Yuriy Zacchia Lun, Ph.D.

Curriculum Vitae et Studiorum





Education

- Ph.D. Comput. sci., Gran Sasso Science Institute (GSSI) / IMT Lucca (joint program).

 Diss. title: Stability and optimal control of polytopic time-inhomogeneous Markov jump linear systems.
- M.Sc. Telecom. Eng., University of L'Aquila. Final score: 110/110.

 Diss. title: Algorithm for refinement of telecommunication network infrastructure localization.
- 2008 **B.Sc. Telecom. Eng., University of L'Aquila**. Final score: 110/110.

Employment History

- Since 2018 Research collaborator, SysMA research unit, IMT School for Advanced Studies Lucca.

 Projects: Industrial cybersecurity SINCERA; Cyber range scenario design and management; Methodologies and tools for data network security.
- 2017 2018 Research collaborator, University of L'Aquila, and Center of Excellence DEWS. Project: Formal verification for security in cyber-physical systems.
 - 2013 Industrial R&D **Assistant Researcher**, WEST Aquila S.r.l.
- 2012 2013 ICT Training **Analyst**, CONSEL ELIS Consortium.

 Activities: Design of the vocational master on "Development of applications and services in the cloud" and teaching of the "Administration of salesforce.com" course.

The Position of the Position

2017/02 - 2017/07

Visiting Ph.D. student within ERASMUS+ for Traineeship programme, OXCAV group, Department of Computer Science, University of Oxford.

Q Awards

Best work in progress paper award, 15th IEEE International Workshop on Factory Communication Systems (WFCS).

X Skills

- - Coding Strong proficiency with MATLAB and LATEX.

Professional Associations

IEEE Member since 2016.

Professional Activities

Technical **reviewer** for several international journals and conferences, including ACM TCPS, Elsevier Automatica, Nonlinear Analysis: Hybrid Syst., and European J. Control, IEEE TAC, L-CSS, and CDC.

2019 Co-chair of a regular session at the 18th European Control Conference (FrC5: Sliding and Switched Control).

Co-chair of a regular session at the 20th IFAC World Congress (MoP24: Stability and Stabilization of Hybrid Systems).

Research Interests

Automatic control of wireless networked control systems, communication, computation, and control co-design, stochastic hybrid systems, formal methods and security in cyber-physical domain.

Research Publications

Journal Articles

- **Zacchia Lun**, Y., D'Innocenzo, A., & Di Benedetto, M. D. (2019). Robust stability of polytopic time-inhomogeneous Markov jump linear systems. *Automatica*, 105, 286–297.

 Odoi:10.1016/j.automatica.2019.03.031
- **Zacchia Lun**, Y., D'Innocenzo, A., Smarra, F., Malavolta, I., & Di Benedetto, M. D. (2019). State of the art of cyber-physical systems security: An automatic control perspective. *Journal of Systems and Software*, 149, 174–216. Odi:10.1016/j.jss.2018.12.006

Conference Proceedings

- Florenzan Reyes, L. F., Smarra, F., **Zacchia Lun**, Y., & D'Innocenzo, A. (2021). Learning Markov models of fading channels in wireless control networks: a regression trees based approach. In *Proceedings of the 20th Mediterranean Conference on Control and Automation (MED)* (pp. 232–237). IEEE. Ø doi:10.1109/MED51440.2021.9480310
- Impicciatore, A., **Zacchia Lun**, Y., Pepe, P., & D'Innocenzo, A. (2021). Optimal output-feedback control and separation principle for Markov jump linear systems modeling wireless networked control scenarios. In *Proceedings of the 2021 American Control Conference (ACC)* (pp. 2700–2706). IEEE. Ø doi:10.23919/ACC50511.2021.9482674
- Zacchia Lun, Y., Rinaldi, C., Alrish, A., D'Innocenzo, A., & Santucci, F. (2020). On the impact of accurate radio link modeling on the performance of WirelessHART control networks. In *Proceedings of the 2020 IEEE Conference on Computer Communications (INFOCOM)* (pp. 2430–2439). IEEE.
 doi:10.1109/INFOCOM41043.2020.9155285
- **Zacchia Lun**, Y., & D'Innocenzo, A. (2019). Stabilizability of Markov jump linear systems modeling wireless networked control scenarios. In *Proceedings of the 58th IEEE Conference on Decision and Control* (CDC) (pp. 5766–5772). IEEE. doi:10.1109/CDC40024.2019.9029202
- **Zacchia Lun**, Y., Abate, A., & D'Innocenzo, A. (2019). Linear quadratic regulation of polytopic time-inhomogeneous Markov jump linear systems. In *Proceedings of the 17th European Control Conference (ECC)* (pp. 4094–4099). IEEE. doi:10.23919/ECC.2019.8796279
- Alrish, A., **Zacchia Lun**, Y., D'Innocenzo, A., & Santucci, F. (2019). Work in Progress: Systematic Derivation of Accurate Analytic Markov Channel Models for Industrial Control. In *Proceedings of the 15th IEEE International Workshop on Factory Communication Systems (WFCS)* (pp. 1–4). IEEE. Ø doi:10.1109/WFCS.2019.8757917

- **Zacchia Lun**, Y., Wheatley, J., D'Innocenzo, A., & Abate, A. (2018). Approximate abstractions of Markov chains with interval decision processes. In *Proceedings of the 6th IFAC Conference on Analysis and Design of Hybrid Systems (ADHS): IFAC-PapersOnLine* (51) 16 (pp. 91–96). Elsevier. Ø doi:10.1016/j.ifacol.2018.08.016
- **Zacchia Lun**, Y., D'Innocenzo, A., & Di Benedetto, M. D. (2017a). Robust LQR for time-inhomogeneous Markov jump switched linear systems. In *Proceedings of the 20th IFAC World Congress: IFAC-PapersOnLine* (50) 1 (pp. 2199–2204). Elsevier. Ø doi:10.1016/j.ifacol.2017.08.281

- **Zacchia Lun**, Y., Tennina, S., Di Renzo, M., Graziosi, F., & Verikoukist, C. (2013). WSN-Aided People Localization: A Ray Tracing Network Planning and Performance Analysis Tool. In *Proceedings of the 11th ACM Conference on Embedded Networked Sensor Systems (SenSys)* (Article 36). ACM. Ø doi:10.1145/2517351.2517406
- Tennina, S., Kartsakli, E., Lalos, A., Antonopoulos, A., Mekikis, P.-V., Di Renzo, M., ... Verikoukis, C. (2013). WSN4QoL: Wireless Sensor Networks for quality of life. In *Proceedings of the 15th IEEE International Conference on e-Health Networking, Applications and Services (HealthCom)* (pp. 277–279). IEEE. Odoi:10.1109/HealthCom. 2013.6720683

Personal Characteristics

Flexibility and adaptability, breadth of interest, ambition, curiosity and enthusiasm, ability to organize and regulate the work, with a flair for problem solving and goal-oriented work.

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I hereby declare that the above written particulars are true to the best of my knowledge and belief.