

# Autoencoder: Grayscale to color image

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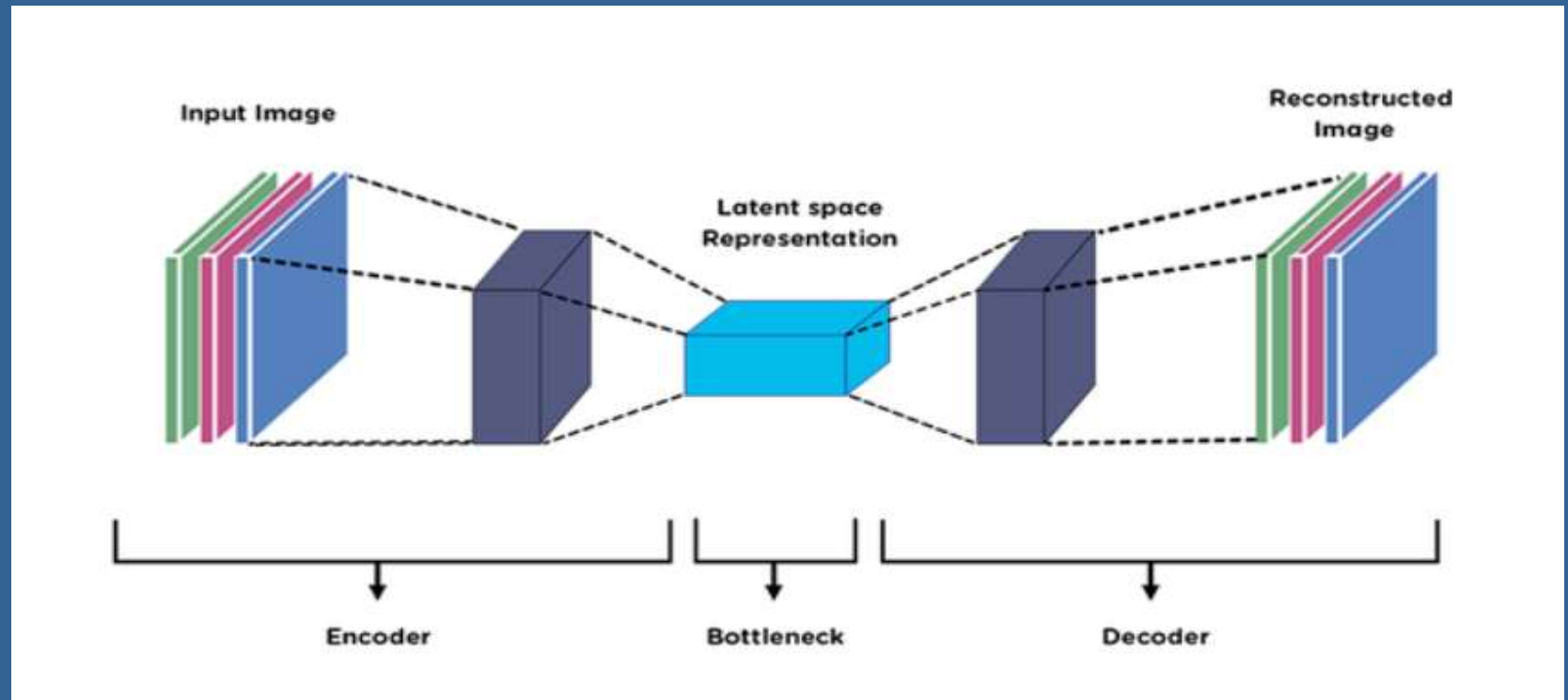
오지훈

# Image Colorization



Image colorization using different softwares require large amount of human effort, time and skill. But special type of deep learning architecture called autoencoder has made this task quiet easy. Automatic image colorization often involves the use of a class of convolutional neural networks (CNN) called autoencoders. These neural networks are able to distill the salient features of an image, and then regenerate the image based on these learned features.

# Introduction



Autoencoders are a special type of deep learning architecture that consist of two networks: an encoder and a decoder. The encoder, through a series of CNN and downsampling, learns a reduced dimensional representation of the input data, while the decoder, through the use of CNN and upsampling, attempts to regenerate the data from these representations. A well-trained decoder is able to regenerate data that is identical or as close as possible to the original input data. Autoencoders are generally used for anomaly detection, denoising images, and colorizing images. Here, I am going to colorize landscape images using an autoencoder.

# Import necessary libraries

```
import numpy as np
import tensorflow as tf
import keras
import cv2
from keras.layers import MaxPool2D, Conv2D, UpSampling2D, Input, Dropout
from keras.models import Sequential
from keras.preprocessing.image import img_to_array
import os
from tqdm import tqdm
import re
import matplotlib.pyplot as plt
```

# Code\_Getting landscape image data, resizing them and appending in array

```
def sorted_alphanumeric(data):
    convert = lambda text: int(text) if text.isdigit() else text.lower()
    alphanum_key = lambda key: [convert(c) for c in re.split('([0-9]+)', key)]
    return sorted(data, key = alphanum_key)

# defining the size of the image
SIZE = 160
color_img = []
path = '../input/landscape-image-colorization/landscape Images/color'
files = os.listdir(path)
files = sorted_alphanumeric(files)
for i in tqdm(files):
    if i == '6000.jpg':
        break
    else:
        img = cv2.imread(path + '/' + i, 1)
        # open cv reads images in BGR format so we have to convert it to RGB
        img = cv2.cvtColor(img, cv2.COLOR_BGR2RGB)
        #resizing image
        img = cv2.resize(img, (SIZE, SIZE))
        img = img.astype('float32') / 255.0
        color_img.append(img_to_array(img))
```

## Sorted\_alphanumeric, OpenCV

To get the image in sorted order

## DataSources

Landscape color and grayscale images  
(each 6000 files)

## Code\_Getting landscape image data, resizing them and appending in array

```
gray_img = []
path = '../input/landscape-image-colorization/landscape Images/gray'
files = os.listdir(path)
files = sorted_alphanumeric(files)
for i in tqdm(files):
    if i == '6000.jpg':
        break
    else:
        img = cv2.imread(path + '/' + i, 1)

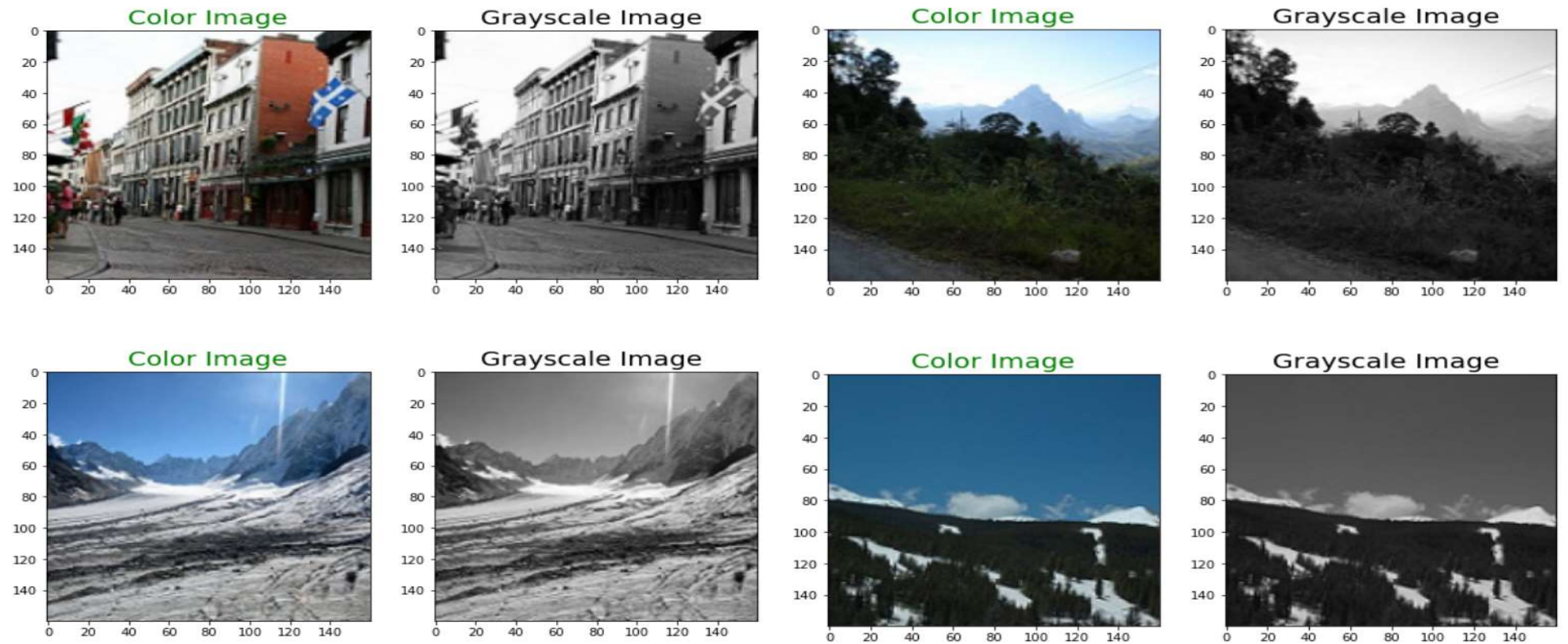
        #resizing image
        img = cv2.resize(img, (SIZE, SIZE))
        img = img.astype('float32') / 255.0
        gray_img.append(img_to_array(img))
```

84%|██████████| 6000/7129 [00:35<00:06, 171.07it/s]

84%|██████████| 6000/7129 [00:31<00:05, 191.33it/s]



# Code\_Plotting Color image and it's corresponding grayscale image



## Code\_Slicing and reshaping

```
train_gray_image = gray_img[:5500]
train_color_image = color_img[:5500]

test_gray_image = gray_img[5500:]
test_color_image = color_img[5500:]
# reshaping
train_g = np.reshape(train_gray_image, (len(train_gray_image), SIZE, SIZE, 3))
train_c = np.reshape(train_color_image, (len(train_color_image), SIZE, SIZE, 3))
print('Train color image shape:', train_c.shape)

test_gray_image = np.reshape(test_gray_image, (len(test_gray_image), SIZE, SIZE, 3))
test_color_image = np.reshape(test_color_image, (len(test_color_image), SIZE, SIZE, 3))
print('Test color image shape', test_color_image.shape)
```

```
Train color image shape: (5500, 160, 160, 3)
Test color image shape (500, 160, 160, 3)
```



# Code\_Defining model

```
from keras import layers

def down(filters, kernel_size, apply_batch_normalization =
True):
    downsample = tf.keras.models.Sequential()
    downsample.add(layers.Conv2D(filters, kernel_size, padding
= 'same', strides = 2))
    if apply_batch_normalization:
        downsample.add(layers.BatchNormalization())
    downsample.add(layers.LeakyReLU())
    return downsample

def up(filters, kernel_size, dropout = False):
    upsample = tf.keras.models.Sequential()
    upsample.add(layers.Conv2DTranspose(filters, kernel_siz
e, padding = 'same', strides = 2))
    if dropout:
        upsample.dropout(0.2)
    upsample.add(layers.LeakyReLU())
    return upsample
```

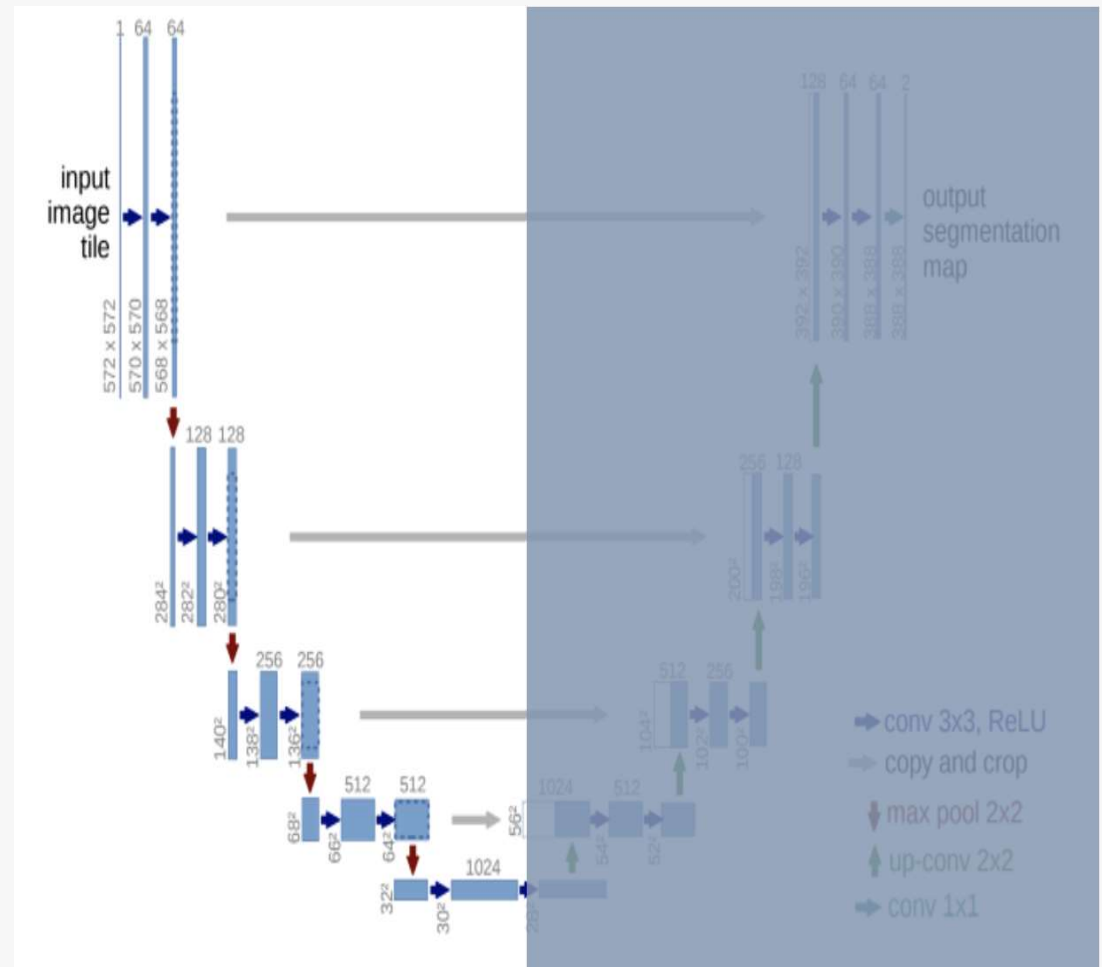
```
def model():
    inputs = layers.Input(shape= [160,160,3])
    d1 = down(128, (3,3), False)(inputs)
    d2 = down(128, (3,3), False)(d1)
    d3 = down(256, (3,3), True)(d2)
    d4 = down(512, (3,3), True)(d3)

    d5 = down(512, (3,3), True)(d4)
    #upsampling
    u1 = up(512, (3,3), False)(d5)
    u1 = layers.concatenate([u1, d4])
    u2 = up(256, (3,3), False)(u1)
    u2 = layers.concatenate([u2, d3])
    u3 = up(128, (3,3), False)(u2)
    u3 = layers.concatenate([u3, d2])
    u4 = up(128, (3,3), False)(u3)
    u4 = layers.concatenate([u4, d1])
    u5 = up(3, (3,3), False)(u4)
    u5 = layers.concatenate([u5, inputs])
    output = layers.Conv2D(3, (2,2), strides = 1, padding = 's
ame')(u5)
    return tf.keras.Model(inputs=inputs, outputs=output)
```

# Code\_Defining model\_U-net Architecture

```
Model: "functional_1"

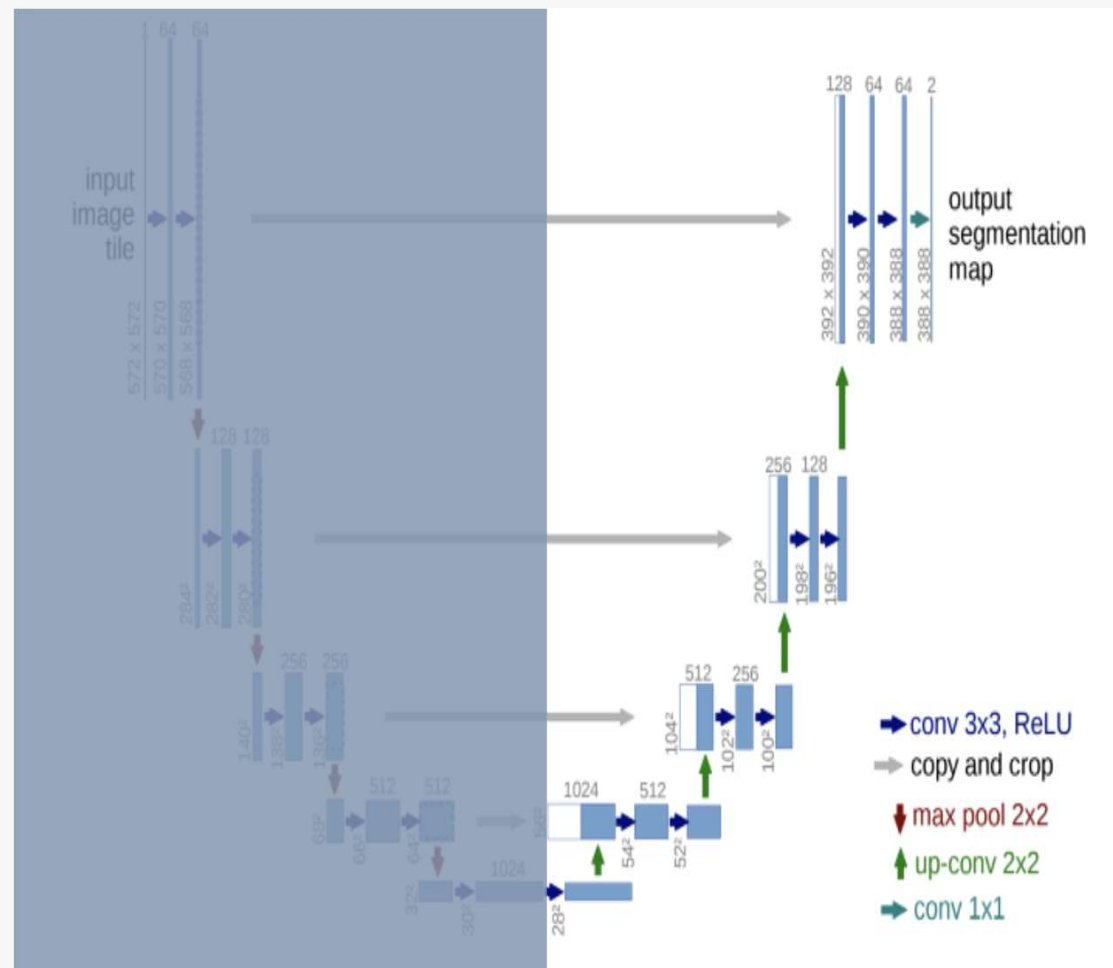
-----
Layer (type)                 Output Shape          Param #
-----
m #      Connected to
-----
input_1 (InputLayer)         [(None, 160, 160, 3)] 0
-----
sequential (Sequential)      (None, 80, 80, 128) 3584
input_1[0][0]
-----
sequential_1 (Sequential)    (None, 40, 40, 128) 1475
84      sequential[0][0]
-----
sequential_2 (Sequential)    (None, 20, 20, 256) 2961
92      sequential_1[0][0]
-----
sequential_3 (Sequential)    (None, 10, 10, 512) 1182
208     sequential_2[0][0]
-----
sequential_4 (Sequential)    (None, 5, 5, 512) 2361
856     sequential_3[0][0]
-----
sequential_5 (Sequential)    (None, 10, 10, 512) 2359
808     sequential_4[0][0]
```



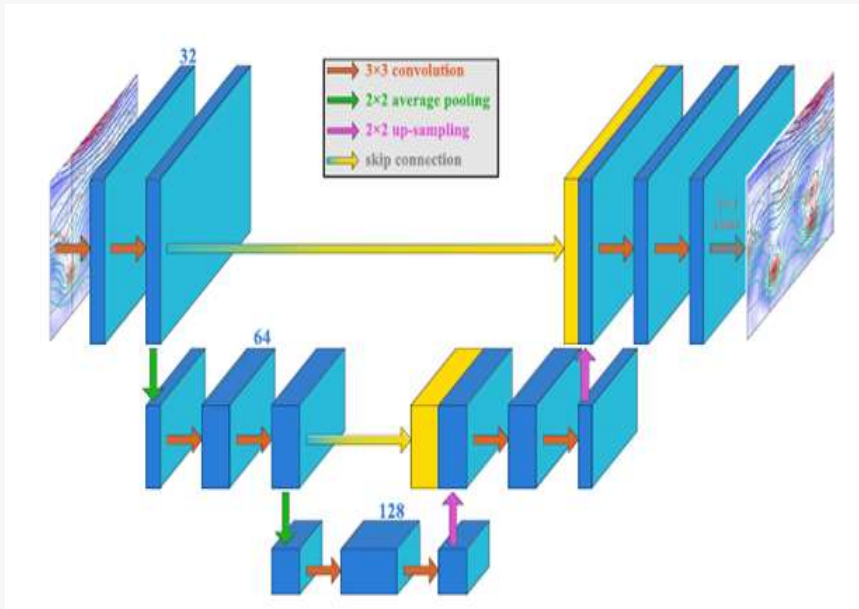
# Code\_Defining model\_U-net Architecture

```

concatenate (Concatenate)      (None, 10, 10, 1024) 0      sequential_5[0][0]
                                sequential_3[0][0]
-----
sequential_6 (Sequential)      (None, 20, 20, 256) 2359552      concatenate[0][0]
-----
concatenate_1 (Concatenate)    (None, 20, 20, 512) 0      sequential_6[0][0]
                                sequential_2[0][0]
-----
sequential_7 (Sequential)      (None, 40, 40, 128) 589952      concatenate_1[0][0]
-----
concatenate_2 (Concatenate)    (None, 40, 40, 256) 0      sequential_7[0][0]
                                sequential_1[0][0]
-----
sequential_8 (Sequential)      (None, 80, 80, 128) 295040      concatenate_2[0][0]
-----
concatenate_3 (Concatenate)    (None, 80, 80, 256) 0      sequential_8[0][0]
                                sequential[0][0]
-----
sequential_9 (Sequential)      (None, 160, 160, 3) 6915      concatenate_3[0][0]
-----
concatenate_4 (Concatenate)    (None, 160, 160, 6) 0      sequential_9[0][0]
                                input_1[0][0]
-----
conv2d_5 (Conv2D)              (None, 160, 160, 3) 75      concatenate_4[0][0]
=====
Total params: 9,602,766
Trainable params: 9,600,206
Non-trainable params: 2,560
    
```

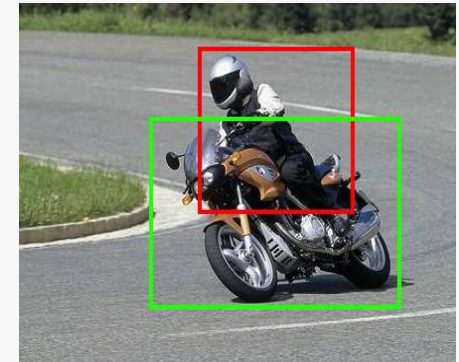


# U-net Architecture



## U-net Architecture

U-Net enhances the standard CNN architecture by adding the corresponding extended path (also referred to as a decoder) with the aim of generating semantic predictions of overall resolution. That is, it generates a split image that emphasizes a specific shape and object found in the image.



CNN

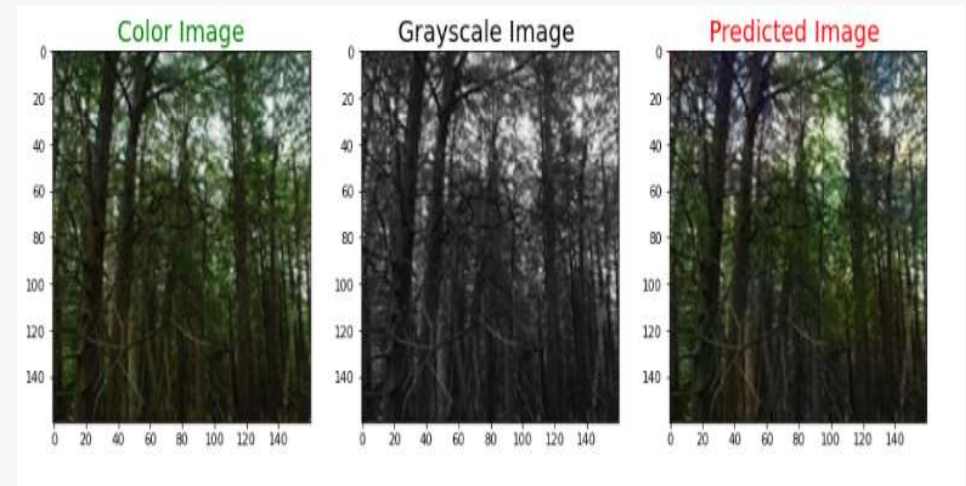


U-Net



# Code\_plotting colorized image along with grayscale and color image

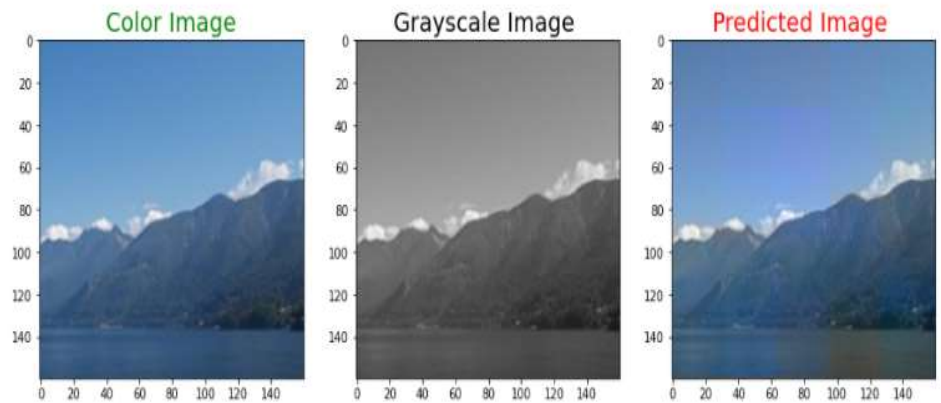
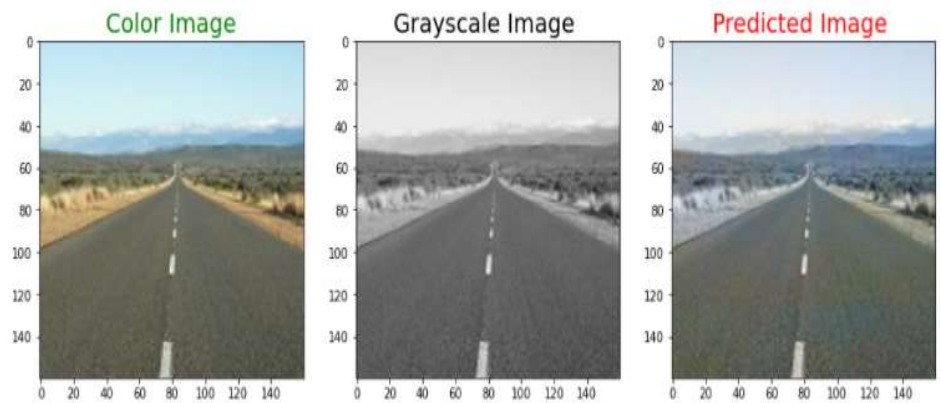
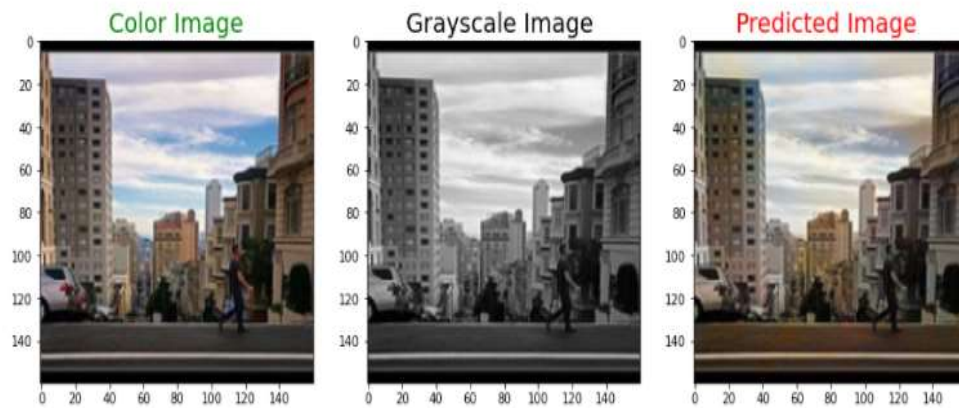
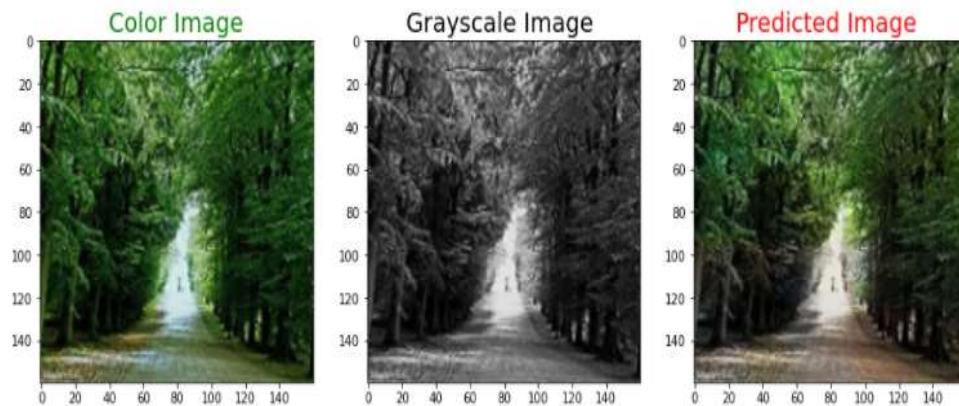
```
def plot_images(color, grayscale, predicted):  
    plt.figure(figsize=(15,15))  
    plt.subplot(1,3,1)  
    plt.title('Color Image', color = 'green', fontsize = 20)  
    plt.imshow(color)  
    plt.subplot(1,3,2)  
    plt.title('Grayscale Image ', color = 'black', fontsize = 20)  
    plt.imshow(grayscale)  
    plt.subplot(1,3,3)  
    plt.title('Predicted Image ', color = 'Red', fontsize = 20)  
    plt.imshow(predicted)  
  
    plt.show()  
  
for i in range(50,58):  
    predicted = np.clip(model.predict(test_gray_image[i].reshape(1,SIZE, SIZE,  
3)),0.0,1.0).reshape(SIZE, SIZE,3)  
    plot_images(test_color_image[i],test_gray_image[i],predicted)
```



```
model.evaluate(test_gray_image, test_color_image)
```

```
16/16 [=====] - 1s 38ms/step - loss: 0.0481 - acc:  
0.5307  
  
[0.04813535511493683, 0.5306968092918396]
```

# Code\_plotting colorized image along with grayscale and color image





## Reference

- <https://www.kaggle.com/theblackmamba31/autoencoder-grayscale-to-color-image>
- <https://www.kaggle.com/shiratorizawa/pix2pix-gan-for-image-colourisation/notebook>
- U-Net: Convolutional Networks for Biomedical Image Segmentation



Thanks

