

kinematics::vec4::RotationTo

kinematics::pose::surface

kinematics::vec3::nrm

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graph LR; A[kinematics::vec4::RotationTo] --> C[kinematics::vec3::nrm]; B[kinematics::pose::surface] --> C;
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The diagram illustrates a function call or data flow. Two input boxes on the left, 'kinematics::vec4::RotationTo' and 'kinematics::pose::surface', have blue arrows pointing to a single output box on the right, 'kinematics::vec3::nrm'. The output box is shaded gray, while the input boxes are white with black borders.