

Stopping problems with an unknown state

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Outline

- 1 Introduction and problem formulation
- 2 Reformulation: filtering theory
- 3 Examples
- 4 Future work

Motivation: a simple hiring game

- Two companies interview a candidate and observe respectively:

$$X_t^1 = \theta t + W_t^1,$$

$$X_t^2 = \theta t + W_t^2,$$

where W^1, W^2 independent.

- θ is the “true” ability level. e.g., $\theta \in \{1, -1\}$, “strong/weak” candidate.
- At any time, the companies can choose to stop the interview process and hire the candidate.
- When hired, the company gain θ .

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Motivation: a hiring game

- Problem: there is only one candidate - competition in the hiring market.
- Companies must act before their competitor:

$$J_1 = \mathbb{E}[\theta \mathbf{1}_{\tau_1 \leq \tau_2}],$$

$$J_2 = \mathbb{E}[\theta \mathbf{1}_{\tau_2 < \tau_1}].$$

- Companies also observe the **inaction** of the competitor.
- Want to preempt each other, but the inaction of the competitor also affects their belief.
- Opportunities to stop would disappear, the rate depends on the state θ .

This game is difficult to solve. However, it motivates us to consider problems with **state-dependent random horizon**.

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Problem formulation

The ingredients of our problem:

- Consider Bernoulli random variable θ

$$\mathbb{P}_\pi(\theta = 1) = \pi = 1 - \mathbb{P}_\pi(\theta = 0),$$

and Brownian motion W independent of θ .

- Let random time γ depend on θ , and be independent of W :

$$\mathbb{P}_\pi(\gamma > t | \theta = i) = F_i(t), \quad i = 0, 1,$$

where F_i continuous, non-increasing, $F_i(0) = 1$.

- Let the underlying X be a diffusion that depend on θ :

$$dX_t = \mu(X_t, \theta)dt + \sigma(X_t)dW_t,$$

and denote $\mu_i(x) = \mu(x, i)$.

- Let the payoff $g, h: [0, \infty) \times \mathbb{R} \times \{0, 1\}$ depend on θ , and denote $g_i(t, x) := g(t, x, i)$ and $h_i(t, x) := h(t, x, i)$.

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Problem formulation

- We consider the following problem:

$$V = \sup_{\tau \in \mathcal{T}^{X,\gamma}} \mathbb{E}_\pi \left[g(\tau, X_\tau, \theta) 1_{\{\tau < \gamma\}} + h(\gamma, X_\gamma, \theta) 1_{\{\tau \geq \gamma\}} \right]. \quad (1)$$

- $\mathcal{T}^{X,\gamma}$: generated by X and $1_{\cdot \geq \gamma}$,
- $\mathcal{T}^{X,\gamma}$: the set of $\mathcal{T}^{X,\gamma}$ -stopping time.

- Note that

- $g(t, x, \theta) = g(t, \theta)$, $h(t, x, \theta) = h(t, \theta)$: statistical problems,
 X serves as an observation process
- $g(t, x, \theta) = g(t, x)$, $h(t, x, \theta) = h(t, x)$: financial problems,
 θ implicitly affect the payoff through X

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Incomplete to complete information

- Observe that:

$$\hat{V} = \sup_{\tau \in \mathcal{T}^X} \mathbb{E}_\pi \left[g(\tau, X_\tau, \theta) 1_{\{\tau < \gamma\}} + h(\gamma, X_\gamma, \theta) 1_{\{\tau \geq \gamma\}} \right] = V. \quad (2)$$

- Define the conditional probability process:

$$\Pi_t := \mathbb{P}_\pi(\theta = 1 | \mathcal{F}_t^X)$$

Proposition

We have

$$\begin{aligned} V = \sup_{\tau \in \mathcal{T}^X} \mathbb{E}_\pi & \left[g_0(\tau, X_\tau)(1 - \Pi_\tau)F_0(\tau) + g_1(\tau, X_\tau)\Pi_\tau F_1(\tau) \right. \\ & \left. - \int_0^\tau h_0(t, X_t)(1 - \Pi_t)dF_0(t) - \int_0^\tau h_1(t, X_t)\Pi_t dF_1(t) \right]. \end{aligned} \quad (3)$$

Moreover, if $\tau \in \mathcal{T}^X$ is optimal in (2), then it is also optimal in (1).

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- The pair (X, Π) satisfies:

$$\begin{cases} dX_t = (\mu_0(X_t) + (\mu_1(X_t) - \mu_0(X_t))\Pi_t) dt + \sigma(X_t) d\hat{W}_t \\ d\Pi_t = \omega(X_t)\Pi_t(1 - \Pi_t) d\hat{W}_t, \end{cases}$$

where $\omega(x) = (\mu_1(x) - \mu_0(x))/\sigma(x)$.

- The process

$$\hat{W}_t := \int_0^t \frac{dX_s}{\sigma(X_s)} - \int_0^t \frac{1}{\sigma(X_s)} (\mu_0(X_s) + (\mu_1(X_s) - \mu_0(X_s))\Pi_s) ds$$

is the innovation process (a \mathbb{P}_π -Brownian motion).

- The process $\Phi := \frac{\Pi_t}{1 - \Pi_t}$ satisfies

$$d\Phi_t = \omega(X_t)\Phi_t(\omega(X_t)\Pi_t dt + d\hat{W}_t) \quad (4)$$

with initial condition $\Phi_0 = \varphi := \pi/(1 - \pi)$.

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A measure change

Lemma

For any $t \geq 0$, denote by $\mathbb{P}_{\pi,t}$ the measure \mathbb{P}_{π} restricted to \mathcal{F}_t , $\pi \in [0, 1]$. We then have

$$\frac{d\mathbb{P}_{0,t}}{d\mathbb{P}_{\pi,t}} = \frac{1 + \varphi}{1 + \Phi_t}.$$

- Under \mathbb{P}_0 , (X, Φ) satisfies

$$\begin{cases} dX_t = \mu_0(X_t) dt + \sigma(X_t) dW_t \\ d\Phi_t = \omega(X_t)\Phi_t dW_t \end{cases} \quad (5)$$

- Introduce the process

$$\Phi_t^\circ := \frac{F_1(t)}{F_0(t)} \Phi_t, \quad (6)$$

the likelihood process on $\{\gamma > t\}$.

- Φ_t° satisfies

$$d\Phi_t^\circ = \frac{1}{f(t)} \Phi_t^\circ df(t) + \omega(X_t)\Phi_t^\circ dW_t, \quad \Phi_0^\circ = \varphi$$

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A measure change

Theorem

Denote by

$$v = \sup_{\tau \in \mathcal{T}^X} \mathbb{E}_0 \left[F_0(\tau) (g_0(\tau, X_\tau) + g_1(\tau, X_\tau) \Phi_\tau^\circ) - \int_0^\tau h_0(t, X_t) dF_0(t) - \int_0^\tau \frac{F_0(t)}{F_1(t)} h_1(t, X_t) \Phi_t^\circ dF_1(t) \right], \quad (7)$$

where (X, Φ°) is given by (5) and (6). Then $V = v/(1 + \varphi)$, where $\varphi = \pi/(1 - \pi)$. Moreover, if $\tau \in \mathcal{T}^X$ is an optimal stopping in (7), then it is also optimal in the original problem (1).

The embedding: $v = v(t, x, \varphi)$.

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Three motivating examples

- We give 3 examples in one-dimension,
- that reduces to problems only Φ° -dependent,
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- Hire a person, strong/weak:

$$X_t = \mu(\theta)t + \sigma W_t$$

with $\mu(0) < \mu(1)$.

- Benefit of hiring:

$$g(t, x, \theta) = \begin{cases} -e^{-rt}c & \text{if } \theta = 0 \\ e^{-rt}d & \text{if } \theta = 1 \end{cases}$$

- Survival probabilities: exponential, with $\lambda_0 < \lambda_1$.
- The stopping problem:

$$V = \sup_{\tau \in \mathcal{T}^{X,Y}} \mathbb{E}_\pi \left[e^{-r\tau} \left(d1_{\{\theta=1\}} - c1_{\{\theta=0\}} \right) 1_{\{\tau < \gamma\}} \right].$$

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2. Closing a short position under recall risk

- Consider a short position in

$$dX_t = \mu(\theta)X_t dt + \sigma X_t dW_t$$

with $\mu(0) < \mu(1)$.

- The random horizon corresponds to a time when the position is recalled: $\lambda_0 > 0 = \lambda_1$.
- The payoffs are $g(t, x, \theta) = h(t, x, \theta) = xe^{-rt}$, and

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$$V = \frac{1}{1+\varphi} \inf_{\tau \in \mathcal{T}^X} \mathbb{E}^0 \left[e^{-r\tau} F_0(\tau) X_\tau (1 + \Phi_\tau^\circ) + \lambda_0 \int_0^\tau e^{-rt} F_0(t) X_t (1 + \Phi_t^\circ) dt \right].$$

- Another change of measure to get rid of X :

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- Let $X_t = \theta t + \sigma W_t$.
- Consider a sequential testing problem of minimising

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with random horizon.

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- 3 Examples
- 4 Future work

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 - Identify examples that are study-able.
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Thank you!

Our paper: Ekström and Wang, “*Stopping problems with an unknown state*”. J. Appl. Probab (2024)