## Assignment 3

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## 1 Exercise 3.25 (last question)

- Q: The **heuristic path algorithm** (Pohl, 1977) is a best-first search in which the evaluation function is f(n) = (2 w)g(n) + wh(n). What kind of search does this perform for w = 0, w = 1, and w = 2?
- A: w = 0: Uniform Cost Search
  - w = 1: A\* Search
  - w = 2: Greedy Best First Search

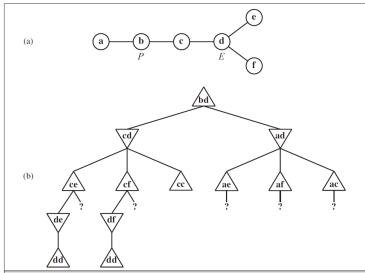
## 2 Exercise 4.1: (a) and (d)

- Q: Give the name of the algorithm that results from each of the following special cases:
  - a. Local beam search with k = 1.
  - d. Simulated annealing with  $T = \infty$  at all times.
- A: a. Hill climbing search.
  - d. Random walk

## 3 Exercise 5.3: (a), (b), and (c)

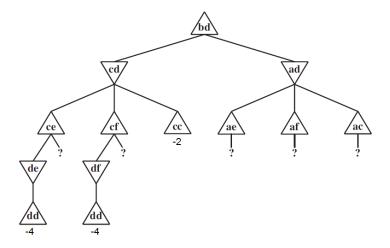
- Q: Imagine that, in Exercise 3.3, one of the friends wants to avoid the other. The problem then becomes a two-player **pursuit-evasion** game. We assume now that the players take turns moving. The game ends only when the players are on the same node; the terminal payoff to the pursuer is minus the total time taken. (The evader "wins" by never losing.) An example is shown in Figure 5.16.
  - a. Copy the game tree and mark the values of the terminal nodes.

- b. Next to each internal node, write the strongest fact you can infer about its value (a number, one or more inequalities such as " $\geq$  14", or a "?").
- c. Beneath each question mark, write the name of the node reached by that branch.

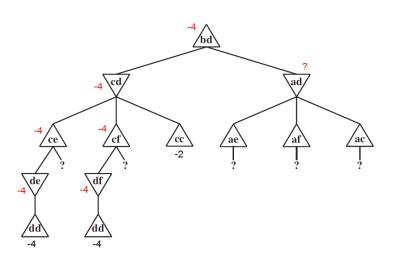


**Figure 5.16** (a) A map where the cost of every edge is 1. Initially the pursuer P is at node  $\mathbf{b}$  and the evader E is at node  $\mathbf{d}$ . (b) A partial game tree for this map. Each node is labeled with the P, E positions. P moves first. Branches marked "?" have yet to be explored.

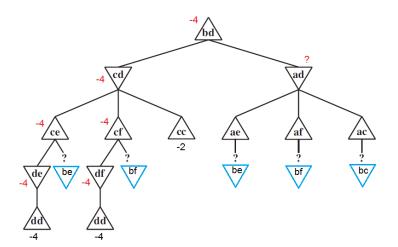
A:



a.



b.



c.