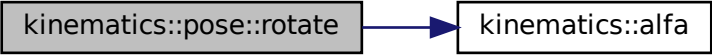


kinematics::pose::rotate



```
graph LR; A[kinematics::pose::rotate] --> B[kinematics::alfa];
```

A diagram showing a relationship between two variables. On the left, a gray rectangular box contains the text 'kinematics::pose::rotate'. A blue arrow points from the right side of this box to the left side of a white rectangular box on the right. The white box contains the text 'kinematics::alfa'. Both boxes have a black border.

kinematics::alfa