LaneHandler

+ waypoints_lane_
+ autoware_lane_

+ LaneHandler()
+ LaneHandler()
+ LaneHandler()
+ setLane()
+ setLane()
+ getAutowareLane()
+ getWaypointsLane()
+ getClosestWaypoint()
# convertFromLaneToWaypoints()
# ConvertFromWaypointsToLane()