```
8.0 a)
// the Floyd-Warshall algorithm that stores the answer
global Ecost(1...n, 1...n) initialized to store the cost of pairs (i,
j) and infinity if no edge is present;
global Pcost(1...n, 1...n) stores the shortest path, initialized to
equal Ecost;
global kIntermediate(1...n, 1...n) initialized to be filled with 0 if
there is an edge, and -1 otherwise;
global G(V, E);
procedure F-W(n);
    for k < -1 to n do
        for i < -1 to n do
            for j < -1 to n do
                if Pcost(i,j) > Pcost(i,k) + Pcost(k,j) then
                    Pcost(i,j) <- Pcost(i,k) + Pcost(k,j);
                    kIntermediate(i,j) <- k; // store the answer
                end if;
            end for:
        end for;
    end for;
end_F-W;
b)
// path recovery algorithm
// drive
procedure PathDrive(i,j);
    if kIntermediate(i,j) == -1 then
        // i and j are not connected
        print('No path');
    else
        PrintPath(i,j);
        print(j);
    end if:
end_PathDrive;
// actual algorithm
procedure PrintPath(i,j);
    k <- kIntermediate(i, j);</pre>
    if k == 0 then
        // shortest path is the edge between i and j
        print(i);
    else
        PrintPath(i,k);
        PrintPath(k,j); // does not print j
    end if;
end_PrintPath;
```

This question requires a slight change to the standard F-W algorithm to calculate 2 edges (i,k) and (k,j). As such, we can put the k-loop inside the i-j-loops and initialize a Best(i,j) as infinity to be updated and store the best k.

```
global Best(1...n, 1...n) stores the best path, initialized to be
filled with infinity;
global Ecost(1...n, 1...n) initialized to store the edge costs. For
pairs with no edges or edges from and to the same vertex, the cost is
infinity;
procedure TwoEdges(n);
    for i < -1 to n do
        for j < -1 to n do
            for k < -1 to n do
                if Best(i,j) > Ecost(i,k) + Ecost(k,j) then
                    Best(i,j) <- Ecost(i,k) + Ecost(k,j);</pre>
                end if:
            end for;
        end for;
    end for;
end_TwoEdges;
```

#### 8.1 Floyd-Warshall

```
else if kIntermediate(i,j) == 0 or kIntermediate(i,j)
== -1 then
                    kIntermediate(i,j) <- k;</pre>
                end if;
            end for;
        end for;
    end for;
end F-W;
8. rwb
Copy G three times, and connect G1 to G2 with only redges; G2 to G3
with only wedges, and G3 to G1 with only bledges. We can then apply
the FW algorithm on this super graph to find all pairs that start and
end at G1.
8.cookie
a)
global Ecost(1...n, 1...n) initialized to store the cost of pairs (i,
j) and infinity if no edge is present;
global Pcost(1...n, 1...n) stores the shortest path, initialized to
equal Ecost;
global kIntermediate(1...n, 1...n) initialized to be filled with 0 if
there is an edge, and -1 otherwise;
global Cookie[1..n];
global G(V, E);
procedure F-W(n);
    for k < -1 to n do
        for i < -1 to n do
            for j <- 1 to n do
                if Pcost(i,j) > Pcost(i,k) + Pcost(k,j) then
                    Pcost(i,j) <- Pcost(i,k) + Pcost(k,j);
                    kIntermediate(i,j) <- k; // store the answer
                end if;
            end for;
        end for;
    end for;
end_F-W;
// path recovery algorithm
// drive
```

```
global cookies initialized at 0;
procedure PathDrive(i,j);
    if kIntermediate(i,j) \neq -1 then
        PrintPath(i,j);
        cookies <- cookies + Cookie[i];</pre>
    end if:
end PathDrive;
// actual algorithm
procedure PrintPath(i,j);
    k <- kIntermediate(i, j);</pre>
    if k == 0 then
        // shortest path is the edge between i and j
        cookies <- cookies + Cookie[i];</pre>
    else
        PrintPath(i,k);
        PrintPath(k,j); // does not print j
    end if;
end_PrintPath;
b)
To store equal paths, we change kIntermediate(i,j) to store an array
of k which offers the shortest path from i to i.
global Ecost(1...n, 1...n) initialized to store the cost of pairs (i,
j) and infinity if no edge is present;
global Pcost(1...n, 1...n) stores the shortest path, initialized to
equal Ecost;
global kIntermediate(1...n, 1...n) initialized to be filled with 0 if
there is an edge, and -1 otherwise;
global Cookie[1..n];
global G(V, E);
procedure F-W(n);
    for k < -1 to n do
        for i <-1 to n do
            for j <- 1 to n do
                 if Pcost(i,j) > Pcost(i,k) + Pcost(k,j) then
                     Pcost(i,j) <- Pcost(i,k) + Pcost(k,j);
                     kIntermediate(i,j).append(k); // store the answer
                 end if;
            end for;
        end for:
    end for;
end_F-W;
// path recovery algorithm
```

```
// drive
global cookies initialized at 0;
procedure PathDrive(i,j);
    if kIntermediate(i,j) \neq -1 then
        cookies <- PrintPath(i,j) + Cookie[j];</pre>
    end if;
end PathDrive;
// actual algorithm
global max initialized to be -infinity;
function PrintPath(i,j);
    for x <- 0 to kIntermediate(i,j).size() do</pre>
        cookies <- 0;</pre>
        k <- kIntermediate(i,j)[x];</pre>
        if k == 0 then
             // shortest path is the edge between i and j
             cookies <- cookies + Cookie[i];</pre>
        else
            PrintPath(i,k);
             PrintPath(k,j); // does not print j
        end if;
        if cookies > max then
             max <- cookies;</pre>
             return max;
        end if;
    end for;
end_PrintPath;
8.vb
a)
Copy Manhattan, connect the two VBs in the two graphs. The edge that
connects VBs has a 0 cost. The complete path would start from G1, and
end in G2.
b)
The constant c should be 8, since the graph is copied into 2, and 2^3
= 8.
```

8.cookied

```
a)
global Ecost(1...n, 1...n) initialized to store the cost of pairs (i,
j) and infinity if no edge is present;
global Pcost(1...n, 1...n) stores the shortest path, initialized to
equal Ecost;
global kIntermediate(1...n, 1...n) initialized to be filled with 0 if
there is an edge, and -1 otherwise;
global Cookie[1..n];
global G(V, E);
procedure F-W(n);
    for k < -1 to n do
        for i <-1 to n do
            for j <-1 to n do
                if Pcost(i,j) > Pcost(i,k) + Pcost(k,j) then
                    if Cookie[k] > 0 then
                        Pcost(i,j) <- Pcost(i,k) + Pcost(k,j);
                        kIntermediate(i,j).append(k); // store the
answer
                    end if;
                end if;
            end for;
        end for;
    end for;
end_F-W;
b)
global Cookie[1..n];
global Best(1...n, 1...n) stores the best path, initialized to be
filled with infinity;
global Ecost(1...n, 1...n) initialized to store the edge costs. For
pairs with no edges or edges from and to the same vertex, the cost is
infinity;
procedure TwoEdges(n);
    for i <-1 to n do
        for j <- 1 to n do
            for k < -1 to n do
                if Best(i,j) > Ecost(i,k) + Ecost(k,j) then
                    if Cookie[k] + Cookie[j] > 0 then
                        Best(i,j) <- Ecost(i,k) + Ecost(k,j);</pre>
                    end if;
                end if;
            end for;
        end for;
    end for;
end_TwoEdges;
```

```
global Ecost(1...n, 1...n) initialized to store the cost of pairs (i,
i) and infinity if no edge is present;
global Pcost(1...n, 1...n) stores the shortest path, initialized to
equal Ecost;
global kIntermediate(1...n, 1...n) initialized to be filled with 0 if
there is an edge, and -1 otherwise;
global G(V, E);
global Edges(i,j) stores the number of edges in the shortest path,
initialized to be 1 if there is an edge, and 0 otherwise;
procedure F-W(n);
    for k < -1 to n do
        for i < -1 to n do
            for j <- 1 to n do
                if Pcost(i,j) > Pcost(i,k) + Pcost(k,j) then
                    Pcost(i,j) <- Pcost(i,k) + Pcost(k,j);
                    kIntermediate(i,j) <- k; // store the answer
                    Edges(i,j) \leftarrow Edges(i,k) + 1;
                end if;
            end for;
        end for;
    end for;
end F-W;
```

## 8.3 Floyd-Warshall

The wrong placement of the k-loop would result in the algorithm calculating the edges from i to k, and k to j. It will not calculate the complete paths.

## 8.21

```
a) global Ecost(1...n, 1...n) initialized to store the cost of pairs (i, j) and infinity if no edge is present; global Pcost(1...n, 1...n) stores the shortest path, initialized to equal Ecost; global kIntermediate(1...n, 1...n) initialized to be filled with 0 if
```

```
there is an edge, and -1 otherwise;
global G(V, E);
procedure F-W(n);
    for k < -1 to n do
        for i < -1 to n do
            for j <-1 to n do
                if Pcost(i,j) > max{longest(i,k), longest(k,j)} then
                    Pcost(i,j) <- max{longest(i,k), longest(k,j)};</pre>
                    kIntermediate(i,j) <- k; // store the answer
                end if;
            end for:
        end for;
    end for;
end F-W;
// algorithm to determine the lonest edge in a path
function longest(i,i);
    for all edges x on path (i,j) return max{x};
end_longest;
b)
global Ecost(1...n, 1...n) initialized to store the cost of pairs (i,
j) and infinity if no edge is present;
global Pcost(1...n, 1...n) stores the shortest path, initialized to
equal Ecost;
global kIntermediate(1...n, 1...n) initialized to be filled with 0 if
there is an edge, and -1 otherwise;
global G(V, E);
procedure F-W(n);
    for k <-1 to n do
        for i < -1 to n do
            for j <-1 to n do
                if Pcost(i,j) > product(i,k) * product(k,j) then
                    Pcost(i,j) <- product(i,k) * product(k,j);</pre>
                    kIntermediate(i,j) <- k; // store the answer
                end if:
            end for;
        end for;
    end for;
end F-W;
// algorithm to determine the product of all edges in a path
function longest(i,j);
    product <- 1;
    for all edges x on path (i,j) do
        product <- product * x;</pre>
    end for:
    return product;
```

```
end longest;
```

c)
That cycles should only be travelled once; If there is an edge with cost between 0 and 1, cycling more times will give smaller paths.

# 8.2 Floyd-Warshall

```
global Ecost(1...n, 1...n) initialized to store the cost of pairs (i,
i) and infinity if no edge is present;
global Pcost(1...n, 1...n) stores the shortest path, initialized to
equal Ecost;
global kIntermediate(1...n, 1...n) initialized to be filled with 0 if
there is an edge, and -1 otherwise;
global G(V, E);
procedure F-W(n);
    for k < -1 to n do
        for i < -1 to n do
            for j <-1 to n do
                 if Pcost(i,j) < Pcost(i,k) + Pcost(k,j) then</pre>
                     kIntermediate(i,j) <- i;
                else
                     kIntermediate(i,j) <- k;</pre>
                end if;
            end for;
        end for:
    end for;
end_F-W;
```

#### 8.33 Shortest path

Copy the graph into 2 pieces. G1 has all edges from s to banks, and G2 has all edges from shops to s. Connect G1 and G2 with edges from banks to shops. Perform a FW algorithm on the overall graph, find the shortest path from s1 to s2.

```
8.39 Floyd-Warshall
Copy G into 2 copies. Connect G1 and G2 with all edges. We start at G1
(or G2), and finish at G1 (or G2).
b)
Copy G into 2 copies. In each subgraph, connect vertices with edges
calculated using the 2-step algorithm. Connect G1 and G2 using the
original edges. We start at G1, and finish at G2.
c)
global Ecost(1...n, 1...n) initialized to store the cost of pairs (i,
j) and infinity if no edge is present;
global Pcost(1...n, 1...n) stores the shortest path, initialized to
equal Ecost;
global kIntermediate(1...n, 1...n) initialized to be filled with 0 if
there is an edge, and -1 otherwise;
global Cookie[1..n];
global G(V, E);
procedure F-W(n);
    for k < -1 to n do
        for i <-1 to n do
            for j <-1 to n do
                if Pcost(i,j) > Pcost(i,k) + Pcost(k,j) and
(Edges(i,k) + 1) \mod 2 == 0 then
                    Pcost(i,j) <- Pcost(i,k) + Pcost(k,j);
                    kIntermediate(i,j) <- k; // store the answer
                end if;
            end for;
        end for:
    end for;
end_F-W;
8.41 Floyd-Warshall
global Ecost(1...n, 1...n) initialized to store the cost of pairs (i,
j) and infinity if no edge is present;
global Pcost(1...n, 1...n) stores the shortest path, initialized to
equal Ecost;
global kIntermediate(1...n, 1...n) initialized to be filled with 0 if
there is an edge, and -1 otherwise;
```

```
global kSecond(1...n, 1...n) same as kIntermediate, but stores the 2nd
shortest path;
global Cookie[1..n];
global G(V, E);
procedure F-W(n);
    for k <-1 to n do
        for i <-1 to n do
            for j <- 1 to n do
                if Pcost(i,j) > Pcost(i,k) + Pcost(k,j) then
                    Pcost(i,j) <- Pcost(i,k) + Pcost(k,j);</pre>
                    kSecond(i,j) <- kIntermediate(i,j);</pre>
                    kIntermediate(i,j) <- k; // store the answer
                else if Pcost(i,j) = Pcost(i,k) + Pcost(k,j) then
                    kSecond(i,j) <- kIntermediate(i,j);</pre>
                end if:
            end for;
        end for:
    end for;
end_F-W;
8.42 Floyd-Warshall
global Ecost(1...n, 1...n) initialized to store the cost of pairs (i,
j) and infinity if no edge is present;
global Pcost(1...n, 1...n) stores the shortest path, initialized to
equal Ecost:
global kIntermediate(1...n, 1...n) initialized to be filled with 0 if
there is an edge, and -1 otherwise;
global shortestCount(1...n, 1...n) initialized to be filled with 1 if
there is an edge, and 0 otherwise;
global G(V, E);
procedure F-W(n);
    for k < -1 to n do
        for i <-1 to n do
            for j < -1 to n do
                if Pcost(i,j) > Pcost(i,k) + Pcost(k,j) then
                    shortestCount(i,i) <- shortestCount(i,k) +</pre>
shortestCount(k,j);
                    Pcost(i,j) <- Pcost(i,k) + Pcost(k,j);
                    kIntermediate(i,j) <- k; // store the answer
                else if Pcost(i,j) = Pcost(i,k) + Pcost(k,j) then
                    shortestCount(i,j) <- shortestCount(i,j) + 1;</pre>
                end if;
            end for;
```

end for;

end for;
end\_F-W;