


LaneHandler::LaneHandler



```
graph LR; A[LaneHandler::LaneHandler] --> B[LaneHandler::convertFromLaneToWaypoints]
```

The diagram consists of two rectangular boxes connected by a horizontal arrow. The left box is shaded gray and contains the text 'LaneHandler::LaneHandler'. The right box is white and contains the text 'LaneHandler::convertFromLaneToWaypoints'. A blue arrow points from the right side of the gray box to the left side of the white box.

LaneHandler::convertFrom  
LaneToWaypoints