

Ode to Joy - TCD ICPC Team Notebook (2019-20)

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1 Java

1.1 Java IO

```

static class Reader {
    BufferedReader br;
    StringTokenizer st;

    public Reader() {
        br = new BufferedReader(new
            InputStreamReader(System.in));
    }

    String next() throws IOException {
        while (st == null || !st.hasMoreTokens()) {
            st = new StringTokenizer(nextLine());
        }
        return st.nextToken();
    }

    int nextInt() throws IOException {
        return Integer.parseInt(next());
    }

    double nextDouble() throws IOException {
        return Double.parseDouble(next());
    }

    long nextLong() throws IOException {
        return Long.parseLong(next());
    }

    String nextLine() throws IOException {
        String str = "";
        str = br.readLine();
        return str;
    }
}

static Reader reader = new Reader();

```

1.2 Segment tree

```

public class SegmentTree {
    static public class SegmentSumTree{
        // store root at i=1; left child at 2*i, and
        // right child at 2*i+1
    }
}

```

```

// Sum function can be replaced by any other
// associative function
int n;
int[] tree;

SegmentSumTree(int n){
    this.tree = new int[4*n];
    this.n=n;
}

void build(int[] arr) {
    build(arr,1,0,n-1);
}

private void build(int[] arr, int i, int tl,
    int tr) {
    if(tl==tr) {
        tree[i]=arr[tl];
    } else {
        int tm = (tl+tr)/2;
        build(arr,i*2,tl,tm);
        build(arr,i*2+1,tm+1,tr);
        tree[i] = tree[2*i] + tree[2*i+1];
    }
}

// get the sum from arr[l] to arr[r]
int sum(int l, int r) {
    return sum(1,0,n-1,l,r);
}

private int sum(int i, int tl, int tr, int l,
    int r) {
    if(l > r) {
        return 0;
    }
    if(tl == l && tr == r) {
        return tree[i];
    }
    int tm = (tl + tr) / 2;
    return sum(i*2, tl, tm, l, Math.min(r, tm
        ))
        + sum(i*2+1, tm+1, tr, Math.max(l,
            tm+1), r);
}

void update(int pos, int newVal) {
    update(1,0,n-1,pos,newVal);
}

private void update(int i, int tl, int tr,
    int pos, int newVal) {
    if(tl==tr) {
        tree[i]=newVal;
    }else {
        int tm = (tl+tr)/2;
        if(pos<=tm){
            update(i*2,tl,tm,pos,newVal);
        } else {
            update(i*2+1,tm+1,tr,pos,newVal);
        }
        tree[i] = tree[2*i] + tree[2*i+1];
    }
}
}
}
}

```

1.3 Maths algorithms

```

public class MathsAlgo {
    public static int gcd(int a, int b) {
        if(b>a) {

```

```

    int t = a;
    a = b;
    b = t;
}
while(b!=0) {
    int t =b;
    b = a % b;
    a = t;
}
return a;
}
}

```

1.4 Basic algorithms

```

public class BasicAlgo {
    public static int binarySearch(int[] arr, int
        val) {
        int lo = 0;
        int hi = arr.length;
        int res = -1;
        while(lo<hi) {
            int mid = lo + (hi-lo)/2;
            if(val == arr[mid]) {
                res = mid;
                break;
            }
            if(val<arr[mid]) {
                hi = mid;
            } else if(val>arr[mid]) {
                lo = mid+1;
            }
        }
        return res;
    }

    public static int rank(int[] arr, int val) {
        int lo = 0;
        int hi = arr.length;
        int res = -1;
        while(lo<hi) {
            int mid = lo + (hi-lo)/2;
            if(val == arr[mid]) {
                res = mid;
                return res;
            }
            if(val<arr[mid]) {
                hi = mid;
            } else if(val>arr[mid]) {
                lo = mid+1;
            }
        }
        return hi;
    }
}

```

1.5 AVL tree

```

public class AVLTree {
    ublic class Node {
        private Node left, right, parent;
        private int height = 1;
        private int value;

        private Node (int val) {
            this.value = val;
        }
    }
}

```

```

}
Node root;
private int height (Node N) {
    if (N == null)
        return 0;
    return N.height;
}
public void insert(int data){
    root = insert(root, data);
}
private Node insert(Node node, int value) {
    if (node == null) {
        return(new Node(value));
    }
    if (value < node.value)
        node.left = insert(node.left, value);
    else
        node.right = insert(node.right, value);
    node.height = Math.max(height(node.left),
        height(node.right)) + 1;
    int balance = getBalance(node);
    if (balance > 1 && value < node.left.value)
        return rightRotate(node);
    if (balance < -1 && value > node.right.value)
        return leftRotate(node);
    if (balance > 1 && value > node.left.value)
    {
        node.left = leftRotate(node.left);
        return rightRotate(node);
    }
    if (balance < -1 && value < node.right.value)
    {
        node.right = rightRotate(node.right);
        return leftRotate(node);
    }
    return node;
}
private Node rightRotate(Node y) {
    Node x = y.left;
    Node T2 = x.right;
    x.right = y;
    y.left = T2;
    y.height = Math.max(height(y.left), height(y.
        right))+1;
    x.height = Math.max(height(x.left), height(x.
        right))+1;
    return x;
}
private Node leftRotate(Node x) {
    Node y = x.right;
    Node T2 = y.left;
    y.left = x;
    x.right = T2;
    x.height = Math.max(height(x.left), height(x.
        right))+1;
    y.height = Math.max(height(y.left), height(y.
        right))+1;
    return y;
}
private int getBalance(Node N) {
    if (N == null)
        return 0;
    return height(N.left) - height(N.right);
}
public void preOrder(Node root) {
    if (root != null) {
        System.out.printf("%d ", root.value);
        preOrder(root.left);
    }
}

```

```

        preOrder(root.right);
    }
}
private Node minValueNode(Node node) {
    Node current = node;
    while (current.left != null)
        current = current.left;
    return current;
}
private Node deleteNode(Node root, int value) {
    if (root == null)
        return root;
    if ( value < root.value )
        root.left = deleteNode(root.left, value);
    else if( value > root.value )
        root.right = deleteNode(root.right, value);
    else {
        if( (root.left == null) || (root.right ==
            null) ) {
            Node temp;
            if (root.left != null)
                temp = root.left;
            else
                temp = root.right;
            if(temp == null) {
                temp = root;
                root = null;
            }
            else // One child case
                root = temp;
            temp = null;
        }
        else {
            Node temp = minValueNode(root.right);
            root.value = temp.value;
            root.right = deleteNode(root.right, temp.
                value);
        }
    }
    if (root == null)
        return root;
    root.height = Math.max(height(root.left),
        height(root.right)) + 1;
    int balance = getBalance(root);
    if (balance > 1 && getBalance(root.left) >=
        0)
        return rightRotate(root);
    if (balance > 1 && getBalance(root.left) < 0)
    {
        root.left = leftRotate(root.left);
        return rightRotate(root);
    }
    if (balance < -1 && getBalance(root.right) <=
        0)
        return leftRotate(root);
    if (balance < -1 && getBalance(root.right) >
        0) {
        root.right = rightRotate(root.right);
        return leftRotate(root);
    }
    return root;
}
}}

```

2 Combinatorial optimization

2.1 Dinic's Algo for Sparse max-flow

```
// Adjacency list implementation of Dinic's
// blocking flow algorithm.
// This is very fast in practice, and only loses
// to push-relabel flow.
//
// Running time:
//  $O(|V|^2 |E|)$ 
//
// INPUT:
// - graph, constructed using AddEdge()
// - source and sink
//
// OUTPUT:
// - maximum flow value
// - To obtain actual flow values, look at
//   edges with capacity > 0
//   (zero capacity edges are residual edges)

#include<cstdio>
#include<vector>
#include<queue>
using namespace std;
typedef long long LL;

struct Edge {
    int u, v;
    LL cap, flow;
    Edge() {}
    Edge(int u, int v, LL cap): u(u), v(v), cap(cap), flow(0) {}
};

struct Dinic {
    int N;
    vector<Edge> E;
    vector<vector<int>>> g;
    vector<int> d, pt;

    Dinic(int N): N(N), E(0), g(N), d(N), pt(N) {}

    void AddEdge(int u, int v, LL cap) {
        if (u != v) {
            E.emplace_back(Edge(u, v, cap));
            g[u].emplace_back(E.size() - 1);
            E.emplace_back(Edge(v, u, 0));
            g[v].emplace_back(E.size() - 1);
        }
    }

    bool BFS(int S, int T) {
        queue<int> q({S});
        fill(d.begin(), d.end(), N + 1);
        d[S] = 0;
        while (!q.empty()) {
            int u = q.front(); q.pop();
            if (u == T) break;
            for (int k: g[u]) {
                Edge &e = E[k];
                if (e.flow < e.cap && d[e.v] > d[e.u] + 1) {
                    d[e.v] = d[e.u] + 1;
                    q.emplace(e.v);
                }
            }
        }
    }
};
```

```

    }
    return d[T] != N + 1;
}

LL DFS(int u, int T, LL flow = -1) {
    if (u == T || flow == 0) return flow;
    for (int &i = pt[u]; i < g[u].size(); ++i) {
        Edge &e = E[g[u][i]];
        Edge &oe = E[g[u][i]^1];
        if (d[e.v] == d[e.u] + 1) {
            LL amt = e.cap - e.flow;
            if (flow != -1 && amt > flow) amt = flow;
            if (LL pushed = DFS(e.v, T, amt)) {
                e.flow += pushed;
                oe.flow -= pushed;
                return pushed;
            }
        }
    }
    return 0;
}

LL MaxFlow(int S, int T) {
    LL total = 0;
    while (BFS(S, T)) {
        fill(pt.begin(), pt.end(), 0);
        while (LL flow = DFS(S, T))
            total += flow;
    }
    return total;
}

// BEGIN CUT
// The following code solves SPOJ problem #4110:
// Fast Maximum Flow (FASTFLOW)

int main()
{
    int N, E;
    scanf("%d%d", &N, &E);
    Dinic dinic(N);
    for(int i = 0; i < E; i++)
    {
        int u, v;
        LL cap;
        scanf("%d%d%lld", &u, &v, &cap);
        dinic.AddEdge(u - 1, v - 1, cap);
        dinic.AddEdge(v - 1, u - 1, cap);
    }
    printf("%lld\n", dinic.MaxFlow(0, N - 1));
    return 0;
}

// END CUT
```

2.2 Global min-cut

```
// Adjacency matrix implementation of Stoer-
// Wagner min cut algorithm.
//
// Running time:
//  $O(|V|^3)$ 
//
// INPUT:
// - graph, constructed using AddEdge()
//
// OUTPUT:
// - (min cut value, nodes in half of min cut)


```

```
#include "template.h"

typedef vector<vi> vvi;
const int INF = 1000000000;

pair<int, vi> GetMinCut(vvi &weights) {
    int N = weights.size();
    vi used(N), cut, best_cut;
    int best_weight = -1;

    for (int phase = N-1; phase >= 0; phase--) {
        vi w = weights[0];
        vi added = used;
        int prev, last = 0;
        for (int i = 0; i < phase; i++) {
            prev = last;
            last = -1;
            for (int j = 1; j < N; j++)
                if (!added[j] && (last == -1 || w[j] > w[last])) last = j;
            if (i == phase-1) {
                for (int j = 0; j < N; j++) weights[prev][j] += weights[last][j];
                for (int j = 0; j < N; j++) weights[j][prev] = weights[j][last];
                used[last] = true;
                cut.push_back(last);
                if (best_weight == -1 || w[last] < best_weight) {
                    best_weight = w[last];
                    best_cut = cut;
                }
            } else {
                for (int j = 0; j < N; j++)
                    w[j] += weights[last][j];
                added[last] = true;
            }
        }
        return make_pair(best_weight, best_cut);
    }

    // BEGIN CUT
    // The following code solves UVA problem #10989:
    // Bomb, Divide and Conquer
    int main() {
        int N;
        cin >> N;
        for (int i = 0; i < N; i++) {
            int n, m;
            cin >> n >> m;
            vvi weights(n, vi(n));
            for (int j = 0; j < m; j++) {
                int a, b, c;
                cin >> a >> b >> c;
                weights[a-1][b-1] = weights[b-1][a-1] = c;
            }
            pair<int, vi> res = GetMinCut(weights);
            cout << "Case #" << i+1 << ": " << res.first << endl;
        }
    }

    // END CUT
```

2.3 Min cost Bipartite Matching

```
// Min cost bipartite matching via shortest
```

```

    augmenting paths
// This is an  $O(n^3)$  implementation of a shortest
// augmenting path
// algorithm for finding min cost perfect
// matchings in dense
// graphs. In practice, it solves 1000x1000
// problems in around 1
// second.
//
// cost[i][j] = cost for pairing left node i
// with right node j
// Lmate[i] = index of right node that left
// node i pairs with
// Rmate[j] = index of left node that right
// node j pairs with
//
// The values in cost[i][j] may be positive or
// negative. To perform
// maximization, simply negate the cost[][]
// matrix.

#include "template.h"
typedef vector<double> VD;
typedef vector<VD> VVD;

double MinCostMatching(const VVD &cost, vi &Lmate
    , vi &Rmate) {
    int n = int(cost.size());

    // construct dual feasible solution
    VD u(n);
    VD v(n);
    for (int i = 0; i < n; i++) {
        u[i] = cost[i][0];
        for (int j = 1; j < n; j++) u[i] = min(u[i],
            cost[i][j]);
    }
    for (int j = 0; j < n; j++) {
        v[j] = cost[0][j] - u[0];
        for (int i = 1; i < n; i++) v[j] = min(v[j],
            cost[i][j] - u[i]);
    }

    // construct primal solution satisfying
    // complementary slackness
    Lmate = vi(n, -1);
    Rmate = vi(n, -1);
    int mated = 0;
    for (int i = 0; i < n; i++) {
        for (int j = 0; j < n; j++) {
            if (Rmate[j] != -1) continue;
            if (fabs(cost[i][j] - u[i] - v[j]) < 1e-10)
            {
                Lmate[i] = j;
                Rmate[j] = i;
                mated++;
                break;
            }
        }
    }

    VD dist(n);
    vi dad(n);
    vi seen(n);

    // repeat until primal solution is feasible
    while (mated < n) {
        // find an unmatched left node
        int s = 0;

```

```

        while (Lmate[s] != -1) s++;

        // initialize Dijkstra
        fill(dad.begin(), dad.end(), -1);
        fill(seen.begin(), seen.end(), 0);
        for (int k = 0; k < n; k++)
            dist[k] = cost[s][k] - u[s] - v[k];

        int j = 0;
        while (true) {
            // find closest
            j = -1;
            for (int k = 0; k < n; k++) {
                if (seen[k]) continue;
                if (j == -1 || dist[k] < dist[j]) j = k;
            }
            seen[j] = 1;

            // termination condition
            if (Rmate[j] == -1) break;

            // relax neighbors
            const int i = Rmate[j];
            for (int k = 0; k < n; k++) {
                if (seen[k]) continue;
                const double new_dist = dist[j] + cost[i][k] -
                    u[i] - v[k];
                if (dist[k] > new_dist) {
                    dist[k] = new_dist;
                    dad[k] = j;
                }
            }

            // update dual variables
            for (int k = 0; k < n; k++) {
                if (k == j || !seen[k]) continue;
                const int i = Rmate[k];
                v[k] += dist[k] - dist[j];
                u[i] -= dist[k] - dist[j];
            }
            u[s] += dist[j];

            // augment along path
            while (dad[j] >= 0) {
                const int d = dad[j];
                Rmate[j] = Rmate[d];
                Lmate[Rmate[j]] = j;
                j = d;
            }
            Rmate[j] = s;
            Lmate[s] = j;

            mated++;
        }

        double value = 0;
        for (int i = 0; i < n; i++)
            value += cost[i][Lmate[i]];

        return value;
    }
}

```

2.4 Min cost Max Flow

```

// Implementation of min cost max flow algorithm
// using adjacency
// matrix (Edmonds and Karp 1972). This
// implementation keeps track of

```

```

// forward and reverse edges separately (so you
// can set cap[i][j] !=
// cap[j][i]). For a regular max flow, set all
// edge costs to 0.
//
// Running time,  $O(|V|^2)$  cost per augmentation
// max flow:  $O(|V|^3)$  augmentations
// min cost max flow:  $O(|V|^4 * \text{MAX\_EDGE\_COST})$  augmentations
//
// INPUT:
// - graph, constructed using AddEdge()
// - source
// - sink
//
// OUTPUT:
// - (maximum flow value, minimum cost value)
// - To obtain the actual flow, look at
// positive values only.

#include <cmath>
#include <vector>
#include <iostream>

using namespace std;

typedef vector<int> VI;
typedef vector<VI> VVI;
typedef long long L;
typedef vector<L> VL;
typedef vector<VL> VVL;
typedef pair<int, int> PII;
typedef vector<PII> VPII;

const L INF = numeric_limits<L>::max() / 4;

struct MinCostMaxFlow {
    int N;
    VVL cap, flow, cost;
    VI found;
    VL dist, pi, width;
    VPII dad;

    MinCostMaxFlow(int N) :
        N(N), cap(N, VL(N)), flow(N, VL(N)), cost(N,
            VL(N)),
        found(N), dist(N), pi(N), width(N), dad(N) {}

    void AddEdge(int from, int to, L cap, L cost) {
        this->cap[from][to] = cap;
        this->cost[from][to] = cost;
    }

    void Relax(int s, int k, L cap, L cost, int dir)
    {
        L val = dist[s] + pi[s] - pi[k] + cost;
        if (cap && val < dist[k]) {
            dist[k] = val;
            dad[k] = make_pair(s, dir);
            width[k] = min(cap, width[s]);
        }
    }

    L Dijkstra(int s, int t) {
        fill(found.begin(), found.end(), false);
        fill(dist.begin(), dist.end(), INF);
        fill(width.begin(), width.end(), 0);
        dist[s] = 0;
        width[s] = INF;

        while (s != -1) {
            int best = -1;

```

```

found[s] = true;
for (int k = 0; k < N; k++) {
    if (found[k]) continue;
    Relax(s, k, cap[s][k] - flow[s][k], cost[
        s][k], 1);
    Relax(s, k, flow[k][s], -cost[k][s], -1);
    if (best == -1 || dist[k] < dist[best])
        best = k;
}
s = best;

for (int k = 0; k < N; k++)
    pi[k] = min(pi[k] + dist[k], INF);
return width[t];
}

pair<L, L> GetMaxFlow(int s, int t) {
    L totflow = 0, totcost = 0;
    while (L amt = Dijkstra(s, t)) {
        totflow += amt;
        for (int x = t; x != s; x = dad[x].first) {
            if (dad[x].second == 1) {
                flow[dad[x].first][x] += amt;
                totcost += amt * cost[dad[x].first][x];
            } else {
                flow[x][dad[x].first] -= amt;
                totcost -= amt * cost[x][dad[x].first];
            }
        }
    }
    return make_pair(totflow, totcost);
}

// BEGIN CUT
// The following code solves UVA problem #10594:
// Data Flow

int main() {
    int N, M;

    while (scanf("%d%d", &N, &M) == 2) {
        VVL v(M, VL(3));
        for (int i = 0; i < M; i++)
            scanf("%Ld%Ld%Ld", &v[i][0], &v[i][1], &v[i]
                [2]);
        L D, K;
        scanf("%Ld%Ld", &D, &K);

        MinCostMaxFlow mcmf(N+1);
        for (int i = 0; i < M; i++) {
            mcmf.AddEdge(int(v[i][0]), int(v[i][1]), K,
                v[i][2]);
            mcmf.AddEdge(int(v[i][1]), int(v[i][0]), K,
                v[i][2]);
        }
        mcmf.AddEdge(0, 1, D, 0);

        pair<L, L> res = mcmf.GetMaxFlow(0, N);

        if (res.first == D) {
            printf("%Ld\n", res.second);
        } else {
            printf("Impossible.\n");
        }
    }

    return 0;
}

// END CUT

```

3 Geometry

3.1 Convex hull

```

// Compute the 2D convex hull of a set of points
// using the monotone chain
// algorithm. Eliminate redundant points from
// the hull if REMOVE_REDUNDANT is
// #defined.
//
// Running time: O(n log n)
//
// INPUT: a vector of input points, unordered
//
// OUTPUT: a vector of points in the convex
// hull, counterclockwise, starting
// with bottommost/leftmost point

#include <cstdio>
#include <cassert>
#include <vector>
#include <algorithm>
#include <cmath>
// BEGIN CUT
#include <map>
// END CUT

using namespace std;

#define REMOVE_REDUNDANT

typedef double T;
const T EPS = 1e-7;
struct PT {
    T x, y;
    PT() {}
    PT(T x, T y) : x(x), y(y) {}
    bool operator<(const PT &rhs) const { return
        make_pair(y,x) < make_pair(rhs.y,rhs.x); }
    bool operator==(const PT &rhs) const { return
        make_pair(y,x) == make_pair(rhs.y,rhs.x); }
};

T cross(PT p, PT q) { return p.x*q.y-p.y*q.x; }
T area2(PT a, PT b, PT c) { return cross(a,b) +
    cross(b,c) + cross(c,a); }

#ifdef REMOVE_REDUNDANT
bool between(const PT &a, const PT &b, const PT &
    c) {
    return (fabs(area2(a,b,c)) < EPS && (a.x-b.x)*(
        c.x-b.x) <= 0 && (a.y-b.y)*(c.y-b.y) <= 0);
}
#endif

void ConvexHull(vector<PT> &pts) {
    sort(pts.begin(), pts.end());
    pts.erase(unique(pts.begin(), pts.end()), pts.
        end());
    vector<PT> up, dn;
    for (int i = 0; i < pts.size(); i++) {
        while (up.size() > 1 && area2(up[up.size()
            -2], up.back(), pts[i]) >= 0) up.pop_back
            ();
        while (dn.size() > 1 && area2(dn[dn.size()
            -2], dn.back(), pts[i]) <= 0) dn.pop_back
            ();
        up.push_back(pts[i]);
        dn.push_back(pts[i]);
    }
}

```

```

}
pts = dn;
for (int i = (int) up.size() - 2; i >= 1; i--)
    pts.push_back(up[i]);

#ifdef REMOVE_REDUNDANT
if (pts.size() <= 2) return;
dn.clear();
dn.push_back(pts[0]);
dn.push_back(pts[1]);
for (int i = 2; i < pts.size(); i++) {
    if (between(dn[dn.size()-2], dn[dn.size()-1],
        pts[i])) dn.pop_back();
    dn.push_back(pts[i]);
}
if (dn.size() >= 3 && between(dn.back(), dn[0],
    dn[1])) {
    dn[0] = dn.back();
    dn.pop_back();
}
pts = dn;
#endif

// BEGIN CUT
// The following code solves SPOJ problem #26:
// Build the Fence (BSHEEP)

int main() {
    int t;
    scanf("%d", &t);
    for (int caseno = 0; caseno < t; caseno++) {
        int n;
        scanf("%d", &n);
        vector<PT> v(n);
        for (int i = 0; i < n; i++) scanf("%lf%lf", &
            v[i].x, &v[i].y);
        vector<PT> h(v);
        map<PT,int> index;
        for (int i = n-1; i >= 0; i--) index[v[i]] =
            i+1;
        ConvexHull(h);

        double len = 0;
        for (int i = 0; i < h.size(); i++) {
            double dx = h[i].x - h[(i+1)%h.size()].x;
            double dy = h[i].y - h[(i+1)%h.size()].y;
            len += sqrt(dx*dx+dy*dy);
        }

        if (caseno > 0) printf("\n");
        printf("%.2f\n", len);
        for (int i = 0; i < h.size(); i++) {
            if (i > 0) printf(" ");
            printf("%d", index[h[i]]);
        }
        printf("\n");
    }
}

// END CUT

```

3.2 Miscellaneous geometry

```

// C++ routines for computational geometry.

#include <iostream>
#include <vector>
#include <cmath>
#include <cassert>

```

```

using namespace std;

double INF = 1e100;
double EPS = 1e-12;

struct PT {
    double x, y;
    PT() {}
    PT(double x, double y) : x(x), y(y) {}
    PT(const PT &p) : x(p.x), y(p.y) {}
    PT operator + (const PT &p) const { return PT(
        x+p.x, y+p.y); }
    PT operator - (const PT &p) const { return PT(
        x-p.x, y-p.y); }
    PT operator * (double c) const { return PT(
        x*c, y*c ); }
    PT operator / (double c) const { return PT(
        x/c, y/c ); }
};

double dot(PT p, PT q) { return p.x*q.x+p.y*q.y; }
double dist2(PT p, PT q) { return dot(p-q,p-q); }
double cross(PT p, PT q) { return p.x*q.y-p.y*q.x; }

ostream &operator<<(ostream &os, const PT &p) {
    os << "(" << p.x << ", " << p.y << ")";
}

// rotate a point CCW or CW around the origin
PT RotateCCW90(PT p) { return PT(-p.y,p.x); }
PT RotateCW90(PT p) { return PT(p.y,-p.x); }
PT RotateCCW(PT p, double t) {
    return PT(p.x*cos(t)-p.y*sin(t), p.x*sin(t)+p.y*cos(t));
}

// project point c onto line through a and b
// assuming a != b
PT ProjectPointLine(PT a, PT b, PT c) {
    return a + (b-a)*dot(c-a, b-a)/dot(b-a, b-a);
}

// project point c onto line segment through a
// and b
PT ProjectPointSegment(PT a, PT b, PT c) {
    double r = dot(b-a,b-a);
    if (fabs(r) < EPS) return a;
    r = dot(c-a, b-a)/r;
    if (r < 0) return a;
    if (r > 1) return b;
    return a + (b-a)*r;
}

// compute distance from c to segment between a
// and b
double DistancePointSegment(PT a, PT b, PT c) {
    return sqrt(dist2(c, ProjectPointSegment(a, b, c)));
}

// compute distance between point (x,y,z) and
// plane ax+by+cz=d
double DistancePointPlane(double x, double y,
    double z,
    double a, double b,
    double c, double d)
{
    return fabs(a*x+b*y+c*z-d)/sqrt(a*a+b*b+c*c);
}

// determine if lines from a to b and c to d are

```

```

parallel or collinear
bool LinesParallel(PT a, PT b, PT c, PT d) {
    return fabs(cross(b-a, c-d)) < EPS;
}

bool LinesCollinear(PT a, PT b, PT c, PT d) {
    return LinesParallel(a, b, c, d)
        && fabs(cross(a-b, a-c)) < EPS
        && fabs(cross(c-d, c-a)) < EPS;
}

// determine if line segment from a to b
// intersects with
// line segment from c to d
bool SegmentsIntersect(PT a, PT b, PT c, PT d) {
    if (LinesCollinear(a, b, c, d)) {
        if (dist2(a, c) < EPS || dist2(a, d) < EPS ||
            dist2(b, c) < EPS || dist2(b, d) < EPS)
            return true;
        if (dot(c-a, c-b) > 0 && dot(d-a, d-b) > 0 &&
            dot(c-b, d-b) > 0)
            return false;
        return true;
    }
    if (cross(d-a, b-a) * cross(c-a, b-a) > 0)
        return false;
    if (cross(a-c, d-c) * cross(b-c, d-c) > 0)
        return false;
    return true;
}

// compute intersection of line passing through a
// and b
// with line passing through c and d, assuming
// that unique
// intersection exists; for segment intersection,
// check if
// segments intersect first
PT ComputeLineIntersection(PT a, PT b, PT c, PT d
    ) {
    b=b-a; d=c-d; c=c-a;
    assert(dot(b, b) > EPS && dot(d, d) > EPS);
    return a + b*cross(c, d)/cross(b, d);
}

// compute center of circle given three points
PT ComputeCircleCenter(PT a, PT b, PT c) {
    b=(a+b)/2;
    c=(a+c)/2;
    return ComputeLineIntersection(b, b+RotateCW90(
        a-b), c, c+RotateCW90(a-c));
}

// determine if point is in a possibly non-convex
// polygon (by William
// Randolph Franklin); returns 1 for strictly
// interior points, 0 for
// strictly exterior points, and 0 or 1 for the
// remaining points.
// Note that it is possible to convert this into
// an *exact* test using
// integer arithmetic by taking care of the
// division appropriately
// (making sure to deal with signs properly) and
// then by writing exact
// tests for checking point on polygon boundary
bool PointInPolygon(const vector<PT> &p, PT q) {
    bool c = 0;
    for (int i = 0; i < p.size(); i++) {
        int j = (i+1)%p.size();
        if ((p[i].y <= q.y && q.y < p[j].y ||
            p[j].y <= q.y && q.y < p[i].y) &&

```

```

        q.x < p[i].x + (p[j].x - p[i].x) * (q.y - p[i].y) / (p[j].y - p[i].y))
            c = !c;
    }
    return c;
}

// determine if point is on the boundary of a
// polygon
bool PointOnPolygon(const vector<PT> &p, PT q) {
    for (int i = 0; i < p.size(); i++)
        if (dist2(ProjectPointSegment(p[i], p[(i+1)%p.size()], q), q) < EPS)
            return true;
    return false;
}

// compute intersection of line through points a
// and b with
// circle centered at c with radius r > 0
vector<PT> CircleLineIntersection(PT a, PT b, PT
    c, double r) {
    vector<PT> ret;
    b = b-a;
    a = a-c;
    double A = dot(b, b);
    double B = dot(a, b);
    double C = dot(a, a) - r*r;
    double D = B*B - A*C;
    if (D < -EPS) return ret;
    ret.push_back(c+a+b*(-B+sqrt(D+EPS))/A);
    if (D > EPS)
        ret.push_back(c+a+b*(-B-sqrt(D))/A);
    return ret;
}

// compute intersection of circle centered at a
// with radius r
// with circle centered at b with radius R
vector<PT> CircleCircleIntersection(PT a, PT b,
    double r, double R) {
    vector<PT> ret;
    double d = sqrt(dist2(a, b));
    if (d > r+R || d+min(r, R) < max(r, R)) return
        ret;
    double x = (d*d-R*R+r*r)/(2*d);
    double y = sqrt(r*r-x*x);
    PT v = (b-a)/d;
    ret.push_back(a+v*x + RotateCCW90(v)*y);
    if (y > 0)
        ret.push_back(a+v*x - RotateCCW90(v)*y);
    return ret;
}

// This code computes the area or centroid of a (
// possibly nonconvex)
// polygon, assuming that the coordinates are
// listed in a clockwise or
// counterclockwise fashion. Note that the
// centroid is often known as
// the "center of gravity" or "center of mass".
double ComputeSignedArea(const vector<PT> &p) {
    double area = 0;
    for(int i = 0; i < p.size(); i++) {
        int j = (i+1) % p.size();
        area += p[i].x*p[j].y - p[j].x*p[i].y;
    }
    return area / 2.0;
}

double ComputeArea(const vector<PT> &p) {
    return fabs(ComputeSignedArea(p));
}

```



```

PT ComputeCentroid(const vector<PT> &p) {
    PT c(0,0);
    double scale = 6.0 * ComputeSignedArea(p);
    for (int i = 0; i < p.size(); i++){
        int j = (i+1) % p.size();
        c = c + (p[i].x*p[j].y - p[j].x*p[i].y);
    }
    return c / scale;
}

// tests whether or not a given polygon (in CW or
// CCW order) is simple
bool IsSimple(const vector<PT> &p) {
    for (int i = 0; i < p.size(); i++) {
        for (int k = i+1; k < p.size(); k++) {
            int j = (i+1) % p.size();
            int l = (k+1) % p.size();
            if (i == l || j == k) continue;
            if (SegmentsIntersect(p[i], p[j], p[k], p[l]))
                return false;
        }
    }
    return true;
}

int main() {
    // expected: (-5,2)
    cerr << RotateCCW90(PT(2,5)) << endl;

    // expected: (5,-2)
    cerr << RotateCW90(PT(2,5)) << endl;

    // expected: (-5,2)
    cerr << RotateCCW(PT(2,5), M_PI/2) << endl;

    // expected: (5,2)
    cerr << ProjectPointLine(PT(-5,-2), PT(10,4),
        PT(3,7)) << endl;

    // expected: (5,2) (7.5,3) (2.5,1)
    cerr << ProjectPointSegment(PT(-5,-2), PT(10,4),
        PT(3,7)) << " "
        << ProjectPointSegment(PT(7.5,3), PT(10,4),
        PT(3,7)) << " "
        << ProjectPointSegment(PT(-5,-2), PT(2.5,1), PT(3,7)) << endl;

    // expected: 6.78903
    cerr << DistancePointPlane(4,-4,3,2,-2,5,-8) <<
        endl;

    // expected: 1 0 1
    cerr << LinesParallel(PT(1,1), PT(3,5), PT(2,1),
        PT(4,5)) << " "
        << LinesParallel(PT(1,1), PT(3,5), PT(2,0),
        PT(4,5)) << " "
        << LinesParallel(PT(1,1), PT(3,5), PT(5,9),
        PT(7,13)) << endl;

    // expected: 0 0 1
    cerr << LinesCollinear(PT(1,1), PT(3,5), PT(2,1), PT(4,5)) << " "
        << LinesCollinear(PT(1,1), PT(3,5), PT(2,0), PT(4,5)) << " "
        << LinesCollinear(PT(1,1), PT(3,5), PT(5,9), PT(7,13)) << endl;

    // expected: 1 1 1 0
    cerr << SegmentsIntersect(PT(0,0), PT(2,4), PT(3,1), PT(-1,3)) << " "

```

```

    << SegmentsIntersect(PT(0,0), PT(2,4), PT(4,3), PT(0,5)) << " "
    << SegmentsIntersect(PT(0,0), PT(2,4), PT(2,-1), PT(-2,1)) << " "
    << SegmentsIntersect(PT(0,0), PT(2,4), PT(5,5), PT(1,7)) << endl;

    // expected: (1,2)
    cerr << ComputeLineIntersection(PT(0,0), PT(2,4), PT(3,1), PT(-1,3)) << endl;

    // expected: (1,1)
    cerr << ComputeCircleCenter(PT(-3,4), PT(6,1), PT(4,5)) << endl;

    vector<PT> v;
    v.push_back(PT(0,0));
    v.push_back(PT(5,0));
    v.push_back(PT(5,5));
    v.push_back(PT(0,5));

    // expected: 1 1 1 0 0
    cerr << PointInPolygon(v, PT(2,2)) << " "
        << PointInPolygon(v, PT(2,0)) << " "
        << PointInPolygon(v, PT(0,2)) << " "
        << PointInPolygon(v, PT(5,2)) << " "
        << PointInPolygon(v, PT(2,5)) << endl;

    // expected: 0 1 1 1 1
    cerr << PointOnPolygon(v, PT(2,2)) << " "
        << PointOnPolygon(v, PT(2,0)) << " "
        << PointOnPolygon(v, PT(0,2)) << " "
        << PointOnPolygon(v, PT(5,2)) << " "
        << PointOnPolygon(v, PT(2,5)) << endl;

    // expected: (1,6)
    // (5,4) (4,5)
    // blank line
    // (4,5) (5,4)
    // blank line
    // (4,5) (5,4)
    vector<PT> u = CircleLineIntersection(PT(0,6), PT(2,6), PT(1,1), 5);
    for (int i = 0; i < u.size(); i++) cerr << u[i] << " "; cerr << endl;
    u = CircleLineIntersection(PT(0,9), PT(9,0), PT(1,1), 5);
    for (int i = 0; i < u.size(); i++) cerr << u[i] << " "; cerr << endl;
    u = CircleCircleIntersection(PT(1,1), PT(10,10), 5, 5);
    for (int i = 0; i < u.size(); i++) cerr << u[i] << " "; cerr << endl;
    u = CircleCircleIntersection(PT(1,1), PT(8,8), 5, 5);
    for (int i = 0; i < u.size(); i++) cerr << u[i] << " "; cerr << endl;
    u = CircleCircleIntersection(PT(1,1), PT(4.5,4.5), 10, sqrt(2.0)/2.0);
    for (int i = 0; i < u.size(); i++) cerr << u[i] << " "; cerr << endl;
    u = CircleCircleIntersection(PT(1,1), PT(4.5,4.5), 5, sqrt(2.0)/2.0);
    for (int i = 0; i < u.size(); i++) cerr << u[i] << " "; cerr << endl;

    // area should be 5.0
    // centroid should be (1.1666666, 1.1666666)
    PT pa[] = { PT(0,0), PT(5,0), PT(1,1), PT(0,5) };
    vector<PT> p(pa, pa+4);
    PT c = ComputeCentroid(p);
    cerr << "Area: " << ComputeArea(p) << endl;

```

```

    cerr << "Centroid: " << c << endl;
    return 0;
}

```

3.3 Geometry using Java Libraries

```

// In this example, we read an input file
// containing three lines, each
// containing an even number of doubles,
// separated by commas. The first two
// lines represent the coordinates of two
// polygons, given in counterclockwise
// (or clockwise) order, which we will call "A"
// and "B". The last line
// contains a list of points, p[1], p[2], ...
//
// Our goal is to determine:
// (1) whether B - A is a single closed shape (
// as opposed to multiple shapes)
// (2) the area of B - A
// (3) whether each p[i] is in the interior of
// B - A
//
// INPUT:
// 0 0 10 0 0 10
// 0 0 10 10 10 0
// 8 6
// 5 1
//
// OUTPUT:
// The area is singular.
// The area is 25.0
// Point belongs to the area.
// Point does not belong to the area.

import java.util.*;
import java.awt.geom.*;
import java.io.*;

public class JavaGeometry {

    // make an array of doubles from a string
    static double[] readPoints(String s) {
        String[] arr = s.trim().split("\\s+");
        double[] ret = new double[arr.length];
        for (int i = 0; i < arr.length; i++) ret[i] = Double.parseDouble(arr[i]);
        return ret;
    }

    // make an Area object from the coordinates
    // of a polygon
    static Area makeArea(double[] pts) {
        Path2D.Double p = new Path2D.Double();
        p.moveTo(pts[0], pts[1]);
        for (int i = 2; i < pts.length; i += 2) p.lineTo(pts[i], pts[i+1]);
        p.closePath();
        return new Area(p);
    }

    // compute area of polygon
    static double computePolygonArea(ArrayList<
        Point2D.Double> points) {
        Point2D.Double[] pts = points.toArray(new
            Point2D.Double[points.size()]);
        double area = 0;
        for (int i = 0; i < pts.length; i++){
            int j = (i+1) % pts.length;

```

```

        area += pts[i].x * pts[j].y - pts[j].
            x * pts[i].y;
    }
    return Math.abs(area)/2;
}

// compute the area of an Area object
// containing several disjoint polygons
static double computeArea(Area area) {
    double totArea = 0;
    PathIterator iter = area.getPathIterator(
        null);
    ArrayList<Point2D.Double> points = new
        ArrayList<Point2D.Double>();

    while (!iter.isDone()) {
        double[] buffer = new double[6];
        switch (iter.currentSegment(buffer))
        {
            case PathIterator.SEG_MOVETO:
            case PathIterator.SEG_LINETO:
                points.add(new Point2D.Double(
                    buffer[0], buffer[1]));
                break;
            case PathIterator.SEG_CLOSE:
                totArea += computePolygonArea(
                    points);
                points.clear();
                break;
        }
        iter.next();
    }
    return totArea;
}

// notice that the main() throws an Exception
// -- necessary to
// avoid wrapping the Scanner object for file
// reading in a
// try { ... } catch block.
public static void main(String args[]) throws
    Exception {
    Scanner scanner = new Scanner(new File("
        input.txt"));
    // also,
    // Scanner scanner = new Scanner (
        System.in);

    double[] pointsA = readPoints(scanner.
        nextLine());
    double[] pointsB = readPoints(scanner.
        nextLine());
    Area areaA = makeArea(pointsA);
    Area areaB = makeArea(pointsB);
    areaB.subtract(areaA);
    // also,
    // areaB.exclusiveOr (areaA);
    // areaB.add (areaA);
    // areaB.intersect (areaA);

    // (1) determine whether B - A is a
    // single closed shape (as
    // opposed to multiple shapes)
    boolean isSingle = areaB.isSingular();
    // also,
    // areaB.isEmpty();

    if (isSingle)
        System.out.println("The area is
            singular.");
    else

```

```

        System.out.println("The area is not
            singular.");
    }

    // (2) compute the area of B - A
    System.out.println("The area is " +
        computeArea(areaB) + ".");

    // (3) determine whether each p[i] is in
    // the interior of B - A
    while (scanner.hasNextDouble()) {
        double x = scanner.nextDouble();
        assert(scanner.hasNextDouble());
        double y = scanner.nextDouble();

        if (areaB.contains(x,y)) {
            System.out.println ("Point
                belongs to the area.");
        } else {
            System.out.println ("Point does
                not belong to the area.");
        }
    }

    // Finally, some useful things we didn't
    // use in this example:
    //
    // Ellipse2D.Double ellipse = new
    // Ellipse2D.Double (double x, double y,
    //                     double
    //                     w, double h);
    //
    // creates an ellipse inscribed in
    // box with bottom-left corner (x,y)
    // and upper-right corner (x+y,w+h)
    //
    // Rectangle2D.Double rect = new
    // Rectangle2D.Double (double x, double
    // Y,
    //                     double
    //                     w, double h);
    //
    // creates a box with bottom-left
    // corner (x,y) and upper-right
    // corner (x+y,w+h)
    //
    // Each of these can be embedded in an
    // Area object (e.g., new Area (rect)).
}

```

3.4 Delaunay Triangulation

```

// Slow but simple Delaunay triangulation. Does
// not handle
// degenerate cases (from O'Rourke, Computational
// Geometry in C)
//
// Generates a Triangulation DT(P) such that no
// point in P in
// inside any Triangle in DT(P)
//
// Running time: O(n^4)
//
// INPUT:      x[] = x-coordinates
//             y[] = y-coordinates
//
// OUTPUT:     triples = a vector containing m
//             triples of indices

```

```

// corresponding to triangle
// vertices
#include "template.h"
typedef double T;
struct triple {
    int i, j, k;
    triple() {}
    triple(int i, int j, int k) : i(i), j(j), k(k)
    {}
};

vector<triple> delaunayTriangulation(vector<T>& x
    , vector<T>& y) {
    int n = x.size();
    vector<T> z(n);
    vector<triple> ret;

    for (int i = 0; i < n; i++)
        z[i] = x[i] * x[i] + y[i] * y[i];

    for (int i = 0; i < n-2; i++) {
        for (int j = i+1; j < n; j++) {
            for (int k = i+1; k < n; k++) {
                if (j == k) continue;
                double xn = (y[j]-y[i])*(z[k]-z[i]) - (y[
                    k]-y[i])*(z[j]-z[i]);
                double yn = (x[k]-x[i])*(z[j]-z[i]) - (x[
                    j]-x[i])*(z[k]-z[i]);
                double zn = (x[j]-x[i])*(y[k]-y[i]) - (x[
                    k]-x[i])*(y[j]-y[i]);
                bool flag = zn < 0;
                for (int m = 0; flag && m < n; m++)
                    flag = flag && ((x[m]-x[i])*xn +
                        (y[m]-y[i])*yn +
                        (z[m]-z[i])*zn <= 0);
                if (flag) ret.push_back(triple(i, j, k));
            }
        }
    }
    return ret;
}

int main() {
    T xs[]={0, 0, 1, 0.9};
    T ys[]={0, 1, 0, 0.9};
    vector<T> x(&xs[0], &xs[4]), y(&ys[0], &ys[4]);
    vector<triple> tri = delaunayTriangulation(x, y
        );

    //expected: 0 1 3
    //           0 3 2

    int i;
    for(i = 0; i < tri.size(); i++)
        printf("%d %d %d\n", tri[i].i, tri[i].j, tri[
            i].k);
    return 0;
}

```

4 Numerical algorithms

4.1 Fast Fourier transform

```

#include <cassert>
#include <cstdio>
#include <cmath>

```



```

struct cpx
{
    cpx() {}
    cpx(double aa):a(aa),b(0){}
    cpx(double aa, double bb):a(aa),b(bb){}
    double a;
    double b;
    double modsq(void) const
    {
        return a * a + b * b;
    }
    cpx bar(void) const
    {
        return cpx(a, -b);
    }
};

cpx operator +(cpx a, cpx b)
{
    return cpx(a.a + b.a, a.b + b.b);
}

cpx operator *(cpx a, cpx b)
{
    return cpx(a.a * b.a - a.b * b.b, a.a * b.b + a
        .b * b.a);
}

cpx operator /(cpx a, cpx b)
{
    cpx r = a * b.bar();
    return cpx(r.a / b.modsq(), r.b / b.modsq());
}

cpx EXP(double theta)
{
    return cpx(cos(theta), sin(theta));
}

const double two_pi = 4 * acos(0);

// in:      input array
// out:      output array
// step:     {SET TO 1} (used internally)
// size:     length of the input/output {MUST BE A
//          POWER OF 2}
// dir:      either plus or minus one (direction of
//          the FFT)
// RESULT: out[k] = \sum_{j=0}^{size - 1} in[j] *
//          exp(dir * 2pi * i * j * k / size)
void FFT(cpx *in, cpx *out, int step, int size,
    int dir)
{
    if(size < 1) return;
    if(size == 1)
    {
        out[0] = in[0];
        return;
    }
    FFT(in, out, step * 2, size / 2, dir);
    FFT(in + step, out + size / 2, step * 2, size /
        2, dir);
    for(int i = 0 ; i < size / 2 ; i++)
    {
        cpx even = out[i];
        cpx odd = out[i + size / 2];
        out[i] = even + EXP(dir * two_pi * i / size)
            * odd;
        out[i + size / 2] = even + EXP(dir * two_pi *
            (i + size / 2) / size) * odd;
    }
}

```

```

// Usage:
// f[0...N-1] and g[0...N-1] are numbers
// Want to compute the convolution h, defined by
// h[n] = sum of f[k]g[n-k] (k = 0, ..., N-1).
// Here, the index is cyclic; f[-1] = f[N-1], f
// [-2] = f[N-2], etc.
// Let F[0...N-1] be FFT(f), and similarly,
// define G and H.
// The convolution theorem says H[n] = F[n]G[n] (
// element-wise product).
// To compute h[] in O(N log N) time, do the
// following:
// 1. Compute F and G (pass dir = 1 as the
// argument).
// 2. Get H by element-wise multiplying F and G
// 3. Get h by taking the inverse FFT (use dir
// = -1 as the argument)
// and *dividing by N*. DO NOT FORGET THIS
// SCALING FACTOR.

int main(void)
{
    printf("If rows come in identical pairs, then
        everything works.\n");

    cpx a[8] = {0, 1, cpx(1,3), cpx(0,5), 1, 0, 2,
        0};
    cpx b[8] = {1, cpx(0,-2), cpx(0,1), 3, -1, -3,
        1, -2};
    cpx A[8];
    cpx B[8];
    FFT(a, A, 1, 8, 1);
    FFT(b, B, 1, 8, 1);

    for(int i = 0 ; i < 8 ; i++)
    {
        printf("%7.2lf%7.2lf", A[i].a, A[i].b);
    }
    printf("\n");
    for(int i = 0 ; i < 8 ; i++)
    {
        cpx Ai(0,0);
        for(int j = 0 ; j < 8 ; j++)
        {
            Ai = Ai + a[j] * EXP(j * i * two_pi / 8);
        }
        printf("%7.2lf%7.2lf", Ai.a, Ai.b);
    }
    printf("\n");

    cpx AB[8];
    for(int i = 0 ; i < 8 ; i++)
        AB[i] = A[i] * B[i];
    cpx aconvb[8];
    FFT(AB, aconvb, 1, 8, -1);
    for(int i = 0 ; i < 8 ; i++)
        aconvb[i] = aconvb[i] / 8;
    for(int i = 0 ; i < 8 ; i++)
    {
        printf("%7.2lf%7.2lf", aconvb[i].a, aconvb[i
            ].b);
    }
    printf("\n");
    for(int i = 0 ; i < 8 ; i++)
    {
        cpx aconvbi(0,0);
        for(int j = 0 ; j < 8 ; j++)
        {
            aconvbi = aconvbi + a[j] * b[(8 + i - j) %
                8];
        }
    }
}

```

```

        printf("%7.2lf%7.2lf", aconvbi.a, aconvbi.b);
    }
    printf("\n");
    return 0;
}

```

4.2 Euclid and Fermat's Theorem

```

// This is a collection of useful code for
// solving problems that
// involve modular linear equations. Note that
// all of the
// algorithms described here work on nonnegative
// integers.
#include "template.h"

// return a % b (positive value)
int mod(int a, int b) {
    return ((a%b) + b) % b;
}

// computes gcd(a,b)
int gcd(int a, int b) {
    while (b) { int t = a%b; a = b; b = t; }
    return a;
}

// computes lcm(a,b)
int lcm(int a, int b) {
    return a / gcd(a, b)*b;
}

// (a^b) mod m via successive squaring
int powermod(int a, int b, int m) {
    int ret = 1;
    while (b) {
        if (b & 1) ret = mod(ret*a, m);
        a = mod(a*a, m);
        b >>= 1;
    }
    return ret;
}

// returns g = gcd(a, b); finds x, y such that g
// = ax + by
int extended_euclid(int a, int b, int &x, int &y)
{
    int xx = y = 0;
    int yy = x = 1;
    while (b) {
        int q = a / b;
        int t = b; b = a%b; a = t;
        t = xx; xx = x - q*xx; x = t;
        t = yy; yy = y - q*yy; y = t;
    }
    return a;
}

// finds all solutions to ax = b (mod n)
vi modular_linear_equation_solver(int a, int b,
    int n) {
    int x, y;
    vi ret;
    int g = extended_euclid(a, n, x, y);
    if (!(b%g)) {
        x = mod(x*(b / g), n);
        for (int i = 0; i < g; i++)
            ret.push_back(mod(x + i*(n / g), n));
    }
    return ret;
}

```

```

}

// computes b such that ab = 1 (mod n), returns
// -1 on failure
int mod_inverse(int a, int n) {
    int x, y;
    int g = extended_euclid(a, n, x, y);
    if (g > 1) return -1;
    return mod(x, n);
}

// Chinese remainder theorem (special case): find
// z such that
// z % m1 = r1, z % m2 = r2. Here, z is unique
// modulo M = lcm(m1, m2).
// Return (z, M). On failure, M = -1.
pii chinese_remainder_theorem(int m1, int r1, int
    m2, int r2) {
    int s, t;
    int g = extended_euclid(m1, m2, s, t);
    if (r1*g != r2*g) return make_pair(0, -1);
    return make_pair(mod(s*r2*m1 + t*r1*m2, m1*m2)
        / g, m1*m2 / g);
}

// Chinese remainder theorem: find z such that
// z % m[i] = r[i] for all i. Note that the
// solution is
// unique modulo M = lcm_i (m[i]). Return (z, M)
// . On
// failure, M = -1. Note that we do not require
// the a[i]'s
// to be relatively prime.
pii chinese_remainder_theorem(const vi &m, const
    vi &r) {
    pii ret = make_pair(r[0], m[0]);
    for (int i = 1; i < m.size(); i++) {
        ret = chinese_remainder_theorem(ret.second,
            ret.first, m[i], r[i]);
        if (ret.second == -1) break;
    }
    return ret;
}

// computes x and y such that ax + by = c
// returns whether the solution exists
bool linear_diophantine(int a, int b, int c, int
    &x, int &y) {
    if (!a && !b) {
        if (c) return false;
        x = 0; y = 0;
        return true;
    }
    if (!a) {
        if (c % b) return false;
        x = 0; y = c / b;
        return true;
    }
    if (!b) {
        if (c % a) return false;
        x = c / a; y = 0;
        return true;
    }
    int g = gcd(a, b);
    if (c % g) return false;
    x = c / g * mod_inverse(a / g, b / g);
    y = (c - a*x) / b;
    return true;
}

int main() {
    // expected: 2

```

```

cout << gcd(14, 30) << endl;

// expected: 2 -2 1
int x, y;
int g = extended_euclid(14, 30, x, y);
cout << g << " " << x << " " << y << endl;

// expected: 95 45
vi sols = modular_linear_equation_solver(14,
    30, 100);
for (int i = 0; i < sols.size(); i++) cout <<
    sols[i] << " ";
cout << endl;

// expected: 8
cout << mod_inverse(8, 9) << endl;

// expected: 23 105
// 11 12
int v1[3]={3,5,7}, v2[3]={2,3,2};
pii ret = chinese_remainder_theorem(vi(v1, v1
    +3), vi(v2, v2+3));
cout << ret.first << " " << ret.second << endl;
int v3[2]={4,6}, v4[2]={3,5};
ret = chinese_remainder_theorem(vi(v3, v3+2),
    vi(v4, v4+2));
cout << ret.first << " " << ret.second << endl;

// expected: 5 -15
if (!linear_diophantine(7, 2, 5, x, y)) cout <<
    "ERROR" << endl;
cout << x << " " << y << endl;
return 0;
}

```

4.3 Sieve for Prime Numbers

```

#include "template.h"
/*
    isPrime stores the largest prime number which
    divides the index
    vector primeNum contains all the prime numbers
*/
vi primeNum;
int isPrime[Lim];

void pop_isPrime(int limit) {
    mem(isPrime, 0);
    repl(i, 2, limit) {
        if (isPrime[i])
            continue;

        if (i <= (int)(sqrt(limit)+10))
            for(ll j = i*i; j <= limit; j += i)
                isPrime[j] = i;

        primeNum.pb(i);
        isPrime[i]=i;
    }
}

int main() {
    fast;
    pop_isPrime(500);
    repl(i, 1, 500)
        cout << i << ' ' << isPrime[i] << '\n';
}

```

4.4 Fast exponentiation

```

/*
    Uses powers of two to exponentiate numbers and
    matrices. Calculates
    n^k in O(log(k)) time when n is a number. If A is
    an n x n matrix,
    calculates A^k in O(n^3*log(k)) time.
*/

#include <iostream>
#include <vector>

using namespace std;

typedef double T;
typedef vector<T> VT;
typedef vector<VT> VVT;

T power(T x, int k) {
    T ret = 1;

    while(k) {
        if(k & 1) ret *= x;
        k >>= 1; x *= x;
    }
    return ret;
}

VVT multiply(VVT& A, VVT& B) {
    int n = A.size(), m = A[0].size(), k = B[0].
        size();
    VVT C(n, VT(k, 0));

    for(int i = 0; i < n; i++)
        for(int j = 0; j < k; j++)
            for(int l = 0; l < m; l++)
                C[i][j] += A[i][l] * B[l][j];

    return C;
}

VVT power(VVT& A, int k) {
    int n = A.size();
    VVT ret(n, VT(n)), B = A;
    for(int i = 0; i < n; i++) ret[i][i]=1;

    while(k) {
        if(k & 1) ret = multiply(ret, B);
        k >>= 1; B = multiply(B, B);
    }
    return ret;
}

int main()
{
    /* Expected Output:
        2.37^48 = 9.72569e+17

        376 264 285 220 265
        550 376 529 285 484
        484 265 376 264 285
        285 220 265 156 264
        529 285 484 265 376 */
    double n = 2.37;
    int k = 48;

    cout << n << "^" << k << " = " << power(n, k)
        << endl;

    double At[5][5] = {
        { 0, 0, 1, 0, 0 },

```

```

{ 1, 0, 0, 1, 0 },
{ 0, 0, 0, 0, 1 },
{ 1, 0, 0, 0, 0 },
{ 0, 1, 0, 0, 0 } };

vector<vector<double>> A(5, vector<double>
    >(5));
for(int i = 0; i < 5; i++)
    for(int j = 0; j < 5; j++)
        A[i][j] = At[i][j];

vector<vector<double>> Ap = power(A, k);

cout << endl;
for(int i = 0; i < 5; i++) {
    for(int j = 0; j < 5; j++)
        cout << Ap[i][j] << " ";
    cout << endl;
}

```

4.5 Simplex Algorithm, Linear Programming

```

// Two-phase simplex algorithm for solving linear
// programs of
// the form (c^T is c Transpose)
//
//      maximize      c^T x
//      subject to    Ax <= b
//                  x >= 0
//
// INPUT: A -- an m x n matrix
//        b -- an m-dimensional vector
//        c -- an n-dimensional vector
//        x -- a vector where the optimal
//        solution will be stored
//
// OUTPUT: value of the optimal solution (
//         infinity if unbounded
//         above, nan if infeasible)
//
// To use this code, create an LPSolver object
// with A, b, and c as
// arguments. Then, call Solve(x).

#include "template.h"

typedef long double DOUBLE;
typedef vector<DOUBLE> VD;
typedef vector<VD> VVD;
typedef vector<int> vi;

const DOUBLE EPS = 1e-9;

struct LPSolver {
    int m, n;
    vi B, N;
    VVD D;

    LPSolver(const VVD &A, const VD &b, const VD &c
        ) :
        m(b.size()), n(c.size()), N(n + 1), B(m), D(m
            + 2, VD(n + 2)) {
        for (int i = 0; i < m; i++) for (int j = 0; j
            < n; j++) D[i][j] = A[i][j];
        for (int i = 0; i < m; i++) { B[i] = n + i; D
            [i][n] = -1; D[i][n + 1] = b[i]; }
        for (int j = 0; j < n; j++) { N[j] = j; D[m][
            j] = -c[j]; }

```

```

        N[n] = -1; D[m + 1][n] = 1;
    }

    void Pivot(int r, int s) {
        double inv = 1.0 / D[r][s];
        for (int i = 0; i < m + 2; i++) if (i != r)
            for (int j = 0; j < n + 2; j++) if (j != s)
                D[i][j] -= D[r][j] * D[i][s] * inv;
        for (int j = 0; j < n + 2; j++) if (j != s) D
            [r][j] *= inv;
        for (int i = 0; i < m + 2; i++) if (i != r) D
            [i][s] *= -inv;
        D[r][s] = inv;
        swap(B[r], N[s]);
    }

    bool Simplex(int phase) {
        int x = phase == 1 ? m + 1 : m;
        while (true) {
            int s = -1;
            for (int j = 0; j <= n; j++) {
                if (phase == 2 && N[j] == -1) continue;
                if (s == -1 || D[x][j] < D[x][s] || D[x][
                    j] == D[x][s] && N[j] < N[s]) s = j;
            }
            if (D[x][s] > -EPS) return true;
            int r = -1;
            for (int i = 0; i < m; i++) {
                if (D[i][s] < EPS) continue;
                if (r == -1 || D[i][n + 1] / D[i][s] < D[
                    r][n + 1] / D[r][s] ||
                    (D[i][n + 1] / D[i][s]) == (D[r][n + 1]
                        / D[r][s]) && B[i] < B[r]) r = i;
            }
            if (r == -1) return false;
            Pivot(r, s);
        }
    }

    DOUBLE Solve(VD &x) {
        int r = 0;
        for (int i = 1; i < m; i++) if (D[i][n + 1] <
            D[r][n + 1]) r = i;
        if (D[r][n + 1] < -EPS) {
            Pivot(r, n);
            if (!Simplex(1) || D[m + 1][n + 1] < -EPS)
                return numeric_limits<DOUBLE>::
                    infinity();
            for (int i = 0; i < m; i++) if (B[i] == -1)
                {
                    int s = -1;
                    for (int j = 0; j <= n; j++)
                        if (s == -1 || D[i][j] < D[i][s] || D[i]
                            [j] == D[i][s] && N[j] < N[s]) s =
                                j;
                    Pivot(i, s);
                }
        }
        if (!Simplex(2)) return numeric_limits<DOUBLE>
            >::infinity();
        x = VD(n);
        for (int i = 0; i < m; i++) if (B[i] < n) x[B
            [i]] = D[i][n + 1];
        return D[m][n + 1];
    }
}

int main() {
    const int m = 4;
    const int n = 3;

```

```

    DOUBLE _A[m][n] = {
        { 6, -1, 0 }, { -1, -5, 0 },
        { 1, 5, 1 }, { -1, -5, -1 }
    };
    DOUBLE _b[m] = { 10, -4, 5, -5 };
    DOUBLE _c[n] = { 1, -1, 0 };

    VVD A(m);
    VD b(_b, _b + m);
    VD c(_c, _c + n);
    for (int i = 0; i < m; i++) A[i] = VD(_A[i], _A
        [i] + n);

    LPSolver solver(A, b, c);
    VD x;
    DOUBLE value = solver.Solve(x);

    cerr << "VALUE: " << value << endl; // VALUE:
        1.29032
    cerr << "SOLUTION:"; // SOLUTION: 1.74194
        0.451613 1
    for (size_t i = 0; i < x.size(); i++) cerr << "
        " << x[i];
    cerr << endl;
    return 0;
}

```

4.6 Constraint Satisfaction Problem

```

// Constraint satisfaction problems
// TODO doesn't compile

#include "template.h"

#define DONE -1
#define FAILED -2

typedef vector<int> vi;
typedef vector<vi> vvi;
typedef vector<vvi> vvvi;

typedef set<int> SI;

// Lists of assigned/unassigned variables.
vi assigned_vars;
SI unassigned_vars;

// For each variable, a list of reductions (each
// of which a list of eliminated
// variables)
vvvi reductions;

// For each variable, a list of the variables
// whose domains it reduced in
// forward-checking.
vvi forward_mods;

// need to implement -----
int Value(int var);

void SetValue(int var, int value);
void ClearValue(int var);

int DomainSize(int var);
void ResetDomain(int var);
void AddValue(int var, int value);
void RemoveValue(int var, int value);

int NextVar() {
    if (unassigned_vars.empty()) return DONE;

    // could also do most constrained...

```

```

    int var = *unassigned_vars.begin();
    return var;
}

int Initialize() {
    // setup here
    return NextVar();
}
// ----- end -- need to
// implement

void UpdateCurrentDomain(int var) {
    ResetDomain(var);
    for (int i = 0; i < reductions[var].size(); i++) {
        vector<int>& red = reductions[var][i];
        for (int j = 0; j < red.size(); j++) {
            RemoveValue(var, red[j]);
        }
    }

    void UndoReductions(int var) {
        for (int i = 0; i < forward_mods[var].size(); i++) {
            int other_var = forward_mods[var][i];
            vi& red = reductions[other_var].back();
            for (int j = 0; j < red.size(); j++) {
                AddValue(other_var, red[j]);
            }
            reductions[other_var].pop_back();
        }
        forward_mods[var].clear();
    }

    bool ForwardCheck(int var, int other_var) {
        vector<int> red;

        foreach value in current_domain(other_var) {
            SetValue(other_var, value);
            if ( !Consistent(var, other_var) ) {
                red.push_back(value);
                RemoveValue(other_var, value);
            }
            ClearValue(other_var);
        }
        if ( !red.empty() ) {
            reductions[other_var].push_back(red);
            forward_mods[var].push_back(other_var);
        }

        return DomainSize(other_var) != 0;
    }
}

```

```

pair<int, bool> Unlabel(int var) {
    assigned_vars.pop_back();
    unassigned_vars.insert(var);

    UndoReductions(var);
    UpdateCurrentDomain(var);

    if ( assigned_vars.empty() ) return make_pair(
        FAILED, true);

    int prev_var = assigned_vars.back();
    RemoveValue(prev_var, Value(prev_var));
    ClearValue(prev_var);
    if ( DomainSize(prev_var) == 0 ) {
        return make_pair(prev_var, false);
    } else {

```

```

        return make_pair(prev_var, true);
    }
}

pair<int, bool> Label(int var) {
    unassigned_vars.erase(var);
    assigned_vars.push_back(var);

    bool consistent;
    foreach value in current_domain(var) {
        SetValue(var, value);
        consistent = true;
        for (int j=0; j<unassigned_vars.size(); j++) {
            int other_var = unassigned_vars[j];
            if ( !ForwardCheck(var, other_var) ) {
                RemoveValue(var, value);
                consistent = false;
                UndoReductions(var);
                ClearValue(var);
                break;
            }
        }
        if ( consistent ) return (NextVar(), true);
    }
    return make_pair(var, false);
}

void BacktrackSearch(int num_var) {
    // (next variable to mess with, whether current
    // state is consistent)
    pair<int, bool> var_consistent = make_pair(
        Initialize(), true);
    while ( true ) {
        if ( var_consistent.second ) var_consistent =
            Label(var_consistent.first);
        else var_consistent = Unlabel(var_consistent.
            first);

        if ( var_consistent.first == DONE ) return;
        // solution found
        if ( var_consistent.first == FAILED ) return;
        // no solution
    }
}

```

5 Graph algorithms

5.1 Fast Dijkstra's algorithm

```

// Implementation of Dijkstra's algorithm using
// adjacency lists
// and priority queue for efficiency.
//
// Running time:  $O(|E| \log |V|)$ 

#include "template.h"
const int INF = 2000000000;

int main() {
    int N, s, t;
    scanf("%d%d%d", &N, &s, &t);
    vector<vector<pii>> edges(N);
    for (int i = 0; i < N; i++) {
        int M;

```

```

        scanf("%d", &M);
        for (int j = 0; j < M; j++) {
            int vertex, dist;
            scanf("%d%d", &vertex, &dist);
            edges[i].push_back(make_pair(dist, vertex))
                ; // note order of arguments here
        }
    }

    // use priority queue in which top element has
    // the "smallest" priority
    priority_queue<pii, vector<pii>, greater<pii>> >
        Q;
    vector<int> dist(N, INF), dad(N, -1);
    Q.push(make_pair(0, s));
    dist[s] = 0;
    while (!Q.empty()) {
        pii p = Q.top();
        Q.pop();
        int here = p.second;
        if (here == t) break;
        if (dist[here] != p.first) continue;

        for (vector<pii>::iterator it = edges[here].
            begin(); it != edges[here].end(); it++) {
            if (dist[here] + it->first < dist[it->
                second]) {
                dist[it->second] = dist[here] + it->first
                    ;
                dad[it->second] = here;
                Q.push(make_pair(dist[it->second], it->
                    second));
            }
        }
    }

    printf("%d\n", dist[t]);
    if (dist[t] < INF)
        for (int i = t; i != -1; i = dad[i])
            printf("%d%c", i, (i == s ? '\n' : ' '));
    return 0;
}

/*
Sample input:
5 0 4
2 1 2 3 1
2 2 4 4 5
3 1 4 3 3 4 1
2 0 1 2 3
2 1 5 2 1

Expected:
5
4 2 3 0
*/

```

5.2 Topological sort (C++)

```

// This function uses performs a non-recursive
// topological sort.
//
// Running time:  $O(|V|^2)$ . If you use adjacency
// lists (vector<map<int>> >),
// the running time is reduced to  $O(|E|)$ .
//
// INPUT: w[i][j] = 1 if i should come before
// j, 0 otherwise

```

```
// OUTPUT: a permutation of 0,...,n-1 (stored
//         in a vector)
//         which represents an ordering of the
//         nodes which
//         is consistent with w
//
// If no ordering is possible, false is returned.
// TODO Optimization required

#include <iostream>
#include <queue>
#include <cmath>
#include <vector>

using namespace std;

typedef double T;
typedef vector<T> VT;
typedef vector<VT> VVT;

typedef vector<int> VI;
typedef vector<VI> VVI;

bool TopologicalSort (const VVI &w, VI &order){
    int n = w.size();
    VI parents (n);
    queue<int> q;
    order.clear();

    for (int i = 0; i < n; i++){
        for (int j = 0; j < n; j++){
            if (w[j][i]) parents[i]++;
            if (parents[i] == 0) q.push (i);
        }

        while (q.size() > 0){
            int i = q.front();
            q.pop();
            order.push_back (i);
            for (int j = 0; j < n; j++){ if (w[i][j]){
                parents[j]--;
                if (parents[j] == 0) q.push (j);
            }
        }

        return (order.size() == n);
    }
}
```

5.3 Union-find set(aka DSU)

```
#include "template.h"

int find(vector<int> &C, int x) { return (C[x] ==
x) ? x : C[x] = find(C, C[x]); }
void merge(vector<int> &C, int x, int y) { C[find
(C, x)] = find(C, y); }

int main() {
    int n = 5;
    vector<int> C(n);
    for (int i = 0; i < n; i++) C[i] = i;
    merge(C, 0, 2);
    merge(C, 1, 0);
    merge(C, 3, 4);
    for (int i = 0; i < n; i++) cout << i << " " <<
        find(C, i) << endl;
    return 0;
}
```

5.4 Kosaraju Strongly connected components

```
// 1.For each vertex u of the graph, mark u as
//    unvisited. Let L be empty.
// 2.For each vertex u of the graph do Visit(u),
//    where Visit(u) is the recursive subroutine:
//    If u is unvisited then:
//        Mark u as visited.
//        For each out-neighbour v of u, do Visit(
//            v).
//        Prepend u to L.
//    Otherwise do nothing.
// 3.For each element u of L in order, do Assign(
//    u,u) where Assign(u,root) is the recursive
//    subroutine:
//    If u has not been assigned to a component
//    then:
//        Assign u as belonging to the component
//        whose root is root.
//        For each in-neighbour v of u, do Assign(
//            v,root).
//    Otherwise do nothing.
vi adj[N], adjt[N];
int n, ordn, cnt, vis[N], ord[N], cmp[N];

void dfs(int x) {
    vis[x] = 1;
    for (auto v : adj[x]) if (!vis[v]) dfs(v);
    ord[ordn++] = x;
}

void dfst(int x) {
    cmp[x] = cnt, vis[x] = 0;
    for (auto v : adjt[u]) if (vis[v]) dfst(v);
}

// in main
for (int i = 1; i <= n; ++i) if (!vis[i]) dfs(i);
for (int i = ordn-1; i >= 0; --i) if (vis[ord[i]
]) cnt++, dfst(ord[i]);
```

5.5 Bellman Ford's algorithm

```
// This function runs the Bellman-Ford algorithm
// for single source
// shortest paths with negative edge weights.
// The function returns
// false if a negative weight cycle is detected.
// Otherwise, the
// function returns true and dist[i] is the
// length of the shortest
// path from start to i.
//
// Running time:  $O(|V|^3)$ 
//
// INPUT: start, w[i][j] = cost of edge from
//         i to j
// OUTPUT: dist[i] = min weight path from
//         start to i
//         prev[i] = previous node on the best
//         path from the start node

#include <iostream>
#include <queue>
```

```
#include <cmath>
#include <vector>

using namespace std;

typedef double T;
typedef vector<T> VT;
typedef vector<VT> VVT;

typedef vector<int> VI;
typedef vector<VI> VVI;

bool BellmanFord (const VVT &w, VT &dist, VI &
    prev, int start){
    int n = w.size();
    prev = VI(n, -1);
    dist = VT(n, 1000000000);
    dist[start] = 0;

    for (int k = 0; k < n; k++){
        for (int i = 0; i < n; i++){
            for (int j = 0; j < n; j++){
                if (dist[j] > dist[i] + w[i][j]){
                    if (k == n-1) return false;
                    dist[j] = dist[i] + w[i][j];
                    prev[j] = i;
                }
            }
        }
    }

    return true;
}
```

5.6 Minimum Spanning Tree: Kruskal

```
/*
Uses Kruskal's Algorithm to calculate the weight
of the minimum spanning
forest (union of minimum spanning trees of each
connected component) of
a possibly disjoint graph, given in the form of a
matrix of edge weights
(-1 if no edge exists). Returns the weight of the
minimum spanning
forest (also calculates the actual edges - stored
in T). Note: uses a
disjoint-set data structure with amortized (
effectively) constant time per
union/find. Runs in  $O(E \cdot \log(E))$  time.
*/
#include "template.h"

typedef int T;
struct edge{
    int u, v;
    T d;
};

struct edgeCmp{
    int operator()(const edge& a, const edge& b) {
        return a.d > b.d; }
};

int find(vector <int>& C, int x) { return (C[x]
== x)?x: C[x]=find(C, C[x]); }

T Kruskal(vii Alist[], int n){
    T weight = 0;

    vector <int> C(n), R(n);
```



```

for(int i=0; i<n; i++) { C[i] = i; R[i] = 0; }
vector<edge> T;
priority_queue<edge, vector<edge>, edgeCmp> E;

rep(i, n)
rep(j, Alist[i].size()) {
    edge e;
    e.u = i, e.v = Alist[i][j].F, e.d = Alist[i][j].S;
    E.push(e);
}

while(T.size() < n-1 && !E.empty()) {
    edge cur = E.top(); E.pop();
    int uc = find(C, cur.u), vc = find(C, cur.v);
    if(uc != vc) {
        T.push_back(cur); weight += cur.d;
        if(R[uc] > R[vc])
            C[vc] = uc;
        else if(R[vc] > R[uc])
            C[uc] = vc;
        else
            C[vc] = uc; R[uc]++;
    }
}
return weight;

int main() {
    int n;
    cin >> n;
    vii Alist[Lim];
    cout << Kruskal(Alist, n) << endl;
}

```

5.7 Eulerian Path Algo

```

#include "template.h"
struct Edge;
typedef list<Edge>::iterator iter;

struct Edge {
    int next_vertex;
    iter reverse_edge;

    Edge(int next_vertex) :next_vertex(next_vertex)
    { }
};

const int max_vertices = 10;
// int num_vertices = 6;
list<Edge> adj[max_vertices]; // adjacency list

vector<int> path;

void find_path(int v) {
    while(adj[v].size() > 0) {
        int vn = adj[v].front().next_vertex;
        adj[vn].erase(adj[v].front().reverse_edge);
        adj[v].pop_front();
        find_path(vn);
    }
    path.push_back(v);
}

void add_edge(int a, int b) {
    adj[a].push_front(Edge(b));
    iter ita = adj[a].begin();

```

```

adj[b].push_front(Edge(a));
iter itb = adj[b].begin();
ita->reverse_edge = itb;
itb->reverse_edge = ita;
}

int main() {
    int total=0, start_vertex = 0;
    rep(i, max_vertices)
        if(adj[i].size() & 1)
            // if the size is odd then increment 'total'
            total++; start_vertex=i; // put the starting vertex as an odd degree vertex
    if(total==0 || total==2) {
        // necessary and sufficient condition to check the existence of an EC
        find_path(start_vertex);
        rep(i, path.size()) cout << path[i] << " ";
    }
    else
        cout << "No Eulerian Circuit\n";
    return 0;
}

```

5.8 FloydWarshall's Algorithm

```

#include "template.h"

typedef double T;
typedef vector<T> vt;
typedef vector<vt> vvt;
typedef vector<vi> vvi;

// This function runs the Floyd-Warshall algorithm for all-pairs shortest paths. Also handles negative edge weights. Returns true if a negative weight cycle is found.
// Running time: O(|V|^3)
// INPUT: Alist[i][j] = Alistweight of edge from i to j
// OUTPUT: Alist[i][j] = shortest path from i to j
// prev[i][j] = node before j on the best path starting at i

bool FloydWarshall(vvt &Alist, vvi &prev) {
    int n = Alist.size();
    prev = vvi(n, vi(n, -1));

    for(int k = 0; k < n; k++){
        for(int i = 0; i < n; i++){
            for(int j = 0; j < n; j++){
                if(Alist[i][j] > Alist[i][k] + Alist[k][j]){
                    Alist[i][j] = Alist[i][k] + Alist[k][j];
                    prev[i][j] = k;
                }
            }
        }
    }

    // check for negative weight cycles
    for(int i=0; i<n; i++)

```

```

        if (Alist[i][i] < 0) return false;
    return true;
}

```

5.9 Prim's Algo in $O(n^2)$ time

```

#include "template.h"

// This function runs Prim's algorithm for constructing minimum weight spanning trees.
// Running time: O(|V|^2)
// INPUT: w[i][j] = cost of edge from i to j
// NOTE: Make sure that w[i][j] is nonnegative and symmetric. Missing edges should be given -1 weight.
// OUTPUT: edges = list of pair<int,int> in minimum spanning tree return total weight of tree

typedef double T;
typedef vector<T> vt;
typedef vector<vt> vvt;
typedef vector<vi> vvi;

T Prim(const vvt &w, vvi &edges) {
    int n = w.size();
    vi found(n);
    vi prev(n, -1);
    vt dist(n, 1000000000);
    int here = 0;
    dist[here] = 0;

    while(here != -1) {
        found[here] = true;
        int best = -1;
        for(int k = 0; k < n; k++) if(!found[k]) {
            if(w[here][k] != -1 && dist[k] > w[here][k]) {
                dist[k] = w[here][k];
                prev[k] = here;
            }
            if(best == -1 || dist[k] < dist[best])
                best = k;
        }
        here = best;
    }

    T tot_weight = 0;
    for(int i = 0; i < n; i++) if(prev[i] != -1) {
        edges.push_back(make_pair(prev[i], i));
        tot_weight += w[prev[i]][i];
    }
    return tot_weight;
}

```

5.10 MST for a directed graph

```

/* Edmond's Algorithm for finding an aborescence
 * Produces an aborescence (directed analog of a minimum

```

```

* spanning tree) of least weight in O(m*n) time
*/

#include "template.h"
#define sz size()
#define D(x) if(1) cout << __LINE__ << " " << #x "
    = " << (x) << endl;
#define D2(x,y) if(1) cout << __LINE__ << " " << #x
    " = " << (x) \
    << ", " << #y " = " << (y) << endl;
typedef vector<vi> vvi;
#define SZ(x) ((x).size())
int N;

vi match;
vi vis;

void couple(int n, int m) { match[n]=m; match[m]=
    n; }

// returns true if something interesting has been
// found, thus a
// augmenting path or a blossom (if blossom is
// non-empty).
// the dfs returns true from the moment the stem
// of the flower is
// reached and thus the base of the blossom is an
// unmatched node.
// blossom should be empty when dfs is called and
// contains the nodes of the blossom when a
// blossom is found.
bool dfs(int n, vvi &conn, vi &blossom) {
    vis[n]=0;
    rep(i, N) {
        if(conn[n][i]) {
            if(vis[i]==-1) {
                vis[i]=1;
                if(match[i]==-1 || dfs(match[i], conn,
                    blossom)) { couple(n,i); return true;
                }
            }
            if(vis[i]==0 || SZ(blossom)) { // found
                flower
                blossom.pb(i); blossom.pb(n);
                if(n==blossom[0]) { match[n]=-1; return
                    true; }
                return false;
            }
        }
    }
    return false;
}

// search for an augmenting path.
// if a blossom is found build a new graph (
// newconn) where the
// (free) blossom is shrunken to a single node
// and recurse.
// if a augmenting path is found it has already
// been augmented
// except if the augmented path ended on the
// shrunken blossom.
// in this case the matching should be updated
// along the appropriate
// direction of the blossom.
bool augment(vvi &conn) {
    rep(m, N) {
        if(match[m]==-1) {
            vi blossom;
            vis=vi(N,-1);
            if(!dfs(m, conn, blossom)) continue;

```

```

        if(SZ(blossom)==0) return true; //
            augmenting path found

        // blossom is found so build shrunken graph
        int base=blossom[0], S=SZ(blossom);
        vvi newconn=conn;
        rep(i, 1, S-1) rep(j, N) newconn[base][j]=
            newconn[j][base]=conn[blossom[i]][j];
        rep(i, 1, S-1) rep(j, N) newconn[blossom[i]
            ][j]=newconn[j][blossom[i]]=0;
        newconn[base][base]=0; // is now the new
            graph
        if(!augment(newconn)) return false;
        int n=match[base];
        D(base);
        // if n!=-1 the augmenting path ended on
            this blossom

        if(n!=-1) rep(i, S) if(conn[blossom[i]][n])
            {
                couple(blossom[i], n);
                if(i&1) for(int j=i+1; j<S; j+=2) couple(
                    blossom[j],blossom[j+1]);
                else for(int j=0; j<i; j+=2) couple(
                    blossom[j],blossom[j+1]);
                break;
            }
        return true;
    }
    return false;
}

int edmonds(vvi &conn) { //conn is the Adjacency
    matrix
    int res=0;
    match=vi(N,-1);
    while(augment(conn)) res++;
    return res;
}

int main() {
    vvi conn(10, vi(10, 0)); // Adjacency matrix
    #define addEdge(x,y) conn[x][y]=conn[y][x] = 1;
    addEdge(1,2);
    addEdge(2,3);
    addEdge(2,5);
    addEdge(5,3);
    addEdge(3,4);
    addEdge(5,6);
    N = conn.size();
    D(edmonds(conn));
    return 0;
}

```

5.11 Maximum Matching in a Bipartite graphss

```

// Hopcraft-Karp Algo for finding Maximum
// Bipartite
// Matching using Augmenting paths

#include "template.h"

const int MAXN1 = 50000;
const int MAXN2 = 50000;
const int MAXM = 150000;

```

```

int n1, n2, edges, last[MAXN1], prev[MAXM], head[
    MAXM];
int matching[MAXN2], dist[MAXN1], Q[MAXN1];
bool used[MAXN1], vis[MAXN1];

void init(int _n1, int _n2) {
    n1 = _n1;
    n2 = _n2;
    edges = 0;
    fill(last, last + n1, -1);
}

void addEdge(int u, int v) {
    head[edges] = v;
    prev[edges] = last[u];
    last[u] = edges++;
}

void bfs() {
    fill(dist, dist + n1, -1);
    int sizeQ = 0;
    for (int u = 0; u < n1; ++u) {
        if (!used[u]) {
            Q[sizeQ++] = u;
            dist[u] = 0;
        }
    }
    for (int i = 0; i < sizeQ; i++) {
        int ul = Q[i];
        for (int e = last[ul]; e >= 0; e = prev[e]) {
            int u2 = matching[head[e]];
            if (u2 >= 0 && dist[u2] < 0) {
                dist[u2] = dist[ul] + 1;
                Q[sizeQ++] = u2;
            }
        }
    }
}

bool dfs(int ul) {
    vis[ul] = true;
    for (int e = last[ul]; e >= 0; e = prev[e]) {
        int v = head[e];
        int u2 = matching[v];
        if (u2 < 0 || !vis[u2] && dist[u2] == dist[ul]
            + 1 && dfs(u2)) {
            matching[v] = ul;
            used[ul] = true;
            return true;
        }
    }
    return false;
}

int maxMatching() {
    fill(used, used + n1, false);
    fill(matching, matching + n2, -1);
    for (int res = 0;;) {
        bfs();
        fill(vis, vis + n1, false);
        int f = 0;
        for (int u = 0; u < n1; ++u)
            if (!used[u] && dfs(u))
                ++f;
        if (!f)
            return res;
        res += f;
    }
}

int main() {
    init(2, 2);
}

```

```

addEdge(0, 0); addEdge(0, 1); addEdge(1, 1);
cout << (2 == maxMatching()) << endl;
}

```

5.12 Articulation Pt/Bridge in a Graph

```

#include "template.h"

// Array u acts as visited bool array, d stores
// DFN No., low
// stores lowest DFN no reachable, par stores
// parent node's DFN no.

int gl = 0;
const int N = 10010;
int u[N], d[N], low[N], par[N];
vi G[N];
void dfs1(int node, int dep) { // find dfs_num and
    dfs_low
    u[node] = 1;
    d[node] = dep; low[node] = dep;
    for (int i = 0; i < G[node].size(); i++) {
        int it = G[node][i];
        if (!u[it]) {
            par[it] = node;
            dfs1(it, dep + 1);
            low[node] = min(low[node], low[it]);
            /* if (low[it] > d[node]) {
                node-it is cut edge/bridge
            } */
            /*
            if (low[it] >= d[node] && (par[node] != -1 ||
                sz(G[node]) > 2)) {
                node is cut vertex/articulation point
            }
            */
        } else if (par[node] != it) low[node] = min(low[
            node], low[it]);
        else par[node] = -1;
    }
}

int main() {
    return 0;
}

```

5.13 Closest Pair of points in a 2D Plane

```

#include "template.h"
const int MAXN = 4;
struct pt {
    int x, y, id;
};
// comparison on basis of x coordinate
inline bool cmp_x (const pt & a, const pt & b) {
    return a.x < b.x || a.x == b.x && a.y < b.y;
}
// comparison on basis of y coordinate
inline bool cmp_y (const pt & a, const pt & b) {
    return a.y < b.y;
}
// a for storing points
pt a[MAXN];
double mindist;
int ansa, ansb;

```

```

inline void upd_ans (const pt & a, const pt & b)
{
    double dist = sqrt ((a.x-b.x)*(a.x-b.x) + (a.y-
        b.y)*(a.y-b.y) + .0);
    if (dist < mindist)
        mindist = dist, ansa = a.id, ansb = b.id;
}
// the basic recursive function
void rec (int l, int r) {
    if (r - l <= 3) {
        for (int i = l; i <= r; ++i)
            for (int j = i + 1; j <= r; ++j)
                upd_ans (a[i], a[j]);
        sort (a + l, a + r + 1, &cmp_y);
        return;
    }

    int m = (l + r) >> 1;
    int midx = a[m].x;
    rec (l, m), rec (m + 1, r);
    static pt t[MAXN];
    merge (a + l, a + m + 1, a + m + 1, a + r + 1, t, &cmp_y);
    copy (t, t + r - l + 1, a + l);

    int tsz = 0;
    for (int i = l; i <= r; ++i)
        if (abs (a[i].x - midx) < mindist) {
            for (int j = tsz - 1; j >= 0 && a[i].y - t[j].y <
                mindist; --j)
                upd_ans (a[i], t[j]);
            t[tsz++] = a[i];
        }

    int main() {
        int n = 4;
        mindist = 1E20; // final answer is stored in
            mindist
        sort (a, a + n, &cmp_x);
        rec (0, n - 1);
        cout << mindist << "\n";
        return 0;
    }
}

```

6 Data structures

6.1 Binary Indexed Tree

```

#include <iostream>
using namespace std;

#define LOGSZ 17

int tree[(1 << LOGSZ) + 1];
int N = (1 << LOGSZ);

// add v to value at x
void set(int x, int v) {
    while (x <= N) {
        tree[x] += v;
        x += (x & -x);
    }
}

// get cumulative sum up to and including x
int get(int x) {
    int res = 0;
    while (x) {
        res += tree[x];
    }
}

```

```

    x -= (x & -x);
}
return res;

// get largest value with cumulative sum less
// than or equal to x;
// for smallest, pass x-1 and add 1 to result
int getind(int x) {
    int idx = 0, mask = N;
    while (mask && idx < N) {
        int t = idx + mask;
        if (x >= tree[t]) {
            idx = t;
            x -= tree[t];
        }
        mask >>= 1;
    }
    return idx;
}

```

6.2 BIT for 2-D plane questions

```

/* Bit used as 2-D structure for a handling
update/range
queries in a matrix in  $\log^2(n)$  time */

#include "template.h"
int bit[M][M], n;
int sum(int x, int y) {
    int ret = 0;
    while (x > 0) {
        int yy = y; while (yy > 0) ret += bit[x
            ][yy], yy -= yy & -yy;
        x -= (x & -x);
    }
    return ret;
}

void update(int x, int y, int val) {
    int y1;
    while (x <= n) {
        y1 = y;
        while (y1 <= n) { bit[x][y1] += val; y1 +=
            (y1 & -y1); }
        x += (x & -x);
    }
}

```

6.3 Lowest common ancestor

```

const int max_nodes, log_max_nodes;
int num_nodes, log_num_nodes, root;

vector<int> children[max_nodes]; // children[i]
// contains the children of node i
int A[max_nodes][log_max_nodes + 1]; // A[i][j] is
// the 2^j-th ancestor of node i, or -1 if that
// ancestor does not exist
int L[max_nodes]; // L[i] is the distance
// between node i and the root

// floor of the binary logarithm of n
int lb(unsigned int n) {
    if (n == 0)
        return -1;
    int p = 0;
    if (n >= 1 << 16) { n >>= 16; p += 16; }
}

```

```

if (n >= 1<< 8) { n >>= 8; p += 8; }
if (n >= 1<< 4) { n >>= 4; p += 4; }
if (n >= 1<< 2) { n >>= 2; p += 2; }
if (n >= 1<< 1) { p += 1; }
return p;
}

void DFS(int i, int l) {
    L[i] = l;
    for(int j = 0; j < children[i].size(); j++)
        DFS(children[i][j], l+1);
}

int LCA(int p, int q) {
    // ensure node p is at least as deep as node q
    if(L[p] < L[q])
        swap(p, q);

    // "binary search" for the ancestor of node p
    // situated on the same level as q
    for(int i = log_num_nodes; i >= 0; i--)
        if(L[p] - (1<<i) >= L[q])
            p = A[p][i];

    if(p == q)
        return p;

    // "binary search" for the LCA
    for(int i = log_num_nodes; i >= 0; i--)
        if(A[p][i] != -1 && A[p][i] != A[q][i]) {
            p = A[p][i];
            q = A[q][i];
        }

    return A[p][0];
}

int main(int argc, char* argv[]) {
    // read num_nodes, the total number of nodes
    log_num_nodes = lb(num_nodes);

    for(int i = 0; i < num_nodes; i++) {
        int p;
        // read p, the parent of node i or -1 if node
        // i is the root

        A[i][0] = p;
        if(p != -1)
            children[p].push_back(i);
        else
            root = i;
    }

    // precompute A using dynamic programming
    for(int j = 1; j <= log_num_nodes; j++)
        for(int i = 0; i < num_nodes; i++)
            if(A[i][j-1] != -1)
                A[i][j] = A[A[i][j-1]][j-1];
            else
                A[i][j] = -1;

    // precompute L
    DFS(root, 0);

    return 0;
}

```

6.4 Lazy Propagation for Range update and Query

```
#include "template.h"
```

```

/*
    A lazy tree implementation of Range Updation &
    Range Query
*/

ll Arr[Lim], Tree[4*Lim], lazy[4*Lim];

void build_tree(int Node, int a, int b) {
    // Do not forget to clear lazy Array before
    // calling build

    if(a == b) {
        Tree[Node] = Arr[a];
    } else if (a < b) {
        int mid = (a+b)>>1, left=Node<<1, right=left|1;
        build_tree(left, a, mid); build_tree(right,
            mid+1, b);
        Tree[Node] = Tree[left]+Tree[right];
    }
}

void Propagate(int Node, int a, int b) {
    int left=Node<<1, right=left|1;
    Tree[Node] += lazy[Node] * (b-a+1);
    if(a != b) {
        lazy[left] += lazy[Node];
        lazy[right] += lazy[Node];
    }
    lazy[Node] = 0;
}

void update_tree (int Node, int start, int end,
    ll value, int a, int b) {
    int mid=(a+b)>>1, left=Node<<1, right=left|1;
    if(lazy[Node] != 0)
        Propagate(Node, a, b);

    if(a > b || a > end || b < start) {
        return;
    } else {
        if (start <= a && b <= end) {
            if (a != b) {
                lazy[left] += value;
                lazy[right] += value;
            }
            Tree[Node] += value * (b - a + 1);
        } else {
            update_tree(left, start, end, value, a, mid);
            update_tree(right, start, end, value, mid
                +1, b);
            Tree[Node]=Tree[left]+Tree[right];
        }
    }
}

ll query(int Node, int start, int end, int a, int
    b) {
    int mid=(a+b)>>1, left=Node<<1, right=left|1;
    if(lazy[Node] != 0)
        Propagate(Node, a, b);

    if (a > b || a > end || b < start) {
        return 0;
    } else {
        ll Sum1, Sum2;
        if (start <= a && b <= end) {
            return Tree[Node];
        } else {
            Sum1 = query(left, start, end, a, mid);

```

```

        Sum2 = query(right, start, end, mid + 1, b);
        return Sum1+Sum2;
    }
}

```

6.5 Range minima query in O(1) time using lookup matrix

```

/* matrix structure for finding the range minima
   in O(1) time using O(n) log(n)) space */
#include "template.h"
#define better(a,b) A[a]<A[b]?(a):(b)
int A[100100], H[1100][1100]; //A is the Array
//and H is the lookup matrix
int make_dp(int n) { // N log N
    rep(i,n) H[i][0]=i;
    for(int l=0,k; (k=1<<l) < n; l++) for(int i
        =0;i+k<n;i++)
        H[i][l+1] = better(H[i][l], H[i+k][l]);
}

int query_dp(int a, int b) {
    int l = __lg(b-a);
    return better(H[a][l], H[b-(1<<l)+1][l]);
}

```

7 String Manipulation

7.1 KMP

```

// return the prefix function
private static int[] KMPpre(final String P) {
    final int n = P.length();
    final int[] pi = new int[n];
    pi[0] = 0;
    int k = 0;
    for (int q = 1; q < n; q++) {
        while (k > 0 && P.charAt(k) != P.charAt(q)) {
            k = pi[k - 1];
        }
        if (P.charAt(k) == P.charAt(q)) {
            k++;
        }
        pi[q] = k;
    }
    return pi;
}

public static Pair<Integer, ArrayList<Integer>>
    KMP(final String haystack, final String
        needle) {
    final int m = haystack.length();
    final int n = needle.length();
    final int[] pi = KMPpre(needle);
    int q = 0;
    int count = 0;
    ArrayList<Integer> resArr = new ArrayList<>();
    for (int i = 0; i < m; i++) {
        while (q > 0 && haystack.charAt(i) != needle.
            charAt(q)) {
            q = pi[q - 1];
        }
        if (haystack.charAt(i) == needle.charAt(q)) {

```

```

q++;
}
if (q == n) {
    count++;
    resArr.add(i + 1 - n);
    q = pi[q - 1];
}
}
return new Pair<Integer, ArrayList<Integer>>(
    count, resArr);
}

```

7.2 Suffix array

```

// Begins Suffix Arrays implementation
// O(n log n) - Manber and Myers algorithm

// SA = The suffix array. Contains the n suffixes
// of txt sorted in lexicographical order.
// Each suffix is represented as a single
// integer (the SAition of txt where it starts).
// iSA = The inverse of the suffix array. iSA[i]
// = the index of the suffix txt[i..n)
// in the SA array. (In other words, SA[i]
// = k <=> iSA[k] = i)
// With this array, you can compare two
// suffixes in O(1): Suffix txt[i..n) is smaller
// than txt[j..n) if and only if iSA[i] <
// iSA[j]
const int MAX = 1000100;
char txt[MAX]; //input
int iSA[MAX], SA[MAX]; //output
int cnt[MAX];
int nex[MAX]; //internal
bool bh[MAX], b2h[MAX];

// Compares two suffixes according to their first
// characters
bool smaller_first_char(int a, int b){
    return txt[a] < txt[b];
}

void suffixSort(int n){
    //sort suffixes according to their first
    // characters
    for (int i=0; i<n; ++i){
        SA[i] = i;
    }
    sort(SA, SA + n, smaller_first_char);
    //SA contains the list of suffixes sorted by
    // their first character

    for (int i=0; i<n; ++i){
        bh[i] = i == 0 || txt[SA[i]] != txt[SA[i-1]];
        b2h[i] = false;
    }

    for (int h = 1; h < n; h <= 1){
        //bh[i] == false if the first h characters
        // of SA[i-1] == the first h characters of
        // SA[i]
        int buckets = 0;
        for (int i=0, j; i < n; i = j){
            j = i + 1;
            while (j < n && !bh[j]) j++;
            nex[i] = j; buckets++;
        }
        if (buckets == n) break; // We are done!
        Lucky bastards!
    }
}

```

```

//{suffixes are separted in buckets
// containing txtings starting with the same
// h characters}

for (int i = 0; i < n; i = nex[i]){
    cnt[i] = 0;
    for (int j = i; j < nex[i]; ++j){
        iSA[SA[j]] = i;
    }
}
cnt[iSA[n - h]]++;
b2h[iSA[n - h]] = true;
for (int i = 0; i < n; i = nex[i]){
    for (int j = i; j < nex[i]; ++j){
        int s = SA[j] - h;
        if (s >= 0){
            int head = iSA[s];
            iSA[s] = head + cnt[head]++; b2h[iSA[s]] = true;
        }
    }
    for (int j = i; j < nex[i]; ++j){
        int s = SA[j] - h;
        if (s >= 0 && b2h[iSA[s]]){
            for (int k = iSA[s]+1; !bh[k] && b2h[k]; k++) b2h[k] = false;
        }
    }
    for (int i=0; i<n; ++i){
        SA[iSA[i]] = i; bh[i] |= b2h[i];
    }
}
for (int i=0; i<n; ++i)
    iSA[SA[i]] = i;
// End of suffix array algorithm

// Begin of the O(n) longest common prefix
// algorithm
// Refer to "Linear-Time Longest-Common-Prefix
// Computation in Suffix
// Arrays and Its Applications" by Toru Kasai,
// Gunho Lee, Hiroki
// Arimura, Setsuo Arikawa, and Kunsoo Park.
int lcp[MAX];
// lcp[i] = length of the longest common prefix
// of suffix SA[i] and suffix SA[i-1]
// lcp[0] = 0
void getlcp(int n)
{
    for (int i=0; i<n; ++i)
        iSA[SA[i]] = i;

    lcp[0] = 0;

    for (int i=0, h=0; i<n; ++i) {
        if (iSA[i] > 0) {
            int j = SA[iSA[i]-1];
            while (i + h < n && j + h < n && txt[i+h] == txt[j+h])
                h++;
            lcp[iSA[i]] = h;
            if (h > 0) h--;
        }
    }
}
// End of longest common prefixes algorithm
int main() {
    int len;
    // gets(txt);
}

```

```

for(int i = 0; i < 1000000; i++)
    txt[i] = 'a';
txt[1000000] = '\0';
len = strlen(txt);
printf("%d", len);
suffixSort(len);
getlcp(len);
return 0;
}

```

7.3 Suffix tree

```

#include <stdio.h>
#include <string.h>
#include <stdlib.h>
#define MAX_CHAR 256

struct SuffixTreeNode {
    struct SuffixTreeNode *children[MAX_CHAR];
    //pointer to other node via suffix
    link
    struct SuffixTreeNode *suffixLink;
    /*(start, end) interval specifies the edge, by
    which the
    node is connected to its parent node. Each edge
    will
    connect two nodes, one parent and one child,
    and
    (start, end) interval of a given edge will be
    stored
    in the child node. Lets say there are two nodes
    A and B
    connected by an edge with indices (5, 8) then
    this
    indices (5, 8) will be stored in node B. */
    int start;
    int *end;
    /*for leaf nodes, it stores the index of suffix
    for
    the path from root to leaf*/
    int suffixIndex;
};

typedef struct SuffixTreeNode Node;

char text[100]; //Input string
Node *root = NULL; //Pointer to root node

/*lastNewNode will point to newly created
internal node,
waiting for it's suffix link to be set, which
might get
a new suffix link (other than root) in next
extension of
same phase. lastNewNode will be set to NULL
when last
newly created internal node (if there is any)
got it's
suffix link reset to new internal node created
in next
extension of same phase. */
Node *lastNewNode = NULL;
Node *activeNode = NULL;
/*activeEdge is represented as input string
character
index (not the character itself)*/
int activeEdge = -1;
int activeLength = 0;

```



```
// remainingSuffixCount tells how many suffixes
// yet to
// be added in tree
int remainingSuffixCount = 0;
int leafEnd = -1;
int *rootEnd = NULL;
int *splitEnd = NULL;
int size = -1; //Length of input string
Node *newNode(int start, int *end)
{
    Node *node = (Node*) malloc(sizeof(Node));
    int i;
    for (i = 0; i < MAX_CHAR; i++)
        node->children[i] = NULL;
    /*For root node, suffixLink will be set to NULL
    For internal nodes, suffixLink will be set to
    root
    by default in current extension and may change
    in
    next extension*/
    node->suffixLink = root;
    node->start = start;
    node->end = end;
    /*suffixIndex will be set to -1 by default and
    actual suffix index will be set later for
    leaves
    at the end of all phases*/
    node->suffixIndex = -1;
    return node;
}

int edgeLength(Node *n) {
    return *(n->end) - (n->start) + 1;
}

int walkDown(Node *currNode){
    /*activePoint change for walk down (APCFWD) using
    Skip/Count Trick (Trick 1). If activeLength is
    greater
    than current edge length, set next internal
    node as
    activeNode and adjust activeEdge and
    activeLength
    accordingly to represent same activePoint*/
    if (activeLength >= edgeLength(currNode)) {
        activeEdge += edgeLength(currNode);
        activeLength -= edgeLength(currNode);
        activeNode = currNode;
        return 1;
    }
    return 0;
}

void extendSuffixTree(int pos) {
    /*Extension Rule 1, this takes care of extending
    all
    leaves created so far in tree*/
    leafEnd = pos;
    /*Increment remainingSuffixCount indicating that
    a
    new suffix added to the list of suffixes yet to
    be
    added in tree*/
    remainingSuffixCount++;
    /*set lastNewNode to NULL while starting a new
    phase,
    indicating there is no internal node waiting for
    its suffix link reset in current phase*/
    lastNewNode = NULL;
    /*Add all suffixes (yet to be added) one by one
    in tree
```

```
while(remainingSuffixCount > 0) {
    if (activeLength == 0)
        activeEdge = pos; //APCFALZ
    /* There is no outgoing edge starting
    with
    // activeEdge from activeNode
    if (activeNode->children[text[activeEdge]] == NULL) {
        //Extension Rule 2 (A new leaf edge
        gets created)
        activeNode->children[text[activeEdge]] =
            newNode(pos, &leafEnd);
    }
    /*A new leaf edge is created in above line
    starting
    from an existing node (the current activeNode),
    and
    if there is any internal node waiting for its
    suffix
    link get reset, point the suffix link from that
    last
    internal node to current activeNode. Then set
    lastNewNode
    to NULL indicating no more node waiting for
    suffix link
    reset.*/
    if (lastNewNode != NULL) {
        lastNewNode->suffixLink =
            activeNode;
        lastNewNode = NULL;
    }
    /* There is an outgoing edge starting with
    activeEdge
    // from activeNode
    else {
        // Get the next node at the end of
        edge starting
        // with activeEdge
        Node *next = activeNode->children[
            text[activeEdge]];
        if (walkDown(next)) { //Do walkdown {
            //Start from next node (the new
            activeNode)
            continue;
        }
        /*Extension Rule 3 (current character
        being processed
        is already on the edge)*/
        if (text[next->start + activeLength]
            == text[pos]) {
            //If a newly created node waiting for its
            //suffix link to be set, then set suffix link
            //of that waiting node to current active node
            if (lastNewNode != NULL &&
                activeNode != root) {
                lastNewNode->suffixLink =
                    activeNode;
                lastNewNode = NULL;
            }
            //APCFER3
            activeLength++;
            /*STOP all further processing in this phase
            and move on to next phase*/
            break;
        }
    }
    /*We will be here when activePoint is in middle
    of
    the edge being traversed and current character
    being processed is not on the edge (we fall off
```

```
the tree). In this case, we add a new internal
node
and a new leaf edge going out of that new node.
This
is Extension Rule 2, where a new leaf edge and a
new
internal node get created*/
splitEnd = (int*) malloc(sizeof(int))
;
*splitEnd = next->start +
    activeLength - 1;
    /*New internal node
    Node *split = newNode(next->start,
    splitEnd);
    activeNode->children[text[activeEdge]] = split;
    //New leaf coming out of new internal
    node
    split->children[text[pos]] = newNode(
    pos, &leafEnd);
    next->start += activeLength;
    split->children[text[next->start]] =
    next;
    /*We got a new internal node here. If there is
    any
    internal node created in last extensions of same
    phase which is still waiting for its suffix link
    reset, do it now.*/
    if (lastNewNode != NULL) {
        /*suffixLink of lastNewNode points to current
        newly
        created internal node*/
        lastNewNode->suffixLink = split;
    }
    /*Make the current newly created internal node
    waiting
    for its suffix link reset (which is pointing to
    root
    at present). If we come across any other internal
    node
    (existing or newly created) in next extension of
    same
    phase, when a new leaf edge gets added (i.e. when
    Extension Rule 2 applies is any of the next
    extension
    of same phase) at that point, suffixLink of this
    node
    will point to that internal node.*/
    lastNewNode = split;
}
/* One suffix got added in tree, decrement the
count of
suffixes yet to be added.*/
remainingSuffixCount--;
if (activeNode == root && activeLength >
    0) { //APCFER2C1
    activeLength--;
    activeEdge = pos -
        remainingSuffixCount + 1;
} else if (activeNode != root) { //
    APCFER2C2
    activeNode = activeNode->suffixLink;
}
}

void print(int i, int j) {
    int k;
```

```

    for (k=i; k<=j; k++)
        printf("%c", text[k]);
}

//Print the suffix tree as well along with
//setting suffix index
//So tree will be printed in DFS manner
//Each edge along with it's suffix index will be
//printed
void setSuffixIndexByDFS(Node *n, int labelHeight)
{
    if (n == NULL) return;

    if (n->start != -1) { //A non-root node
        //Print the label on edge from parent to
        //current node
        print(n->start, *(n->end));
    }

    int leaf = 1;
    int i;
    for (i = 0; i < MAX_CHAR; i++) {
        if (n->children[i] != NULL) {
            if (leaf == 1 && n->start != -1)
                printf(" [%d]\n", n->suffixIndex);

            //Current node is not a leaf as it
            //has outgoing
            //edges from it.
            leaf = 0;
            setSuffixIndexByDFS(n->children[i],
                                labelHeight +
                                edgeLength(n->children[i]));
        }
    }

    if (leaf == 1) {
        n->suffixIndex = size - labelHeight;
        printf(" [%d]\n", n->suffixIndex);
    }
}

void freeSuffixTreeByPostOrder(Node *n) {
    if (n == NULL)
        return;
    int i;
    for (i = 0; i < MAX_CHAR; i++) {
        if (n->children[i] != NULL) {
            freeSuffixTreeByPostOrder(n->children[i]);
        }
    }

    if (n->suffixIndex == -1)
        free(n->end);
    free(n);
}

/*Build the suffix tree and print the edge labels
//along with
//suffixIndex. suffixIndex for leaf edges will be
//>= 0 and
//for non-leaf edges will be -1*/
void buildSuffixTree() {
    size = strlen(text);
    int i;
    rootEnd = (int*) malloc(sizeof(int));
    *rootEnd = -1;

    /*Root is a special node with start and end
    //indices as -1,
    //as it has no parent from where an edge
    //comes to root*/
    root = newNode(-1, rootEnd);
}

```

```

activeNode = root; //First activeNode will be
//root
for (i=0; i<size; i++)
    extendSuffixTree(i);
int labelHeight = 0;
setSuffixIndexByDFS(root, labelHeight);

//Free the dynamically allocated memory
freeSuffixTreeByPostOrder(root);
}

// driver program to test above functions
int main(int argc, char *argv[]) {
    // strcpy(text, "abc"); buildSuffixTree();
    // strcpy(text, "xabxac#");
    // buildSuffixTree();
    // strcpy(text, "xabxa"); buildSuffixTree();
    // strcpy(text, "xabxa$"); buildSuffixTree();
    strcpy(text, "abcbxabcd$"); buildSuffixTree();
    // strcpy(text, "geeksforgeeks$");
    // buildSuffixTree();
    // strcpy(text, "THIS IS A TEST TEXT$");
    // buildSuffixTree();
    // strcpy(text, "AABAACAADAABAAABAA$");
    // buildSuffixTree();
    return 0;
}

```

7.4 Aho Corasick Structure for string matching

```

#include "template.h"

#define NC 26 // No of characters
#define NP 10005
#define M 100005
#define MM 500005 // Max no of states

// b stores the strings in dictionary, g stores
// the trie using states,
// a is the query string, lenb stores length of
// strings in b
// output stores the index of word which end at
// the corresponding state
// f stores the blue edge (largest suffix of
// current word), pre is useless!
// marked represent that this word occurs in
// string a

char a[M];
char b[NP][105];
int nb, cnt[NP], lenb[NP], alen;
int g[MM][NC], ng, f[MM], marked[MM];
int output[MM], pre[MM];

#define init(x) {rep(_i,NC)g[x][_i] = -1; f[x]=
//marked[x]=0; output[x]=pre[x]=-1; }

void match() {
    ng = 0;
    init(0);
    // part 1 - building trie
    rep(i,nb) {
        cnt[i] = 0;
        int state = 0, j = 0;

```

```

        while(g[state][b[i][j]] != -1 && j < lenb[i])
            state = g[state][b[i][j]], j++;
        while( j < lenb[i] ) {
            g[state][ b[i][j] ] = ++ng;
            state = ng;
            init( ng );
            ++j;
        }
        // if( ng >= MM ) { cerr <<"i am dying"<<endl;
        // while(1); } // suicide
        output[ state ] = i;
    }

    // part 2 - building failure function
    queue< int > q;
    rep(i,NC) if( g[0][i] != -1 ) q.push( g[0][i] );
    while( !q.empty() ) {
        int r = q.front(); q.pop();
        rep(i,NC) if( g[r][i] != -1 ) {
            int s = g[r][i];
            q.push( s );
            int state = f[r];
            while( g[state][i] == -1 && state ) state =
                f[state];
            f[s] = g[state][i] == -1 ? 0 : g[state][i];
        }
    }

    // final smash
    int state = 0;
    rep(i,alen) {
        while( g[state][a[i]] == -1 ) {
            state = f[state];
            if( !state ) break;
        }
        state = g[state][a[i]] == -1 ? 0 : g[state][a[i]];
        if( state && output[ state ] != -1 ) marked[
            state ] ++;
    }

    // counting
    rep(i,ng+1) if( i && marked[i] ) {
        int s = i;
        while( s != 0 ) cnt[ output[s] ] += marked[i],
            s = f[s];
    }
}

```

7.5 Tries Structure for storing strings

```

#include "template.h"
typedef struct Trie{
    int words, prefixes; //only proper prefixes(
    // words not included)
    // bool isleaf; //for only checking words not
    // counting prefix or words
    struct Trie * edges[26];
    Trie(){
        words = 0; prefixes = 0;
        rep(i,26)
            edges[i] = NULL;
    }
} Trie;
Trie * root;
void addword(Trie * node, string a){
    rep(i,a.size()){
        if(node->edges[a[i] - 'a'] == NULL)
            node->edges[a[i] - 'a'] = new Trie();
        node = node->edges[a[i] - 'a'];
    }
}

```

```

    node->prefixes++;
}
// node->isleaf = true;
node->prefixes--;
node->words++;
}

int count_words(Trie * node, string a){
    rep(i,a.size()){
        if(node->edges[a[i] - 'a'] == NULL)
            return 0;
        node = node->edges[a[i] - 'a'];
    }
    return node->words;
}

int count_prefixes(Trie * node, string a){
    rep(i,a.size()){
        if(node->edges[a[i] - 'a'] == NULL)
            return 0;
        node = node->edges[a[i] - 'a'];
    }
    return node->prefixes;
}

// bool find(Trie * node, string a){
//     rep(i,a.size()){
//         if(node->edges[a[i] - 'a'] == NULL)
//             return false;
//         node = node->edges[a[i] - 'a'];
//     }
//     return node->isleaf;
// }

int main(){
    root = new Trie();
    rep(i,26)
        if(root->edges[i] != NULL)
            cout<<(char)('a' + i);
    return 0;
}

```

7.6 Treaps Data structure implementation

```

#include "template.h"
const int N = 100 * 1000;
struct node { int value, weight, ch[2], size; } T
[ N+10 ]; int nodes;
#define Child(x,c) T[x].ch[c]
#define Value(x) T[x].value
#define Weight(x) T[x].weight
#define Size(x) T[x].size
#define Left Child(x,0)
#define Right Child(x,1)
int update(int x) { if(!x) return 0; Size(x) = 1+
    Size(Left)+Size(Right); return x; }
int newnode(int value, int prio) {
    T[++nodes]=(node){value,prio,0,0};
    return update(nodes);
}
void split(int x, int by, int &L, int &R)
{
    if(!x) { L=R=0; }
    else if(Value(x) < Value(by)) { split(Right,by,
        Right,R); update(L=x); }
    else { split(Left,by,L,Left); update(R=x); }
}
int merge(int L, int R)

```

```

{
    if(!L) return R; if(!R) return L;
    if(Weight(L)<Weight(R)) { Child(L,1) = merge(
        Child(L,1), R); return update(L); }
    else { Child(R,0) = merge(L, Child(R, 0));
        return update(R); }
}
int insert(int x, int n)
{
    if(!x) { return update(n); }
    if(Weight(n)<=Weight(x)) { split(x,n,Child(n,0),
        Child(n,1)); return update(n); }
    else if(Value(n) < Value(x)) Left=insert(Left,n
        ); else Right=insert(Right,n);
    return update(x);
}
int del(int x, int value)
{
    if(!x) return 0;
    if(value == Value(x)) { int q = merge(Left,
        Right); return update(q); }
    if(value < Value(x)) Left = del(Left,value);
    else Right = del(Right, value);
    return update(x);
}
int find_GE(int x, int value) {
    int ret=0;
    while(x) { if(Value(x)==value) return x;
        if(Value(x)>value) ret=x, x=Left; else x=
        Right; }
    return ret;
}
int find(int x, int value) {
    for(; x; x=Child(x,Value(x)<value)) if(Value(x)
        ==value) return x;
    return 0;
}
int findmin(int x) { for(;Left;x=Left); return x;
}
int findmax(int x) { for(;Right;x=Right); return
    x; }
int findkth(int x, int k) {
    while(x) {
        if(k<=Size(Left)) x=Left;
        else if(k==Size(Left)+1) return x;
        else { k-=Size(Left)+1; x=Right; }
    }
}
int queryrange(int &x, int a1, int a2, int k)
{
    a1 = find(x, a1); a2 = find(x, a2);
    assert(a1 && a2);
    int a,b,c; split(x,a1,a,b); split(b,a2,b,c);
    int ret = findkth(b,k);
    x = merge(a, merge(b,c));
    return Value(ret);
}
int main(){
    return 0;
}

```

7.7 Z's Algorithm, KMP's Bro

```

/* Z algorithm for matching substrings. KMP's
    Brother */
vector<int> zfunction(char *s) {
    int N = strlen(s), a=0, b=0;
    vector<int> z(N, N);

```

```

    for (int i = 1; i < N; i++) {
        int k = i<b ? min(b-i, z[i-a]) : 0;
        while (i+k < N && s[i+k]==s[k]) ++k;
        z[i] = k;
        if (i+k > b) { a=i; b=i+k; }
    }
    return z;
}

```

Definition:
 $z[i] = \max \{k: s[i..i+k-1]=s[0..k-1]\}$

8 Miscellaneous

8.1 C++ template

```

#include <bits/stdc++.h>
#include <ext/pb_ds/assoc_container.hpp>
#include <ext/pb_ds/tree_policy.hpp>

using namespace __gnu_pbds;
using namespace std;
template <typename T>
using ordered_set = tree<T, null_type, less<T>,
    rb_tree_tag,
    tree_order_statistics_node_update>;

const long long Mod = 1e9 + 7;
const long long Inf = 1e18;
const long long Lim = 1e5 + 1e3;
const double eps = 1e-10;

typedef long long ll;
typedef vector<int> vi;
typedef vector<vi> vvi;
typedef vector<ll> vl;
typedef pair<int, int> pii;
typedef pair<ll, ll> pll;

#define F first
#define S second
#define mp make_pair
#define pb push_back
#define pi 2*acos(0.0)
#define rep2(i,b,a) for(ll i = (ll)b, _a = (ll)a;
    i >= _a; i--)
#define repl(i,a,b) for(ll i = (ll)a, _b = (ll)b;
    i <= _b; i++)
#define rep(i,n) for(ll i = 0, _n = (ll)n; i <
    _n; i++)
#define mem(a,val) memset(a,val,sizeof(a))
#define all(v) v.begin(), v.end()
#define fast ios_base::sync_with_stdio(false),cin
    .tie(0),cout.tie(0);

int main () {
    ordered_set<int> X;
    X.insert(1); X.insert(2); X.insert(4); X.
        insert(8); X.insert(16);
    cout << *X.find_by_order(5) << '\n';
    cout << X.order_of_key(4) << '\n';
    return 0;
}

```

8.2 C++ input/output

```
#include "template.h"

int main() {
    // Output a specific number of digits past the
    // decimal point,
    // in this case 5
    cout.setf(ios::fixed); cout << setprecision(5);
    cout << 100.0/7.0 << endl;
    cout.unsetf(ios::fixed);

    // Output the decimal point and trailing zeros
    cout.setf(ios::showpoint);
    cout << 100.0 << endl;
    cout.unsetf(ios::showpoint);

    // Output a '+' before positive values
    cout.setf(ios::showpos);
    cout << 100 << " " << -100 << endl;
    cout.unsetf(ios::showpos);

    // Output numerical values in hexadecimal
    cout << hex << 100 << " " << 1000 << " " <<
        10000 << dec << endl;
}
```

8.3 Longest increasing subsequence

```
// Given a list of numbers of length n, this
// routine extracts a
// longest increasing subsequence.
//
// Running time: O(n log n)
//
// INPUT: a vector of integers
// OUTPUT: a vector containing the longest
// increasing subsequence

#include <iostream>
#include <vector>
#include <algorithm>

using namespace std;

typedef vector<int> VI;
typedef pair<int,int> PII;
typedef vector<PII> VPII;

#define STRICTLY_INCREASNG

VI LongestIncreasingSubsequence(VI v) {
    VPII best;
    VI dad(v.size(), -1);

    for (int i = 0; i < v.size(); i++) {
#ifdef STRICTLY_INCREASNG
        PII item = make_pair(v[i], 0);
        VPII::iterator it = lower_bound(best.begin(),
            best.end(), item);
        item.second = i;
#else
        PII item = make_pair(v[i], i);
        VPII::iterator it = upper_bound(best.begin(),
            best.end(), item);
#endif
        if (it == best.end()) {
            dad[i] = (best.size() == 0 ? -1 : best.back()
                ().second);
            best.push_back(item);
        } else {
            dad[i] = dad[it->second];
        }
    }
}
```

```
        *it = item;
    }
}

VI ret;
for (int i = best.back().second; i >= 0; i =
    dad[i])
    ret.push_back(v[i]);
reverse(ret.begin(), ret.end());
return ret;
}
```

8.4 Longest common subsequence

```
/*
Calculates the length of the longest common
subsequence of two vectors.
Backtracks to find a single subsequence or all
subsequences. Runs in
O(m*n) time except for finding all longest common
subsequences, which
may be slow depending on how many there are.
*/
```

```
#include <iostream>
#include <vector>
#include <set>
#include <algorithm>

using namespace std;

typedef int T;
typedef vector<T> VT;
typedef vector<VT> VVT;

typedef vector<int> VI;
typedef vector<VI> VVI;

void backtrack(VVI& dp, VT& res, VT& A, VT& B,
    int i, int j)
{
    if(!i || !j) return;
    if(A[i-1] == B[j-1]) { res.push_back(A[i-1]);
        backtrack(dp, res, A, B, i-1, j-1); }
    else
    {
        if(dp[i][j-1] >= dp[i-1][j]) backtrack(dp,
            res, A, B, i, j-1);
        else backtrack(dp, res, A, B, i-1, j);
    }
}

void backtrackall(VVI& dp, set<VT>& res, VT& A,
    VT& B, int i, int j)
{
    if(!i || !j) { res.insert(VI()); return; }
    if(A[i-1] == B[j-1])
    {
        set<VT> tempres;
        backtrackall(dp, tempres, A, B, i-1, j-1);
        for(set<VT>::iterator it=tempres.begin(); it
            !=tempres.end(); it++)
        {
            VT temp = *it;
            temp.push_back(A[i-1]);
            res.insert(temp);
        }
    }
    else
    {

```

```
        if(dp[i][j-1] >= dp[i-1][j]) backtrackall(dp,
            res, A, B, i, j-1);
        if(dp[i][j-1] <= dp[i-1][j]) backtrackall(dp,
            res, A, B, i-1, j);
    }
}

VT LCS(VI& A, VI& B)
{
    VVI dp;
    int n = A.size(), m = B.size();
    dp.resize(n+1);
    for(int i=0; i<=n; i++) dp[i].resize(m+1, 0);

    for(int i=1; i<=n; i++)
        for(int j=1; j<=m; j++)
        {
            if(A[i-1] == B[j-1]) dp[i][j] = dp[i-1][j]
                -1+1;
            else dp[i][j] = max(dp[i-1][j], dp[i][j-1])
                ;
        }

    VT res;
    backtrack(dp, res, A, B, n, m);
    reverse(res.begin(), res.end());
    return res;
}

set<VT> LCSall(VI& A, VI& B)
{
    VVI dp;
    int n = A.size(), m = B.size();
    dp.resize(n+1);
    for(int i=0; i<=n; i++) dp[i].resize(m+1, 0);
    for(int i=1; i<=n; i++)
        for(int j=1; j<=m; j++)
        {
            if(A[i-1] == B[j-1]) dp[i][j] = dp[i-1][j]
                -1+1;
            else dp[i][j] = max(dp[i-1][j], dp[i][j-1])
                ;
        }

    set<VT> res;
    backtrackall(dp, res, A, B, n, m);
    return res;
}

int main()
{
    int a[] = { 0, 5, 5, 2, 1, 4, 2, 3 }, b[] = {
        5, 2, 4, 3, 2, 1, 2, 1, 3 };
    VI A = VI(a, a+8), B = VI(b, b+9);
    VI C = LCS(A, B);

    for(int i=0; i<C.size(); i++) cout << C[i] << "
        ";
    cout << endl << endl;

    set<VI> D = LCSall(A, B);
    for(set<VI>::iterator it = D.begin(); it != D.
        end(); it++)
    {
        for(int i=0; i<(*it).size(); i++) cout << (*
            it)[i] << " ";
        cout << endl;
    }
}
```

8.5 Gauss Jordan

```
// Gauss-Jordan elimination with full pivoting.
```

```
//
// Uses:
// (1) solving systems of linear equations (AX=
//      B)
// (2) inverting matrices (AX=I)
// (3) computing determinants of square
//      matrices
//
// Running time: O(n^3)
//
// INPUT:   a[][] = an nxn matrix
//          b[][] = an nxm matrix
//
// OUTPUT:  X      = an nxm matrix (stored in b
//          [][])
//          A^{-1} = an nxn matrix (stored in a
//          [][])
//          returns determinant of a[][]

#include "template.h"
using namespace std;

typedef double T;
typedef vector<T> vt;
typedef vector<vt> vvt;

T GaussJordan(vvt &a, vvt &b) {
    const int n = a.size();
    const int m = b[0].size();
    vi irow(n), icol(n), ipiv(n);
    T det = 1;

    for (int i = 0; i < n; i++) {
        int pj = -1, pk = -1;
        for (int j = 0; j < n; j++) if (!ipiv[j])
            for (int k = 0; k < n; k++) if (!ipiv[k])
                if (fabs(a[j][k]) > fabs(a[pj][pk]))
                    { pj = j; pk = k; }
        if (fabs(a[pj][pk]) < eps) { cerr << "Matrix
            is singular." << endl; exit(0); }
        ipiv[pj]++;
        swap(a[pj], a[pk]);
        swap(b[pj], b[pk]);
        if (pj != pk) det *= -1;
        irow[i] = pj;
        icol[i] = pk;

        T c = 1.0 / a[pk][pk];
        det *= a[pk][pk];
        a[pk][pk] = 1.0;
        for (int p = 0; p < n; p++) a[pk][p] *= c;
        for (int p = 0; p < m; p++) b[pk][p] *= c;
        for (int p = 0; p < n; p++) if (p != pk) {
            c = a[p][pk];
            a[p][pk] = 0;
            for (int q = 0; q < n; q++) a[p][q] -= a[pk]
                [q] * c;
            for (int q = 0; q < m; q++) b[p][q] -= b[pk]
                [q] * c;
        }
    }

    for (int p = n-1; p >= 0; p--) if (irow[p] !=
        icol[p]) {
        for (int k = 0; k < n; k++) swap(a[k][irow[p]
            ], a[k][icol[p]]);
    }

    return det;
}

int main() {
    vvt a(100), b(100);
```

```
    double det = GaussJordan(a, b);
}
```

8.6 Miller-Rabin Primality Test

```
// Randomized Primality Test (Miller-Rabin):
// Error rate: 2^{(-TRIAL)}
// Almost constant time. srand is needed
#include "template.h"

ll ModularMultiplication(ll a, ll b, ll m) {
    ll ret=0, c=a;
    while(b) {
        if(b&1) ret=(ret+c)%m;
        b>>=1; c=(c+c)%m;
    }
    return ret;
}

ll ModularExponentiation(ll a, ll n, ll m) {
    ll ret=1, c=a;
    while(n) {
        if(n&1) ret=ModularMultiplication(ret, c, m);
        n>>=1; c=ModularMultiplication(c, c, m);
    }
    return ret;
}

bool Witness(ll a, ll n) {
    ll u=n-1;
    int t=0;
    while(!(u&1)){u>>=1; t++;}
    ll x0=ModularExponentiation(a, u, n), x1;
    for(int i=1; i<=t; i++) {
        x1=ModularMultiplication(x0, x0, n);
        if(x1==1 && x0!=1 && x0!=n-1) return true;
        x0=x1;
    }
    if(x0!=1) return true;
    return false;
}

ll Random(ll n) {
    ll ret=rand(); ret*=32768;
    ret+=rand(); ret*=32768;
    ret+=rand(); ret*=32768;
    ret+=rand();
    return ret%n;
}

bool IsPrimeFast(ll n, int TRIAL) {
    while(TRIAL--) {
        ll a=Random(n-2)+1;
        if(Witness(a, n)) return false;
    }
    return true;
}

// The property is increasing
```

8.7 Binary Search

```
#include "template.h"
bool works(int m){
    // if Array[m] is the value to be searched,
    // return true
    // else return false
}

// The property is increasing
```

```
int BinarySearch(int l, int h){
    int m;
    while(l <= h){ m = (l+h) / 2; if(works(m)) l=m
        +1; else h=m-1; }
    return l-1;
}
// The property is decreasing
// while(l <= h){ m = (l+h) / 2; if(works(m)) h=
// m-1; else l=m+1; }
// return h+1;
```

8.8 Playing with dates

```
// Routines for performing computations on dates.
// In these routines,
// months are expressed as integers from 1 to 12,
// days are expressed
// as integers from 1 to 31, and years are
// expressed as 4-digit
// integers.
#include "template.h"
string dayOfWeek[] = {"Mon", "Tue", "Wed", "Thu",
    "Fri", "Sat", "Sun"};

// converts Gregorian date to integer (Julian day
// number)
int dateToInt (int m, int d, int y){
    return
        1461 * (y + 4800 + (m - 14) / 12) / 4 +
        367 * (m - 2 - (m - 14) / 12 * 12) / 12 -
        3 * ((y + 4900 + (m - 14) / 12) / 100) / 4 +
        d - 32075;
}

// converts integer (Julian day number) to
// Gregorian date: month/day/year
void intToDate (int jd, int &m, int &d, int &y){
    int x, n, i, j;
    x = jd + 68569;
    n = 4 * x / 146097;
    x -= (146097 * n + 3) / 4;
    i = (4000 * (x + 1)) / 1461001;
    x -= 1461 * i / 4 - 31;
    j = 80 * x / 2447;
    d = x - 2447 * j / 80;
    x = j / 11;
    m = j + 2 - 12 * x;
    y = 100 * (n - 49) + i + x;
}

// converts integer (Julian day number) to day of
// week
string intToDay (int jd){ return dayOfWeek[jd %
    7]; }
```

8.9 Hashing

```
#include "template.h"
const int N = 1e5;

// fhash[i] stores hash of s from s[0] to s[i],
// bhash stores hash
// for s[i] to s[n-1], calcFhash/CalcBhash,
// calculate hash from
// s[l] to s[r] in forward/backward direction
```



```

struct HASH{
    pii fhash[N], bhash[N];
    pii p[N], ip[N];
    string s;
    int n;
    HASH(string str){
        s = str; n = s.size();
    }
    void init(){
        p[0] = ip[0] = mp(1,1);
        repl(1,1,N-1){
            p[i].F = 31LL * p[i-1].F % Mod;
            p[i].S = 37LL * p[i-1].S % Mod;
            ip[i].F = 129032259LL * ip[i-1].F % Mod;
            ip[i].S = 621621626LL * ip[i-1].S % Mod;
        }
    }
    void infHash(){
        repl(i,0,n-1){
            fhash[i].F = (1LL * s[i] * p[i].F + ( (i) ?
                fhash[i-1].F : 0 ) ) % Mod;
            fhash[i].S = (1LL * s[i] * p[i].S + ( (i) ?
                fhash[i-1].S : 0 ) ) % Mod;
        }
    }
    void inbHash(){
        rep2(i,n-1,0){
            bhash[i].F = (1LL * s[i] * p[n-i-1].F + ( (
                i<n-1) ? bhash[i+1].F : 0 ) ) % Mod;
            bhash[i].S = (1LL * s[i] * p[n-i-1].S + ( (
                i<n-1) ? bhash[i+1].S : 0 ) ) % Mod;
        }
    }
    pii CalcFhash(int l,int r){
        if(l > r) return mp(0,0);
        pii ret;
        ret.F = 1LL * (fhash[r].F - ((l)?fhash[l-1].F

```

```

        :0) + Mod) * ip[l].F % Mod;
        ret.S = 1LL * (fhash[r].S - ((l)?fhash[l-1].S
        :0) + Mod) * ip[l].S % Mod;
        return ret;
    }
    pii CalcBhash(int l,int r){
        if(l > r) return mp(0,0);
        pii ret;
        ret.F = 1LL * (bhash[l].F - ((r<n-1)?bhash[r
            +1].F:0) + Mod) * ip[n-1-r].F % Mod;
        ret.S = 1LL * (bhash[l].S - ((r<n-1)?bhash[r
            +1].S:0) + Mod) * ip[n-1-r].S % Mod;
        return ret;
    }
};

int main() {return 0;}

```

8.10 Mobius function

```

void MOB(int n){
    vector<int> mob(n);
    for(int i = 1; i < n ; ++i) mob[i] = 1;
    for(int i = 2; i < N ; i++){
        if(pf[i] == 1){
            if(1LL * i * i < N){
                for(int j = i*i ; j < N ; j += (i*i) ){
                    mob[j] = 0;
                }
            }
            for(int j = i ; j < N ; j+=i){
                mob[j] *= -1;
            }
        }
    }
}

```

8.11 Mo's Algorithm

```

// Algorithm for sorting the queries in an order
// which
// minimizes the time required from  $O(n^2)$  to  $O((n + Q)\sqrt{n})$ 
// +  $Q\log Q$  This is done by sorting the queries in
// order of range on which they are performed
// We store the queries and sort them using the
// compare
// function cmp. Also we need to make an add
// function to
// calculate the value of range (l,r+1) from
// value of range
// (l,r) and (l+1,r) from the value of (l,r), and
// a remove
// function to calculate the value of (l-1, r)
// from the value
// of (l,r) and (l,r-1) from the value of (l,r)
// in constant time

// S is the max integer number which is less than
// sqrt(N);
int S = (int)(sqrt(N)); // Here see if you want
ll
bool cmp(Query A, Query B)
{
    if (A.l / S != B.l / S) return A.l / S < B.l /
        S;
    return A.r > B.r;
}

```

9 Theory

Combinatorics

Sums

$$\begin{aligned} \sum_{k=0}^n k &= n(n+1)/2 & \binom{n}{k} &= \frac{n!}{(n-k)!k!} \\ \sum_{k=a}^b k &= (a+b)(b-a+1)/2 & \binom{n}{k} &= \binom{n-1}{k} + \binom{n-1}{k-1} \\ \sum_{k=0}^n k^2 &= n(n+1)(2n+1)/6 & \binom{n+1}{k} &= \frac{n+1}{n-k+1} \binom{n}{k} \\ \sum_{k=0}^n k^3 &= n^2(n+1)^2/4 & \binom{n}{k+1} &= \frac{n-k}{k+1} \binom{n}{k} \\ \sum_{k=0}^n k^4 &= (6n^5 + 15n^4 + 10n^3 - n)/30 & \binom{n}{k} &= \frac{n}{n-k} \binom{n-1}{k} \\ \sum_{k=0}^n k^5 &= (2n^6 + 6n^5 + 5n^4 - n^2)/12 & \binom{n}{k} &= \frac{n-k+1}{k} \binom{n}{k-1} \\ \sum_{k=0}^n x^k &= (x^{n+1} - 1)/(x - 1) & 12! &\approx 2^{28.8} \\ \sum_{k=0}^n kx^k &= (x - (n+1)x^{n+1} + nx^{n+2})/(x-1)^2 & 20! &\approx 2^{61.1} \\ 1 + x + x^2 + \dots &= 1/(1-x) \end{aligned}$$

Binomial coefficients

Number of ways to pick a multiset of size k from n elements: $\binom{n+k-1}{k}$

Number of n -tuples of non-negative integers with sum s : $\binom{s+n-1}{n-1}$, at most s : $\binom{s+n}{n}$

Number of n -tuples of positive integers with sum s : $\binom{s-1}{n-1}$

Number of lattice paths from $(0,0)$ to (a,b) , restricted to east and north steps: $\binom{a+b}{a}$

Multinomial theorem. $(a_1 + \dots + a_k)^n = \sum \binom{n}{n_1, \dots, n_k} a_1^{n_1} \dots a_k^{n_k}$, where $n_i \geq 0$ and $\sum n_i = n$.

$$\binom{n}{n_1, \dots, n_k} = M(n_1, \dots, n_k) = \frac{n!}{n_1! \dots n_k!}$$

$$M(a, \dots, b, c, \dots) = M(a + \dots + b, c, \dots) M(a, \dots, b)$$

Catalan numbers. $C_n = \frac{1}{n+1} \binom{2n}{n}$. $C_0 = 1$, $C_n = \sum_{i=0}^{n-1} C_i C_{n-1-i}$. $C_{n+1} = C_n \frac{4n+2}{n+2}$.

$C_0, C_1, \dots = 1, 1, 2, 5, 14, 42, 132, 429, 1430, 4862, 16796, 58786, 208012, 742900, \dots$

C_n is the number of: properly nested sequences of n pairs of parentheses; rooted ordered binary trees with $n+1$ leaves; triangulations of a convex $(n+2)$ -gon.

Derangements. Number of permutations of $n = 0, 1, 2, \dots$ elements without fixed points is $1, 0, 1, 2, 9, 44, 265, 1854, 14833, \dots$. Recurrence: $D_n = (n-1)(D_{n-1} + D_{n-2}) = nD_{n-1} + (-1)^n$. Corollary: number of permutations with exactly k fixed points is $\binom{n}{k} D_{n-k}$.

Stirling numbers of 1st kind. $s_{n,k}$ is $(-1)^{n-k}$ times the number of permutations of n elements with exactly k permutation cycles. $|s_{n,k}| = |s_{n-1,k-1}| + (n-1)|s_{n-1,k}|$. $\sum_{k=0}^n s_{n,k} x^k = x^n$

Stirling numbers of 2nd kind. $S_{n,k}$ is the number of ways to partition a set of n elements into exactly k non-empty subsets. $S_{n,k} = S_{n-1,k-1} + kS_{n-1,k}$. $S_{n,1} = S_{n,n} = 1$. $x^n = \sum_{k=0}^n S_{n,k} x^{\underline{k}}$

Bell numbers. B_n is the number of partitions of n elements. $B_0, \dots = 1, 1, 2, 5, 15, 52, 203, \dots$. $B_{n+1} = \sum_{k=0}^n \binom{n}{k} B_k = \sum_{k=1}^n S_{n,k}$. Bell triangle: $B_r = a_{r,1} = a_{r-1,r-1}$, $a_{r,c} = a_{r-1,c-1} + a_{r,c-1}$.

Bernoulli numbers. $\sum_{k=0}^{m-1} k^n = \frac{1}{n+1} \sum_{k=0}^n \binom{n+1}{k} B_k m^{n+1-k}$. $\sum_{j=0}^m \binom{m+1}{j} B_j = 0$. $B_0 = 1$, $B_1 = -\frac{1}{2}$. $B_n = 0$, for all odd $n \neq 1$.

Eulerian numbers. $E(n, k)$ is the number of permutations with exactly k descents ($i : \pi_i < \pi_{i+1}$) / ascents ($\pi_i > \pi_{i+1}$) / excedances ($\pi_i > i$) / $k+1$ weak excedances ($\pi_i \geq i$).

Formula: $E(n, k) = (k+1)E(n-1, k) + (n-k)E(n-1, k-1)$. $x^n = \sum_{k=0}^{n-1} E(n, k) \binom{x+k}{n}$.

Burnside's lemma. The number of orbits under group G 's action on set X :

$|X/G| = \frac{1}{|G|} \sum_{g \in G} |X_g|$, where $X_g = \{x \in X : g(x) = x\}$. ("Average number of fixed points.")

Let $w(x)$ be weight of x 's orbit. Sum of all orbits' weights: $\sum_{o \in X/G} w(o) = \frac{1}{|G|} \sum_{g \in G} \sum_{x \in X_g} w(x)$.

Number Theory

Linear diophantine equation. $ax + by = c$. Let $d = \gcd(a, b)$. A solution exists iff $d|c$. If (x_0, y_0) is any solution, then all solutions are given by $(x, y) = (x_0 + \frac{b}{d}t, y_0 - \frac{a}{d}t)$, $t \in \mathbb{Z}$. To find some solution (x_0, y_0) , use extended GCD to solve $ax_0 + by_0 = d = \gcd(a, b)$, and multiply its solutions by $\frac{c}{d}$.

Linear diophantine equation in n variables: $a_1x_1 + \dots + a_nx_n = c$ has solutions iff $\gcd(a_1, \dots, a_n)|c$. To find some solution, let $b = \gcd(a_2, \dots, a_n)$, solve $a_1x_1 + by = c$, and iterate with $a_2x_2 + \dots = y$.

Extended GCD

```
// Finds g = gcd(a,b) and x, y such that ax+by=g.
// Bounds: |x|<=b+1, |y|<=a+1.
void gcdext(int &g, int &x, int &y, int a, int b)
{ if (b == 0) { g = a; x = 1; y = 0; }
  else      { gcdext(g, y, x, b, a % b); y = y - (a / b) * x; } }
```

Multiplicative inverse of a modulo m : x in $ax + my = 1$, or $a\phi(m)^{-1} \pmod{m}$.

Chinese Remainder Theorem. System $x \equiv a_i \pmod{m_i}$ for $i = 1, \dots, n$, with pairwise relatively-prime m_i has a unique solution modulo $M = m_1m_2\dots m_n$: $x = a_1b_1\frac{M}{m_1} + \dots + a_nb_n\frac{M}{m_n} \pmod{M}$, where b_i is modular inverse of $\frac{M}{m_i}$ modulo m_i .

System $x \equiv a \pmod{m}$, $x \equiv b \pmod{n}$ has solutions iff $a \equiv b \pmod{g}$, where $g = \gcd(m, n)$. The solution is unique modulo $L = \frac{mn}{g}$, and equals: $x \equiv a + T(b-a)m/g \equiv b + S(a-b)n/g \pmod{L}$, where S and T are integer solutions of $mT + nS = \gcd(m, n)$.

Prime-counting function. $\pi(n) = |\{p \leq n : p \text{ is prime}\}|$. $n/\ln(n) < \pi(n) < 1.3n/\ln(n)$. $\pi(1000) = 168$, $\pi(10^6) = 78498$, $\pi(10^9) = 50\,847\,534$. n -th prime $\approx n \ln n$.

Miller-Rabin's primality test. Given $n = 2^r s + 1$ with odd s , and a random integer $1 < a < n$.

If $a^s \equiv 1 \pmod{n}$ or $a^{2^j s} \equiv -1 \pmod{n}$ for some $0 \leq j \leq r-1$, then n is a probable prime. With bases 2, 7 and 61, the test identifies all composites below 2^{32} . Probability of failure for a random a is at most $1/4$.

Pollard- ρ . Choose random x_1 , and let $x_{i+1} = x_i^2 - 1 \pmod{n}$. Test $\gcd(n, x_{2k+i} - x_{2k})$ as possible n 's factors for $k = 0, 1, \dots$. Expected time to find a factor: $O(\sqrt{m})$, where m is smallest prime power in n 's factorization. That's $O(n^{1/4})$ if you check $n = p^k$ as a special case before factorization.

Fermat primes. A Fermat prime is a prime of form $2^{2^n} + 1$. The only known Fermat primes are 3, 5, 17, 257, 65537. A number of form $2^n + 1$ is prime only if it is a Fermat prime.

Perfect numbers. $n > 1$ is called perfect if it equals sum of its proper divisors and 1. Even n is perfect iff $n = 2^{p-1}(2^p - 1)$ and $2^p - 1$ is prime (Mersenne's). No odd perfect numbers are yet found.

Carmichael numbers. A positive composite n is a Carmichael number ($a^{n-1} \equiv 1 \pmod{n}$) for all a : $\gcd(a, n) = 1$, iff n is square-free, and for all prime divisors p of n , $p-1$ divides $n-1$.

Number/sum of divisors. $\tau(p_1^{a_1} \dots p_k^{a_k}) = \prod_{j=1}^k (a_j + 1)$. $\sigma(p_1^{a_1} \dots p_k^{a_k}) = \prod_{j=1}^k \frac{p_j^{a_j+1} - 1}{p_j - 1}$.

Euler's phi function. $\phi(n) = |\{m \in \mathbb{N}, m \leq n, \gcd(m, n) = 1\}|$.
 $\phi(mn) = \frac{\phi(m)\phi(n)\gcd(m, n)}{\phi(\gcd(m, n))}$. $\phi(p^a) = p^{a-1}(p-1)$. $\sum_{d|n} \phi(d) = \sum_{d|n} \phi(\frac{n}{d}) = n$.

Euler's theorem. $a^{\phi(n)} \equiv 1 \pmod{n}$, if $\gcd(a, n) = 1$.

Wilson's theorem. p is prime iff $(p-1)! \equiv -1 \pmod{p}$.

Mobius function. $\mu(1) = 1$. $\mu(n) = 0$, if n is not squarefree. $\mu(n) = (-1)^s$, if n is the product of s distinct primes. Let f, F be functions on positive integers. If for all $n \in \mathbb{N}$, $F(n) = \sum_{d|n} f(d)$, then $f(n) = \sum_{d|n} \mu(d)F(\frac{n}{d})$, and vice versa. $\phi(n) = \sum_{d|n} \mu(d)\frac{n}{d}$. $\sum_{d|n} \mu(d) = 1$.

If f is multiplicative, then $\sum_{d|n} \mu(d)f(d) = \prod_{p|n} (1 - f(p))$, $\sum_{d|n} \mu(d)^2 f(d) = \prod_{p|n} (1 + f(p))$.

Legendre symbol. If p is an odd prime, $a \in \mathbb{Z}$, then $\left(\frac{a}{p}\right)$ equals 0, if $p|a$; 1 if a is a quadratic residue modulo p ; and -1 otherwise. Euler's criterion: $\left(\frac{a}{p}\right) = a^{\frac{p-1}{2}} \pmod{p}$.

Jacobi symbol. If $n = p_1^{a_1} \dots p_k^{a_k}$ is odd, then $\left(\frac{a}{n}\right) = \prod_{i=1}^k \left(\frac{a}{p_i}\right)^{k_i}$.

Primitive roots. If the order of g modulo m ($\min n > 0: g^n \equiv 1 \pmod{m}$) is $\phi(m)$, then g is called a primitive root. If Z_m has a primitive root, then it has $\phi(\phi(m))$ distinct primitive roots. Z_m has a primitive root iff m is one of 2, 4, p^k , $2p^k$, where p is an odd prime. If Z_m has a primitive root g , then for all a coprime to m , there exists unique integer $i = \text{ind}_g(a)$ modulo $\phi(m)$, such that $g^i \equiv a \pmod{m}$. $\text{ind}_g(a)$ has logarithm-like properties: $\text{ind}(1) = 0$, $\text{ind}(ab) = \text{ind}(a) + \text{ind}(b)$.

If p is prime and a is not divisible by p , then congruence $x^n \equiv a \pmod{p}$ has $\gcd(n, p-1)$ solutions if $a^{(p-1)/\gcd(n, p-1)} \equiv 1 \pmod{p}$, and no solutions otherwise. (Proof sketch: let g be a primitive root, and $g^i \equiv a \pmod{p}$, $g^u \equiv x \pmod{p}$. $x^n \equiv a \pmod{p}$ iff $g^{nu} \equiv g^i \pmod{p}$ iff $nu \equiv i \pmod{p}$.)

Discrete logarithm problem. Find x from $a^x \equiv b \pmod{m}$. Can be solved in $O(\sqrt{m})$ time and space with a meet-in-the-middle trick. Let $n = \lceil \sqrt{m} \rceil$, and $x = ny - z$. Equation becomes $a^{ny} \equiv ba^z \pmod{m}$. Precompute all values that the RHS can take for $z = 0, 1, \dots, n-1$, and brute force y on the LHS, each time checking whether there's a corresponding value for RHS.

Pythagorean triples. Integer solutions of $x^2 + y^2 = z^2$. All relatively prime triples are given by: $x = 2mn, y = m^2 - n^2, z = m^2 + n^2$ where $m > n, \gcd(m, n) = 1$ and $m \not\equiv n \pmod{2}$. All other triples are multiples of these. Equation $x^2 + y^2 = 2z^2$ is equivalent to $(\frac{x+y}{2})^2 + (\frac{x-y}{2})^2 = z^2$.

Postage stamps/McNuggets problem. Let a, b be relatively-prime integers. There are exactly $\frac{1}{2}(a-1)(b-1)$ numbers *not* of form $ax + by$ ($x, y \geq 0$), and the largest is $(a-1)(b-1) - 1 = ab - a - b$.

Fermat's two-squares theorem. Odd prime p can be represented as a sum of two

squares iff $p \equiv 1 \pmod{4}$. A product of two sums of two squares is a sum of two squares. Thus, n is a sum of two squares iff every prime of form $p = 4k+3$ occurs an even number of times in n 's factorization.

RSA. Let p and q be random distinct large primes, $n = pq$. Choose a small odd integer e , relatively prime to $\phi(n) = (p-1)(q-1)$, and let $d = e^{-1} \pmod{\phi(n)}$. Pairs (e, n) and (d, n) are the public and secret keys, respectively. Encryption is done by raising a message $M \in Z_n$ to the power e or d , modulo n .

String Algorithms

Burrows-Wheeler inverse transform. Let $B[1..n]$ be the input (last column of sorted matrix of string's rotations.) Get the first column, $A[1..n]$, by sorting B . For each k -th occurrence of a character c at index i in A , let $\text{next}[i]$ be the index of corresponding k -th occurrence of c in B . The r -th row of the matrix is $A[r], A[\text{next}[r]], A[\text{next}[\text{next}[r]]], \dots$

Huffman's algorithm. Start with a forest, consisting of isolated vertices. Repeatedly merge two trees with the lowest weights.

Graph Theory

Euler's theorem. For any planar graph, $V - E + F = 1 + C$, where V is the number of graph's vertices, E is the number of edges, F is the number of faces in graph's planar drawing, and C is the number of connected components. Corollary: $V - E + F = 2$ for a 3D polyhedron.

Vertex covers and independent sets. Let M, C, I be a max matching, a min vertex cover, and a max independent set. Then $|M| \leq |C| = N - |I|$, with equality for bipartite graphs. Complement of an MVC is always a MIS, and vice versa. Given a bipartite graph with partitions (A, B) , build a network: connect source to A , and B to sink with edges of capacities, equal to the corresponding nodes' weights, or 1 in the unweighted case. Set capacities of the original graph's edges to the infinity. Let (S, T) be a minimum s - t cut. Then a maximum(-weighted) independent set is $I = (A \cap S) \cup (B \cap T)$, and a minimum(-weighted) vertex cover is $C = (A \cap T) \cup (B \cap S)$.

Matrix-tree theorem. Let matrix $T = [t_{ij}]$, where t_{ij} is the number of multiedges between i and j , for $i \neq j$, and $t_{ii} = -\deg_i$. Number of spanning trees of a graph is equal to the determinant of a matrix obtained by deleting any k -th row and k -th column from T .

Euler tours. Euler tour in an undirected graph exists iff the graph is connected and each vertex has an even degree. Euler tour in a directed graph exists iff in-degree of each vertex equals its out-degree, and underlying undirected graph is connected. Construction:

```
doit(u) :
  for each edge e = (u, v) in E, do: erase e, doit(v)
  prepend u to the list of vertices in the tour
```

Stable marriages problem. While there is a free man m : let w be the most-preferred woman to whom he has not yet proposed, and propose m to w . If w is free, or is engaged to someone whom she prefers less than m , match m with w , else deny proposal.

Stoer-Wagner's min-cut algorithm. Start from a set A containing an arbitrary vertex. While $A \neq V$, add to A the most tightly connected vertex ($z \notin A$ such that

$\sum_{x \in A} w(x, z)$ is maximized.) Store cut-of-the-phase (the cut between the last added vertex and rest of the graph), and merge the two vertices added last. Repeat until the graph is contracted to a single vertex. Minimum cut is one of the cuts-of-the-phase.

Tarjan's offline LCA algorithm. (Based on DFS and union-find structure.)

```
DFS(x) :
  ancestor[Find(x)] = x
  for all children y of x:
    DFS(y); Union(x, y); ancestor[Find(x)] = x
  seen[x] = true
  for all queries {x, y}:
    if seen[y] then output "LCA(x, y) is ancestor[Find(y)]"
```

Strongly-connected components. Kosaraju's algorithm.

1. Let G^T be a transpose G (graph with reversed edges.)
1. Call $\text{DFS}(G^T)$ to compute finishing times $f[u]$ for each vertex u .
3. For each vertex u , in the order of decreasing $f[u]$, perform $\text{DFS}(G, u)$.
4. Each tree in the 3rd step's DFS forest is a separate SCC.

2-SAT. Build an implication graph with 2 vertices for each variable – for the variable and its inverse; for each clause $x \vee y$ add edges (\bar{x}, y) and (\bar{y}, x) . The formula is satisfiable iff x and \bar{x} are in distinct SCCs, for all x . To find a satisfiable assignment, consider the graph's SCCs in topological order from sinks to sources (i.e. Kosaraju's last step), assigning 'true' to all variables of the current SCC (if it hasn't been previously assigned 'false'), and 'false' to all inverses.

Randomized algorithm for non-bipartite matching. Let G be a simple undirected graph with even $|V(G)|$. Build a matrix A , which for each edge $(u, v) \in E(G)$ has $A_{i,j} = x_{i,j}$, $A_{j,i} = -x_{i,j}$, and is zero elsewhere. Tutte's theorem: G has a perfect matching iff $\det G$ (a multivariate polynomial) is identically zero. Testing the latter can be done by computing the determinant for a few random values of $x_{i,j}$'s over some field. (e.g. Z_p for a sufficiently large prime p)

Prufer code of a tree. Label vertices with integers 1 to n . Repeatedly remove the leaf with the smallest label, and output its only neighbor's label, until only one edge remains. The sequence has length $n - 2$. Two isomorphic trees have the same sequence, and every sequence of integers from 1 and n corresponds to a tree. Corollary: the number of labelled trees with n vertices is n^{n-2} .

Erdos-Gallai theorem. A sequence of integers $\{d_1, d_2, \dots, d_n\}$, with $n - 1 \geq d_1 \geq d_2 \geq \dots \geq d_n \geq 0$ is a degree sequence of some undirected simple graph iff $\sum d_i$ is even and $d_1 + \dots + d_k \leq k(k - 1) + \sum_{i=k+1}^n \min(k, d_i)$ for all $k = 1, 2, \dots, n - 1$.

Games

Grundy numbers. For a two-player, normal-play (last to move wins) game on a graph (V, E) : $G(x) = \text{mex}(\{G(y) : (x, y) \in E\})$, where $\text{mex}(S) = \min\{n \geq 0 : n \notin S\}$. x is

losing iff $G(x) = 0$.

Sums of games.

- *Player chooses a game and makes a move in it.* Grundy number of a position is xor of grundy numbers of positions in summed games.
- *Player chooses a non-empty subset of games (possibly, all) and makes moves in all of them.* A position is losing iff each game is in a losing position.
- *Player chooses a proper subset of games (not empty and not all), and makes moves in all chosen ones.* A position is losing iff grundy numbers of all games are equal.
- *Player must move in all games, and loses if can't move in some game.* A position is losing if any of the games is in a losing position.

Misère Nim. A position with pile sizes $a_1, a_2, \dots, a_n \geq 1$, not all equal to 1, is losing iff $a_1 \oplus a_2 \oplus \dots \oplus a_n = 0$ (like in normal nim.) A position with n piles of size 1 is losing iff n is *odd*.

Bit tricks

Clearing the lowest 1 bit: $x \& (x - 1)$, all trailing 1's: $x \& (x + 1)$

Setting the lowest 0 bit: $x | (x + 1)$

Enumerating subsets of a bitmask m :

```
x=0; do { ...; x=(x+1~m)&m; } while (x!=0);
```

`__builtin_ctz`/`__builtin_clz` returns the number of trailing/leading zero bits.

`__builtin_popcount`(unsigned x) counts 1-bits (slower than table lookups).

For 64-bit unsigned integer type, use the suffix 'll', i.e. `__builtin_popcountll`.

Math

Stirling's approximation $z! = \Gamma(z+1) = \sqrt{2\pi} z^{z+1/2} e^{-z} (1 + \frac{1}{12z} + \frac{1}{288z^2} - \frac{139}{51840z^3} + \dots)$

Taylor series. $f(x) = f(a) + \frac{x-a}{1!} f'(a) + \frac{(x-a)^2}{2!} f^{(2)}(a) + \dots + \frac{(x-a)^n}{n!} f^{(n)}(a) + \dots$

$\sin x = x - \frac{x^3}{3!} + \frac{x^5}{5!} - \frac{x^7}{7!} + \dots$

$\ln x = 2(a + \frac{a^3}{3} + \frac{a^5}{5} + \dots)$, where $a = \frac{x-1}{x+1}$. $\ln x^2 = 2 \ln x$.

$\arctan x = x - \frac{x^3}{3} + \frac{x^5}{5} - \frac{x^7}{7} + \dots$, $\arctan x = \arctan c + \arctan \frac{x-c}{1+xc}$ (e.g $c=.2$)

$\pi = 4 \arctan 1$, $\pi = 6 \arcsin \frac{1}{2}$

List of Primes

1e5	3	19	43	49	57	69	103	109	129	151	153
1e6	33	37	39	81	99	117	121	133	171	183	
1e7	19	79	103	121	139	141	169	189	223	229	
1e8	7	39	49	73	81	123	127	183	213		