

kinematics::vec4::RotationTo2

```
graph LR; A[kinematics::vec4::RotationTo2] --> B[kinematics::vec4::C]; A --> C[kinematics::vec4::conj];
```

A diagram showing a function call. A gray box on the left contains the text 'kinematics::vec4::RotationTo2'. Two blue arrows originate from the right side of this box. The top arrow points to a white box containing 'kinematics::vec4::C'. The bottom arrow points to a white box containing 'kinematics::vec4::conj'.

kinematics::vec4::C

kinematics::vec4::conj