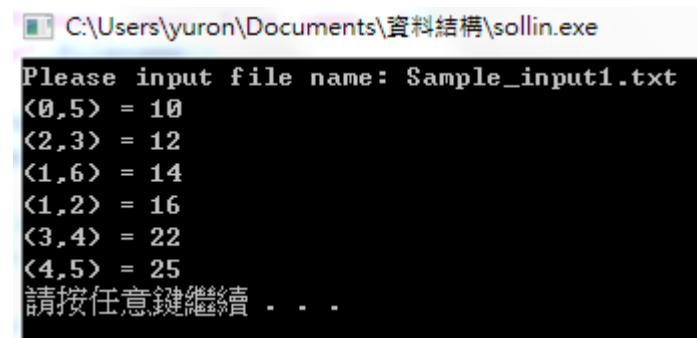


開發平台：Windows7

開發環境：DEV-C++4.9.9.2

sollin 程式功能：

輸入檔案名稱〈含副檔名〉，印出 minimum spanning tree



```
C:\Users\yuron\Documents\資料結構\sollin.exe
Please input file name: Sample_input1.txt
<0,5> = 10
<2,3> = 12
<1,6> = 14
<1,2> = 16
<3,4> = 22
<4,5> = 25
請按任意鍵繼續 . . .
```

sollin 程式架構：

```
typedef struct{           //use to record a edge
    int endpoint1;        //one endpoint of edge
    int endpoint2;        //another endpoint of edge
    int weight;           //weight of edge
}EDGE;
```

}EDGE;

EDGE Find_min_cost_edge() :

```
EDGE Find_min_cost_edge(int **graph,int vertex,int **MST,int *flag,int cur_vertex)
{
    EDGE min;
    int i,next_vertex[vertex],front = 0,rear = 0;

    next_vertex[0] = -1;           //Queue to store set member
    min.weight = INT_MAX;
    while( cur_vertex != -1 )      //search the set for min. cost edge
    {
        for(i = 0 ; i < vertex ; i++) //search min. cost edge for current vertex in graph
            if( graph[cur_vertex][i] && (graph[cur_vertex][i] < min.weight) )
            {
                min.weight = graph[cur_vertex][i];           //min is used to record the smallest cost edge
                min.endpoint1 = cur_vertex;
                min.endpoint2 = i;
            }
        for(i = 0 ; i < vertex ; i++) // find other vertices in set
        {
            if( MST[cur_vertex][i] && !flag[i])
            {
                next_vertex[rear] = i;
                next_vertex[++rear] = -1;
            }
        }
        flag[cur_vertex] = 1;
        cur_vertex = next_vertex[front++]; //move to next vertex in set until no vertex in set
    }
    return min;
}
```

void Sollin_MST() :

```
void Sollin_MST(int **graph,int vertex,int **MST)
{
    int n = 0,i,j;
    int flag[vertex];
    EDGE temp;

    for(i = 0 ; i < vertex ; i++) flag[i] = 0; //initializing flag
    while(n < vertex-1)
    {
        for(i = 0 ; i < vertex ; i++) //each stage start
        {
            if(flag[i]) continue; //searched vertices will be ignored
            temp = Find_min_cost_edge(graph,vertex,MST,flag,i);
            MST[temp.endpoint1][temp.endpoint2] = temp.weight; //store min. cost edge of a tree to minimum spanning tree
        }
        for(i = 0 ; i < vertex ; i++) //reset flag for next stage and eliminate picked edge from graph
        {
            flag[i] = 0; //reset
            for(j = i ; j < vertex ; j++)
            {
                if(MST[i][j] || MST[j][i]) //adjacency matrix of undirected graph is symmetric
                { //store non-zero value to another side
                    (MST[i][j] != 0) ? (MST[j][i] = MST[i][j]) : (MST[i][j] = MST[j][i]);
                    graph[i][j] = graph[j][i] = 0; //eliminate
                    n++;
                }
            }
        }
    }
}
```

void List_MST_edge()：儲存 minimum spanning tree 的所有邊，並且由小到大排

序〈使用 insertion sort〉，最後印出結果。

aoe_network 程式功能：

輸入檔案名稱〈含副檔名〉，印出邊的 early time, late time, critical activities 和

critical path

```
C:\Users\yuron\Documents\資料結構\aoe_network.exe
Please input file name: a.txt
activity      early time    late time     slack
<0,1> :       0         0         0
<0,2> :       0         2         2
<0,3> :       0         3         3
<1,4> :       6         6         0
<2,4> :       4         6         2
<3,5> :       5         8         3
<4,6> :       7         7         0
<4,7> :       7         7         0
<5,7> :       7        10         3
<6,8> :      16        16         0
<7,8> :      14        14         0
critical path:
<0,1>
<1,4>
<4,6>,<4,7>
<7,8>
<6,8>
```

aoe_network 程式架構：

```
void AOE() :
```

```

void AOE(int **graph,int *count,int vertex)           //count record the number of predecessors
{
    int i,j,k,early[vertex],late[vertex];
    int e,l,slack,flag;

    modified_TopoSort(graph,count,early,vertex);      //calculate earliest start time by modified_TopoSort

    for(i = 0 ; i < vertex ; i++) late[i] = early[vertex-1]; //initialize latest time for vertex to finished time
    for(i = vertex -2 ; i >= 0; i--)                    //calculate latest time with inverse order of top. sort(count
        for(j = 0 ; j < vertex ; j++)
            if( graph[count[i]][j] && (late[count[i]] > late[j] - graph[count[i]][j]))
                late[count[i]] = late[j] - graph[count[i]][j];

    printf("activity\tearly time\tlate time\tslack\n");
    for(i = 0 ; i < vertex ; i++)
        for(j = 0 ; j < vertex ; j++)                //calculate early and late of activities(edges)
            if( graph[i][j])
            {
                e = early[i];
                l = late[j] - graph[i][j];
                slack = l - e;
                printf("( %d,%d)\t: \t %d\t\t %d\t\t %d\n",i,j,e,l,slack);
                if(slack) graph[i][j] = 0;              //delete noncritical activities
            }

    printf("critical path:\n");
    for(i = 0 ; i < vertex ; i++)                      //print all critical paths

```

```
void modified_TopoSort() :
```

```
void modified_TopoSort(int **graph,int *count,int *early,int vertex)
{
    int i,j,k,top = -1,order = 0;
    int temp[vertex];

    for(i = 0 ; i < vertex ; i++)           //push starting vertex to stack
        if( !count[i])
        {
            count[i] = top;
            top = i;
        }
    for(i = 0 ; i < vertex ; i++) early[i] = 0; //initializing earliest start time for vertex to zero
    for(i = 0 ; i < vertex ; i++)           //determine the topological order(refer to textbook) and earliest start time
    {
        if(top <= -1)
        {
            printf("Infeasible network! Network has a cycle.");
            system("pasue");
            exit(EXIT_FAILURE);
        }
    }
}
```

```

else
{
    k = top;                                //pop from stack
    top = count[k];                         //top move down
    count[k] = order--;                     //record top. order in pop element
    for(j = 0 ; j < vertex ; j++)
        if( graph[k][j])
        {
            count[j]--;
            if( !count[j])
            {
                count[j] = top;
                top = j;
            }
            if(early[j] < early[k] + graph[k][j]) early[j] = early[k] + graph[k][j]; //determine early
        }
    }
}
for(i = 0 ; i < vertex ; i++) temp[i] = -count[i]; //count become top. ordered vertices in network
for(i = 0 ; i < vertex ; i++) count[temp[i]] = i;

```