Three parts of computational thinking

- Abstraction
- Decomposition
- Algorithmic thinking

Abstraction = Process of removing unnecessary details to simplify a problem or system, focusing only on the relevant information needed to solve it

Purpose of Abstraction:

- To reduce complexity.
- To make a problem or system easier to understand.
- To allow developers to focus on the core aspects of a problem without being distracted by irrelevant details.

Decomposition = Decomposition is the process of breaking down a complex problem or system into smaller, more manageable parts that are easier to solve or understand.

Advantages of decomposition:

- Problems are easier to solve
- Different people can work on different parts of a problem at a time → Reduces development time
- Program components developed in one program can be used in other programs

Algorithm = Step-by-step set of instructions designed to perform a specific task or solve a problem.

A computer program is an implementation of an algorithm

Pseudocode:

- Informal description
- No standardised syntax
- Intended for human reading

1. Linear Search

- Time Complexity:
 - Best Case: O(1) (when the target element is the first in the list).
 - Worst Case: O(n) (when the target element is at the end or not found).

Advantages:

- Simple to implement.
- Works on both sorted and unsorted data.

Disadvantages:

 Inefficient for large datasets since it checks every element.

2. Binary Search

Describe the steps a binary search will follow to look for a number in a sorted list.

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• Time Complexity:

- Best Case: O(1) (when the target element is the middle one).
- Worst Case: O(log n) (divides the list in half each step).

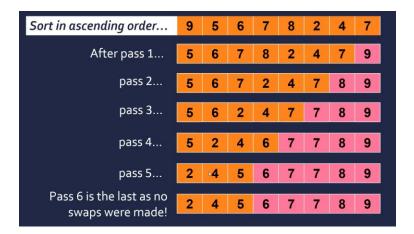
Advantages:

- Much faster than linear search for large datasets.
- Efficient on sorted data.

Disadvantages:

- Only works on sorted data (requires extra effort if data isn't sorted).
- More complex to implement.
- 1. Initialise two pointers (Left pointer at the start of the array and right pointer for the end of the array)
- 2. Calculate midpoint of array by doing:
- mid = (I+r)//2
- 3. Check if midpoint is smaller or greater than target
- 4. If midpoint > target then repeat on right side else check on left side

Bubble sort – Performs passes



□ Time Complexity:

- Best Case: O(n) (when the list is already sorted).
- Worst Case: O(n²) (when the list is in reverse order).

□ Advantages:

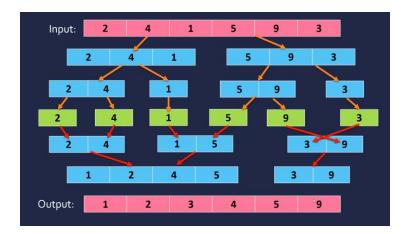
- Simple to understand and implement.
- Doesn't need additional memory (in-place sorting).
- Good for small datasets

□ Disadvantages:

- Very inefficient for large datasets.
- Slow compared to more advanced sorting algorithms.

Merge sort:

- Divide and conquer



□ Time Complexity:

- Best Case: O(nlogn).
- Worst Case: O(nlogn) (always divides and combines).

□ Advantages:

- Efficient for large datasets.
- · Works well with linked lists.
- Always guarantees O(nlogn) performance.

□ Disadvantages:

- Requires additional memory for splitting and merging.
- More complex to code compared to bubble sort.

Insertion sort:

 Creates a new list and appends new elements and sorts them at the same time



☐ Time Complexity:

- **Best Case**: O(n) (when the list is already sorted).
- Worst Case: O(n²) (when the list is in reverse order).

□ Advantages:

- · Simple to implement.
- Works well for small or nearly sorted datasets.
- In-place sorting (no extra memory needed).

□ Disadvantages:

- Inefficient for large datasets.
- Comparatively slower than merge sort.

Flowchart = Method of representing the sequences in an algorithm in the form of a diagram