

kinematics::vec3::isnum



```
graph LR; A[kinematics::vec3::isnum] --> B[kinematics::vec3::isinf]; A --> C[kinematics::vec3::isnan];
```

A diagram showing a node on the left, labeled 'kinematics::vec3::isnum', which is shaded gray. Two blue arrows point from the right side of this node to two separate white nodes on the right. The top white node is labeled 'kinematics::vec3::isinf' and the bottom white node is labeled 'kinematics::vec3::isnan'. All nodes have black borders.

kinematics::vec3::isinf

kinematics::vec3::isnan