LaneArrayHandler

+ lanes_
+ autoware_lanearray_

+ LaneArrayHandler()
+ setLaneArray()
# convertFromLaneArrayToWaypoints
Vector()

#lanes_handler_

CKetiLocalPlanning

nh
pub_LocalPath
pub_LocalTrajectoriesRviz
pub_WaypointTrajectoriesRviz
sub_current_pose
sub_WayPlannerPaths
current_pose_

+ CKetiLocalPlanning()
+ ~CKetiLocalPlanning()
+ PlannerMainLoop()
# callbackGetCurrentPose()
# callbackGetWayPlannerPath()