Yunxiang Zhang

RESEARCH INTERESTS

My current research revolves around virtual/augmented/mixed reality, human-computer interaction, and generative AI, with a focus on multimodal interface design and AI-assisted content creation for immersive applications. More broadly, I enjoy combining theoretical insights from physical, perceptual, and cognitive sciences with machine learning tools to solve challenging real-world problems.

EDUCATION

New York University New York City, USA

Doctor of Philosophy in Computer Science and Engineering Sep 2022 - Dec 2025 (expected)

Advisor: Prof. Oi Sun

The Chinese University of Hong Kong Hong Kong SAR, China

Master of Philosophy in Information Engineering Aug 2020 - Aug 2022

Thesis: Towards Physically Realistic Human-Environment Interaction in Virtual and Augmented Reality

Advisor: Prof. Dahua Lin

Shanghai Jiao Tong University Shanghai, China

Master of Engineering in Electronics and Communication Engineering Sep 2017 - Mar 2020

Thesis: Similarity-Based Approach to Neural Network Pruning

Advisor: Prof. Bingbing Ni

École Polytechnique Palaiseau, France

Diplôme d'Ingénieur in Computer Science (double-degree program between SJTU and EP) Apr 2016 - Aug 2018

Shanghai Jiao Tong University Shanghai, China

Bachelor of Engineering in Information Engineering Sep 2013 - Aug 2017

RESEARCH EXPERIENCE

Research Intern, Intel Graphics Research Bellevue, USA

Mentors: Dr. Alexandr Kuznetsov and Dr. Akshay Jindal May 2023 - Aug 2023

Research Intern, Vector Institute Toronto, Canada Mentor: Prof. Nicolas Papernot Mar 2020 - Jun 2020

Research Intern, LTCI Télécom Paris Paris, France

Mentors: Prof. Samy Blusseau, Prof. Santiago Velasco-Forero, Prof. Isabelle Bloch, and Prof. Jesús Angulo Apr 2018 - Aug 2018

PUBLICATIONS

· Accelerating Saccadic Response through Spatial and Temporal Cross-Modal Misalignments SIGGRAPH 2024

Daniel Jiménez Navarro, Xi Peng, Yunxiang Zhang, Karol Myszkowski, Hans-Peter Seidel, Qi Sun, Ana Serrano

· Mixed Reality Interface for Whole-Body Balancing and Manipulation of Humanoid Robot

International Conference on Ubiquitous Robots (UR 2024)

Hyunjong Song, Gabriel Bronfman, Yunxiang Zhang, Qi Sun, Joo H. Kim

· Toward Optimized VR/AR Ergonomics: Modeling and Predicting User Neck Muscle Contraction

SIGGRAPH 2023 Paper

Yunxiang Zhang, Kenneth Chen, Qi Sun

• Force-Aware Interface via Electromyography for Natural VR/AR Interaction

ACM Transactions on Graphics (SIGGRAPH Asia 2022) Paper

Yunxiang Zhang, Benjamin Liang, Boyuan Chen, Paul M. Torrens, S. Farokh Atashzar, Dahua Lin, Qi Sun

• CaPC Learning: Confidential and Private Collaborative Learning

International Conference on Learning Representations (ICLR 2021) Paper

Christopher A. Choquette-Choo*, Natalie Dullerud*, Adam Dziedzic*, Yunxiang Zhang*, Somesh Jha, Nicolas Papernot, Xiao Wang

· Exploiting Channel Similarity for Network Pruning

IEEE Transactions on Circuits and Systems for Video Technology (TCSVT 2023) Paper

Chenglong Zhao, Yunxiang Zhang, Bingbing Ni

• Max-plus Operators Applied to Filter Selection and Model Pruning in Neural Networks
International Symposium on Mathematical Morphology and Its Application to Signal and Image Processing (ISMM 2019) Paper
Yunxiang Zhang, Samy Blusseau, Santiago Velasco-Forero, Isabelle Bloch, Jesus Angulo

* Equal contributions, authors ordered alphabetically

AWARDS

New York UniversityDeborah Rosenthal MD Award (2024)New York UniversitySoE Fellowship (2022 – 2023)The Chinese University of Hong KongPostgraduate Scholarship (2020 – 2022)Shanghai Jiao Tong UniversitySPEIT Academic Excellence Scholarship (2015 – 2016)Shanghai Jiao Tong UniversityArdian Scholarship (2014 – 2015)

ACADEMIC SERVICES

Conference Reviewer: SIGGRAPH, SIGGRAPH Asia, TVCG, AAAI, IEEE VR, ISMAR

TEACHING EXPERIENCE

Teaching Assistant, Virtual and Augmented Reality (CS-GY 9223), New York University

2022 Fall

Teaching Assistant, Final Year Project (IERG 4998/4999), The Chinese University of Hong Kong

2020 – 2022

SKILLS

Programming: Python (primary), C#, C/C++
 Tools: PyTorch, TensorFlow, OpenGL, Libigl
 Software: Blender, Unity, Matlab, MeshLab
 Language: Mandarin, English, French