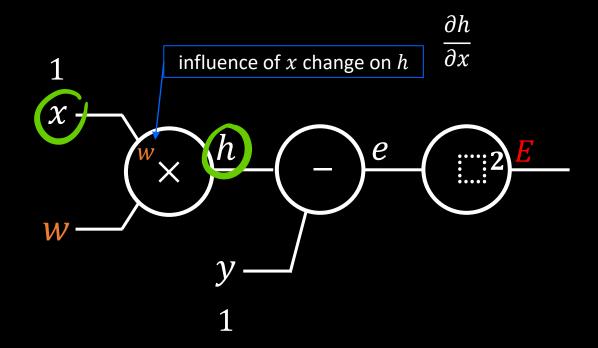
$$E = (wx - y)^2$$

- The part representing a neuron
- Where is a synapse?
- Which one is an input data?
- The output of a neuron
- Find hypothesis
- Find a correct answer or ground truth.
- Imagine *E* having multiple inputs.

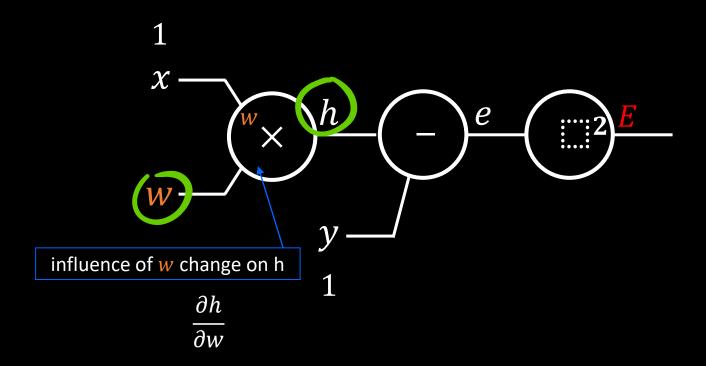
$$E = (w \cdot x - y)^2$$

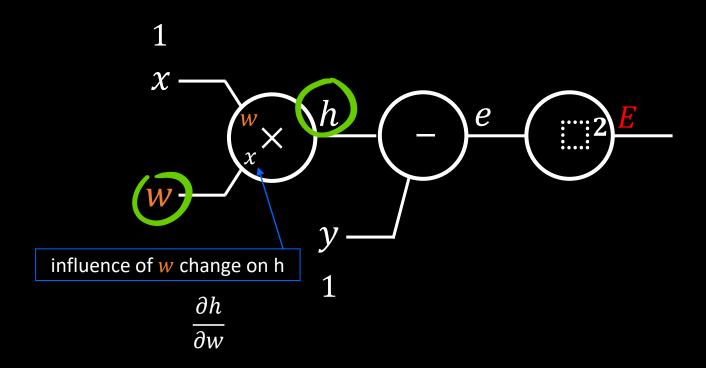


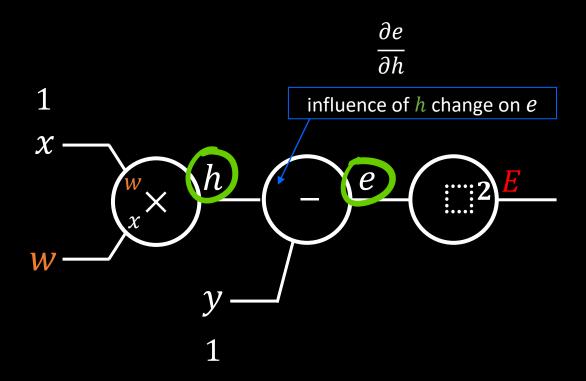


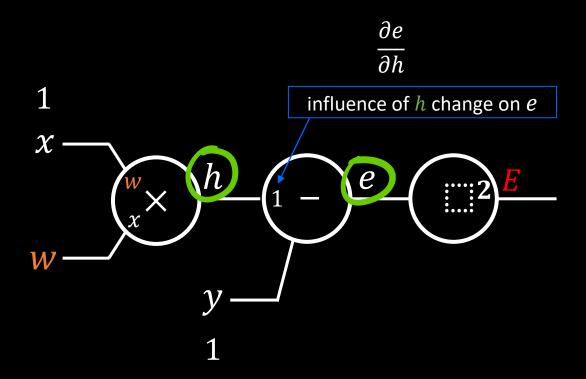


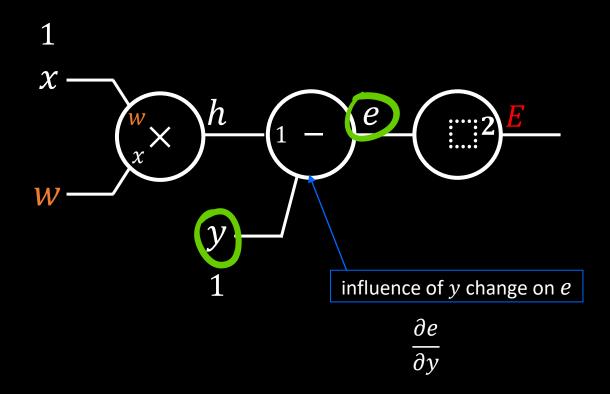
### Local gradient

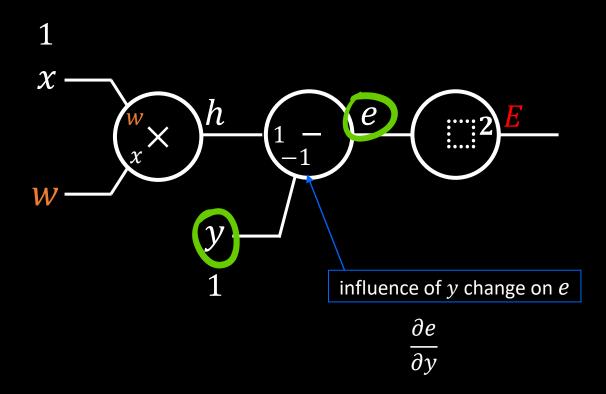


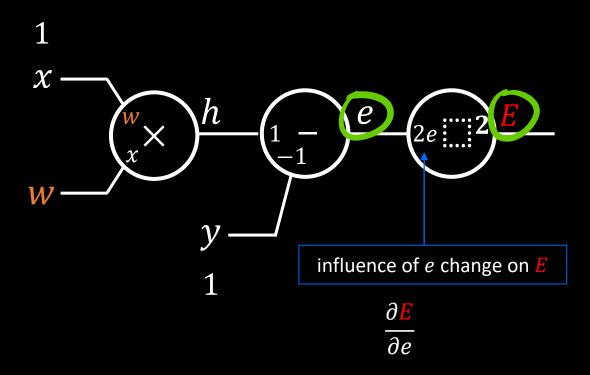




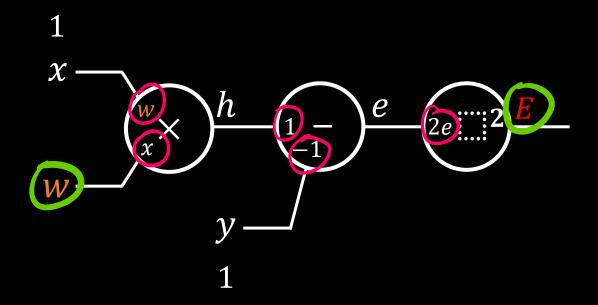






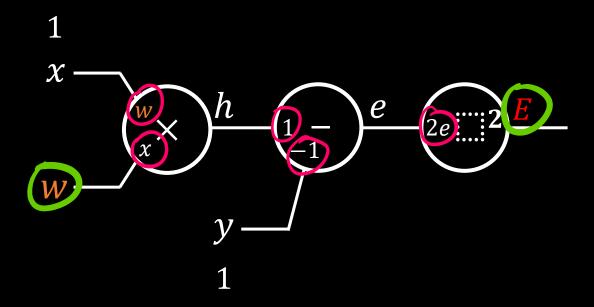


#### 5 Local Gradients in the gates

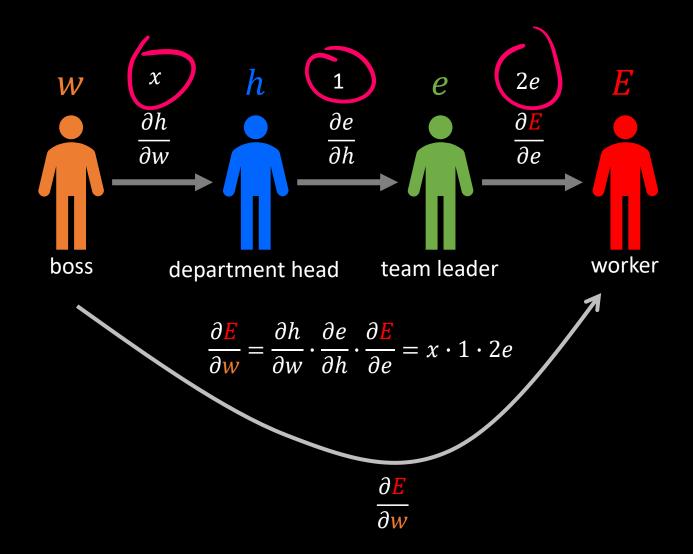


How can we get the influence of w change on E?

#### 5 Local Gradients in gates



#### Influence between persons

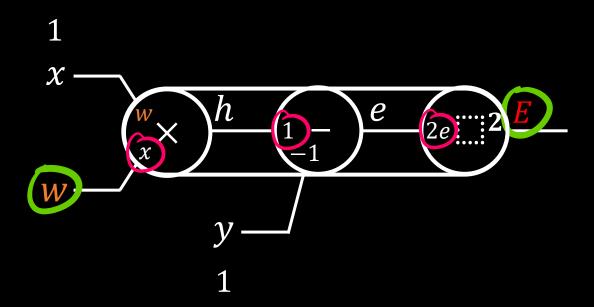


### The influence of w change on E

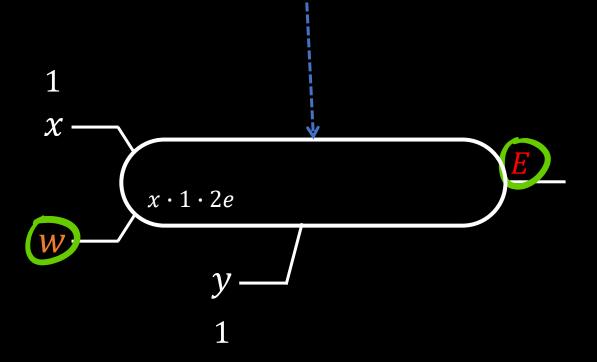
$$\frac{\partial \mathbf{E}}{\partial \mathbf{w}} = \frac{\partial h}{\partial \mathbf{w}} \times \frac{\partial e}{\partial h} \times \frac{\partial \mathbf{E}}{\partial e}$$

Chain rule!

#### Merging the Gates

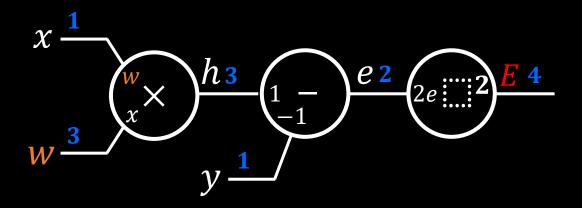


#### Composite Gate



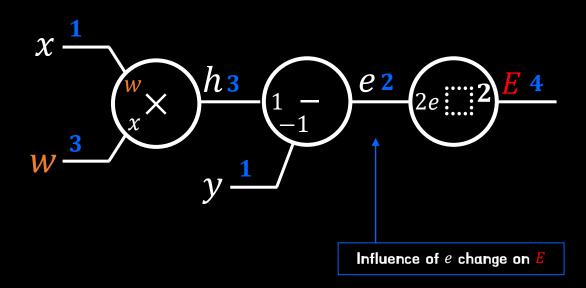
#### Forward propagation

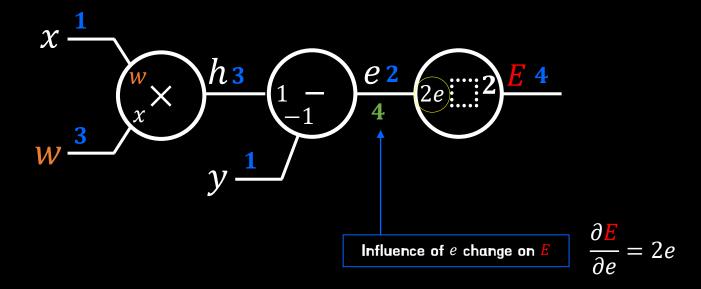
Let (x, y) = (1, 1) and w = 3, then compute E.

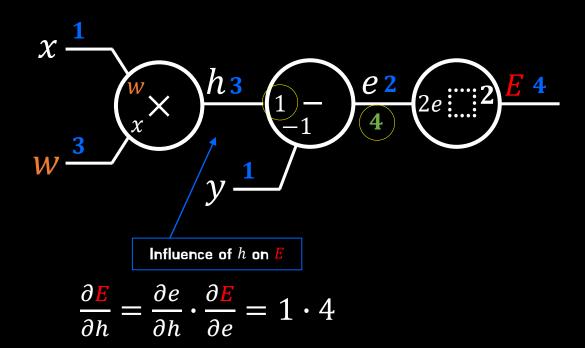


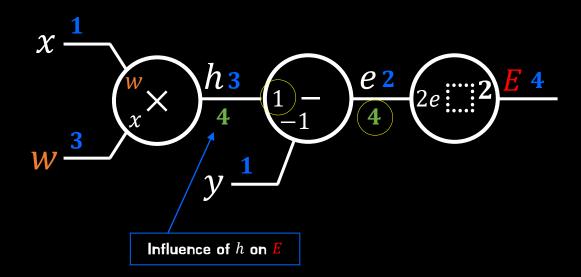
### Error is big (4), so let's update w

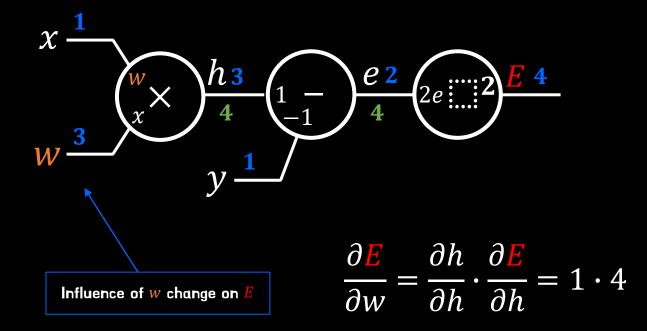
using back-propagation.

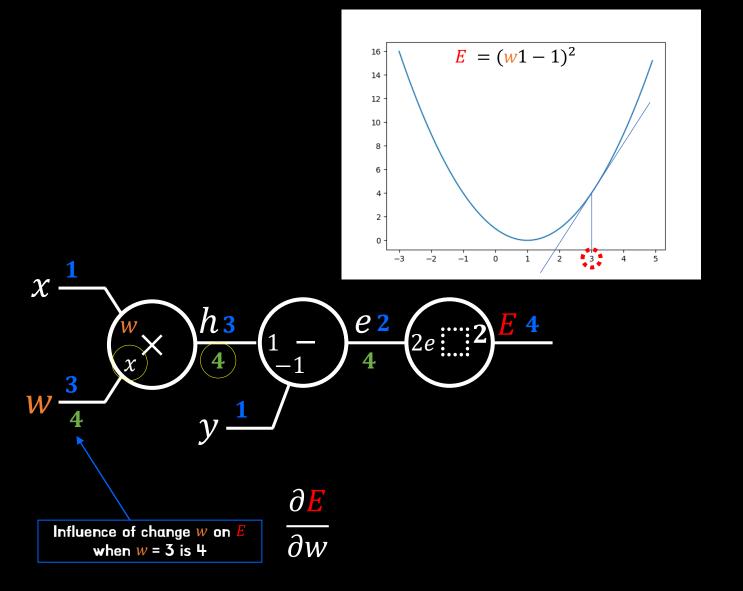












Back-propagation, the process to apply chain rules

 $\frac{\partial E}{\partial w}$ 

$$\frac{\partial \mathbf{E}}{\partial \mathbf{w}}$$

$$w = 3 - 0.1 * 4$$
  
 $w = 2.6$  (updated!)

Tuned parameter after 1 step learning

After enough number of steps (epochs), the parameter w will be optimized properly.

by Paul Webros (1974, 1982) and

Geoffrey Hinton (1986)



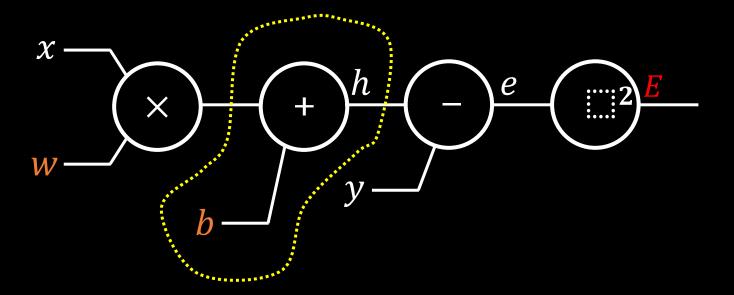
Yann LeCun (his post doc)

```
import tensorflow as tf
#---- training data
x_{data} = [1]
y_{data} = [1]
                                                                      train operation to
#---- a neuron / neural network
                                                                        update w to
w = tf.Variable(tf.random.normal([1]))
                                                                     minimize cost(error)
hypo = w * x_data
#---- learning
cost = (hypo - y_data) ** 2
train = tf.train.GradientDescentOptimizer(learning_rate=0.01).minimize(cost)
sess = tf.Session()
sess.run(tf.global_variables_initializer())
for i in range(1001):
    sess.run(train) # 1-run, 1-update of W \rightarrow 1001 updates
    if i % 100 == 0:
        print('w:', sess.run(w), 'cost:', sess.run(cost))
#---- testing(prediction)
x_{data} = [2]
print(sess.run(x_data * w))
```

#### Extension of the Graph

• adding bias **b** (one more plus gate)

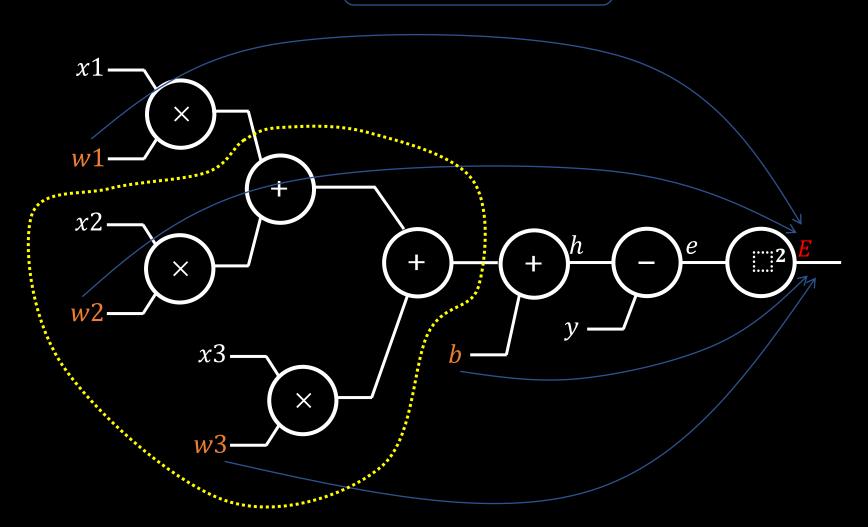
$$E = ((wx + b) - y)^2$$



#### Extension of the Graph

• a neuron with 3 inputs (2 more + gate)

$$E = ((w1x1 + w2x2 + w3x3 + b) - y)^2$$



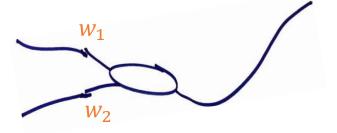
## Learning, making the connection better

#### Cost (Error) graph

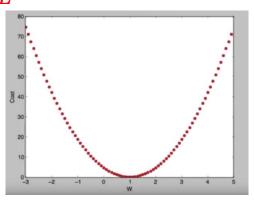




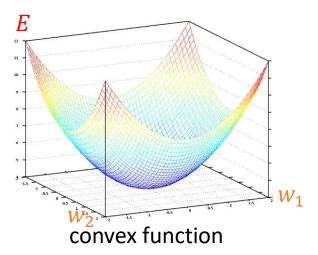
$$E = (w_1 \cdot 1 + w_2 \cdot 1 - 1)^2$$







#### convex function



## Lab 02.with\_bias.py Parameter tuning including bias

# Lab 03.py Using multiple data

#### Lab 04.py

## Training a neuron having multiple inputs