

Fig. 1. Static training (A) and dynamic training (B) results from each limb position and load for intact limb subjects. Boxes show the mean and standard error.

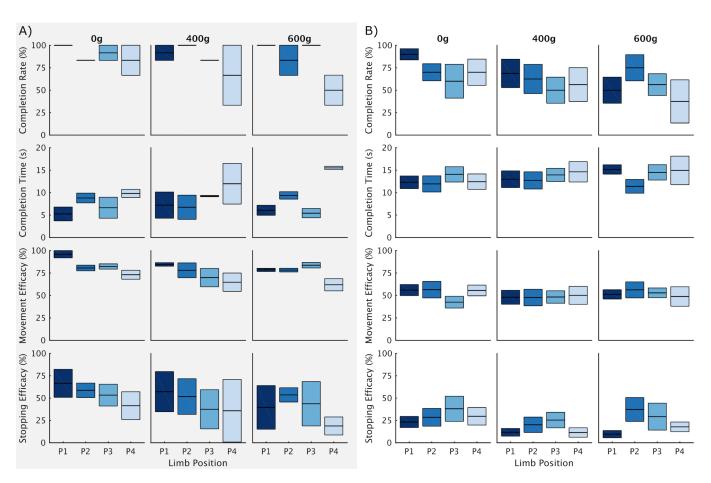


Fig. 2. Static training results from each limb position and load for amputee subjects (A: subjects who used 3DOF controllers, B: subjects who used 2DOF controllers). Boxes show the mean and standard error.

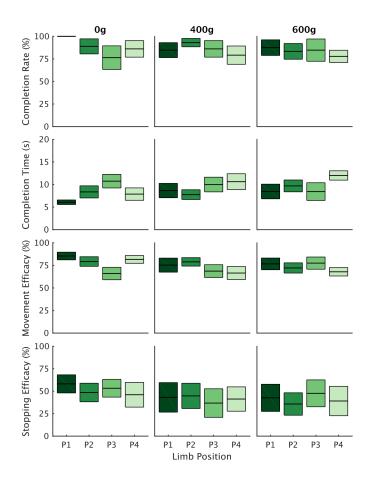


Fig. 3. Dynamic training results from each limb position and load for amputee subjects. Boxes show the mean and standard error.