

A Banach spaces-based mixed-primal finite element method for the coupled Brinkman-Forchheimer and nonlinear transport equations*

FERNANDO A. ARTAZA[†] SERGIO CAUCAO[‡]
GABRIEL N. GATICA[§] BRAYAN R. SANDOVAL[¶]

Abstract

We propose and analyze a Banach spaces-based mixed-primal finite element method for the coupling of the Brinkman–Forchheimer equations with a nonlinear transport phenomenon

.....

Key words: Brinkman–Forchheimer equations, nonlinear transport, pseudostress-velocity formulation, fixed point theory, perturbed saddle-point, mixed finite elements

Mathematics subject classifications (2000): 65N30, 65N12, 65N15, 35Q79, 80A20, 76R05, 76D07

1 Introduction

Preliminary notations

Let $\Omega \subset \mathbb{R}^n$, $n \in \{2, 3\}$, be a bounded domain with polyhedral boundary Γ , and let \mathbf{n} be the outward unit normal vector on Γ . In what follows, standard notation is adopted for Lebesgue spaces $L^p(\Omega)$ and Sobolev spaces $W^{s,p}(\Omega)$, with $s \in \mathbb{R}$ and $p > 1$, whose corresponding norms, either for the scalar, vectorial, or tensorial case, are denoted by $\|\cdot\|_{0,p;\Omega}$ and $\|\cdot\|_{s,p;\Omega}$, respectively. In particular, given a non-negative integer m , $W^{m,2}(\Omega)$ is also denoted by $H^m(\Omega)$, and the notations of its norm and seminorm are simplified to $\|\cdot\|_{m,\Omega}$ and $|\cdot|_{m,\Omega}$, respectively. In addition, $H^{1/2}(\Gamma)$ is the space of traces of functions of $H^1(\Omega)$, and $H^{-1/2}(\Gamma)$ denotes its dual. On the other hand, given any generic scalar functional space S , we let \mathbf{S} and \mathbb{S} be the corresponding vectorial and tensorial counterparts, whereas $\|\cdot\|$, with no subscripts, will be employed for the norm of any element or operator whenever there is no confusion about the space to which they belong. Also, $|\cdot|$ denotes the Euclidean norm in both

*This research was supported by ANID-Chile through the projects CENTRO DE MODELAMIENTO MATEMÁTICO (FB210005), ANILLO OF COMPUTATIONAL MATHEMATICS FOR DESALINATION PROCESSES (ACT210087), and Fondecyt 11220393; by Grupo de Investigación en Análisis Numérico y Cálculo Científico (GIANuC²), Universidad Católica de la Santísima Concepción; and by Centro de Investigación en Ingeniería Matemática (CI²MA), Universidad de Concepción.

[†]CI²MA and Departamento de Ingeniería Matemática, Universidad de Concepción, Casilla 160-C, Concepción, Chile, email: fartaza2019@udec.cl.

[‡]GIANuC² and Departamento de Matemática y Física Aplicadas, Universidad Católica de la Santísima Concepción, Casilla 297, Concepción, Chile, email: scaucao@ucsc.cl.

[§]CI²MA and Departamento de Ingeniería Matemática, Universidad de Concepción, Casilla 160-C, Concepción, Chile, email: ggatica@ci2ma.udec.cl.

[¶]CI²MA and Departamento de Ingeniería Matemática, Universidad de Concepción, Casilla 160-C, Concepción, Chile, email: bsandoval2018@udec.cl.

\mathbb{R}^n and $\mathbb{R}^{n \times n}$, and as usual, \mathbb{I} stands for the identity tensor in $\mathbb{R}^{n \times n}$. In turn, for any vector fields $\mathbf{v} = (v_i)_{i=1,n}$ and $\mathbf{w} = (w_i)_{i=1,n}$, we set the gradient, divergence, and tensor product operators, as

$$\nabla \mathbf{v} := \left(\frac{\partial v_i}{\partial x_j} \right)_{i,j=1,n}, \quad \operatorname{div}(\mathbf{v}) := \sum_{j=1}^n \frac{\partial v_j}{\partial x_j}, \quad \text{and} \quad \mathbf{v} \otimes \mathbf{w} := (v_i w_j)_{i,j=1,n},$$

whereas for any tensor fields $\boldsymbol{\tau} = (\tau_{ij})_{i,j=1,n}$ and $\boldsymbol{\zeta} = (\zeta_{ij})_{i,j=1,n}$, we let $\mathbf{div}(\boldsymbol{\tau})$ be the divergence operator div acting along the rows of $\boldsymbol{\tau}$, and define the transpose, the trace, the deviatoric tensor, and the tensor inner product, respectively, as

$$\boldsymbol{\tau}^t := (\tau_{ji})_{i,j=1,n}, \quad \operatorname{tr}(\boldsymbol{\tau}) := \sum_{i=1}^n \tau_{ii}, \quad \boldsymbol{\tau}^d := \boldsymbol{\tau} - \frac{1}{n} \operatorname{tr}(\boldsymbol{\tau}) \mathbb{I}, \quad \text{and} \quad \boldsymbol{\tau} : \boldsymbol{\zeta} := \sum_{i,j=1}^n \tau_{ij} \zeta_{ij}.$$

Furthermore, for each $t \in [1, +\infty)$ we introduce the Banach space

$$\mathbb{H}(\mathbf{div}_t; \Omega) := \left\{ \boldsymbol{\tau} \in \mathbb{L}^2(\Omega) : \mathbf{div}(\boldsymbol{\tau}) \in \mathbf{L}^t(\Omega) \right\},$$

equipped with the natural norm

$$\|\boldsymbol{\tau}\|_{\mathbf{div}_t; \Omega} := \|\boldsymbol{\tau}\|_{0, \Omega} + \|\mathbf{div}(\boldsymbol{\tau})\|_{0, t; \Omega} \quad \forall \boldsymbol{\tau} \in \mathbb{H}(\mathbf{div}_t; \Omega).$$

Additionally, we recall that, proceeding as in [3, eq. (1.43), Section 1.3.4] (see also [1, Section 4.1] and [2, Section 3.1]), one can prove that for $t \in \begin{cases} (1, +\infty] \text{ in } \mathbb{R}^2, \\ [\frac{6}{5}, +\infty] \text{ in } \mathbb{R}^3, \end{cases}$ there holds

$$\langle \boldsymbol{\tau} \mathbf{n}, \mathbf{v} \rangle = \int_{\Omega} \left\{ \boldsymbol{\tau} : \nabla \mathbf{v} + \mathbf{v} \cdot \mathbf{div}(\boldsymbol{\tau}) \right\} \quad \forall (\boldsymbol{\tau}, \mathbf{v}) \in \mathbb{H}(\mathbf{div}_t; \Omega) \times \mathbf{H}^1(\Omega), \quad (1.1)$$

where $\langle \cdot, \cdot \rangle$ denotes in (1.1) the duality pairing between $\mathbf{H}^{-1/2}(\Gamma)$ and $\mathbf{H}^{1/2}(\Gamma)$.

2 The model problem

We consider a porous medium occupying the region Ω , and assume that a viscous fluid governed by the Brinkman-Forchheimer equations flows through it, so that the sought variables are its pressure p and velocity \mathbf{u} . In addition, we let ϕ be the concentration of a chemical component transported by the fluid, which is advected and diffused in Ω according to the corresponding physical principle. Alternatively, ϕ could represent the temperature of the fluid, among several other possibilities. In this way, the coupled model of interest is given by the following system of partial differential equations:

$$\begin{aligned} -\mu \Delta \mathbf{u} + \mathbf{D} \mathbf{u} + \mathbf{F} |\mathbf{u}|^{\rho-2} \mathbf{u} + \nabla p &= \phi \mathbf{f} & \text{in } \Omega, \\ \operatorname{div}(\mathbf{u}) &= 0 & \text{in } \Omega, \\ \operatorname{div}(\vartheta(|\nabla \phi|) \nabla \phi - \phi \mathbf{u} - f(\phi) \mathbf{g}) &= g & \text{in } \Omega, \\ \mathbf{u} = \mathbf{u}_D \quad \text{and} \quad \phi &= \phi_D & \text{on } \Gamma, \end{aligned} \quad (2.1)$$

where μ is the constant viscosity of the fluid, $\mathbf{D}, \mathbf{F} > 0$ are the Darcy and Forchheimer coefficients, respectively, ρ is a given number in $[3, 4]$, $\vartheta : \mathbb{R}^+ \rightarrow \mathbb{R}^+$ is a nonlinear diffusivity function, f is a nonlinear flux acting in the direction of \mathbf{g} , which, in turn, is a constant vector pointing in the

direction of gravity, \mathbf{f} and g are given source functions, and \mathbf{u}_D and ϕ_D are Dirichlet data for \mathbf{u} and ϕ , respectively. Regarding ϑ , we assume that there exist constants $\vartheta_1, \vartheta_2 > 0$ such that

$$\vartheta_1 \leq \vartheta(t) \leq \vartheta_2 \quad \text{and} \quad \vartheta_1 \leq \vartheta(t) + t \vartheta'(t) \leq \vartheta_2 \quad \forall t \in \mathbb{R}^+. \quad (2.2)$$

In addition, f is required to be bounded and Lipschitz-continuous, which means that there exist constants $f_1, f_2, L_f > 0$ such that

$$f_1 \leq f(t) \leq f_2 \quad \text{and} \quad |f(t) - f(s)| \leq L_f |s - t| \quad \forall s, t \in \mathbb{R}^+. \quad (2.3)$$

Now, due to the incompressibility of the fluid (cf. second row of (2.1)), \mathbf{u}_D must formally satisfy the compatibility condition

$$\int_{\Gamma} \mathbf{u}_D \cdot \mathbf{n} = 0. \quad (2.4)$$

On the other hand, for the uniqueness of p we look for this unknown in the space

$$L_0^2(\Omega) := \left\{ q \in L^2(\Omega) : \int_{\Omega} q = 0 \right\}.$$

Next, in order to derive a mixed-primal formulation for (2.1), we first define as an auxiliary unknown the fluid pseudostress

$$\boldsymbol{\sigma} := \mu \nabla \mathbf{u} - p \mathbb{I}, \quad (2.5)$$

so that the first row of (2.1) becomes

$$-\mathbf{div}(\boldsymbol{\sigma}) + \mathbb{D} \mathbf{u} + \mathbf{F} |\mathbf{u}|^{\rho-2} \mathbf{u} = \phi \mathbf{f}. \quad (2.6)$$

Thus, taking matrix trace along with the fact that $\text{tr}(\nabla \mathbf{u}) = \text{div}(\mathbf{u}) = 0$, and then applying the deviatoric operator, we deduce from (2.5) that

$$p = -\frac{1}{n} \text{tr}(\boldsymbol{\sigma}) \quad \text{and} \quad \frac{1}{\mu} \boldsymbol{\sigma}^d = \nabla \mathbf{u}, \quad (2.7)$$

which are equivalent to the pair of equations formed by the incompressibility condition and (2.5). Hence, eliminating the unknown p , and computing it afterwards according to the identity provided in (2.7), the original system (2.1) can be stated, equivalently, as: Find $\boldsymbol{\sigma}$, \mathbf{u} , and ϕ in suitable spaces to be indicated below, such that

$$\begin{aligned} \frac{1}{\mu} \boldsymbol{\sigma}^d &= \nabla \mathbf{u} && \text{in } \Omega, \\ -\mathbf{div}(\boldsymbol{\sigma}) + \mathbb{D} \mathbf{u} + \mathbf{F} |\mathbf{u}|^{\rho-2} \mathbf{u} &= \phi \mathbf{f} && \text{in } \Omega, \\ \text{div}(\vartheta(|\nabla \phi|) \nabla \phi - \phi \mathbf{u} - f(\phi) \mathbf{g}) &= g && \text{in } \Omega, \\ \mathbf{u} = \mathbf{u}_D \quad \text{and} \quad \phi &= \phi_D && \text{on } \Gamma, \\ \int_{\Omega} \text{tr}(\boldsymbol{\sigma}) &= 0. \end{aligned} \quad (2.8)$$

3 The variational formulation

Find $(\boldsymbol{\sigma}, \mathbf{u}) \in \mathbf{H} \times \mathbf{Q}$ and $(\phi, \xi) \in \mathbf{X} \times \mathbf{Y}$ such that

$$\begin{aligned} \mathbf{a}(\boldsymbol{\sigma}, \boldsymbol{\tau}) + \mathbf{b}(\boldsymbol{\tau}, \mathbf{u}) &= \mathbf{F}(\boldsymbol{\tau}) & \forall \boldsymbol{\tau} \in \mathbf{H}, \\ \mathbf{b}(\boldsymbol{\sigma}, \mathbf{v}) - \mathbf{c}_{\mathbf{u}}(\mathbf{u}, \mathbf{v}) &= \mathbf{G}_{\phi}(\mathbf{v}) & \forall \mathbf{v} \in \mathbf{Q}, \\ [\mathbf{A}_{\mathbf{u}}(\phi), \varphi] + \mathbf{B}(\varphi, \xi) &= \mathbf{F}_{\phi}(\varphi) & \forall \varphi \in \mathbf{X}, \\ \mathbf{B}(\phi, \eta) &= \mathbf{G}(\eta) & \forall \eta \in \mathbf{Y}, \end{aligned} \quad (3.1)$$

where the bilinear forms $\mathbf{a} : \mathbf{H} \times \mathbf{H} \rightarrow \mathbb{R}$, $\mathbf{b} : \mathbf{H} \times \mathbf{Q} \rightarrow \mathbb{R}$, and $\mathbf{c}_{\mathbf{z}} : \mathbf{Q} \times \mathbf{Q} \rightarrow \mathbb{R}$, and the nonlinear operator $\mathbf{A}_{\mathbf{z}} : \mathbf{X} \rightarrow \mathbf{X}'$, for each $\mathbf{z} \in \mathbf{Q}$, and the bilinear form $\mathbf{B} : \mathbf{X} \times \mathbf{Y} \rightarrow \mathbb{R}$, and the linear functionals $\mathbf{F} : \mathbf{H} \rightarrow \mathbb{R}$, $\mathbf{G}_{\psi} : \mathbf{Q} \rightarrow \mathbb{R}$ and $\mathbf{F}_{\psi} : \mathbf{X} \rightarrow \mathbb{R}$, for each $\psi \in \mathbf{X}$, and $\mathbf{G} : \mathbf{Y} \rightarrow \mathbb{R}$, are defined as

$$\mathbf{a}(\boldsymbol{\zeta}, \boldsymbol{\tau}) := \frac{1}{\mu} \int_{\Omega} \boldsymbol{\zeta}^{\mathbf{d}} : \boldsymbol{\tau}^{\mathbf{d}} \quad \forall \boldsymbol{\zeta}, \boldsymbol{\tau} \in \mathbf{H}, \quad (3.2)$$

$$\mathbf{b}(\boldsymbol{\tau}, \mathbf{v}) := \int_{\Omega} \mathbf{v} \cdot \operatorname{div}(\boldsymbol{\tau}) \quad \forall (\boldsymbol{\tau}, \mathbf{v}) \in \mathbf{H} \times \mathbf{Q}, \quad (3.3)$$

$$\mathbf{c}_{\mathbf{z}}(\mathbf{w}, \mathbf{v}) := \mathbf{D} \int_{\Omega} \mathbf{w} \cdot \mathbf{v} + \mathbf{F} \int_{\Omega} |\mathbf{z}|^{\rho-2} \mathbf{w} \cdot \mathbf{v} \quad \forall \mathbf{w}, \mathbf{v} \in \mathbf{Q}, \quad (3.4)$$

$$[\mathbf{A}_{\mathbf{z}}(\psi), \varphi] := \int_{\Omega} \vartheta(|\nabla \psi|) \nabla \psi \cdot \nabla \varphi - \int_{\Omega} \psi \mathbf{z} \cdot \nabla \varphi \quad \forall \psi, \varphi \in \mathbf{X}, \quad (3.5)$$

$$\mathbf{B}(\varphi, \eta) := \langle \eta, \varphi \rangle \quad \forall (\varphi, \eta) \in \mathbf{X} \times \mathbf{Y}, \quad (3.6)$$

$$\mathbf{F}(\boldsymbol{\tau}) := \langle \boldsymbol{\tau} \mathbf{n}, \mathbf{u}_{\mathbf{D}} \rangle \quad \forall \boldsymbol{\tau} \in \mathbf{H}, \quad (3.7)$$

$$\mathbf{G}_{\psi}(\mathbf{v}) := - \int_{\Omega} \psi \mathbf{f} \cdot \mathbf{v} \quad \forall \mathbf{v} \in \mathbf{Q}, \quad (3.8)$$

$$\mathbf{F}_{\psi}(\varphi) := \int_{\Omega} f(\psi) \mathbf{g} \cdot \nabla \varphi - \int_{\Omega} g \varphi \quad \forall \varphi \in \mathbf{X}, \quad (3.9)$$

and

$$\mathbf{G}(\eta) := \langle \eta, \phi_{\mathbf{D}} \rangle \quad \forall \eta \in \mathbf{Y}. \quad (3.10)$$

Note here that $[\cdot, \cdot]$ represents the duality pairing between \mathbf{X}' and \mathbf{X} . In turn, in the definitions of \mathbf{B} (cf. (3.6)) and \mathbf{G} (cf. (3.10)), $\langle \cdot, \cdot \rangle$ stands for the duality pairing between $\mathbf{H}^{-1/2}(\Gamma)$ and $\mathbf{H}^{1/2}(\Gamma)$, whereas in the definition of \mathbf{F} (cf. (3.7)) $\langle \cdot, \cdot \rangle$ denotes the duality pairing between $\mathbf{H}^{-1/2}(\Gamma)$ and $\mathbf{H}^{1/2}(\Gamma)$.

4 The Galerkin scheme

5 A priori error analysis

6 Numerical results

References

- [1] J. CAMAÑO, C. MUÑOZ AND R. OYARZÚA, *Numerical analysis of a dual-mixed problem in non-standard Banach spaces*. Electron. Trans. Numer. Anal. 48 (2018), 114–130.

- [2] E. COLMENARES, G.N. GATICA AND S. MORAGA, *A Banach spaces-based analysis of a new fully-mixed finite element method for the Boussinesq problem*. ESAIM Math. Model. Numer. Anal. 54 (2020), no. 5, 1525–1568.
- [3] G.N. GATICA, *A Simple Introduction to the Mixed Finite Element Method. Theory and Applications*. SpringerBriefs in Mathematics. Springer, Cham, 2014.