```
#include "interrupt.h'
 2
 3
     struct keys key [4] = \{0\};
 4
 5
     uchar rx arry[50];
 6
     uchar rx_data
 7
     uchar rx_pointer
 8
 9
      void HAL UART RxCpltCallback(UART HandleTypeDef *huart)
10
          if(huart->Instance == USART1)
11
12
13
              rx_arry[rx_pointer++]=rx_data;
14
              HAL_UART_Receive_IT(huart, (uint8_t *)&rx_data, 1);
15
16
      void HAL_TIM_PeriodElapsedCallback(TIM_HandleTypeDef *htim)
17
18
19
          if(htim->Instance == TIM6)
20
21
              \text{key}[0]. value =
                               HAL_GPIO_ReadPin (GPIOB, GPIO_PIN_0);
22
                               HAL GPIO ReadPin (GPIOB, GPIO PIN 1)
              key[1]. value
              key[2]. value
key[3]. value
23
                    ].value =
                               HAL GPIO ReadPin (GPIOB, GPIO PIN 2)
24
                               HAL_GPIO_ReadPin(GPIOA, GPIO_PIN_0)
25
26
27
28
                   switch(key[i].state)
29
30
31
                            if(key[i].value == 0) key[i].state = 1;
32
33
34
                            if(key[i].value == 0)
35
36
                                 key[i].state = 2;
37
                                key[i].click_time
38
39
                            else \text{ key[i]. state} = 0;
40
41
42
43
44
45
46
47
48
49
50
51
52
53
54
55
56
57
58
59
60
61
62
63
64
65
66
                            if(\text{key[i]. value} == 0)
67
                                 key[i].click_time++;
68
69
70
                                 if(key[i].click_time >70)
71
                                     key[i].long flag
```

```
72
73
74
75
                                               else key[i].short_flag =
                                               key[i].state = 0;
76
77
78
79
80
81
82
83
84
                                  key[i].double_time++;
if(key[i].double_time>30)
85
86
                                        key[i]. short_flag = 1;
key[i]. double_state = 0;
87
88
89
90
91
92
93
```