6.4420Comp Fab Pset4

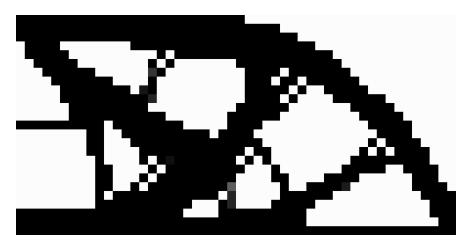
Nomi Yu

April 2024

2.2 Topology Optimization

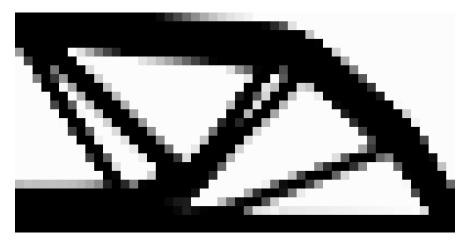
2.2.1 Optimality Condition

This is a straightforward bisection search. We note that a larger λ means a smaller density. Thus, if the density is too large, we reduce it by increasing the lower bound λ , and if density is too small, we increase it by reducing the upper bound λ



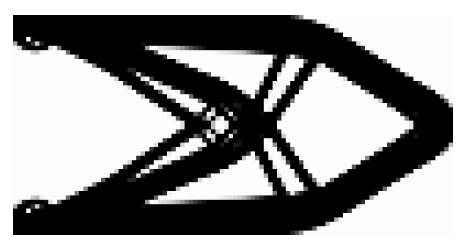
2.2.2 Sensitivity Filtering

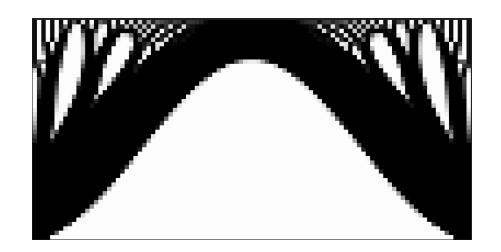
This section was straightforward. I implemented as the comments suggested.



2.2.3 Cantilever and Bridge

This section was straightforward. I optimized with grid size 100

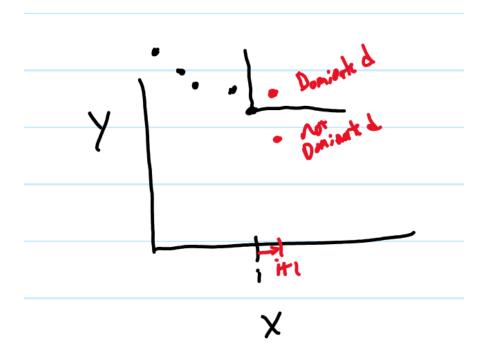




3 Performance Space

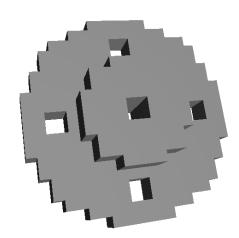
3.1 Pareto Front

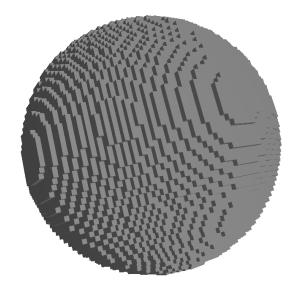
In this analysis, minimal values are preferred, and point i dominates point j if $x_i < x_j$ and $y_i < y_j$. I sorted the data based on increasing x values and iterated through. Then for any given point (ex. at point i), any subsequent point i+n, n>0 will have a larger x value. If the subsequent point has a larger y value, then it is dominated by i. Otherwise, it is a pareto point (when point i is also a pareto point).



3.2 Bridges

Nothing was particularly complex in this section. I ran results using the accelerated voxelization. The following are example results of voxelization on test meshes:





Below is the resulting pareto front of the bridge designs.

