

kinematics::vec4::Trans



```
graph LR; A[kinematics::vec4::Trans] --> B[kinematics::vec4::conj]
```

A diagram showing a transition from the state `kinematics::vec4::Trans` to `kinematics::vec4::conj`. The first state is in a gray box, and the second is in a white box, connected by a blue arrow.

kinematics::vec4::conj