

# Lecture 6: C Programming I

ME/AE 6705

Introduction to Mechatronics

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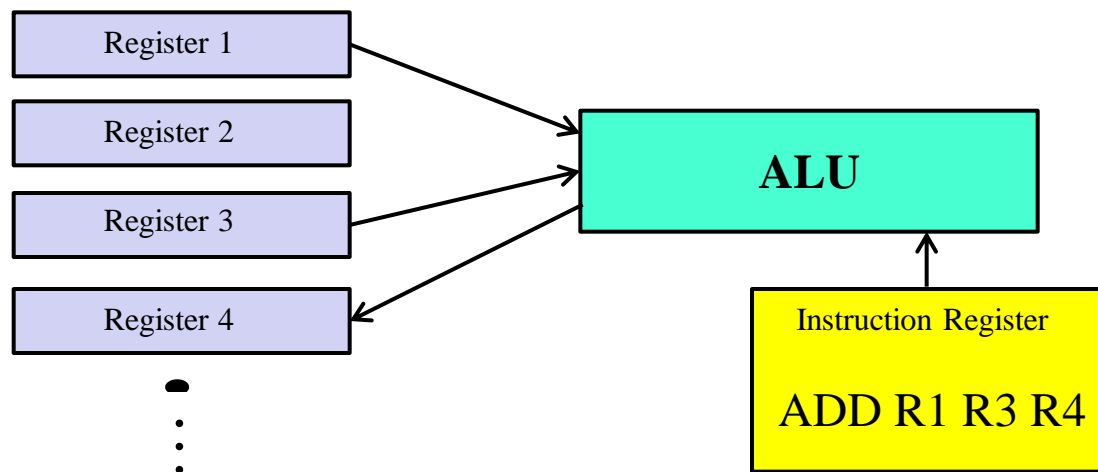
# Lesson Objectives

- Understand hierarchy of programming languages/methods
  - Machine language, assembly, C/C++
- Understand basic structure of C program
- Be comfortable with use of C data types
- Be able to decompose program into functions and use appropriate flow control
- Demonstrate concepts through multiple examples



# Fundamentals of Processor Execution

- Arithmetic & Logic Unit of microprocessor is responsible for taking data and performing some (simple) operation
  - More complex operations built from series of simple ones
  - ALU made up of series of logic gates



# Configuration Registers

- Registers are particular 32-bit memory locations
- Processor uses registers for configuration purposes
  - These registers are fixed memory locations that serve a particular purpose
  - Example: Flash size register

## Other Important Registers:

- Instruction register
- Data registers on ALU
- ADC configuration registers
- PWM configuration registers
- ...

This register reflects the size of flash main memory available on the device.

Figure 6-6. SYS\_FLASH\_SIZE Register

31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16
SIZE															
r	r	r	r	r	r	r	r	r	r	r	r	r	r-1	r	r
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
SIZE															
r	r	r	r	r	r	r	r	r	r	r	r	r	r	r	r

Table 6-3. SYS\_FLASH\_SIZE Register Description

BIT	FIELD	TYPE	RESET	DESCRIPTION
31-0	SIZE	R	Variable	Indicates the size (in bytes) of the flash main memory on the device. This is divided equally between the two banks.



# Data Registers

- Processor also contains registers used to hold data during processing
- These registers are the size of one WORD
  - 32-bit on 32-bit processors
  - 8-bit on 8-bit processors
- These registers hold intermediate data
  - Either taken from memory to be operated on
  - Or staged in registers before being shipped to memory

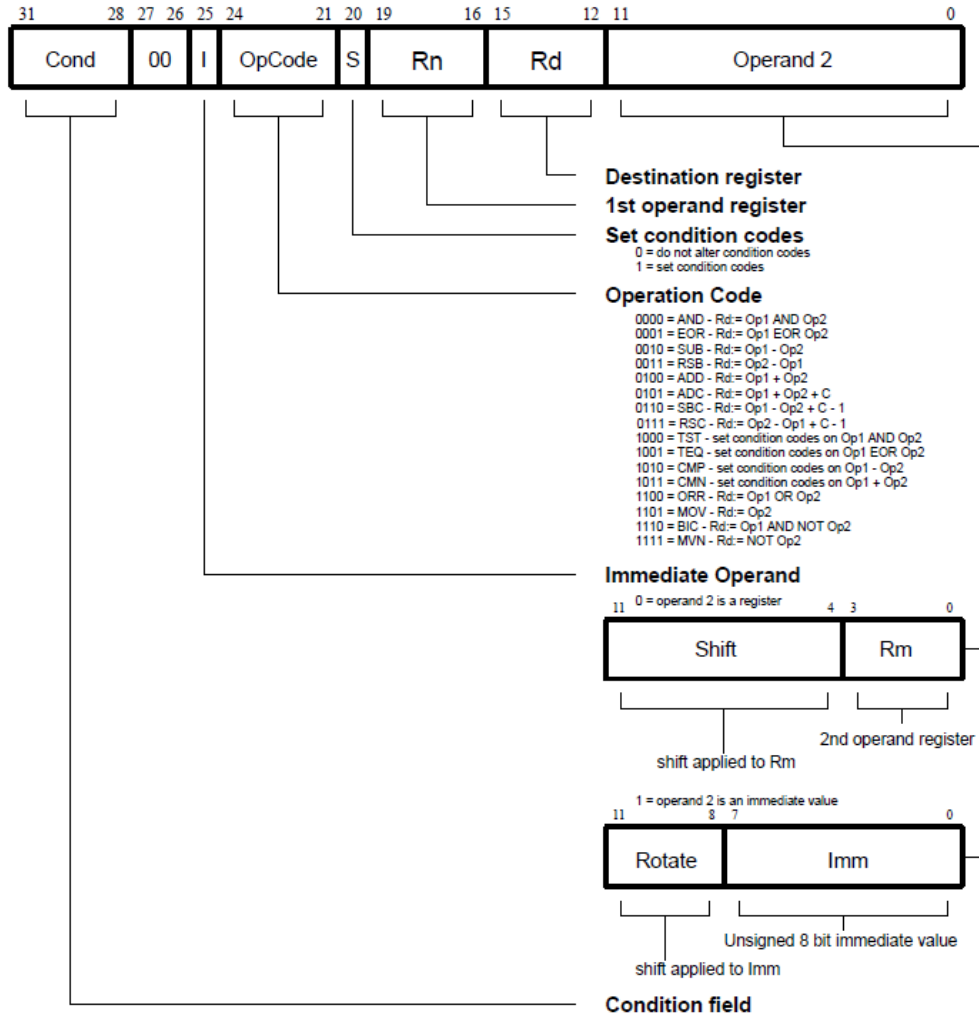


# Instruction Register

- Holds the instruction that ALU is executing
- An *instruction* is a 32-bit value that determines what operation is to be performed
- An *instruction set* is defined by the processor manufacturer
  - ALU can only perform operations in its instruction set
- Instructions also can have arguments associated with them
  - Tell ALU pieces of data on which instruction should be performed

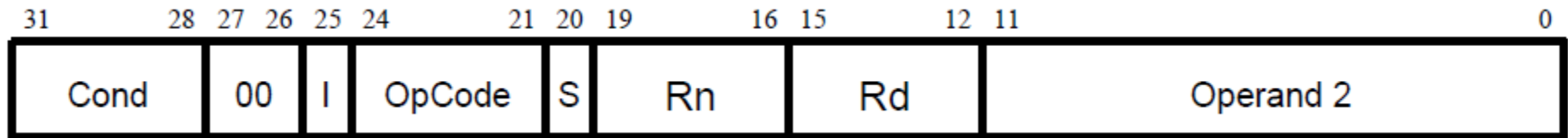


# MSPM0 Instructions



- Instructions are 32-bit binary values
- Contain fields specifying operation to perform, register addresses with relevant data, and configuration flags
- Instruction format located in ARM Cortex datasheet
- Instruction format to the left applies to all “data processing” instructions (add, subtract, etc)

# MSPM0 Instructions



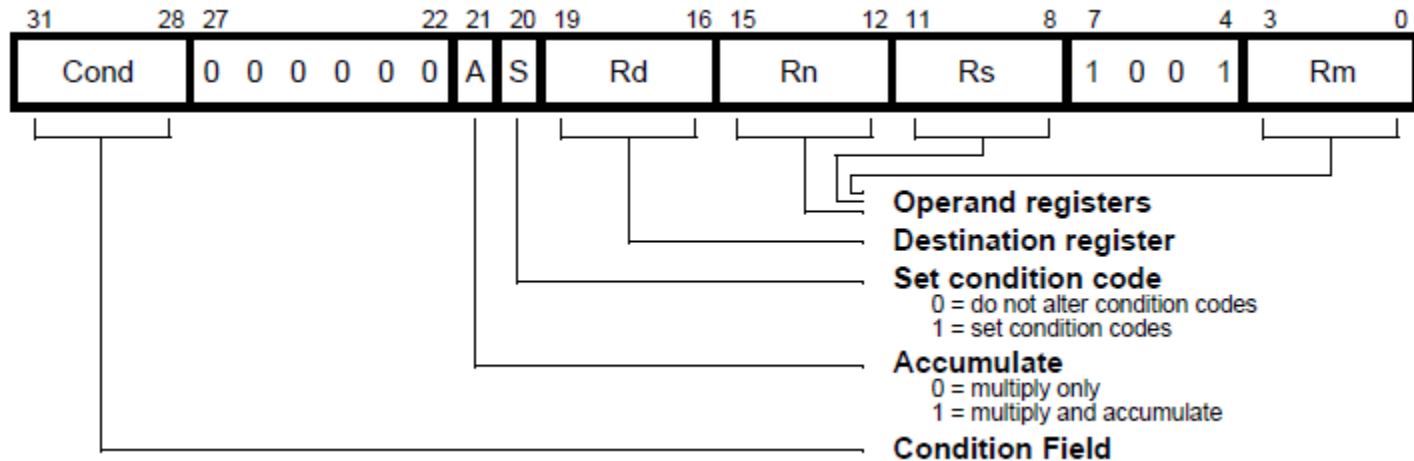
- Example: Add instruction (ADD)
  - OpCode 0100
  - Rd = destination (result) register
  - Rn = register containing first argument
  - Operand2 = register containing second argument
    - *Or can contain second argument itself (depends on I bit)*
  - Executes  $Rd = Rn + \text{Operand2}$
  - Takes 1 clock cycle for ALU to execute



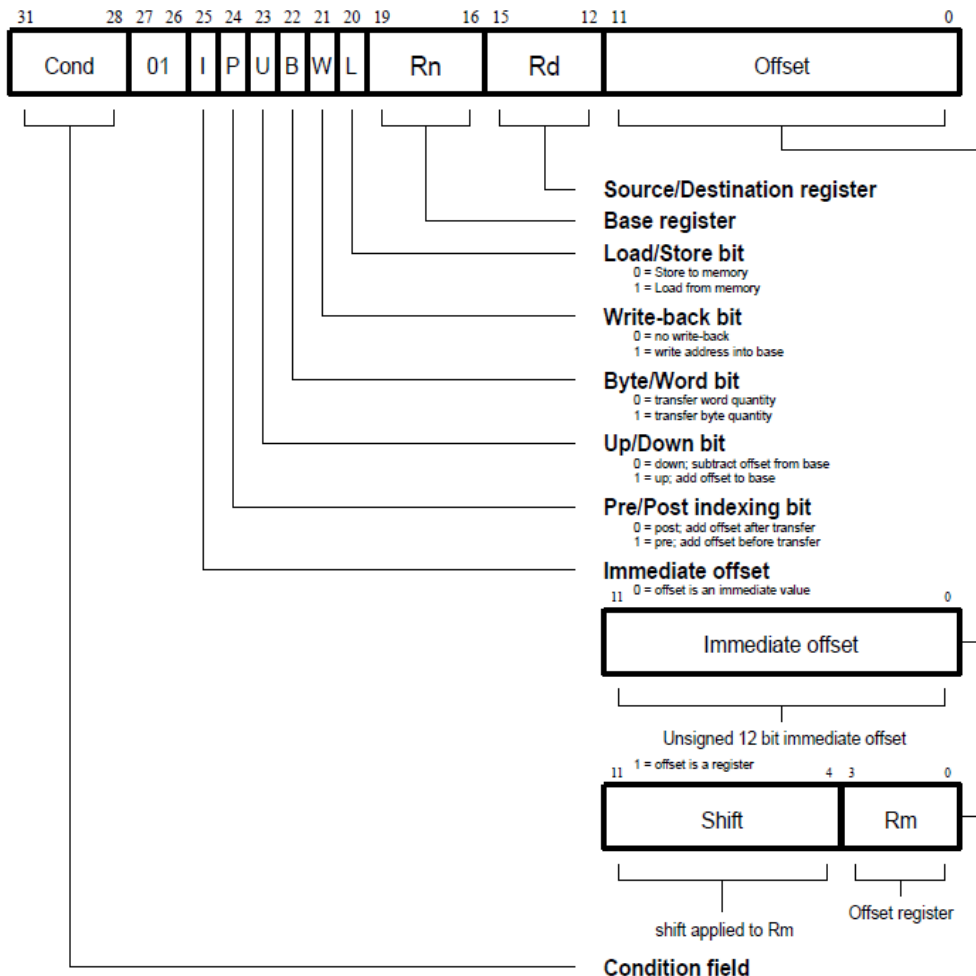


# MSPM0 Instructions

- Example: Multiply instruction (MUL)
  - Multiplies  $Rd = Rm * Rs$  ( $Rn$  field ignored)
  - May take several clock cycles to complete depending on instruction configuration



# MSPM0 Instructions



- Load/store instruction
- Like ADD instruction, LDR/STR instruction is configured by the bits within the 32-bit instruction
- For instance, bit L is used to determine whether it is a Store instruction (1) or Load instruction (0)
- Store means send data from Rn to Rd
- Load means send data from Rd to Rn
- Takes 3 clock cycles to execute

# Writing a Program

- Theoretically you can write a program for MSPM0 completely in machine language by typing in the hex values of each instruction sequentially
  - Not feasible
- Alternatively, you can write a program in assembly language by typing in each instruction and associated arguments in assembly format
  - Assembly language can then be converted to machine language by a computer program (assembler)



# Assembly Language

- Assembly language is low level programming language consisting of individual instructions
  - Essentially abstracts “binary” instructions above into more readable language
- Examples of assembly instructions for MSPM0

```
ADD    R2,  R1,  R3    ; R2 = R1+R3
```

Add instructions

```
ADDS   R4,  R4,  #100   ; R4 = R4 + 100
```

```
AND     R9,  R2,  #0xFF00 ; R9 = R2&0xFF00
```

And instruction

```
MUL     R10,  R2,  R5    ; R10 = R2*R5
```

Multiply instruction

```
STR     R2,  [R9, R12]   ; Store 32-bit value in R2 into  
                           memory address R9+R12
```

Store instruction

# Assembly Language

- ARM Cortex M processor has over 150 instructions

Operation		\$	Assembler	S updates	Action	Notes
Add	Add		ADD{S} Rd, Rn, <Operand2>	N Z C V	Rd := Rn + Operand2	N
	with carry		ADC{S} Rd, Rn, <Operand2>	N Z C V	Rd := Rn + Operand2 + Carry	N
	wide	T2	ADD Rd, Rn, #<imm12>		Rd := Rn + imm12, imm12 range 0-4095	T, P
	saturating {doubled}	5E	Q{D}ADD Rd, Rm, Rn		Rd := SAT(Rm + Rn)      doubled: Rd := SAT(Rm + SAT(Rn * 2))	Q
Address	Form PC-relative address		ADR Rd, <label>		Rd := <label>, for <label> range from current instruction see Note L	N, L
Subtract	Subtract		SUB{S} Rd, Rn, <Operand2>	N Z C V	Rd := Rn - Operand2	N
	with carry		SBC{S} Rd, Rn, <Operand2>	N Z C V	Rd := Rn - Operand2 - NOT(Carry)	N
	wide	T2	SUB Rd, Rn, #<imm12>	N Z C V	Rd := Rn - imm12, imm12 range 0-4095	T, P
	reverse subtract		RSB{S} Rd, Rn, <Operand2>	N Z C V	Rd := Operand2 - Rn	N
	reverse subtract with carry		RSC{S} Rd, Rn, <Operand2>	N Z C V	Rd := Operand2 - Rn - NOT(Carry)	A
	saturating {doubled}	5E	Q{D}SUB Rd, Rm, Rn		Rd := SAT(Rm - Rn)      doubled: Rd := SAT(Rm - SAT(Rn * 2))	Q
	Exception return without stack		SUBS PC, LR, #<imm8>		PC = LR - imm8, CPSR = SPSR(current mode), imm8 range 0-255.	T

Branch	Branch		B <label>	PC := label. label is this instruction $\pm 32\text{MB}$ (T2: $\pm 16\text{MB}$ , T: $-252 - +256\text{B}$ )		N, B
	with link		BL <label>	LR := address of next instruction, PC := label. label is this instruction $\pm 32\text{MB}$ (T2: $\pm 16\text{MB}$ ).		
	and exchange	4T	BX Rm	PC := Rm. Target is Thumb if Rm[0] is 1, ARM if Rm[0] is 0.		N
	with link and exchange (1)	5T	BLX <label>	LR := address of next instruction, PC := label, Change instruction set. label is this instruction $\pm 32\text{MB}$ (T2: $\pm 16\text{MB}$ ).		C
	with link and exchange (2)	5	BLX Rm	LR := address of next instruction, PC := Rm[31:1]. Change to Thumb if Rm[0] is 1, to ARM if Rm[0] is 0.		N
	and change to Jazelle state	5J	BXJ Rm	Change to Jazelle state if available		
	Compare, branch if (non) zero	T2	CB{N}Z Rn, <label>	If Rn {== or !=} 0 then PC := label. label is (this instruction + 4-130).		N T U
	Table Branch Byte	T2	TBB [Rn, Rm]	PC = PC + ZeroExtend( Memory( Rn + Rm, 1) << 1). Branch range 4-512. Rn can be PC.		T U
	Table Branch Halfword	T2	TBH [Rn, Rm, LSL #1]	PC = PC + ZeroExtend( Memory( Rn + Rm << 1, 2) << 1). Branch range 4-131072. Rn can be PC.		T U

Move data	Move		MOV{S} Rd, <Operand2>	N Z C	Rd := Operand2	N
	NOT		MVN{S} Rd, <Operand2>	N Z C	Rd := 0xFFFFFFFF EOR Operand2	N
	top	T2	MOVT Rd, #<imm16>		Rd[31:16] := imm16, Rd[15:0] unaffected, imm16 range 0-65535	
	wide	T2	MOV Rd, #<imm16>		Rd[15:0] := imm16, Rd[31:16] = 0, imm16 range 0-65535	
	40-bit accumulator to register	XS	MRA RdLo, RdHi, Ac		RdLo := Ac[31:0], RdHi := Ac[39:32]	
	register to 40-bit accumulator	XS	MAR Ac, RdLo, RdHi		Ac[31:0] := RdLo, Ac[39:32] := RdHi	

# Assembly Language

- Example ARM Cortex assembly code
  - For function my\_asm

```
my_asm
; ARM Assembly language function to set LED1 bit to a value passed from C
; LED1 gets value (passed from C compiler in R0) ; LED1 is on GPIO port 1 bit 18
; See Chapter 9 in the LPC1768 User Manual
; for all of the GPIO register info and addresses
; Pinnames.h has the mbed modules pin port and bit connections ;
; Load GPIO Port 1 base address in register R1
    LDR    R1, =0x2009C020 ; 0x2009C020 = GPIO port 1 base address
; Move bit mask in register R2 for bit 18 only
    MOV.W  R2, #0x040000 ; 0x040000 = 1<<18 all "0"s with a "1" in bit 18
; value passed from C compiler code is in R0 - compare to a "0"
    CMP    R0, #0 ; value == 0 ?
; (If-Then-Else) on next two instructions using equal cond from the zero flag
    ITE EQ
; STORE if EQ - clear led 1 port bit using GPIO FIOCLR register and mask
    STREQ  R2, [R1,#0x1C] ; if==0, clear LED1 bit
; STORE if NE - set led 1 port bit using GPIO FIOSET register and mask
    STRNE  R2, [R1,#0x18] ; if==1, set LED1 bit
; Return to C using link register (Branch indirect using LR - a return)
    BX     LR
END
```

# Assembly Language

- Example assembly language program (not ARM):

```
_vector_add:  ← Function name
mov.u32 %r1, %tid.x;
mov.u32 %r2, %envreg3;
add.s32 %r3, %r1, %r2;
mov.u32 %r4, %ctaid.x;  ← Move unsigned 32-bit number
mov.u32 %r5, %ntid.x;
mad.lo.s32 %r6, %r4, %r5, %r3;
shl.b32 %r7, %r6, 2;
ld.param.u32 %r8, [vector_add_param_1];
ld.param.u32 %r9, [vector_add_param_0];
add.s32 %r10, %r9, %r7;  ← Add signed 32-bit number
add.s32 %r11, %r8, %r7;
ld.param.u32 %r12, [vector_add_param_2];
ld.global.u32 %r13, [%r10];
ld.global.u32 %r14, [%r11];  ← Load unsigned 32-bit number
add.s32 %r15, %r14, %r13;
add.s32 %r16, %r12, %r7;
st.global.u32 [%r16], %r15;
ret;
```

# Writing a Program

- MCU's used to be programmable only using assembly language
  - All complex functionality had to be expressed in simple instructions
- Problem: To implement complex functionality, writing assembly programs from scratch extremely time consuming
  - Programs can be very long – simple line of C code becomes 10's of lines of assembly





# Writing a Program

- For instance, previous 18-line assembly program was assembly language version of this C function:

```
void vector_add(int *A, int *B, int *C) {  
  
    // Get the index of the current element to be processed  
    int i = get_global_id(0);  
  
    // Perform addition  
    C[i] = A[i] + B[i];  
}
```

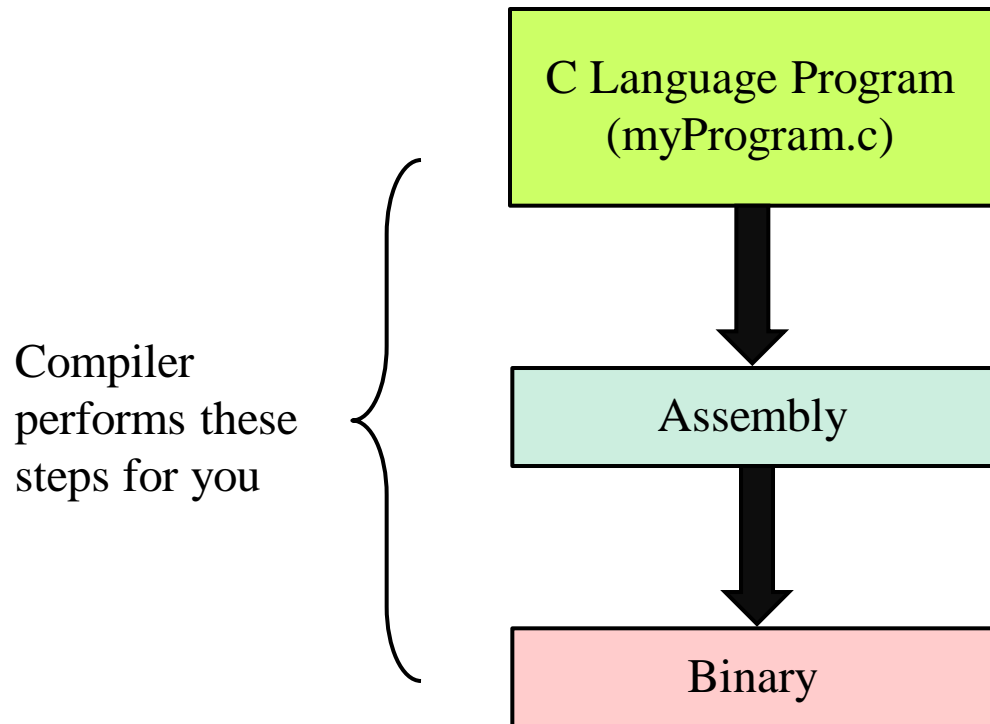


# C Language Basics

- Thus higher level languages like C were developed to limit developer effort to reasonable level
- C language is built on top of assembly code
- Facts about C language:
  - Developed in 1970 at Bell Laboratories
    - *Replaced earlier languages such as FORTRAN*
  - Very flexible and elegant language, used extremely widely
  - C++ written on top of C language to enable object-oriented programming
  - MSPM0 supports variant of C called C99

# C Language Basics

- Compiling workflow



- C Compiler is a computer program that translates C language to machine instructions (binary)
- Running program successfully results in executable file
- Since different processors use different instruction sets, processor manufacturer has to provide compiler for their device



# C Language Basics

- Simple C program

```
// Simple C program

#include <stdio.h>

int main(){

    int miles, yards ;
    float kilometers ;

    miles = 26 ;
    yards = 385 ;
    kilometers = 1.069 * (miles + yards/1760.0) ;

    printf("\nA marathon is %f kilometers\n\n",kilometers) ;

    return 0 ;

}
```



# C Language Basics

- Simple C program

```
// Simple C program      Comment
#include <stdio.h>         Header file include
int main(){               Main function definition
    int miles, yards ;    Variable declarations
    float kilometers ;
    miles = 26 ;           Assignments
    yards = 385 ;
    kilometers = 1.069 * (miles + yards/1760.0) ;
    printf("\nA marathon is %f kilometers\n\n",kilometers) ;
    return 0 ;            Print statement
}
```



# C Language Basics

- In C programs, data is stored in “variables”
- Variables are declared by the programmer
  - When a variable is declared, memory is allocated to store the data for that variable
- All variables must have an associated data type
  - In MSPM0 C, can be declared as int, float, double, etc.
  - Can also use int32\_t, int16\_t, uint32\_t, etc.

# C Language Basics

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  - In MSPM0 C, can be declared as int, float, double, etc.
  - Can also use int32\_t, int16\_t, uint32\_t, etc.
- Data type tells compiler:
  - How much memory should be allocated for this variable
  - How to interpret data in memory location (signed, unsigned, float, etc.)

# C Language Basics

- All programs in C must contain a “main” function
  - This is where program execution always begins
  - Other functions can be called from main function
  - Main function can never be called by another function

```
// Simple C program
#include <stdio.h>

int main(){

    int miles, yards ;
    float kilometers ;
    ...

    return 0 ;

}
```





# C Language Basics

- Assignment statements assign the value of one variable (or number) to another variable  
= sign used for assignment
- All declarations and assignment statements in C end with a semicolon (“;”)
- To the right of = sign in assignment operations, can add any operations or function calls you like

```
kilometers = 1.069 * (miles + yards/1760.0) ;
```



# C Language Basics

- Basic mathematical operations
  - + add two numbers
  - subtract two numbers
  - \* multiply two numbers
  - / divide two numbers
- Standard order of operations used when multiple operations performed on same line
  - Parentheses used to define desired order of operations

```
kilometers = 1.069 * (miles + yards/1760.0) ;
```



# Printf Statements

- Recall our discussion of printf from last class
- printf prints a string of characters formatted according to our specification in code

```
float res = 15.7 ;  
printf("res = %f\n", res) ;
```

→ prints: res = 15.7000

```
int32_t res = 15 ;  
printf("res = %d\n", res) ;
```

→ prints: res = 15



# Preprocessor

- Compiler actually composed of two programs:
  - Preprocessor: Goes through code before compilation and makes modifications
  - Compiler: Actually translates code to machine language
- Preprocessor directives:
  - All start with a “#” sign
  - Tell the preprocessor to do something prior to compilation
  - Two used often: `#include` and `#define`



# #include Statements

- Oftentimes we define lots of variables (or functions) in separate files to make our code more modular and readable

```
// Simple C program
#include <stdio.h>

int main(){

    ...

    return 0 ;

}
```

← #include statement says to take all code in file “stdio.h” and place it in this part of code prior to compilation



# Header Files

- Most of the time, `#include` is used to include header files in your code
- Header files contain common functions, variable declarations, etc.
  - Always end in “.h”
- For instance, `printf(...)` is a function that is defined in `stdio.h`
  - Without including this, compiler doesn't know what `printf(...)` refers to
- ARM codebase comes with many header files (`math.h`, `stdio.h`, ...) but you can write your own

# #define Statements

- Another common preprocessor directive is #define
- This says to replace all instances of [first argument] in code with [second argument]
  - Allows you to change something in multiple places easily

```
#define C 325

int main(){
    int newVal = C ;
    ...
    newVal = log(C)/log(2);
    return 0 ;
}
```

*During compile time, all values of C will get populated with 325.*



# Functions

- Functions allow you to decompose program into discrete modules
- Functions are declared in C using following structure:

```
type  function_name ( argument list ){  
  
    variable definitions  
  
    statements ...  
  
    return ...  
  
}
```





# Functions

- All functions return something
  - Thus they are declared with a data type specifying what type of data they will return
- Example: Consider function “square” which computes square of two values

```
// Returns value of x^2
int square (int x){

    int ans = x*x ;

    return ans ;

}
```



# Functions

- A function can return any data type you want
- If you don't want a function to return anything, you can declare it as a type void function
- Example: Function that prints "hello!"

```
// Prints "hello!" to screen
void print_hello(){

    printf("hello!") ;

    return ;

}
```



# Functions

- When return statement is encountered, execution of the function is terminated and control goes back to environment which called function
  - Return statements may contain an expression:

```
// Returns value of x^2
int square (int x){

    return x*x ;

}
```

- Functions of type void do not need to include return statement

```
void print_hello(){

    printf("hello!") ;

}
```

# Functions

- Function arguments are sent to function by calling environment
  - These are variables that can be used by function
  - Some, all, or none of the function's variables can be sent in as arguments

```
// Sums x, y, and then multiplies result by 2.5
float do_math (int x, int y){

    float z = (float)(x+y)
    return z*2.5 ;
}
```



# Functions

- When variables are passed in as an argument, a copy of them is actually being passed
  - A variable (passed in as argument) which is changed inside function is not also changed outside

```
// Sums x, y, and then multiplies result by 2
int do_math (int x, int y){

    x = x+y
    return x*2 ;
}

int main (){

    int x = 4, y = 7 ;

    printf("x=%d\n", do_math(x,y)) ;    // Will print "x = 22"
    printf("x=%d\n", x) ;                // Will print "x = 4"
}
```

# Functions

- Functions may of course be called from other functions
- Compiler compiles your code sequentially
  - If a function is called before it is defined, compiler will not know what that function call refers to


```
int main () {  
  
    int x = 4, y = 7 ;  
    printf("x=%d\n", do_math(x,y)) ;    // Will print "x = 22"  
    printf("x=%d\n", x) ;                // Will print "x = 4"  
}  
  
int do_math (int x, int y) {  
  
    x = x+y  
    return x*2 ;  
}
```

*Compiling will fail – cannot  
find function do\_math.*

# Functions

- Instead, need to add function prototype before function is called
  - Usually all function prototypes located at top of file

```
int do_math(int x, int y) ;  
  
int main () {  
    int x = 4, y = 7 ;  
    printf("x=%d\n", do_math(x,y)) ;    // Will print "x = 22"  
    printf("x=%d\n", x) ;                // Will print "x = 4"  
}  
  
int do_math (int x, int y) {  
    x = x+y  
    return x*2 ;  
}
```



*Function prototype contains  
return type, name, and  
argument list of function.*

# Main Function

- All programs require definition of a function called “main”
- main function in traditional C:
  - Takes arguments which are provided in command line
  - Always returns int value (specifying program return value)

```
// Traditional C main function
int main (int argc, char *argv[]){
    ...
    return 0 ;
}
```

- main function for MSPM0
  - Takes no arguments (void) and returns void

```
// MSPM0 main function
void main(void){
    ...
    return ;
}
```



# Flow Control

- As program is executing, you oftentimes will require conditional statements, loops, or both
- C provides various flow control mechanisms:
  - if-else statement
  - while loop
  - for loop
  - switch statement
- if-else and switch statements provide conditional execution
- while and for loops provide repetitive execution



# Flow Control

- Relational, equality, and logical operators

Type	Meaning	Symbol
Relational Operators	Less than	<
	Greater than	>
	Less than or equal to	<=
	Greater than or equal to	>=
Equality Operators	Equal to	==
	Not equal to	!=
Logical Operators	Negation	!
	Logical and	&&
	Logical or	



# Flow Control

- If statement:

```
if (expression) {  
    ...  
}
```

- Code in {} brackets only gets executed if [expression] evaluates to true
- Same exact functionality as in MATLAB



# Flow Control

- Example:

```
if((a > 5) && (b != 7)){  
  
    ...  
  
}
```

- Statements inside if statement will execute only if a is greater than 5 and b is not equal 7
- Otherwise these statements will be skipped



# Flow Control

- Else statement can be used in conjunction to define code that will be executed if if statement is not entered
- Example:

```
if((a > 5) && (b != 7)){  
    c = 54 ;  
}  
else{  
    c = 0 ;  
}
```



# Flow Control

- If-else statements can be grouped together to define series of alternative execution paths
- Example:

```
if(a < 5){  
    c = 54 ;           // Will execute only when a < 5  
}  
else if((a >=5) && (a < 14)){  
    c = 55 ;           // Will execute only when 5 <= a < 14  
}  
else{  
    c = 0 ;           // Will execute otherwise  
}
```



# Flow Control

- While loop will repeat execution of code within {} while a certain condition remains true
- Example:

```
while(i < 100){  
    printf("i = %d\n", i)  
    i++ ;  
}
```

- While loops often used when the number of times the loop is performed is not known a priori



# Flow Control

- While loops can be used to create infinite loops
  - Loops which never end

```
while(1) {  
    printf("I'm still running.\n")  
}
```

- In C, logical expressions return either 1 (true) or 0 (false)
    - *0 is always treated as “false”*
    - *Anything not zero is considered “true”*
- Infinite loops used often in microcontroller programming to wrap around main processing loop





# Flow Control

- for loop used to execute code iteratively
  - Similar to while loop
- With for loop, you specify
  1. Variable initialization at start of loop
  2. End condition of loop
  3. Action to take every time loop is repeated
- Example:

```
for(i = 0; i < 12; i++){  
    printf("i = %d\n", i) ;  
}
```



# Flow Control

- Example of factorial function using while loop

```
// Computes n factorial
int computeFactorial(int n){

    int factorial = 1 ;

    for(i = 1; i <= n; i++){
        factorial = factorial*i ;
    }

    return factorial ;
}
```

- Any while loop can always be made into a for loop



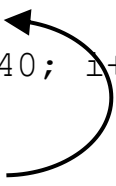
# Flow Control

- Use the “break” keyword to jump out of a loop when a certain condition is met

```
while(1) {  
    printf("I'm still running.\n")  
    i++ ;  
    if(i > 22){  
        break;  
    }  
}
```

- break will only jump out of lowest level loop

```
while(1) {  
    for(i = 0; i < 40; i++) {  
        if(i > 22){  
            break;  
        }  
    }  
}
```



*Jumps back into while loop*

# Flow Control

- Switch statement is generalization of if-else
  - Used when there are many possible else-if's
- Example:

```
switch (c){  
    case 'a':  
        a_cnt++ ;  
        break ;  
    case 'b':  
        b_cnt++ ;  
        break ;  
    default:  
        other_cnt++ ;  
}
```

- Evaluate whether c is equal to a, b, or something else
- Execute logic after the appropriate case statement
- break terminates switch statement



# Comments

- Your code should always be commented well
- Essential when building codes for real mechatronic systems
  - Real codes may be 1000's of lines
  - Important if you ever want someone else to see your code
  - Should comment approximately every line
- Comments in C:
  - Any line preceded by two slashes //
  - Between /\* and \*/ mark



# Comments

- Examples

```
// Example switch statement
switch (c){
    case 'a':
        // Increment a counter
        a_cnt++ ;
        break ;
    case 'b':
        // Increment b counter
        b_cnt++ ;
        break ;
    default:
        // Increment other counter
        other_cnt++ ;
}
/* This is an example of another comment, used to
   comment out multiple lines at once.  */
```

