


kinematics::LineLoopMarker



```
graph LR; A[kinematics::LineLoopMarker] --> B[kinematics::LineMarker]
```

The diagram consists of two rectangular boxes connected by a horizontal arrow. The left box is shaded gray and contains the text 'kinematics::LineLoopMarker'. The right box is white and contains the text 'kinematics::LineMarker'. A dark blue arrow points from the right side of the gray box to the left side of the white box, indicating a relationship or inheritance.

kinematics::LineMarker