## **Report for Lab2-part 2**

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Reference: In this part, the code is based on Lecture 6 Slides Page. 43.

## \_learn\_node\_parameter\_w()

In this function, we get  $w_{u_0}, w_{u_1}, \dots, w_{u_n}$ . We can adjust the formula in the slides Page. 43 to become a solvable form of the function np.linalg.solve(). As np.linalg.solve(A,b) will calculate X for AX = b, in our case x is  $[w_{u_0}, w_{u_1}, \dots, w_{u_n}]^T$ . So the problem becomes to get A and b. We can change the equation in slides into a matrix product-friendly form, take  $\frac{\partial L}{\partial w_{u_0}}$  as an example:

$$\sum_{n=1}^{N} (w_{u1}x_{u1,n} + \dots + w_{uC}x_{uC,n} + w_{u0} \cdot 1) \cdot 1 = \sum_{n=1}^{N} x_{u,n}$$
(2)

Then by listing all the  $[w_{u_0}, w_{u_1}, \dots, w_{u_n}]^T$ , we can modify it into an Ax=b matrix form:

$$\begin{bmatrix} \sum_{n=1}^{N} 1 \cdot 1 & \sum_{n=1}^{N} 1 \cdot x_{u1,n} & \sum_{n=1}^{N} 1 \cdot x_{u2,n} & \cdots & \sum_{n=1}^{N} 1 \cdot x_{uC,n} \\ \sum_{n=1}^{N} 1 \cdot x_{u1,n} & \sum_{n=1}^{N} x_{u1,n} x_{u1,n} & \sum_{n=1}^{N} x_{u1,n} x_{u2,n} & \cdots & \sum_{n=1}^{N} x_{u1,n} x_{uC,n} \\ \sum_{n=1}^{N} 1 \cdot x_{u2,n} & \sum_{n=1}^{N} x_{u2,n} x_{u1,n} & \sum_{n=1}^{N} x_{u2,n} x_{u2,n} & \cdots & \sum_{n=1}^{N} x_{u2,n} x_{uC,n} \\ \vdots & \vdots & \vdots & \ddots & \vdots & \vdots \\ \sum_{n=1}^{N} 1 \cdot x_{uC,n} & \sum_{n=1}^{N} x_{uC,n} x_{u1,n} & \sum_{n=1}^{N} x_{uC,n} x_{u2,n} & \cdots & \sum_{n=1}^{N} x_{uC,n} x_{uC,n} \end{bmatrix} \begin{bmatrix} w_{u_0} \\ w_{u_1} \\ \vdots \\ w_{u_C} \end{bmatrix} = \begin{bmatrix} \sum_{n=1}^{N} x_{u,n} \\ \sum_{n=1}^{N} x_{u,n} \\ \vdots \\ \sum_{n=1}^{N} x_{u,n} \end{bmatrix}$$

$$(3)$$

As there is 1 in equations, we can expand our input, adding 1 to its first column, expanding its dimension to  $N \times (I+1)$ , then we can build A with dimension (I+1,I+1,N), where the third dimension is used for sum operation. Then we can get A by 3-loop iteration and a sum-up operation:

The matrix b is easy to get, then weights can get via np.linalg.solve(A,b)

## \_learn\_node\_parameter\_var()

For this part, we need to calculate the derivative of L w.r.t to  $\sigma^2$ , and let it equal to zero

$$\frac{\partial L}{\partial \sigma^2} \sum_{n=1}^{N} \{ -\frac{1}{2} \log(2\pi \sigma_u^2) - \frac{1}{2\sigma_u^2} \left( x_{u,n} - \left( \sum_{c \in x_{\pi_u}} w_{uc} x_{uc,n} + w_{u0} \right) \right) \} = -\frac{N}{2\sigma_u^2} + \frac{1}{(2\sigma_u^2)^2} \sum_{n=1}^{N} \left( x_{u,n} - \left( \sum_{c \in x_{\pi_u}} w_{uc} x_{uc,n} + w_{u0} \right) \right) = 0$$

Then move  $\sigma^2$  to one side, modify the equation to

$$\sigma^2 = \sum_{n=1}^{N} \left( x_{u,n} - \left( \sum_{c \in x_{\pi_u}} w_{uc} x_{uc,n} + w_{u0} \right) \right) / N \tag{5}$$

Then we can write code based on this formula:

```
x_un = outputs
sum_c = None
if inputs is None:
    sum_c = 0
else:
    sum_c = np.sum(weights[1:]*inputs,axis=1)
var = np.sum((x_un-(sum_c+weights[0]))**2)/len(x_un)
```

## \_get\_learned\_parameters()

In this function, nx is used to build the graph and get the parent nodes of the current node, and then we can get the output and input of the current node and call the former 2 functions in loop iteration.