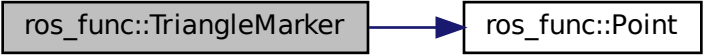


ros\_func::TriangleMarker



```
graph LR; A[ros_func::TriangleMarker] --> B[ros_func::Point]
```

ros\_func::Point