### Follow-the-Winner Approach

中心思想: increasing market weights of more successful experts/ stocks.

- 1. Universal Portfolios(UP):
  - UP 和 BAH strategy 類似,不同點在 BAH 投資的是 single stock,而 UP 投資的是 a set of stocks(multiple classes)。
  - 1991 年 Cover 版本:最初給每個投資組合經理投資  $\mathsf{d}\mu$  (b),期末 wealth 會變成 $S_n(b)\mathsf{d}\mu$ (b),再加上 exponential rate of  $W_n(b)$ 。  $S_n(b) = \mathsf{e}^{\mathsf{n}W_n(b)}$
  - 1996 年 Cover and Ordentlich 版本: UP 被改良為 µ-Weighted
    Universal Portfolio, (µ代表 a given distribution on the space of valid
    portfolio △m), a historical performance weighed average of all valid
    constant rebalanced portfolios(根據每位 CRP 經理以前的績效做加權平均的動作)

## 2. Exponential Gradient(EG):

- 主要是解決 $b_{t+1}$ arg  $\max_{b \in \Delta m} \eta \log b \cdot X_t R(b, b_t)$  的最佳化問題。
- 論文中 Helmbold 提到兩種解決方法: Gradient Projection (GP)採用 的是 L2-norm regularization 和 Expectation Maximization (EM)採用 的是X<sup>2</sup> regularization
- 這個演算法重要的一個參數是 <u>learning rate η > 0</u>,為了要達到特定的 regret bound,需要最小化 η。但當 η 趨近於 0 時,EG 會 reduce 成 UCRP
- EG 後來被 Das and Banerjee 改良為 OGU

#### 3. Follow the Leader(FTL):

- try to track the Best Constant Rebalanced Portfolio (BCRP) until time t
- 依據前面的 benchmark BCRP 是有納入 exponential growth rate 的
- Gaivoronski and Stella 假設在 <u>stationary markets</u>的狀況下,提出 Successive Constant Rebalanced Portfolios (SCRP) 和 Weighted Successive Constant Rebalanced Portfolios (WSCRP)
- 但在 the historical market is <u>non-stationary</u>的狀況下, Gaivoronski and Stella 提出 Variable Rebalanced Portfolios (VRP), 這裡提到藉由 <u>a specified window size</u>計算 BCRP。
- 後來持續修正成可以處理 three types of portfolio selection task 的 Adaptive Portfolio Selection (APS)、處理交易成本的 Threshold Portfolio Selection (TPS),當新投資組合的 expected return 比舊的 還高時(超過門檻),進行 rebalance。

- 4. Follow the Regularized Leader(FTRL):
  - 比 FTL 多了 a regularization term
  - the regularization term only concerns the next portfolio
  - Online Newton Step (ONS), by solving the optimization problem with L2-norm regularization via online convex optimization technique
  - the Geometric Brownian Motion (GBM) model, which is a probabilistic model of stock returns
  - Exp-Concave-FTL, follows a slightly different form of optimization problem with L2-norm regularization
  - Online Newton Update (ONU), which guarantees that the overall performance is no worse than any convex combination of its underlying experts
- 5. Aggregating-type Algorithms:
  - 前提 the i.i.d. assumption is controversial in real markets
  - Aggregating Algorithm (AA), the general setting for AA is to define a
    countable or finite set of base experts and sequentially allocate the
    resource among multiple base experts in order to achieve a good
    performance that is no worse than any fixed combination of
    underlying experts
  - Switching Portfolios (SP) to track a changingmarket, in which the stock's behaviors may change frequently
  - Gaussian Random Walk (GRW) strategy, which switches among the base experts according to Gaussian distribution

# HELMBOLD 的 Exponential Gradient(EG)演算法

On-Line Portfolio Selection Using Multiplicative Updates 前提假設

- Consider a portfolio containing N stocks
- price relatives X (Xi=the next day's opening price of the th stock divided by its opening price on the current day)
- portfolio weight vector W (Wi 總和=1)

The ith entry of a portfolio w is the proportion of the total portfolio value invested in the ith stock.

總結
$$\mathbf{W} \cdot \mathbf{X} = \sum_{i}^{N} X_{i} Y_{i}$$

### Exponential Gradient(EG)

類似 Kivinen and Warmuth 的 framework

Kivinen and Warmuth 希望找到 $W^{t+1}$ 趨近於 $W^t$ ,而 HELMBOLD 修改成 $W^{t+1}$ 是  $F(W^{t+1})=\eta\log(W^{t+1}\cdot X^t)-d\left(W^{t+1},W^t\right)$ 的 maximum 註:

- learning rate η > 0,為控制因素(如果 $W^{t+1}$ 趨近於 $W^*$ ,η 又是 large,那就會偏離)
- d = a distance measure that serves as a penalty term(設定 penalty term 是為了使 $W^{t+1}$ 趨近於 $W^t$ )

a distance function for motivating updates(不同 distance function 會產生不同 update rules)

$$D_{RE}(\mathbf{u} \parallel \mathbf{v}) \stackrel{\text{def}}{=} \sum_{i=1}^{N} u_i \log \frac{u_i}{v_i}$$

second-order Taylor approximation(u=v),  $X^2$ -distance

$$D_{X^2}(\mathbf{u} \| \mathbf{v}) \stackrel{\text{def}}{=} \frac{1}{2} \sum_{i=1}^{N} \frac{(u_i - v_i)^2}{v_i}$$

因為無法 maximize F 所以改 maximize  $\mathcal{F}$ (上面有一個箭頭,將 the N partial derivatives 設為 zero)

再加上 additional constraint $\sum_{i=1}^N W_i^{t+1} = 1$ ,就稱為 exponentiated gradient(EG(n) ) update

$$W_i^{t+1} = \frac{W^t \exp(\eta X_i^t / W^t \cdot X^t)}{\sum_{j=1}^N W_i^t \exp(\eta X_i^t / W^t \cdot X^t)}$$

另外如果納入考量 $X^2$ -distance,就稱為 $X^2$ (η)- update