CZ2003: Tutorial 9

Due on March 23, 2021 at 10:30am

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The following VRML code defines a Transform node:

Assuming a column represented position vector, write in a proper order the individual matrices composing this transformation. The final matrix is not required.

Solution

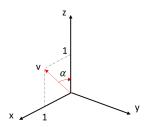
Order for VRML Transform node: 1) Scale, 2) Rotation, 3) Translation

Scaling:

$$S = \begin{bmatrix} 3 & 0 & 0 & 0 \\ 0 & 3 & 0 & 0 \\ 0 & 0 & 3 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

Rotation:

First, Align vector V = (1, 0, 1) to z-axis



Angle between V to Z-axis (α):

$$\alpha = \pi/2 - tan^{-}1(1)$$

$$\alpha = \pi/4$$

$$\alpha = \pi/4$$

Therefore, first rotate about y-axis by $-\alpha = -\pi/4$

Then, since the rotation axis is aligned with z-axis, rotate about z-axis by π

Finally, undo the first preprocessing step by rotating about y-axis by $\pi/4$

$$R = \begin{bmatrix} \cos(\pi/4) & 0 & \sin(\pi/4) & 0 \\ 0 & 1 & 0 & 0 \\ -\sin(\pi/4) & 0 & \cos(\pi/4) & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} \cos(\pi) & -\sin(\pi) & 0 & 0 \\ \sin(\pi) & \cos(\pi) & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} \cos(-\pi/4) & 0 & \sin(-\pi/4) & 0 \\ 0 & 1 & 0 & 0 \\ -\sin(-\pi/4) & 0 & \cos(-\pi/4) & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$R = \begin{bmatrix} \sqrt{2}/2 & 0 & \sqrt{2}/2 & 0 \\ 0 & 1 & 0 & 0 \\ -\sqrt{2}/2 & 0 & \sqrt{2}/2 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} -1 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} \sqrt{2}/2 & 0 & -\sqrt{2}/2 & 0 \\ 0 & 1 & 0 & 0 \\ \sqrt{2}/2 & 0 & \sqrt{2}/2 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

Translation:

$$T = \begin{bmatrix} 1 & 0 & 0 & 3 \\ 0 & 1 & 0 & 2 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

Therefore, final transformation matrix $(M)\colon M=TRS$

$$M = \begin{bmatrix} 1 & 0 & 0 & 3 \\ 0 & 1 & 0 & 2 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} \sqrt{2}/2 & 0 & \sqrt{2}/2 & 0 \\ 0 & 1 & 0 & 0 \\ -\sqrt{2}/2 & 0 & \sqrt{2}/2 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} -1 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} \sqrt{2}/2 & 0 & -\sqrt{2}/2 & 0 \\ 0 & 1 & 0 & 0 \\ \sqrt{2}/2 & 0 & \sqrt{2}/2 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 3 & 0 & 0 & 0 \\ 0 & 3 & 0 & 0 \\ 0 & 0 & 3 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

A unit cube with vertices at points (0,0,0), (0,1,0), (1,1,0), (1,0,0), (0,0,1), ..., (1,0,1) is transformed into a prism with the respective vertices at points (-1,0,0), (-1,2,0), (2,0,0), (2,-2,0), (0,0,2), ..., (3,-2,2) by an affine transformation matrix. Find a single matrix representing this transformation.

Solution

1.) Choose 4 non-coplanar points:

Before transformation: (0,0,0), (0,1,0), (1,1,0), (1,0,1)

After transformation: (-1,0,0), (-1,2,0), (2,0,0), (3,-2,2)

Transformation Matrix: M

$$M = \begin{bmatrix} a & b & c & l \\ d & e & f & m \\ g & h & i & n \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

Therefore,

$$\begin{bmatrix} a & b & c & l \\ d & e & f & m \\ g & h & i & n \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} = \begin{bmatrix} -1 \\ 0 \\ 0 \\ 1 \end{bmatrix}$$
$$1 = -1, \mathbf{m} = \mathbf{0}, \mathbf{n} = \mathbf{0}$$

$$\begin{bmatrix} a & b & c & -1 \\ d & e & f & 0 \\ g & h & i & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 0 \\ 1 \\ 0 \\ 1 \end{bmatrix} = \begin{bmatrix} -1 \\ 2 \\ 0 \\ 1 \end{bmatrix}$$

$$b - 1 = -1$$

$$\mathbf{b}=\mathbf{0},\mathbf{e}=\mathbf{2},\mathbf{h}=\mathbf{0}$$

$$\begin{bmatrix} a & 0 & c & -1 \\ d & 2 & f & 0 \\ g & 0 & i & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \\ 0 \\ 1 \end{bmatrix} = \begin{bmatrix} 2 \\ 0 \\ 0 \\ 1 \end{bmatrix}$$
$$(a-1=2), \ (d+2=0), \ (g=0)$$
$$\mathbf{a}=\mathbf{3}, \mathbf{d}=-\mathbf{2}, \mathbf{g}=\mathbf{0}$$

$$\begin{bmatrix} 3 & 0 & c & -1 \\ -2 & 2 & f & 0 \\ 0 & 0 & i & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ 0 \\ 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 3 \\ -2 \\ 2 \\ 1 \end{bmatrix}$$
$$(3+c-1=3), \ (-2+f=-2), \ (i=2)$$
$$\mathbf{c} = \mathbf{1}, \mathbf{f} = \mathbf{0}, \mathbf{i} = \mathbf{2}$$

$$\therefore \mathbf{M} = \begin{bmatrix} 3 & 0 & 1 & -1 \\ -2 & 2 & 0 & 0 \\ 0 & 0 & 2 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

Assuming a column represented position vector, write in a proper order individual matrices implementing the transformation of reflection about a straight line defined parametrically by $x=1-t, y=0, z=2t, t\in (-\infty,\infty)$. The final matrix is not required.

Solution

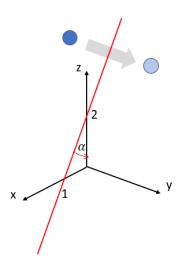
To get straight line, get for t = 1, 0 and -1

t=-1: (2,0,-2)

t=0: (1,0,0)

t=1: (0,0,2)

By visualizing the reflection, we get the following figure:



Where $\alpha = tan^{-}1(1/2) = 0.463$

Therefore, the following steps are required:

1) Translate by -1 in x-axis such that the reflection axis passes through the origin

$$T_1 = \begin{bmatrix} 1 & 0 & 0 & -1 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

2) Rotate about y-axis for an angle of α such that the reflection axis is aligned with z-axis

$$R_2 = \begin{bmatrix} cos(0.463) & 0 & sin(0.463) & 0 \\ 0 & 1 & 0 & 0 \\ -sin(0.463) & 0 & cos(0.463) & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 0.894 & 0 & 0.447 & 0 \\ 0 & 1 & 0 & 0 \\ -0.447 & 0 & 0.894 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

3) Perform reflection about z-axis

$$R_3 = \begin{bmatrix} -1 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

4) Rotate about y-axis for an angle of $-\alpha$ (undo step 2)

$$R_4 = \begin{bmatrix} cos(-0.463) & 0 & sin(-0.463) & 0 \\ 0 & 1 & 0 & 0 \\ -sin(-0.463) & 0 & cos(-0.463) & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 0.894 & 0 & -0.447 & 0 \\ 0 & 1 & 0 & 0 \\ 0.447 & 0 & 0.894 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

5) Translate by 1 in x-axis (undo step 1)

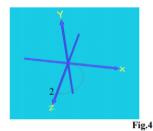
$$T_5 = \begin{bmatrix} 1 & 0 & 0 & 1 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

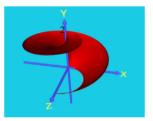
Therefore, final transformation matrix $(M)\colon$

 $M = T_5 R_4 R_3 R_2 T_1$

$$M = \begin{bmatrix} 1 & 0 & 0 & 1 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 0.894 & 0 & -0.447 & 0 \\ 0 & 1 & 0 & 0 \\ 0.447 & 0 & 0.894 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} -1 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 0.894 & 0 & 0.447 & 0 \\ 0 & 1 & 0 & 0 \\ -0.447 & 0 & 0.894 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & -1 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

A semi-circle on the ZX plane in shown in Fig.4 (left). It undergoes a sweeping by a full rotation about the Y-axis and a translation along the Y-axis by 2 units simultaneously, which provides a surface shown in Fig.4(right). Utilizing transformation matrices. derive a parametric representation of the surface.





Solution

Step 1: define parametric equations for the semi-circle curve.

$$x_0(\alpha) = \sin(\alpha)$$

$$y_0(\alpha) = 0$$

$$z_0(\alpha) = 1 + \cos(\alpha)$$

$$alpha \in [0, \pi]$$

Step 2: Multiply the coordinates by 3D rotation matrix and figure out range of rotation angle

$$\begin{bmatrix} x(\alpha,\beta) \\ y(\alpha,\beta) \\ z(\alpha,\beta) \\ 1 \end{bmatrix} = \begin{bmatrix} \cos(\beta) & 0 & \sin(\beta) & 0 \\ 0 & 1 & 0 & 0 \\ -\sin(\beta) & 0 & \cos(\beta) & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x_0(\alpha) \\ y_0(\alpha) \\ z_0(\alpha) \\ 1 \end{bmatrix}$$

$$x(\alpha, \beta) = \cos(\beta)x_0(\alpha) + \sin(\beta)z_0(\alpha)$$
$$y(\alpha, \beta) = y_0(\alpha)$$
$$z(\alpha, \beta) = -\sin(\beta)x_0(\alpha) + \cos(\beta)z_0(\alpha)$$
$$\beta \in [0, 2\pi]$$

Step 3: Handle translational sweeping

$$y(\alpha, \beta) = y_0(\alpha) + f(\beta)$$

$$f(\beta) = A + B\beta$$

$$f(0) = A$$

$$= 0$$

$$\therefore A = 0$$

$$f(2\pi) = 2\pi B$$

$$= 2$$

$$\therefore B = 1/\pi$$

$$\therefore y(\alpha,\beta) = y_0(\alpha) + \beta/\pi$$

$$\begin{split} x(\alpha,\beta) &= \cos(\beta) \sin(\alpha) + \sin(\beta) (1 + \cos(\alpha)) \\ y(\alpha,\beta) &= \beta/\pi \\ z(\alpha,\beta) &= -\sin(\beta) \sin(\alpha) + \cos(\beta) (1 + \cos(\alpha)) \\ alpha &\in [0,\pi] \ \beta \in [0,2\pi] \end{split}$$

Step 4: Rename α, β to $u, v, u, v \in [0, 1]$

$$u = \alpha/\pi$$
$$v = \beta/2\pi$$

Therefore,

$$\begin{split} x(u,v) &= cos(2\pi v)sin(\pi u) + sin(2\pi v)(1 + cos(\pi u)) \\ y(u,v) &= 2v \\ z(u,v) &= -sin(2\pi v)sin(\pi u) + cos(2\pi v)(1 + cos(\pi u)) \\ u,v &\in [0,1] \end{split}$$

