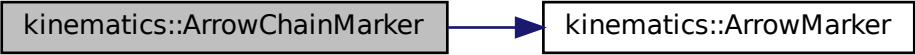


kinematics::ArrowChainMarker



```
graph LR; A[kinematics::ArrowChainMarker] --> B[kinematics::ArrowMarker]
```

The diagram illustrates a relationship between two classes. On the left, a gray rectangular box contains the text 'kinematics::ArrowChainMarker'. A dark blue arrow points from the right side of this box to the left side of a white rectangular box on the right, which contains the text 'kinematics::ArrowMarker'. Both boxes have a black border.

kinematics::ArrowMarker