

kinematics::vec4::normalize



```
graph LR; A[kinematics::vec4::normalize] --> B[kinematics::vec4::nrm]
```

A diagram showing a mapping from the function `kinematics::vec4::normalize` to `kinematics::vec4::nrm`. The first box is gray and the second is white, connected by a blue arrow.

kinematics::vec4::nrm