

Program Assignment 1 - 3D α -shape*Prof. Jyh-Ming Lien*

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1 3D α -shape

1.1 Problem definition and Analysis

Let $P := \{p_1, p_2, \dots, p_n\}$ be a set of points in the plane. In that, an α -shape of P is the intersection of all closed circles with radius α that contain all the points. In other words, for a given value α and input as 3D, the α -shape includes all the tetrahedra in the Delaunay Triangulation which have an empty circumsphere with *squared radius* equal or smaller than α^2 . The value of α goes from $0 \rightarrow \infty$.

$$\begin{cases} \alpha \rightarrow 0 : \alpha\text{-shape is } P. \\ \alpha \rightarrow \infty : \alpha\text{-shape is } CH(P). \\ \alpha \rightarrow 1 : \alpha\text{-shape is a collection of triangles in } DT(P) \text{ whose circumcircles have diameters } \leq \alpha. \end{cases}$$

1.2 Platforms

Languages: C

Platform: Microsoft visual Studio 2013

1.3 Examples of Inputs

1. There are 12 test data.
2. Each data file has different values.
3. Each line has three value, x, y, z .

1.4 Problem-solving methods and algorithms

A tetrahedron is composed of four triangular faces. It has four faces, six edges, and four vertices. For all tetrahedron, there exists a sphere called 'circumsphere' which completely encloses the tetrahedron. All tetrahedron's vertices all lie on the surface of its circumsphere. The point at the centre of the circumsphere is the circumcentre. When the six edges of a tetrahedron are given, we can determine the radius of the circumsphere. Let the length of edges be $p, q, r, a, b, \text{ and } c$. Let the T be the volume of the tetrahedron and the radius of the sphere be r . Also, let the products of the opposite edge of the tetrahedron be $e = ap, f = bq, g = cr$ and the area of the triangle whose sides are products of these edges be $area$. Then, the radius r

$$r = \frac{area}{6T}$$

We can calculate the area of the triangle whose sides have lengths a, b , and c by Heron's area formula.

$$S = \sqrt{s(s-a)(s-b)(s-c)},$$
$$s = \frac{a+b+c}{2}$$

Also, we can calculate the volume of a tetrahedron with a function `Volumei(face, vertex)`.

```
volume = fabs(Volumei(&face, tetra->vertex[3]));

if (facet->normal[3] < 0.0 && volume) {
    area = areaTriangle(tetra);
    radius = area / (6 * volume);
    squared_radius = radius * radius;
    if (squared_radius <= alpha) {
        tetra->face[0] = MakeFace(tetra->vertex[0], tetra->vertex[1],
                                tetra->vertex[2], NULL);
        tetra->face[1] = MakeFace(tetra->vertex[3], tetra->vertex[1],
                                tetra->vertex[0], NULL);
        tetra->face[2] = MakeFace(tetra->vertex[2], tetra->vertex[3],
                                tetra->vertex[0], NULL);
        tetra->face[3] = MakeFace(tetra->vertex[1], tetra->vertex[2],
                                tetra->vertex[3], NULL);
    }
}
```

Since volume has sign, I made it into an absolute value. Then, calculate a radius and compare the radius with given value, α . Draw only tetrahedra with *squared radius* equal or smaller than α^2 .

1.5 Results Analysis and Discussion

In this report, implement α -shape algorithm by using *qhull*. For determining the radius of a circumsphere, I have to calculate the area of the triangle which lengths of sides are the products

of the opposite edge of the tetrahedron. I used Heron's area formula to compute the area. By reducing the value of α , α -shape exhibited the specific shape of the P . Finally,

$$\lim_{\alpha \rightarrow 0} P_\alpha = P$$

$$\lim_{\alpha \rightarrow \infty} p_\alpha = CH(P)$$

1.6 Outputs

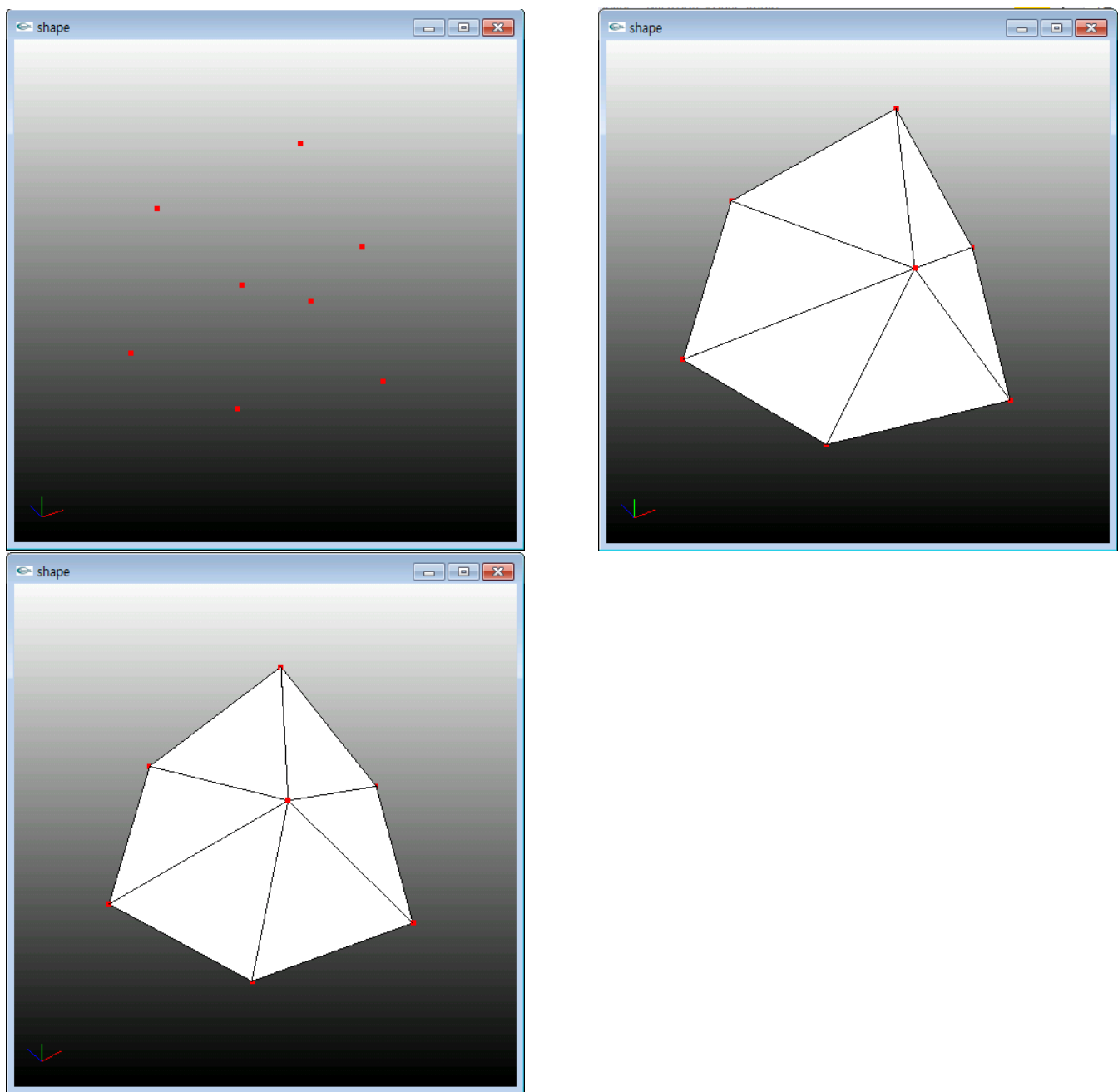


Figure 1: $\alpha = 0$, $\alpha = 2$, $\alpha = 10$ *i.cube*

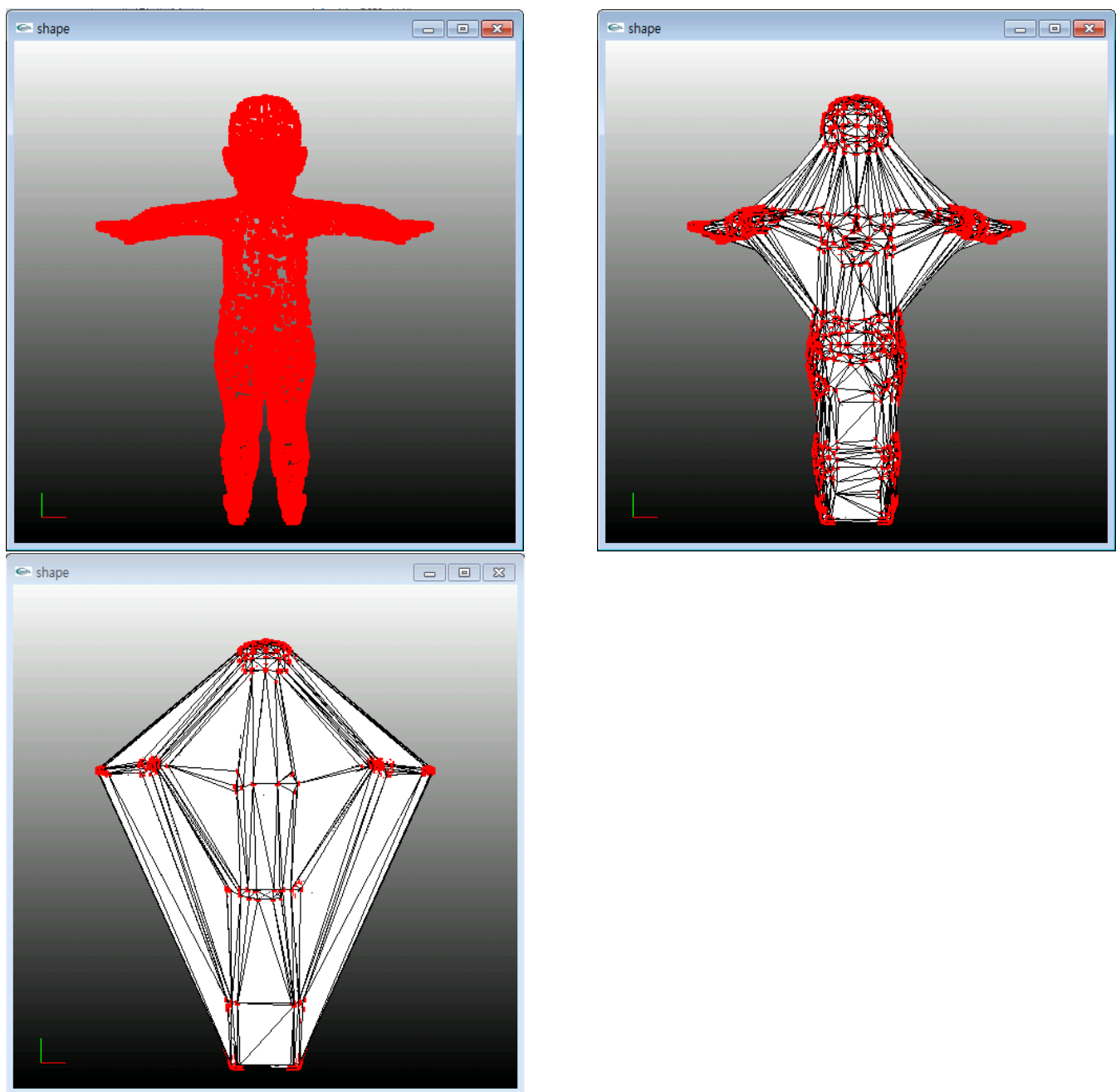


Figure 2: $\alpha = 0$, $\alpha = 10$, $\alpha = 100$ *i.bb*

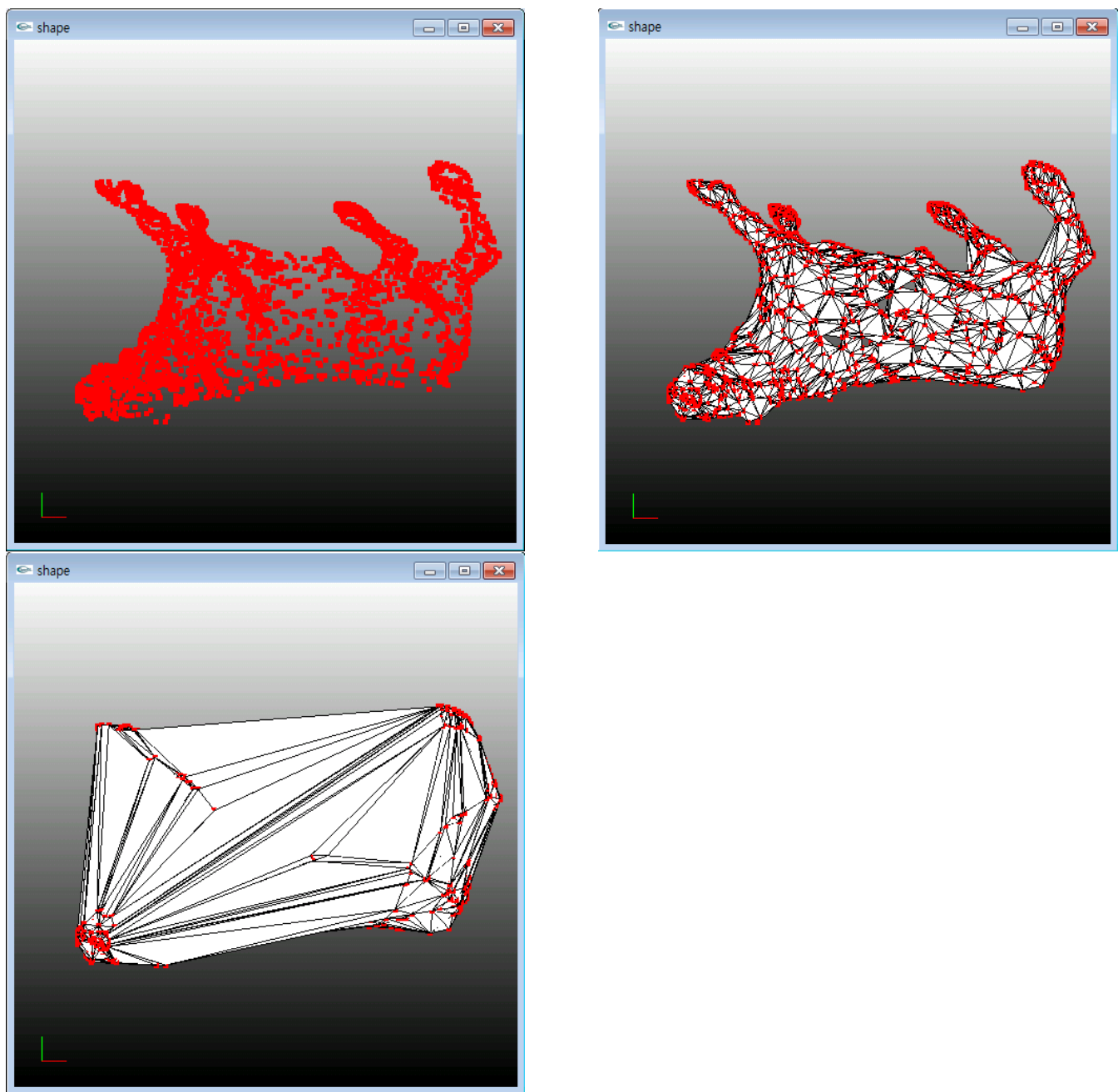


Figure 3: $\alpha = 0$, $\alpha = 100$, $\alpha = 1000$ *i.bull*

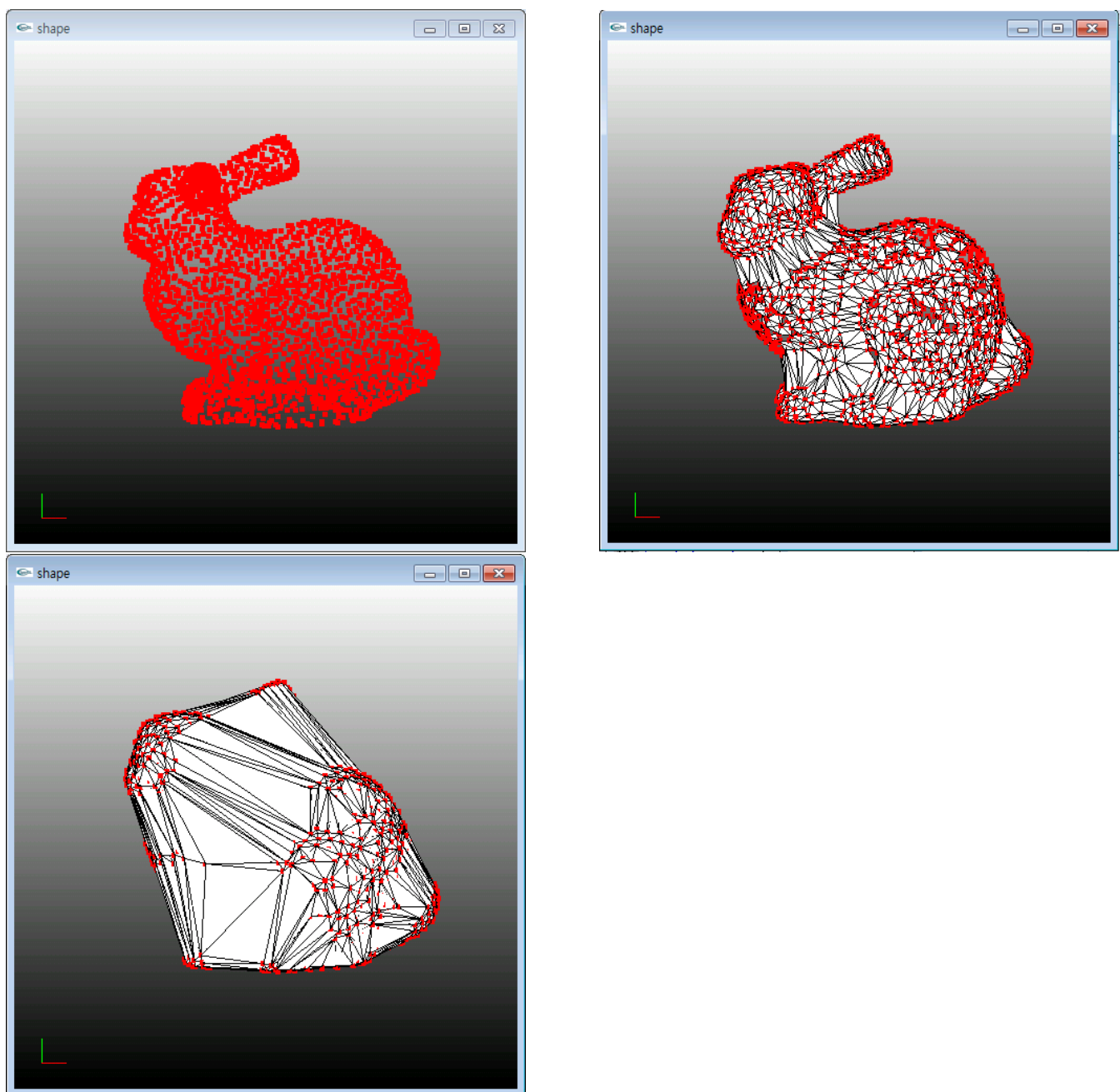


Figure 4: $\alpha = 0$, $\alpha = 10$, $\alpha = 100$ *i.bunny*

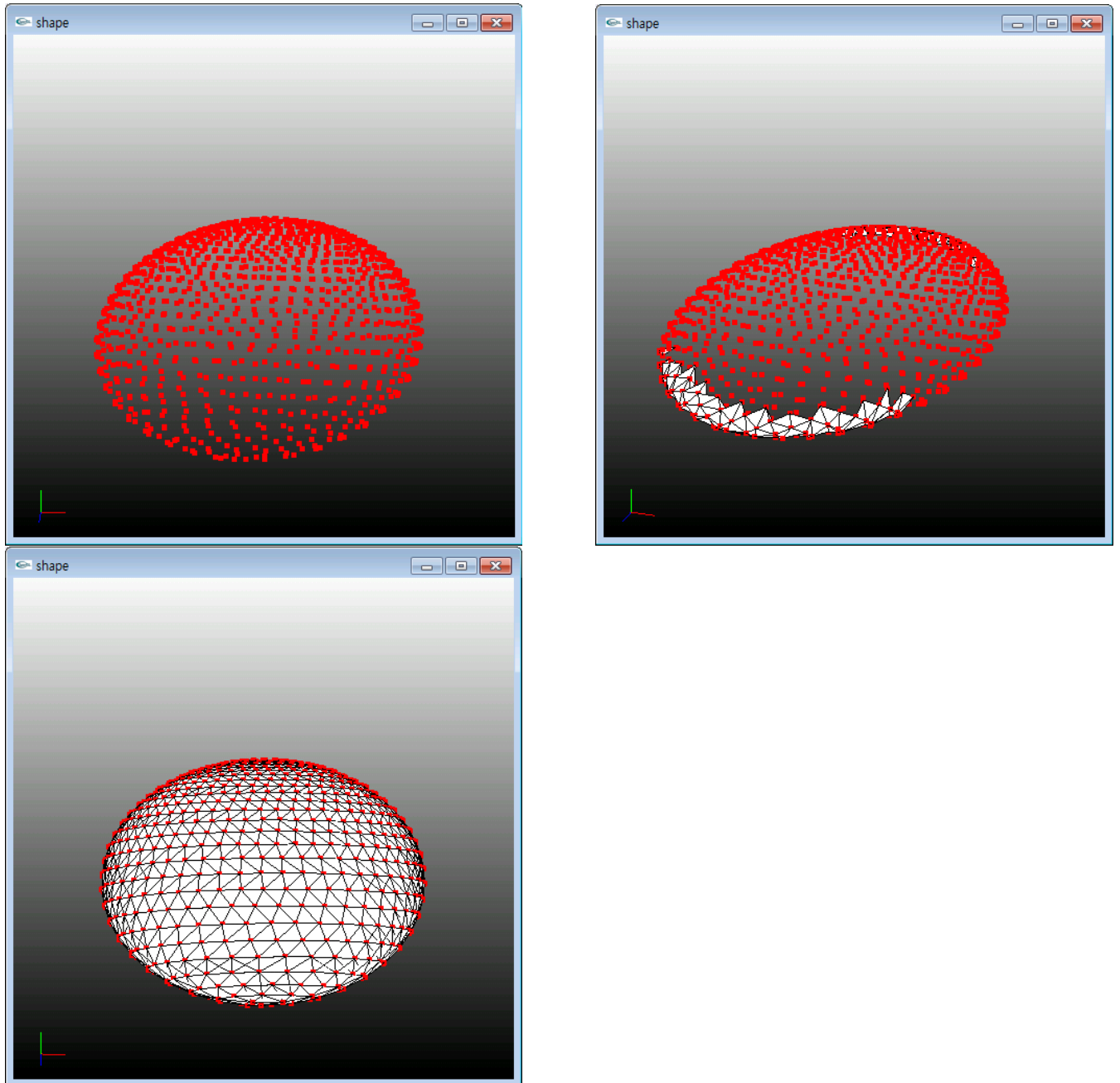


Figure 5: $\alpha = 0$, $\alpha = 10$, $\alpha = 100$ *i.ellipsoid*

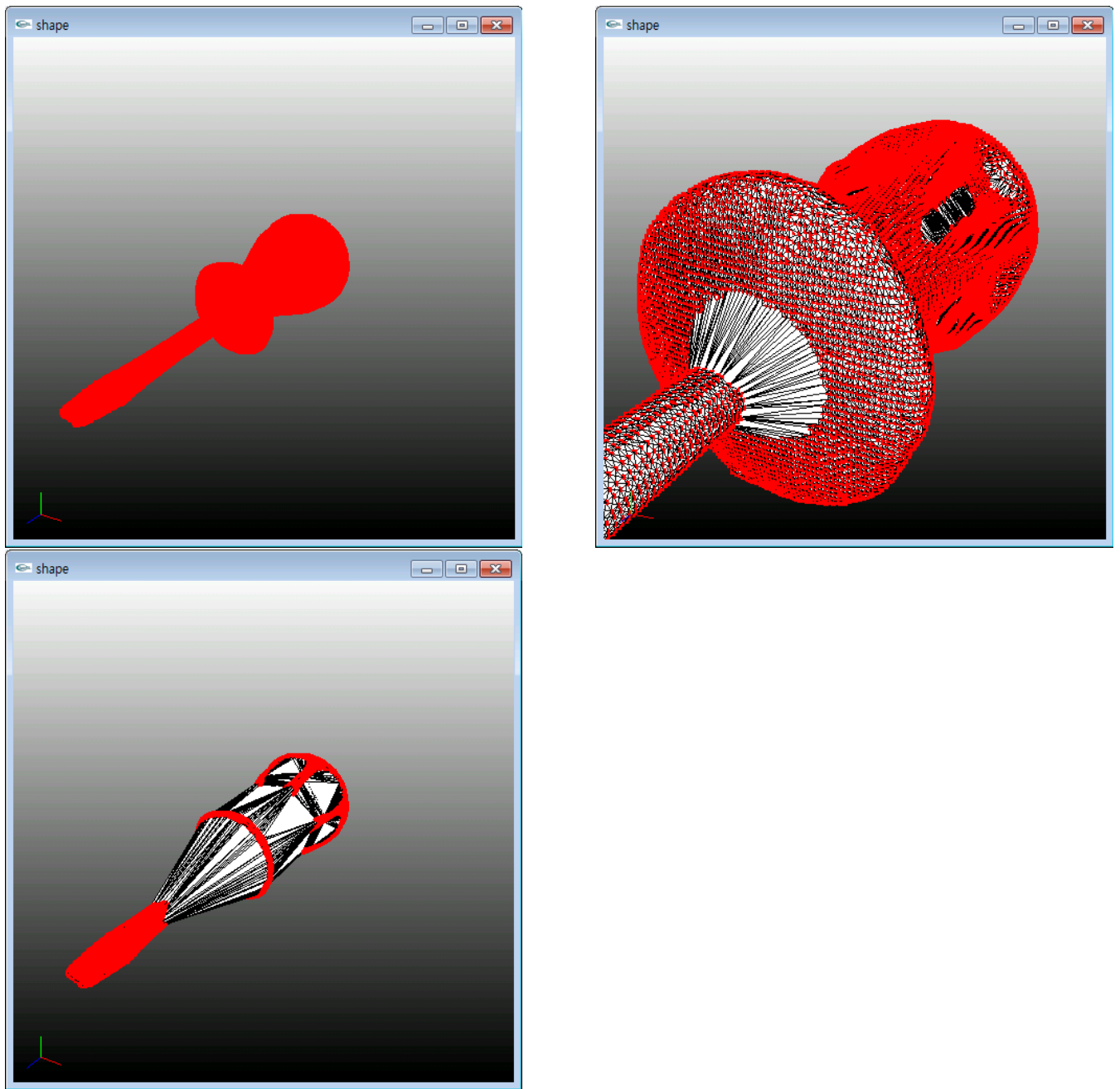


Figure 6: $\alpha = 0$, $\alpha = 100$, $\alpha = 1000$ *i.screwdriver*

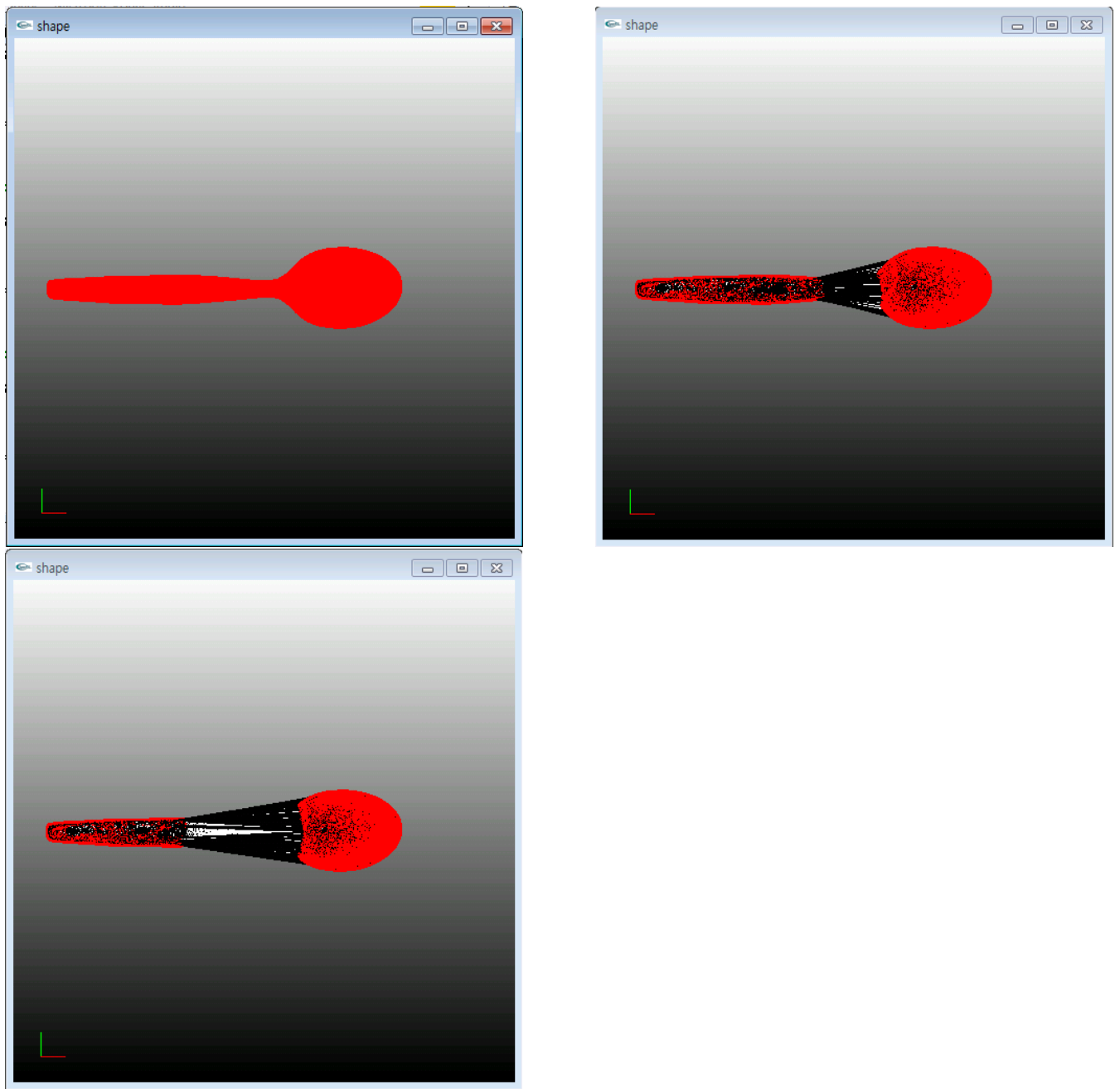


Figure 7: $\alpha = 0$, $\alpha = 1000$, $\alpha = 3000$ *i.spoon*

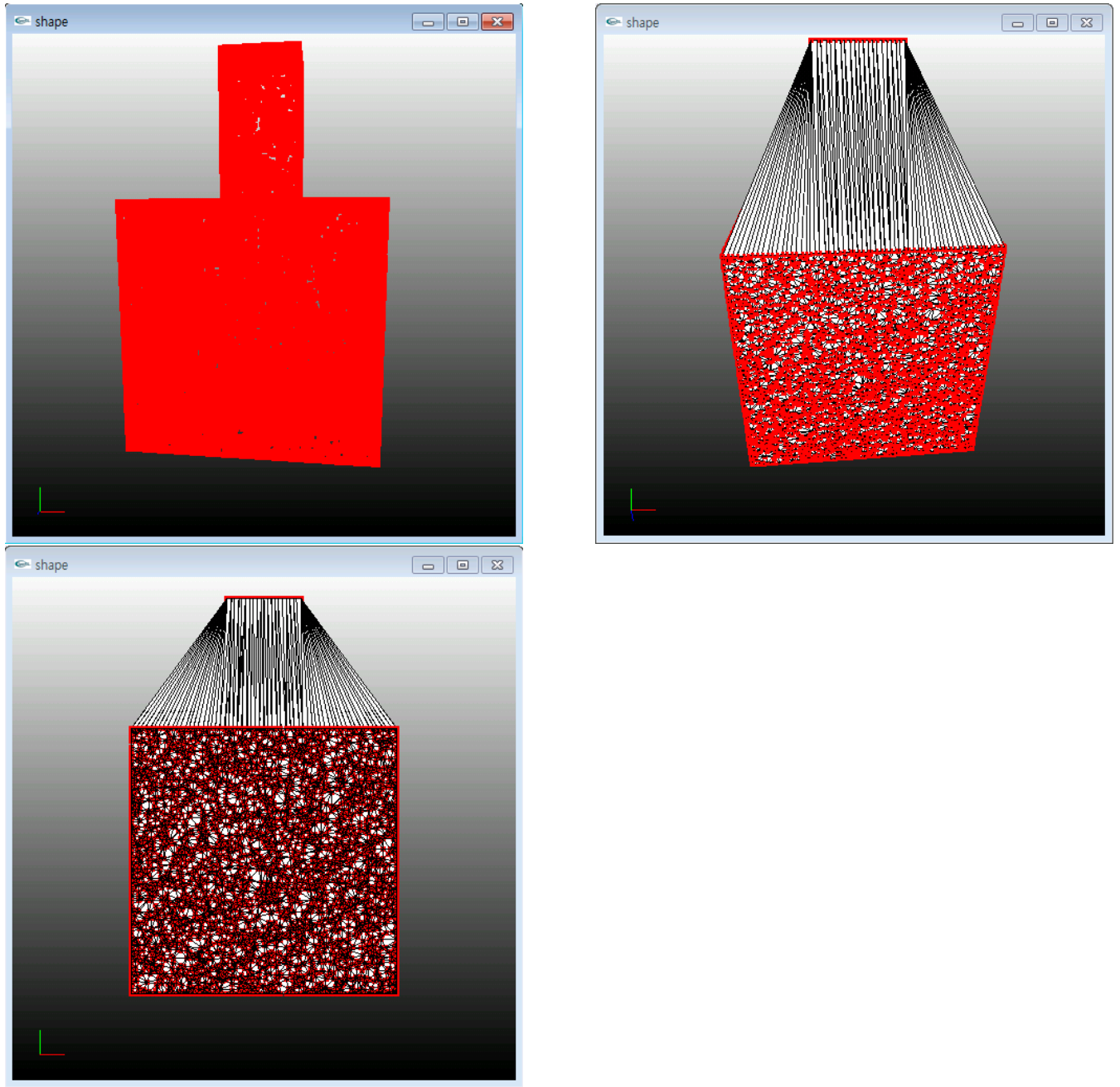


Figure 8: $\alpha = 0$, $\alpha = 1000$, $\alpha = 10000$ *i.T*

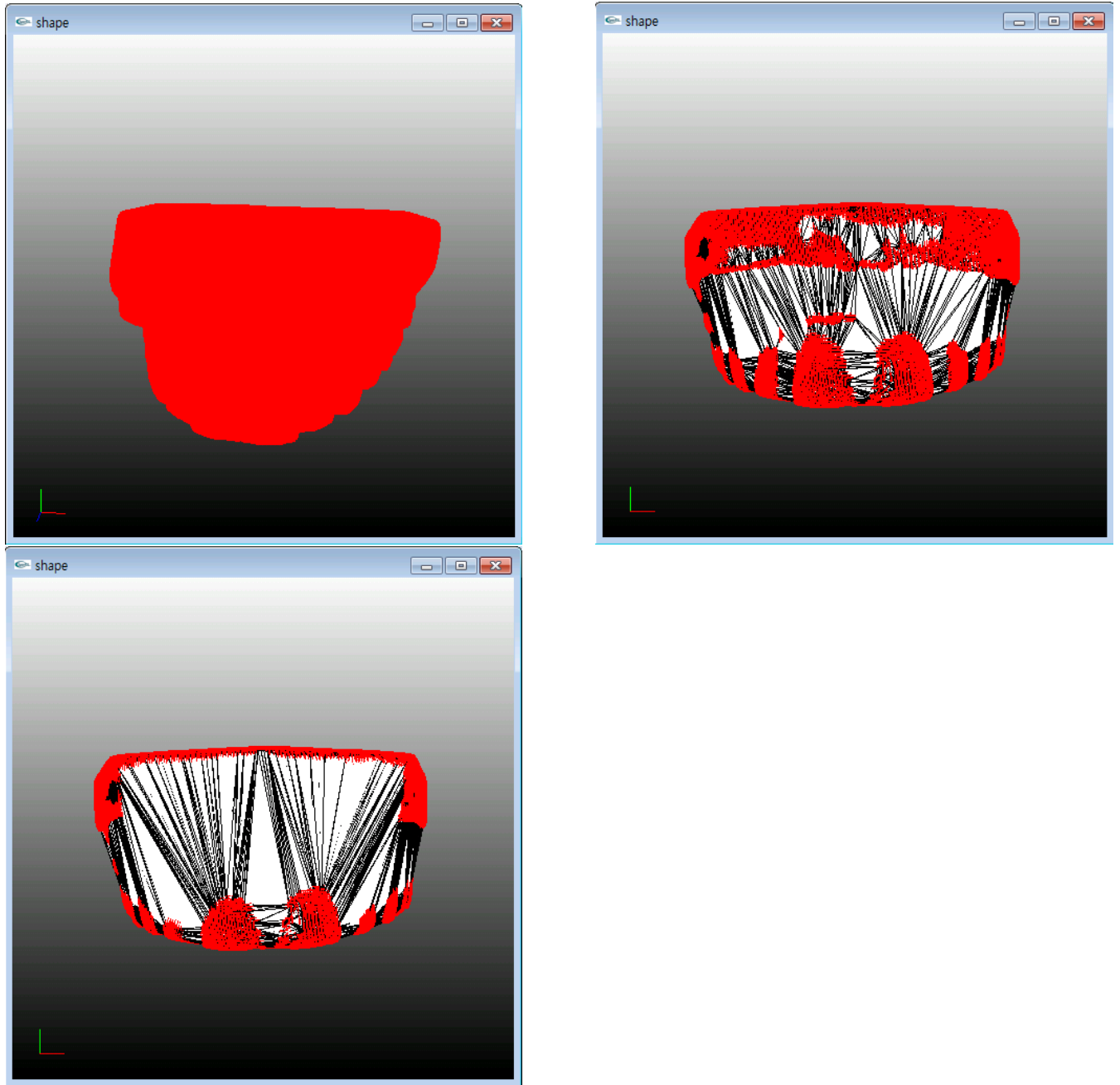


Figure 9: $\alpha = 0$, $\alpha = 100$, $\alpha = 1000$ *i.teeth*

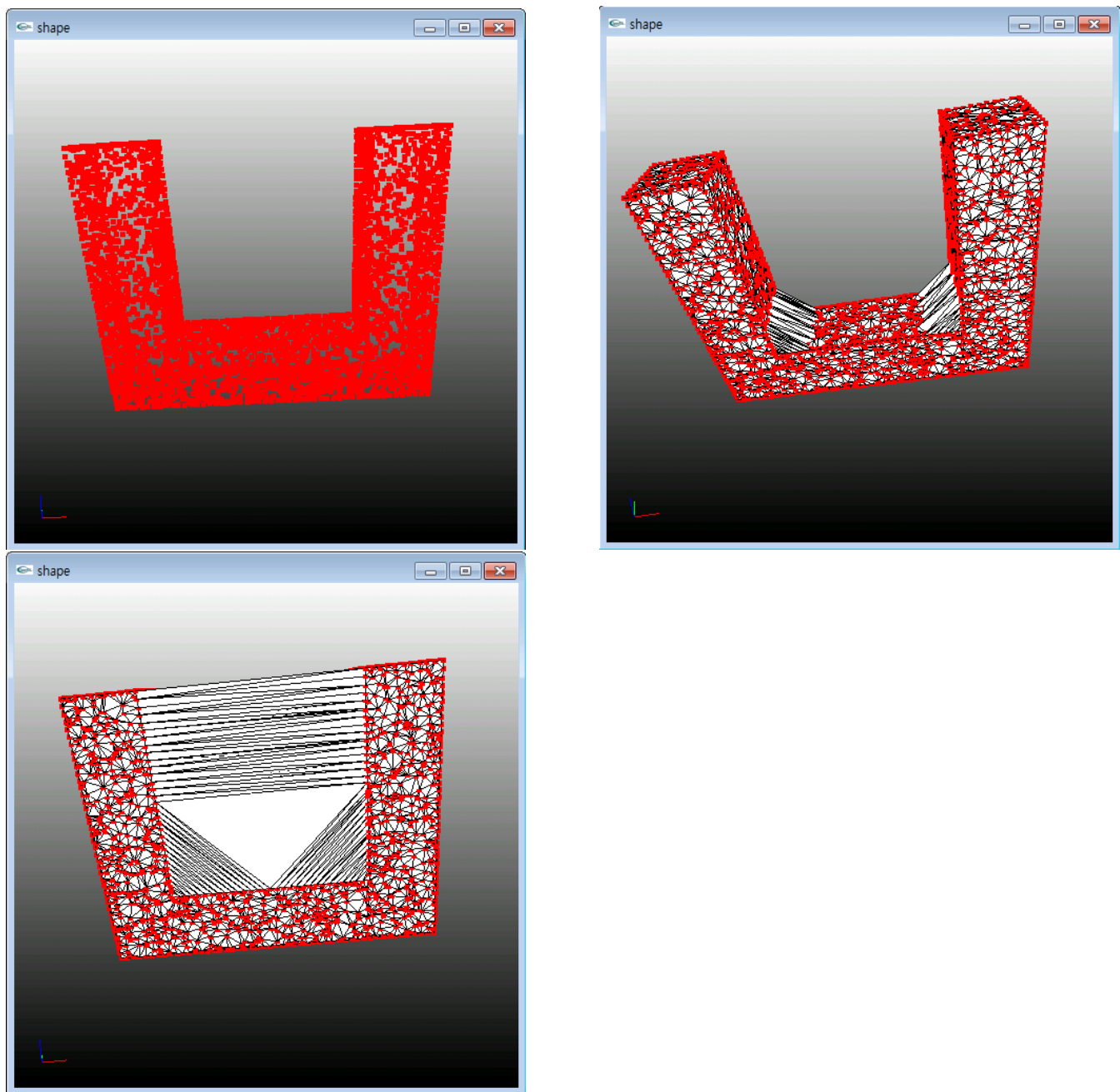


Figure 10: $\alpha = 0$, $\alpha = 10$, $\alpha = 100$ *i.U*

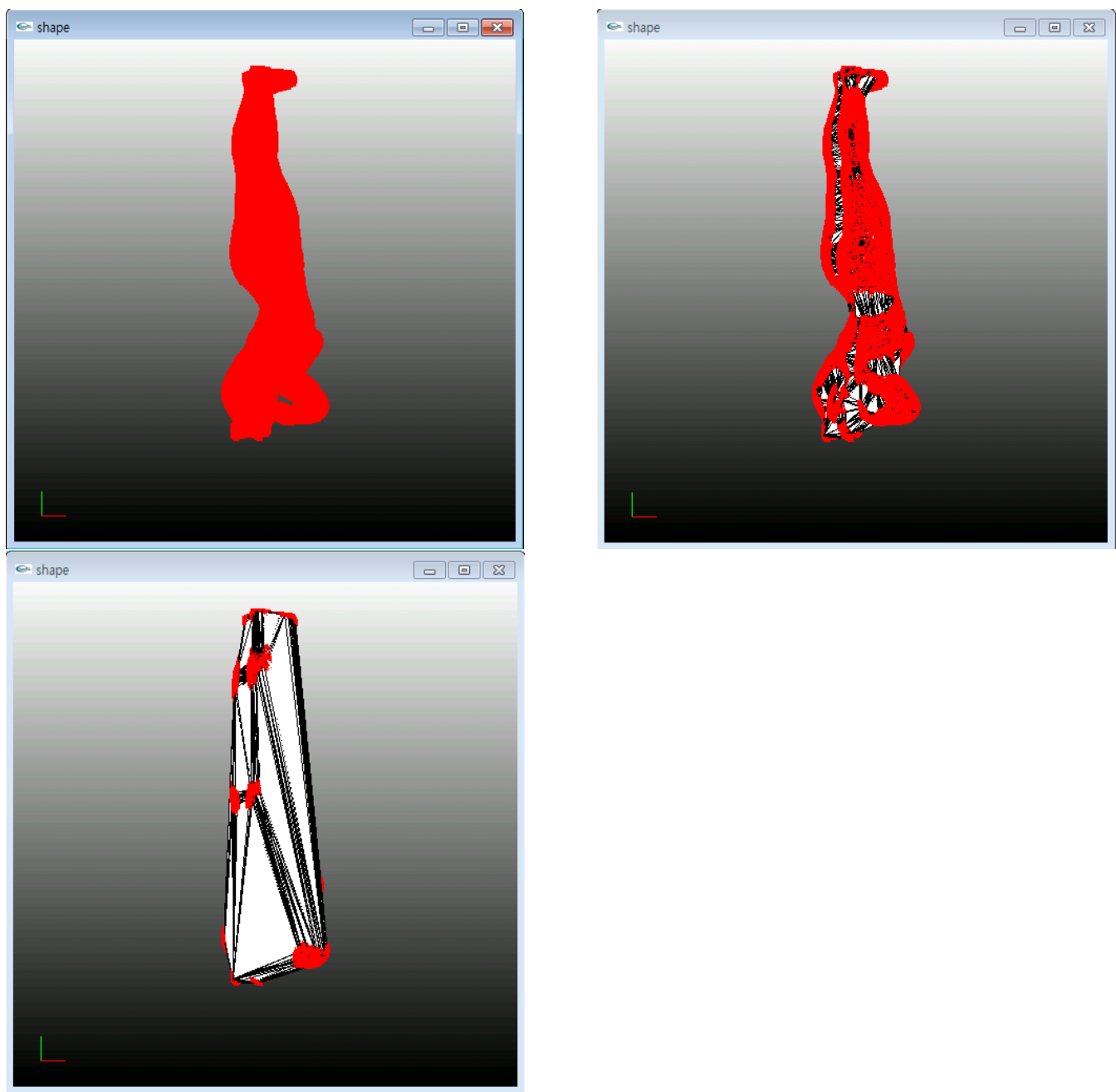


Figure 11: $\alpha = 0, \alpha = 10, \alpha = 1000$ *i.woman*

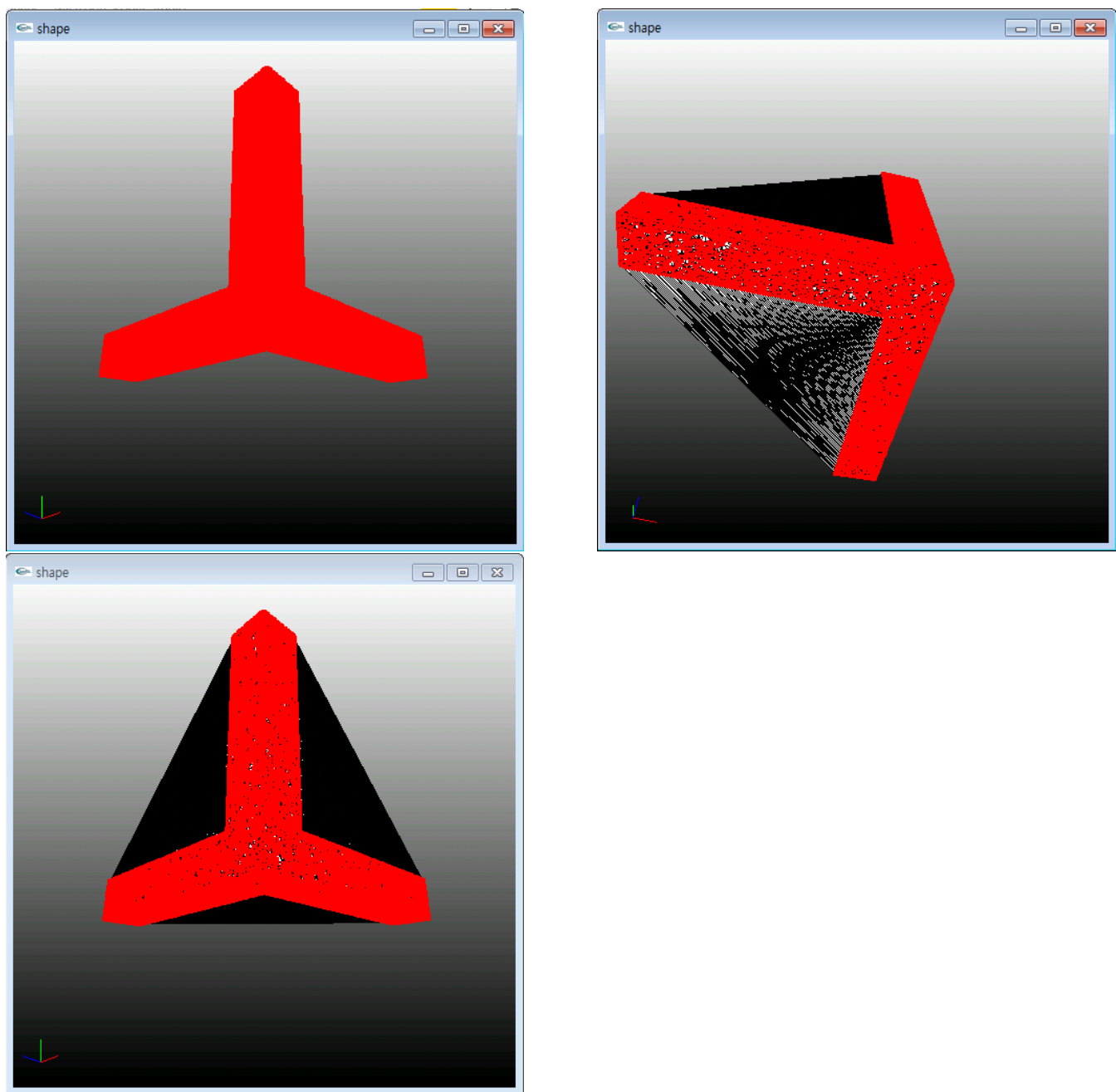


Figure 12: $\alpha = 0$, $\alpha = 100$, $\alpha = 1000$ *i. Y*