

10.4 The Cross Product

Determinant of Order 2

$$\begin{bmatrix} a & b \\ c & d \end{bmatrix} = ad - bc$$

Ex 1

$$\begin{bmatrix} 2 & 1 \\ -6 & 4 \end{bmatrix} = 2(4) - 1(-6) = \boxed{14}$$

Determinant of Order 3

$$\begin{bmatrix} a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \\ c_1 & c_2 & c_3 \end{bmatrix} = a_1 \begin{bmatrix} b_2 & b_3 \\ c_2 & c_3 \end{bmatrix} - a_2 \begin{bmatrix} b_1 & b_3 \\ c_1 & c_3 \end{bmatrix} + a_3 \begin{bmatrix} b_1 & b_2 \\ c_1 & c_2 \end{bmatrix}$$

Ex 2

$$\begin{bmatrix} 1 & 2 & -1 \\ 3 & 0 & 1 \\ -5 & 4 & 2 \end{bmatrix}$$

$$1 \begin{bmatrix} 0 & 1 \\ 4 & 2 \end{bmatrix} - 2 \begin{bmatrix} 3 & 1 \\ -5 & 2 \end{bmatrix} + (-1) \begin{bmatrix} 3 & 0 \\ -5 & 4 \end{bmatrix}$$

$$1(0(2) - 1(4)) - 2(3(2) - 1(3(2) - 1(-5))) + (-1)(3(4) - 0(-5))$$

$$1(-4) - 2() - 1(12) \rightarrow \boxed{-38}$$

Definition

If $\vec{a} = \langle a_1, a_2, a_3 \rangle$ and $\vec{b} = \langle b_1, b_2, b_3 \rangle$, then the cross product of \vec{a} & \vec{b} is the vector.

$$\vec{a} \times \vec{b} = \begin{bmatrix} \vec{i} & \vec{j} & \vec{k} \\ a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \end{bmatrix}$$

Ex 3

If $\vec{a} = \langle 1, 3, 4 \rangle$ & $\vec{b} = \langle 2, 7, -5 \rangle$ find $\vec{a} \times \vec{b}$.

$$\begin{aligned}\vec{a} \cdot \vec{b} &= \begin{bmatrix} \vec{i} & \vec{j} & \vec{k} \\ 1 & 3 & 4 \\ 2 & 7 & -5 \end{bmatrix} \\ &= \vec{i} \begin{bmatrix} 3 & 4 \\ 7 & -5 \end{bmatrix} - \vec{j} \begin{bmatrix} 1 & 4 \\ 2 & -5 \end{bmatrix} + \vec{k} \begin{bmatrix} 1 & 3 \\ 2 & 7 \end{bmatrix} \\ &= \vec{i}(-15 - 28) - \vec{j}(-5 - 8) + \vec{k}(7 - 6) \\ &= \boxed{-43\vec{i} + 13\vec{j} + \vec{k}}\end{aligned}$$

Example 4

Show that if $\vec{a} = \langle a_1, a_2, a_3 \rangle$, then $\vec{a} \times \vec{b} = 0$

$$\begin{aligned}& \begin{bmatrix} \vec{i} & \vec{j} & \vec{k} \\ a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \end{bmatrix} \\ &= \vec{i} \begin{bmatrix} a_2 & a_3 \\ b_2 & b_3 \end{bmatrix} - \vec{j} \begin{bmatrix} a_1 & a_3 \\ b_1 & b_3 \end{bmatrix} + \vec{k} \begin{bmatrix} a_1 & a_2 \\ b_1 & b_2 \end{bmatrix}\end{aligned}$$

$$\vec{a}(a_2a_3 - a_3b_2) - \vec{j}(a_1a_3 - a_3a_1) + \vec{k}(a_1a_2a_2a_1)$$

$$\vec{0} + \vec{0} + \vec{0} = \boxed{\vec{0}}$$

Theorem

The vector $\vec{a} \cdot \vec{b}$ is orthogonal to both vectors \vec{a} & \vec{b} .

Proof

Let $\vec{a} = \langle a_1, a_2, a_3 \rangle$ & $\vec{b} = \langle b_1, b_2, b_3 \rangle$. Now,

$$\begin{aligned}& \begin{bmatrix} \vec{i} & \vec{j} & \vec{k} \\ a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \end{bmatrix} = \vec{i} \begin{bmatrix} a_2 & a_3 \\ b_2 & b_3 \end{bmatrix} - \vec{j} \begin{bmatrix} a_1 & a_3 \\ b_1 & b_3 \end{bmatrix} + \vec{k} \begin{bmatrix} a_1 & a_2 \\ b_1 & b_2 \end{bmatrix} \\ &= a_1(a_2b_3 - a_3b_2) - a_2(a_1b_3 - a_3b_1) + a_3(a_1b_2 - a_2b_1) \\ &a_1a_2b_3 - a_1a_3b_2 - a_2a_1b_3 - a_3b_1 + a_2a_3b_1 + ab_1 + a_3a_1b_2 - a_3a_2b_1 = 0\end{aligned}$$

By similar computations, $(\vec{a} \cdot \vec{b}) \cdot \vec{b} = 0$. Therefore, $\vec{a} \cdot \vec{b}$ is orthogonal to both \vec{a} & \vec{b} .

Theorem

If θ is the angle between \vec{a} & \vec{b} (so $0 \leq \theta \leq \pi$), then

$$|\vec{a} \cdot \vec{b}| = \vec{a}\vec{b}\sin \theta$$

Corollary

Two nonzero vectors \vec{a} & \vec{b} are parallel if and only if $\vec{a} \cdot \vec{b} = 0$.

Interpretation of Cross Product

Area of parallelogram = base \cdot height = $|\vec{a}||\vec{b}|\sin\theta = |\vec{a} \cdot \vec{b}|$

Ex 5

Find a vector perpendicular to the plane that passes through the points $P(1, 4, 6)$, $Q(-2, 5 - 1)$, & $R(1, -1, 1)$.

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Ex 6

Find the area of the triangle with vertices $P(1, 4, 6)$, $Q(-2, 5 - 1)$, & $R(1, -1, 1)$.

$$\text{Area} = \frac{1}{2} |\vec{PQ} \cdot \vec{PR}|$$

$$\frac{1}{2} \sqrt{(-40)^2 + (-15)^2 + (15)^2}$$

$$\frac{1}{2} \sqrt{2050}$$

$$\frac{1}{2} \sqrt{25(82)}$$

$$\boxed{\frac{5}{2} \sqrt{82}}$$

Theorem

If \vec{a} , \vec{b} & \vec{c} are vectors and c is a scalar, then

$$1) \vec{a} \cdot \vec{b} = -\vec{b} \cdot \vec{a}$$

$$2) (c\vec{a})$$

$$3)$$

$$4)$$

$$5)$$

$$6) \vec{a} \cdot (\vec{b} \cdot \vec{c}) = (\vec{a} \cdot \vec{c})\vec{b} - (\vec{a} \cdot \vec{b})\vec{c}$$

Triple Products

$$\vec{a} \cdot (\vec{b} \cdot \vec{c}) = \begin{bmatrix} a_1 & a_2 & a_3 \\ b_2 & b_2 & b_3 \\ c_1 & c_2 & c_2 \end{bmatrix}$$

$$V = (\text{Area of Base})(\text{Height})$$

$$|\vec{b} \cdot \vec{c}| \cdot |\vec{a}| \cdot |\cos\theta|$$

$$|\vec{a} \cdot (\vec{b} \cdot \vec{c})|$$

Note

If $\vec{a} \cdot (\vec{b} \cdot \vec{c}) = 0$, then the vectors are coplanar (lie on the same plane).

Ex 7

If $\vec{a} = \langle 1, 4, -7 \rangle$, $\vec{b} = \langle 2, -1, 4 \rangle$ & $\vec{c} = \langle 0, -9, 18 \rangle$, then

$$\vec{a} \cdot (\vec{b} \cdot \vec{c}) = \begin{bmatrix} 1 & 4 & -7 \\ 2 & -1 & 4 \\ 0 & -9 & 18 \end{bmatrix}$$

$$1(-18 - (-36)) - 4(36 - 0) - 7(-18 - 0)$$

$$18 - 144 + 126$$

$$0$$

Thus, \vec{a} , \vec{b} , & \vec{c} are coplanar.

Torque

Consider a force \vec{F} acting on a rigid body at a point given by a position vector \vec{r} . The torque τ (relative to the origin) is

$$\vec{\tau} = \vec{r} \cdot \vec{F}$$

and measures the tendency of the body to rotate about the origin. The magnitude of the torque vector is

$$|\vec{\tau}| = |\vec{r} \cdot \vec{F}| = |\vec{r}| \cdot |\vec{F}| \cdot \sin \theta$$

where θ is the angle between \vec{r} & \vec{F} .

Ex 8

A bolt is tightened by applying a $40N$ force to a $0.25m$ wrench. Find the magnitude of the torque about the center of the bolt.

$$|\tau| = 0.25(40) \sin 75^\circ$$

$$\boxed{9.66N \cdot m}$$