

```
using System;
using System.Net;
using System.Net.Sockets;
using System.Threading;
using Microsoft.SPOT;
using Microsoft.SPOT.Hardware;
using SecretLabs.NETMF.Hardware;
using SecretLabs.NETMF.Hardware.Netduino;

namespace Greesha
{
    public class Program
    {
        public static void Main()
        {
            Robot Klichko = new Robot();

            Klichko.Go(270, 9);
            Klichko.Go(200, 4);
            Klichko.Go(300, 6);

            Klichko.Motors(0, 0);
            Thread.Sleep(Timeout.Infinite);
        }
    }
}
```