


Streaming GNN via Continual Learning¹

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MAP670G - Data Stream Processing

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¹original paper: Streaming Graph Neural Networks via Continual Learning 

Overview

- 1 Framework: StreamingGNN
- 2 Proposed method: ContinualGNN
- 3 Our contributions & Future
- 4 Problems

Framework: StreamingGNN

- In real case, network data is formed in a *streaming* fashion
 - Nodes and edges are modified over time.
- Patterns: Neighborhood information of nodes.
 - *New patterns* may appear and *Existing patterns* still maintain

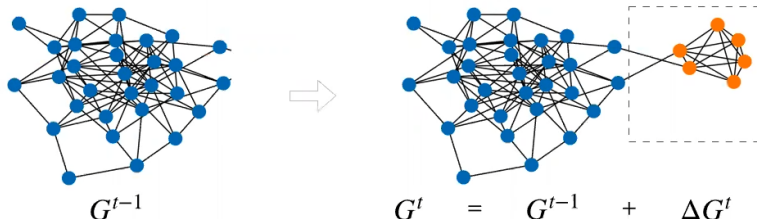


Figure: streaming networks.

StreamingGNN - current methods

- PretrainedGNN
 - Use a pre-trained GNN model to generate representations of unseen nodes and changed nodes on G^t : *Inductive learning*
 - Performance degrades if nodes are not in the pre-trained model.
- RetrainedGNN
 - Retrain the GNN at every time step.
 - High performance but computationally costly.

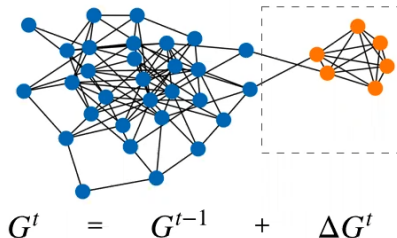


Figure: streaming networks.

StreamingGNN - current methods

- OnlineGNN

- Train GNN based on ΔG^t using θ^{t-1} to initialize.
- **Catastrophic forgetting** when the patterns in ΔG^t are different from θ^{t-1} , knowledge of θ^{t-1} may be abruptly lost.

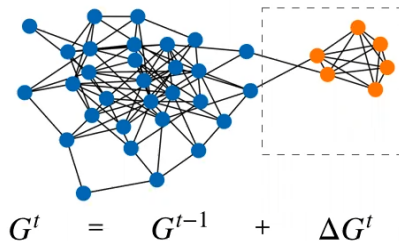


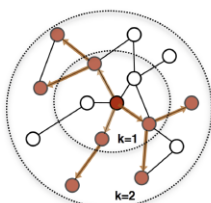
Figure: streaming networks.

Proposed method: ContinualGNN

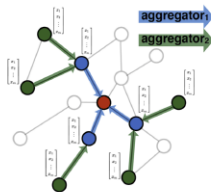
- Problem to solve:

Given streaming network G , at each time t , based on G^t the current graph. Detect new patterns incrementally while *preserving* existing patterns.

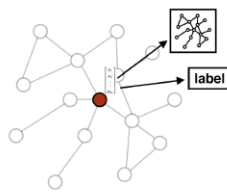
ContinualGNN - GraphSAGE



1. Sample neighborhood



2. Aggregate feature information from neighbors



3. Predict graph context and label using aggregated information

2

Figure: Visual illustration of the GraphSAGE sample and aggregate approach.

ContinualGNN

- Two main tasks:
 - Current task: Training on ΔG^t
 - Previous task: Training on $(\Delta G^1, \Delta G^2, \dots, \Delta G^{t-1}) = G^{t-1}$

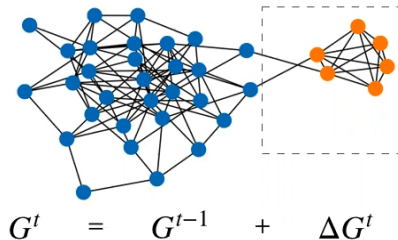


Figure: streaming networks.

ContinualGNN

- Loss function:
 - Using Bayes' rule:

$$\log p(\theta|G^{t-1}, \Delta G^t) = \log p(\Delta G^t|\theta) + \log p(\theta|G^{t-1}) - \log p(\Delta G^t)$$

- General loss function of ContinualGNN at time t is:

$$L = L_{new} + L_{existing}$$

where the first term L_{new} is the loss function on the influenced parts of networks, and $L_{existing} = L_{data} + L_{model}$ aims to consolidate patterns on previous data.

ContinualGNN

- General loss function of ContinualGNN at time t is:

$$L = L_{new} + L_{data} + L_{model}$$

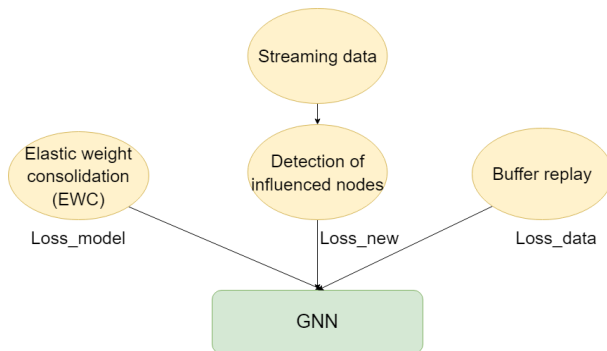


Figure: loss components.

Our contributions & Future

- Provide a more standard data format based on **Pytorch Geometric**
- **Refactor** the original code: more clean, efficient code
- **Remove the coupling relation** between the code with a specific dataset used in the paper

Problems

- Some problems of being integrated into (Deep) River:
 - ContinualGNN is not typically an online learning model, it has memories of the past data.
 - The ContinualGNN is based on graphSAGE, which is too complex and inefficient for (Deep) River.
 - The data type is different, for River the data should all be a dictionary, it's hard to convert graph data into a dictionary.