HW3

February 9, 2020

1 Example Template for HW3

This notebook contains the same template code as "logisticClassify2.py", but reorganized to make it simpler to edit and solve in iPython. Feel free to use this for your homework, or do it another way, as you prefer.

```
In [2]: from __future__ import division
    import numpy as np
    np.random.seed(0)

import mltools as ml
    import sys
    sys.path.append('code')

import matplotlib.pyplot as plt  # use matplotlib for plotting with inline plots
    plt.set_cmap('jet');
    %matplotlib inline
    import warnings
    warnings.filterwarnings('ignore'); # for deprecated matplotlib functions
```

1.1 Problem 1

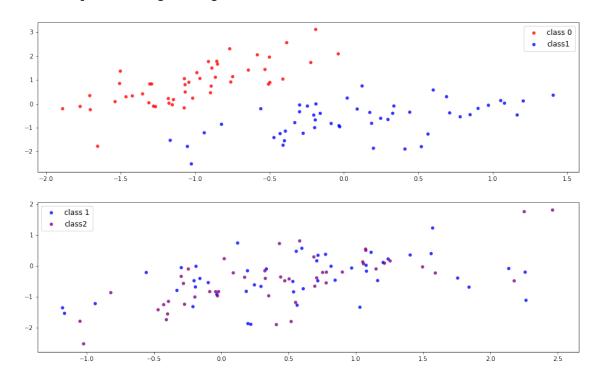
```
In [3]: iris = np.genfromtxt("data/iris.txt",delimiter=None)
    X, Y = iris[:,0:2], iris[:,-1]  # get first two features & target
    X,Y = ml.shuffleData(X,Y)  # reorder randomly rather than by class label
    X,_ = ml.transforms.rescale(X)  # rescale to improve numerical stability, speed conve

XA, YA = X[Y<2,:], Y[Y<2]  # Dataset A: class O vs class 1
    XB, YB = X[Y>0,:], Y[Y>0]  # Dataset B: class 1 vs class 2
```

1.1.1 P1.1

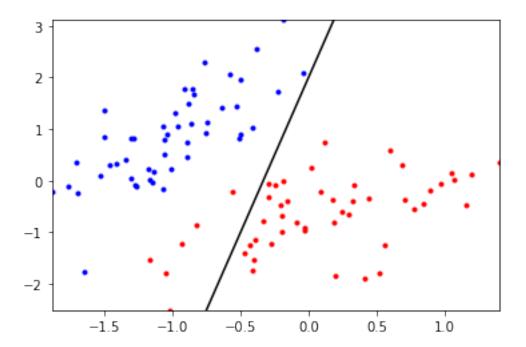
```
ax1[1].scatter(XB[YA==1,0], XB[YA==1,1], alpha=0.8, c='purple', edgecolors='none', s=3
ax1[1].legend(['class 1','class2'],fontsize=12)
```

Out[3]: <matplotlib.legend.Legend at 0x2918e9bbda0>

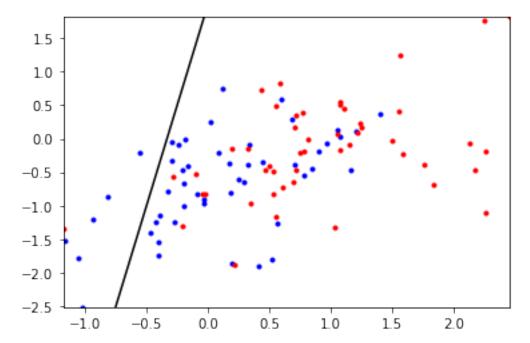


Class 0 and Class 1 are linearly seperable. Class 1 and class 2 are not linearly seperable.

1.1.2 P1.2



In [5]: learnerB = logisticClassify2()
 learnerB.classes = np.unique(YB) # store the class values for this problem
 learnerB.theta = np.array([2,6,-1]); # TODO: insert hard-coded values
 learnerB.plotBoundary(XB,YB)
 plt.show()



1.1.3 P1.3

```
In []: def predict(self, X):
    z = self.theta[0] + X.dot(self.theta[1:])
        Yhat = np.asarray(self.classes)[(z > 0).astype(int)]
        return Yhat

In [6]: learnerA = logisticClassify2()
        learnerA.classes = np.unique(YA)  # store the class values for this problem
        learnerA.theta = np.array([2,6,-1]); # TODO: insert hard-coded values
        print("Error fraction of data set A is: {}".format(learnerA.err(XA,YA)))

Error fraction of data set A is: 0.06060606060606061

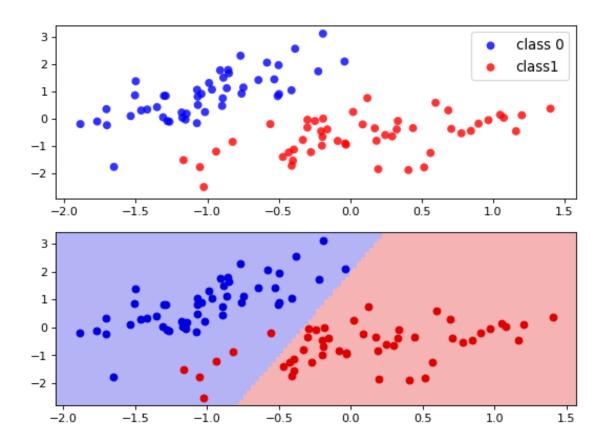
In [7]: learnerB = logisticClassify2()
        learnerB.classes = np.unique(YB)  # store the class values for this problem
        learnerB.theta = np.array([2,6,-1]); # TODO: insert hard-coded values
        print("Error fraction of data set B is: {}".format(learnerA.err(XB,YB)))

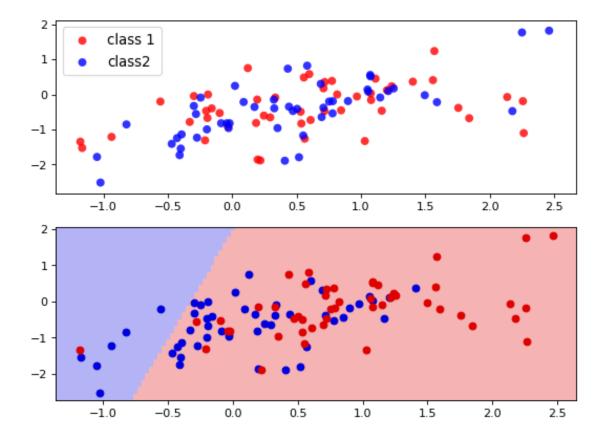
Error fraction of data set B is: 0.55555555555555555
```

If predict is implemented, then the inherited 2D visualization function should work; you can verify your decision boundary from P1.2:

1.1.4 P1.4

```
In [8]: plt.figure(num=None, figsize=(8, 6), dpi=80, facecolor='w', edgecolor='k')
    plt.subplot(211)
    plt.scatter(XA[YA==0,0], XA[YA==0,1], alpha=0.8, c='blue', edgecolors='none', s=50)
    plt.scatter(XA[YA==1,0], XA[YA==1,1], alpha=0.8, c='red', edgecolors='none', s=50)
    plt.legend(['class 0','class1'],fontsize=12)
    plt.subplot(212)
    ml.plotClassify2D(learnerA,XA,YA)
    plt.show()
```





1.2 ...

Here is an example of latex equations that may be useful for expressing the gradient:

1.2.1 1.5 Gradient of NLL

Our negative log-likelihood loss is:

$$J_j(\theta) = -\begin{cases} \log(\sigma(x^{(i)} \cdot \theta)) & \text{if } y^{(i)} = 1\\ \log(1 - \sigma(x^{(i)} \cdot \theta)) & \text{if } y^{(i)} = 0 \end{cases}$$

Thus, its gradient is:

$$\nabla J_j(\theta) = (something)$$

1.2.2 P1.5

$$J_i(\theta) = -\begin{cases} \log(\sigma(x^{(i)} \cdot \theta)) & \text{if } y^{(i)} = 1\\ \log(1 - \sigma(x^{(i)} \cdot \theta)) & \text{if } y^{(i)} = 0 \end{cases}$$
$$\sigma(r) = (1 + exp(-r))^{-1}$$
$$J_i(\theta) = -\log(\sigma(x^{(i)} \cdot \theta)) - \log(1 - \sigma(x^{(i)} \cdot \theta))$$

Thus, its gradient is:

$$\nabla J_{i}(\theta) = \frac{-y^{(i)}\sigma'(x^{(i)} \cdot \theta)}{\sigma(x^{(i)} \cdot \theta)} + \frac{(1 - y^{(i)} \cdot \sigma'(x^{(i)} \cdot \theta)}{1 - \sigma(x^{(i)} \cdot \theta)}$$

$$\sigma'(x^{(i)} \cdot \theta) = \sigma(x^{(i)} \cdot \theta) \cdot (1 - \sigma(x^{(i)} \cdot \theta)) \cdot (x^{(i)} \cdot \theta)'$$

$$\sigma'(x^{(i)} \cdot \theta) = \sigma(x^{(i)} \cdot \theta) \cdot (1 - \sigma(x^{(i)} \cdot \theta)) \cdot x^{(i)}$$

$$\nabla J_{i}(\theta) = \frac{-y^{(i)}\sigma'(x^{(i)} \cdot \theta)}{\sigma(x^{(i)} \cdot \theta)} + \frac{(1 - y^{(i)}) \cdot \sigma'(x^{(i)} \cdot \theta)}{1 - \sigma(x^{(i)} \cdot \theta)}$$

$$\nabla J_{i}(\theta) = \frac{-y^{(i)} \cdot x^{(i)}\sigma(x^{(i)} \cdot \theta) \cdot (1 - \sigma(x^{(i)} \cdot \theta))}{\sigma(x^{(i)} \cdot \theta)} + \frac{(1 - y^{(i)} \cdot x^{(i)} \cdot \sigma(x^{(i)} \cdot \theta) \cdot (1 - \sigma(x^{(i)} \cdot \theta))}{1 - \sigma(x^{(i)} \cdot \theta)}$$

$$\nabla J_{i}(\theta) = -y^{(i)} \cdot (1 - \sigma(x^{(i)} \cdot \theta)) \cdot x^{(i)} + (1 - y^{(i)} \cdot \sigma(x^{(i)} \cdot \theta)) \cdot x^{(i)}$$

$$\nabla J_{i}(\theta) = -y^{(i)} \cdot (1) \cdot x^{(i)} + (1) \cdot \sigma(x^{(i)} \cdot \theta) \cdot x^{(i)}$$

$$\nabla J_{i}(\theta) = (-y^{(i)} + \sigma(x^{(i)} \cdot \theta)) \cdot x^{(i)}$$

$$\nabla J_{i}(\theta) = (-y^{(i)} + \sigma(x^{(i)} \cdot \theta)) \cdot x^{(i)}$$

1.2.3 P1.7

```
def train(self, X, Y, initStep=1.0, stopTol=1e-4, stopEpochs=5000, plot=None):
In [2]:
                 """ Train the logistic regression using stochastic gradient descent """
                 from IPython import display
                 M,N = X.shape;
                                                      # initialize the model if necessary:
                 self.classes = np.unique(Y); # Y may have two classes, any values
                 XX = np.hstack((np.ones((M,1)),X)) # XX is X, but with an extra column of ones
                 YY = ml.toIndex(Y,self.classes); # YY is Y, but with canonical values 0 or 1
                 if len(self.theta)!=N+1: self.theta=np.random.rand(N+1);
                 # init loop variables:
                 epoch=0; done=False; Jnll=[]; J01=[];
                 while not done:
                     stepsize, epoch = initStep*2.0/(2.0+epoch), epoch+1; # update stepsize
                     # Do an SGD pass through the entire data set:
                     for i in np.random.permutation(M):
                         ri = 1.0 / (1.0 + np.exp(-XX[i,:].dot(self.theta)))  # TODO: comput
gradi = -(1-ri)*XX[i,:] if YY[i] else ri*XX[i,:];  # TODO: compute
                         self.theta -= np.float64(stepsize) * np.float64(gradi); # take a grad
                     J01.append( self.err(X,Y) ) # evaluate the current error rate
```

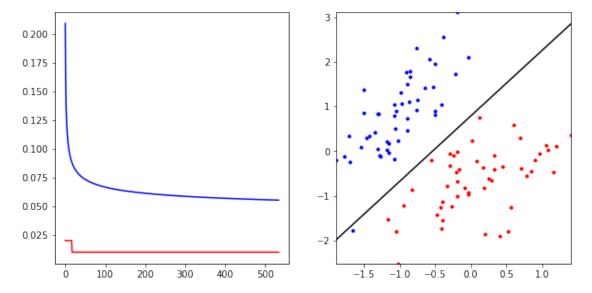
```
## TODO: compute surrogate loss (logistic negative log-likelihood)
## Jsur = - sum_i [ (log si) if yi==1 else (log(1-si)) ]
JL = 1.0/(1.0+np.exp(-(XX.dot(self.theta))))
Jnll.append( -np.mean(YY*np.log(JL)+(1-YY)*np.log(1-JL)) ) # TODO evaluate
display.clear_output(wait=True);
plt.subplot(1,2,1); plt.cla(); plt.plot(Jnll,'b-',J01,'r-'); # plot losses
if N==2: plt.subplot(1,2,2); plt.cla(); self.plotBoundary(X,Y); # & predic
plt.pause(.01); # let OS draw the plot

## For debugging: you may want to print current parameters & losses
# print self.theta, ' => ', Jnll[-1], ' / ', J01[-1]
# raw_input() # pause for keystroke

# TODO check stopping criteria: exit if exceeded # of epochs ( > stopEpoch
done = epoch>=stopEpochs or (epoch>1 and abs(Jnll[-1]-Jnll[-2])<stopTol);</pre>
```

1.2.4 P1.7

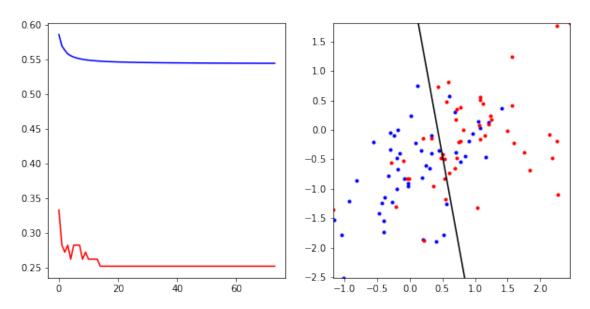
```
In [10]: plt.rcParams['figure.figsize'] = (10,5)  # make a wide figure, for two subplots
    learnerA = logisticClassify2()
    learnerA.theta = np.float64(np.array([0,0,0]))
    learnerA.train(XA,YA,initStep=1e-1,stopEpochs=1000,stopTol=1e-5);
```



For the step size, use initStep*2.0/(2.0+epoch) where epoch is the current step number. Which means that we take big step as initstep at the beginning and as the step number goes up, the step size we use will decreases. The stopping criteria use is when the nearby two batch grident decent lose function less tha 1e-4.

Error rate is red and surrgote loss is blue.

```
learnerB.theta = np.float64(np.array([0,0]))
learnerB.train(XB,YB,initStep=1e-1,stopEpochs=1000,stopTol=1e-5);
```



For the step size, use initStep*2.0/(2.0+epoch) where epoch is the current step number. Which means that we take big step as initstep at the beginning and as the step number goes up, the step size we use will decreases. The stopping criteria use is when the nearby two batch grident decent lose function less tha 1e-4.

Error rate is red and surrgote loss is blue.

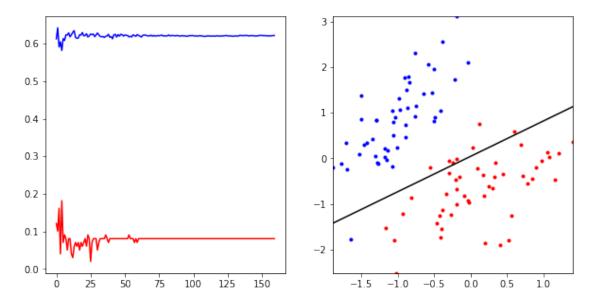
1.2.5 P1.8

```
def ltrain(self, X, Y, initStep=1.0, stopTol=1e-4, stopEpochs=5000,alpha=1,plot=Non
In [3]:
                """ Train the logistic regression using stochastic gradient descent
                from IPython import display
                M,N = X.shape;
                                                    # initialize the model if necessary:
                self.classes = np.unique(Y);
                                                    # Y may have two classes, any values
                XX = np.hstack((np.ones((M,1)),X)) # XX is X, but with an extra column of ones
                YY = ml.toIndex(Y,self.classes);
                                                   # YY is Y, but with canonical values 0 or 1
                if len(self.theta)!=N+1: self.theta=np.random.rand(N+1);
                # init loop variables:
                epoch=0; done=False; Jnll=[]; J01=[];
                while not done:
                    stepsize, epoch = initStep*2.0/(2.0+epoch), epoch+1; # update stepsize
                    # Do an SGD pass through the entire data set:
                    for i in np.random.permutation(M):
                        ri = 1.0 / (1.0 + np.exp(-XX[i,:].dot(self.theta)))
                                                                                  # TODO: comput
                        gradi = -(1-ri)*XX[i,:]+alpha*2*self.theta if YY[i] else ri*XX[i,:]+alpha*2*self.theta
                        self.theta -= np.float64(stepsize) * np.float64(gradi); # take a grad
```

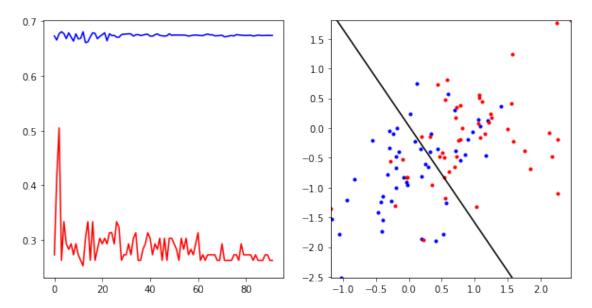
```
J01.append( self.err(X,Y) ) # evaluate the current error rate
## TODO: compute surrogate loss (logistic negative log-likelihood)
## Jsur = -sum_i [ (log si) if yi==1 else (log(1-si)) ]
JL = 1.0/(1.0+np.exp(-(XX.dot(self.theta))))
display.clear_output(wait=True);
plt.subplot(1,2,1); plt.cla(); plt.plot(Jnll,'b-',J01,'r-'); # plot losses
if N==2: plt.subplot(1,2,2); plt.cla(); self.plotBoundary(X,Y); # & predic
                                # let OS draw the plot
plt.pause(.01);
## For debugging: you may want to print current parameters & losses
# print self.theta, ' => ', Jnll[-1], ' / ', J01[-1]
# raw_input()
              # pause for keystroke
# TODO check stopping criteria: exit if exceeded # of epochs ( > stopEpoch
done = epoch>=stopEpochs or (epoch>1 and abs(Jnll[-1]-Jnll[-2])<stopTol);</pre>
```

2

In [3]: plt.rcParams['figure.figsize'] = (10,5) # make a wide figure, for two subplots
 learnerA = logisticClassify2()
 learnerA.theta = np.float64(np.array([0,0,0]))
 learnerA.ltrain(XA,YA,initStep=1e-1,stopEpochs=1000,stopTol=1e-5,alpha=2);



learnerB.theta = np.float64(np.array([0,0,0]))
learnerB.ltrain(XB,YB,initStep=1e-1,stopEpochs=1000,stopTol=1e-5,alpha=2);



In []:

2.1 Problem 2

 $T(a+bx_1)$

2.
$$T((a*b)x_1 + (c/a)x_2)$$

3.
$$T((x_1-a)^2+(x_2-b)^2+c)$$

4.
$$T(a + x_1 + cx_2) \times T(d + bx_1 + cx_2)$$

1. $T(a + bx_1)$ is a straight line perpendicular to x1 axis, thus it can only shatter the plane to left side and right side. For (b) we can just place the line between the two points. Thus, VC dimension >= 2. Consider (c), if y(2,2) is 1, y(4,8) is -1 and y(6,4) is 1. then no vertical line can shatter this data set. Thus VC dimension <3.

Thus, VC dimension is 2.

2. $T((a*b)x_1 + (c/a)x_2)$ linear classifier can shatter (b) if we just put the line through between the place for two points and put them on different sides. Thus VC dimension >= 2. Consider (c), if y(2,2) is 1, y(4,8) is 1 and y(6,4) is -1. Then no line in this form can splot (2,2) and (4,8) on one side and (6,4) in the other side. THus VC dimensiuon <3.

Thus, VC dimension is 2.

3. $T((x_1 - a)^2 + (x_2 - b)^2 + c)$ is a circle classifier which we can place the circle original every where in the plane. Thus, by including one or two or three points in the plane and leave the other out. (c) can be shattered. thus VC dimension >=3. For (d),consider that, (2,2) and (8,6) and (4,8) are -1 while (6,4) is +1. Then, since no circle can include (2,2) and (8,6) and (4,8) without include (2,2) thus. Cannot be shattered. Thus, VC dimension <4.

Thus VC dimension is 3.

4. $T(a + x_1 + cx_2) \times T(d + bx_1 + cx_2)$ two parrel lines classifiers can shatter (6) by classifying any possibility for middle +1 two sides -1 or two sides +1 and middle -1. Thus, (d) can be easily shattered. Thus, VC dimension >= 4

2.2 Problem 3

I did this by myself without discussing with others.

In []: