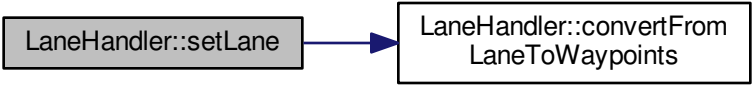


LaneHandler::setLane



```
graph LR; A[LaneHandler::setLane] --> B[LaneHandler::convertFromLaneToWaypoints]
```

The diagram consists of two rectangular boxes connected by a horizontal arrow. The left box is shaded gray and contains the text 'LaneHandler::setLane'. A dark blue arrow points from the right side of this box to the left side of the right box. The right box is white with a black border and contains the text 'LaneHandler::convertFromLaneToWaypoints' on two lines.

LaneHandler::convertFrom
LaneToWaypoints