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1  #include "interrupt.h"
2
3  #define PA15_FREQ 1000000
4  #define PB4_FREQ 1000000
5
6  struct keys key[4] = {0};
7
8  uint PA15_freq, PA15_duty;
9  uint PA15_rise, PA15_fall;
10
11 uint PB4_freq, PB4_duty;
12 uint PB4_rise, PB4_fall;
13
14 char rx_array[50];
15 char rx_data;
16 char rx_pointer;
17
18 void HAL_UART_RxCpltCallback(UART_HandleTypeDef *huart)
19 {
20     if(huart->Instance == USART1)
21     {
22         rx_array[rx_pointer++] = rx_data;
23         HAL_UART_Receive_IT(huart, (uint8_t *)&rx_data, 1);
24     }
25 }
26 void HAL_TIM_IC_CaptureCallback(TIM_HandleTypeDef *htim)
27 {
28     if(htim->Instance == TIM8)
29     {
30         if(htim->Channel == HAL_TIM_ACTIVE_CHANNEL_1)
31         {
32             PA15_rise = __HAL_TIM_GetCounter(htim);
33             __HAL_TIM_SetCounter(htim, 0);
34             PA15_freq = PA15_FREQ/PA15_rise;
35             PA15_duty = PA15_fall*100/PA15_rise;
36         }
37         else if(htim->Channel == HAL_TIM_ACTIVE_CHANNEL_2)
38         {
39             PA15_fall = __HAL_TIM_GetCounter(htim);
40         }
41     }
42
43     if(htim->Instance == TIM3)
44     {
45         if(htim->Channel == HAL_TIM_ACTIVE_CHANNEL_1)
46         {
47             PB4_rise = __HAL_TIM_GetCounter(htim);
48             __HAL_TIM_SetCounter(htim, 0);
49             PB4_freq = PB4_FREQ/PB4_rise;
50             PB4_duty = PB4_fall*100/PB4_rise;
51         }
52         else if(htim->Channel == HAL_TIM_ACTIVE_CHANNEL_2)
53         {
54             PB4_fall = __HAL_TIM_GetCounter(htim);
55         }
56     }
57 }
58 void HAL_TIM_PeriodElapsedCallback(TIM_HandleTypeDef *htim)
59 {
60     if(htim->Instance == TIM6)
61     {
62         key[0].value = HAL_GPIO_ReadPin(GPIOB, GPIO_PIN_0);
63         key[1].value = HAL_GPIO_ReadPin(GPIOB, GPIO_PIN_1);
64         key[2].value = HAL_GPIO_ReadPin(GPIOB, GPIO_PIN_2);
65         key[3].value = HAL_GPIO_ReadPin(GPIOA, GPIO_PIN_0);
66
67         for(int i=0; i<4; i++)
68         {
69             switch(key[i].state)
70             {
71                 case 0:

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```
72         if(key[i].value == 0) key[i].state = 1;
73         break;
74     case 1:
75         if(key[i].value == 0)
76         {
77             key[i].state = 2;
78             key[i].click_time = 0;
79         }
80         else key[i].state = 0;
81         break;
82     case 2:
83         if(key[i].value == 0)
84             key[i].click_time++;
85         else
86         {
87             if(key[i].click_time > 80)
88                 key[i].long_flag = 1;
89             else key[i].short_flag = 1;
90
91             key[i].state = 0;
92         }
93         break;
94     }
95 }
96 }
97 }
98 }
```