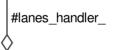
LaneArrayHandler + autoware lanearray

- + LaneArrayHandler()
- + setLaneArray()

+ lanes

convertFromLaneArrayToWaypoints Vector()



CKetiLocalPlanning

nh

pub LocalPath # pub_LocalTrajectoriesRviz

pub WaypointTrajectoriesRviz

sub current pose

sub WayPlannerPaths

current pose

+ CKetiLocalPlanning()

+ ~CKetiLocalPlanning() + PlannerMainLoop()

callbackGetCurrentPose()

callbackGetWayPlannerPath()