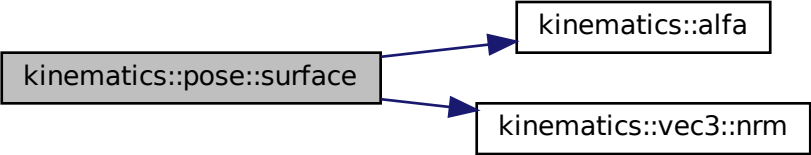


kinematics::pose::surface



```
graph LR; A[kinematics::pose::surface] --> B[kinematics::alfa]; A --> C[kinematics::vec3::nrm];
```

A diagram showing a central node on the left, 'kinematics::pose::surface', which is shaded gray. Two blue arrows originate from its right side. The top arrow points to a white node labeled 'kinematics::alfa'. The bottom arrow points to a white node labeled 'kinematics::vec3::nrm'. All nodes are rectangular with black borders.

kinematics::alfa

kinematics::vec3::nrm