

# Visual Data Analytics Volume Visualization

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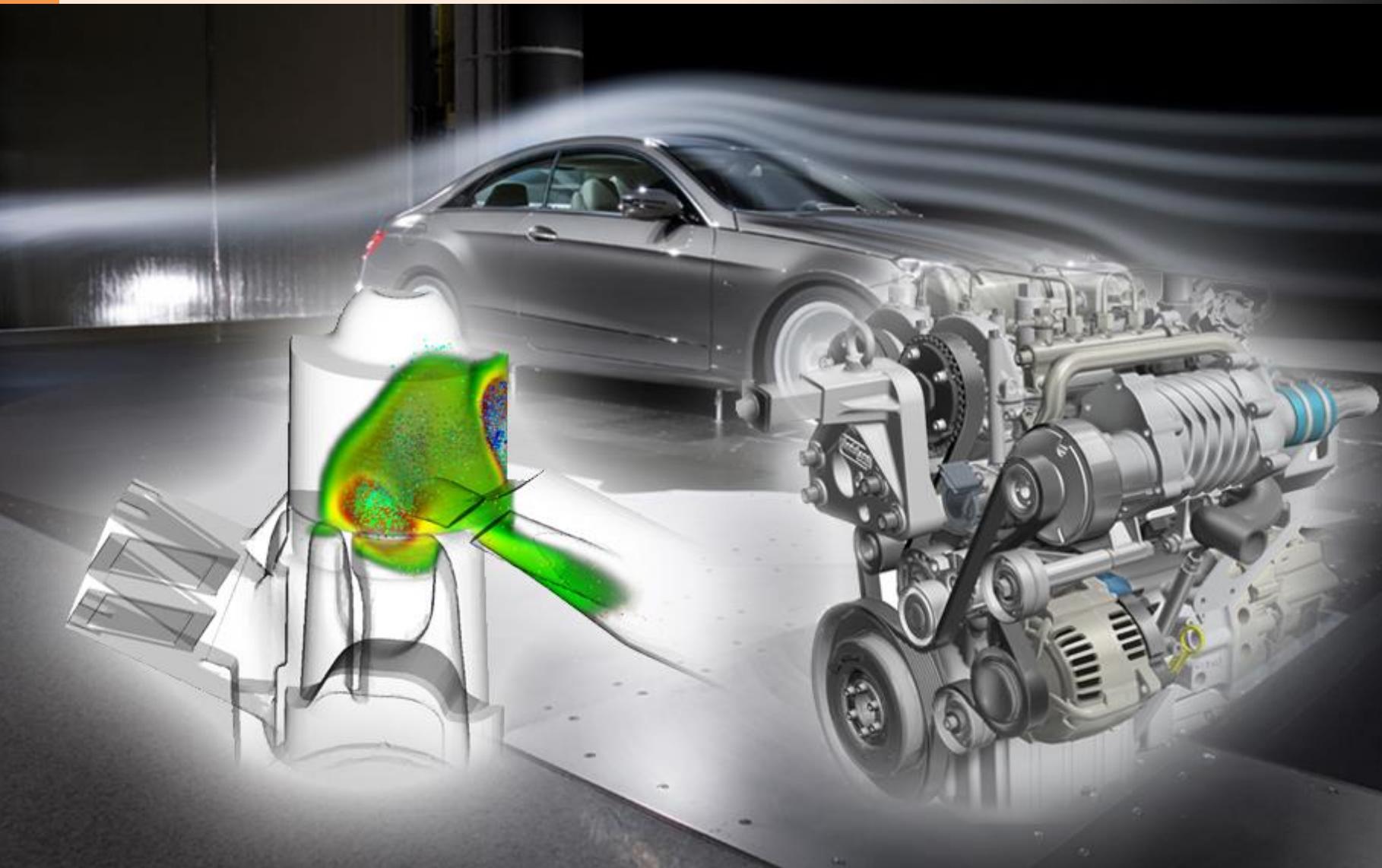
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# Medical scanners

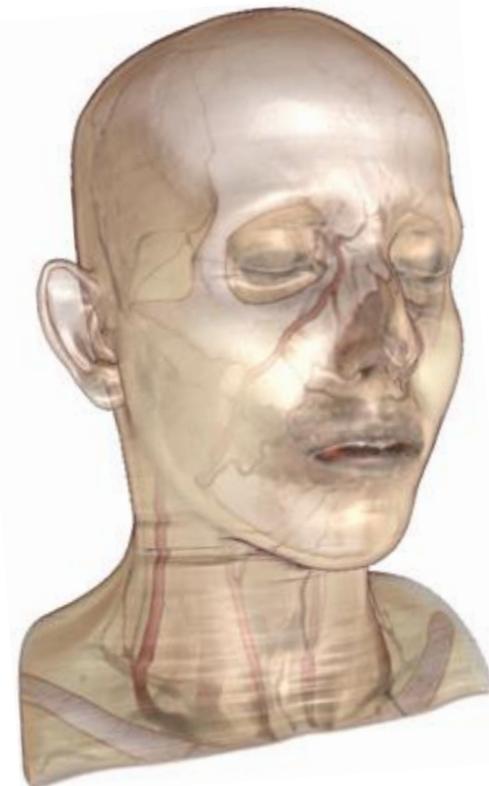
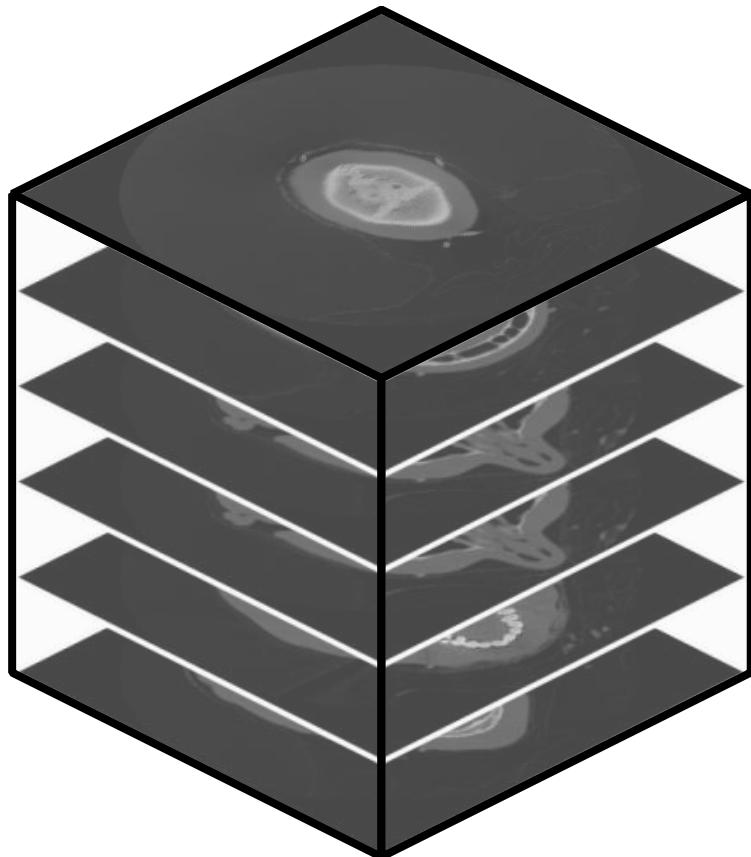


# Automotive Engineering



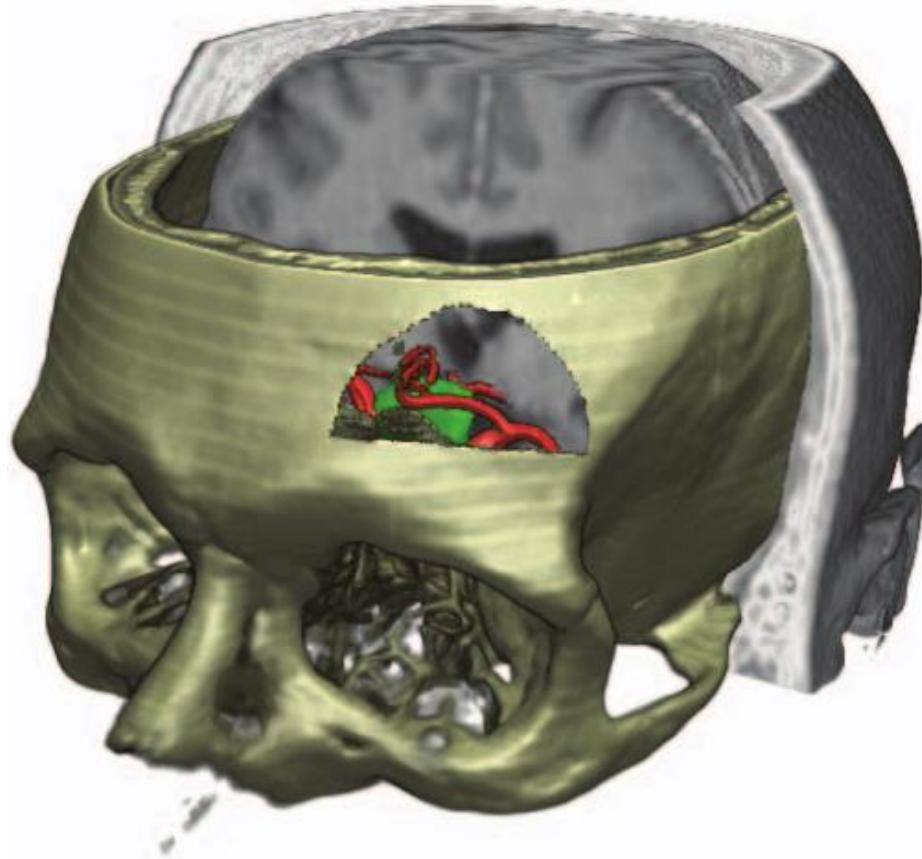
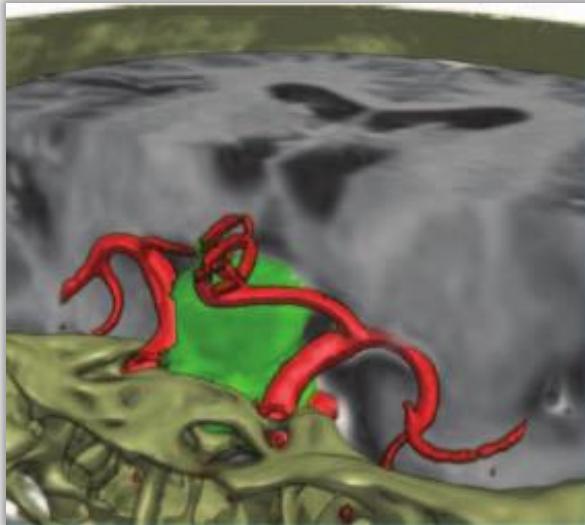
# Volume visualization

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# Visualization – Examples

- Preoperative planning of a tumor resection



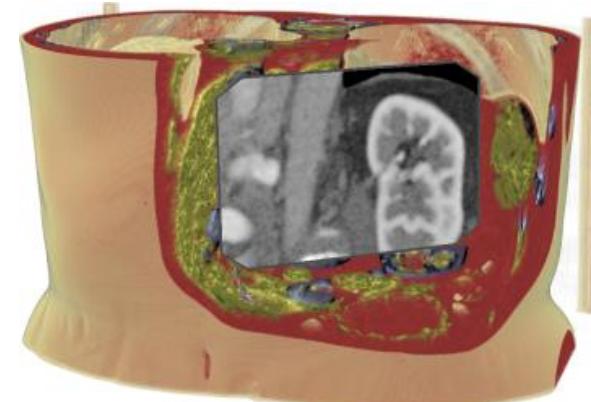
[Beyer et al. 2007]

Black/white: brain – Magnetic Resonance Imaging (MRI)  
Green: tumor – MRI  
Red: vessels – Magnetic Resonance Angiogram (MRA)  
Brown: skull – Computer Tomography (CT)

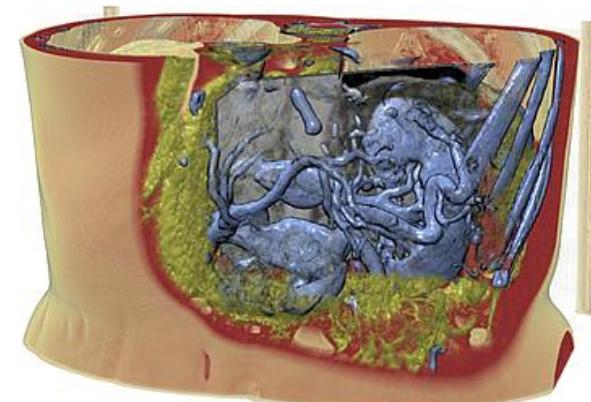
# Visualization – Examples

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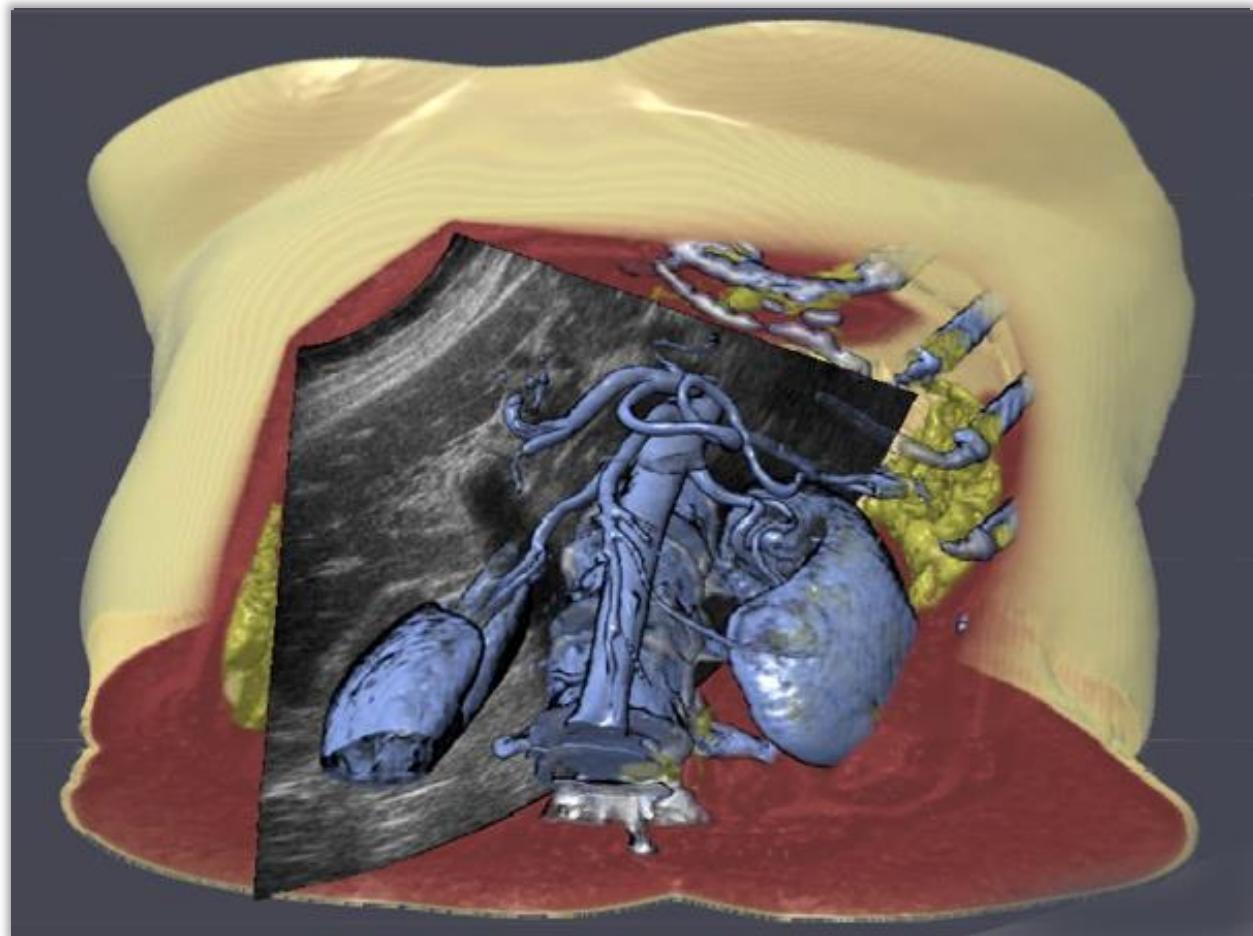
- CT scan with embedded Ultrasound data



Traditional cutaway



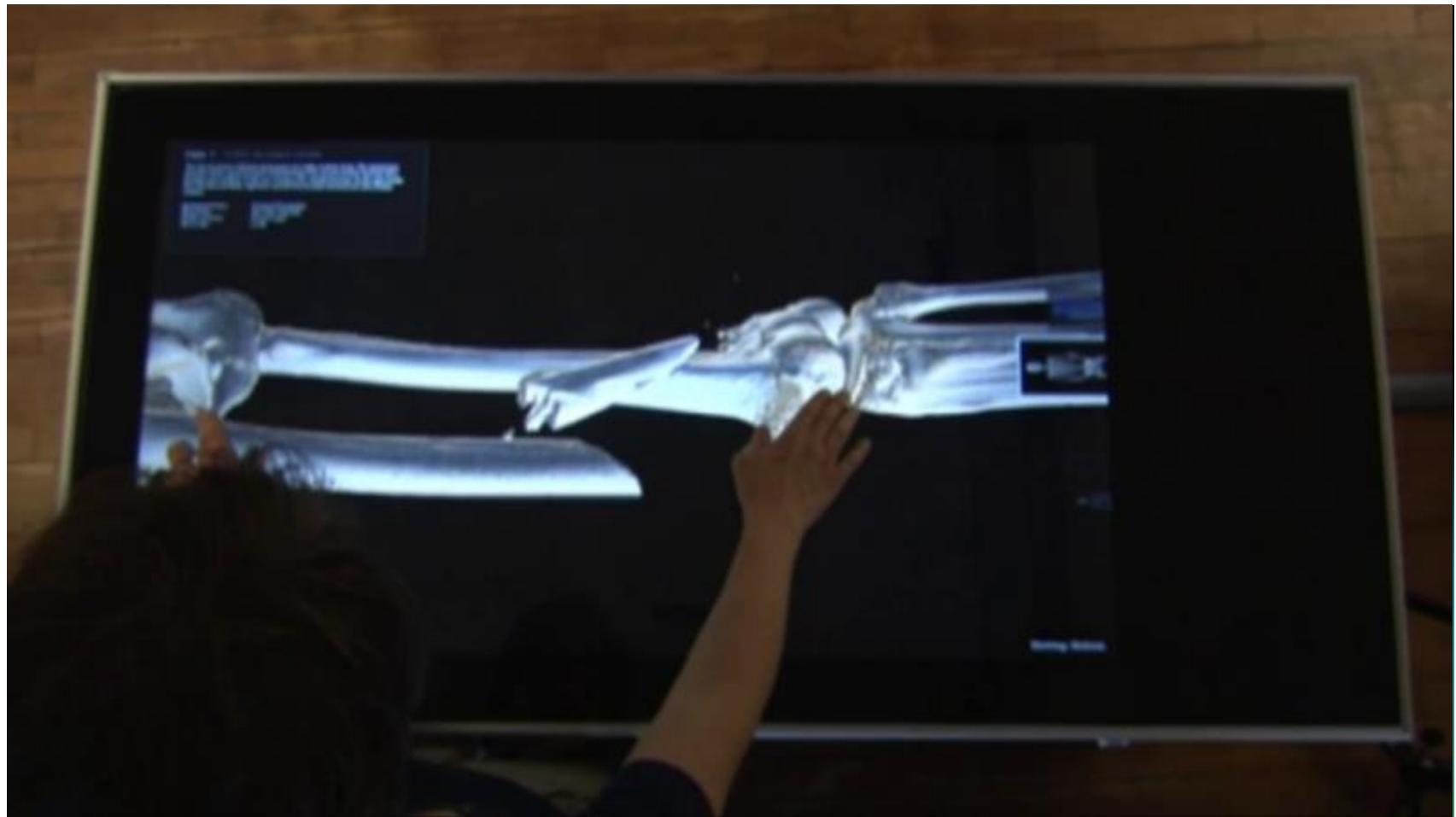
Contextual cutaway



[Burns et al. 2007]

# Visualization – Examples

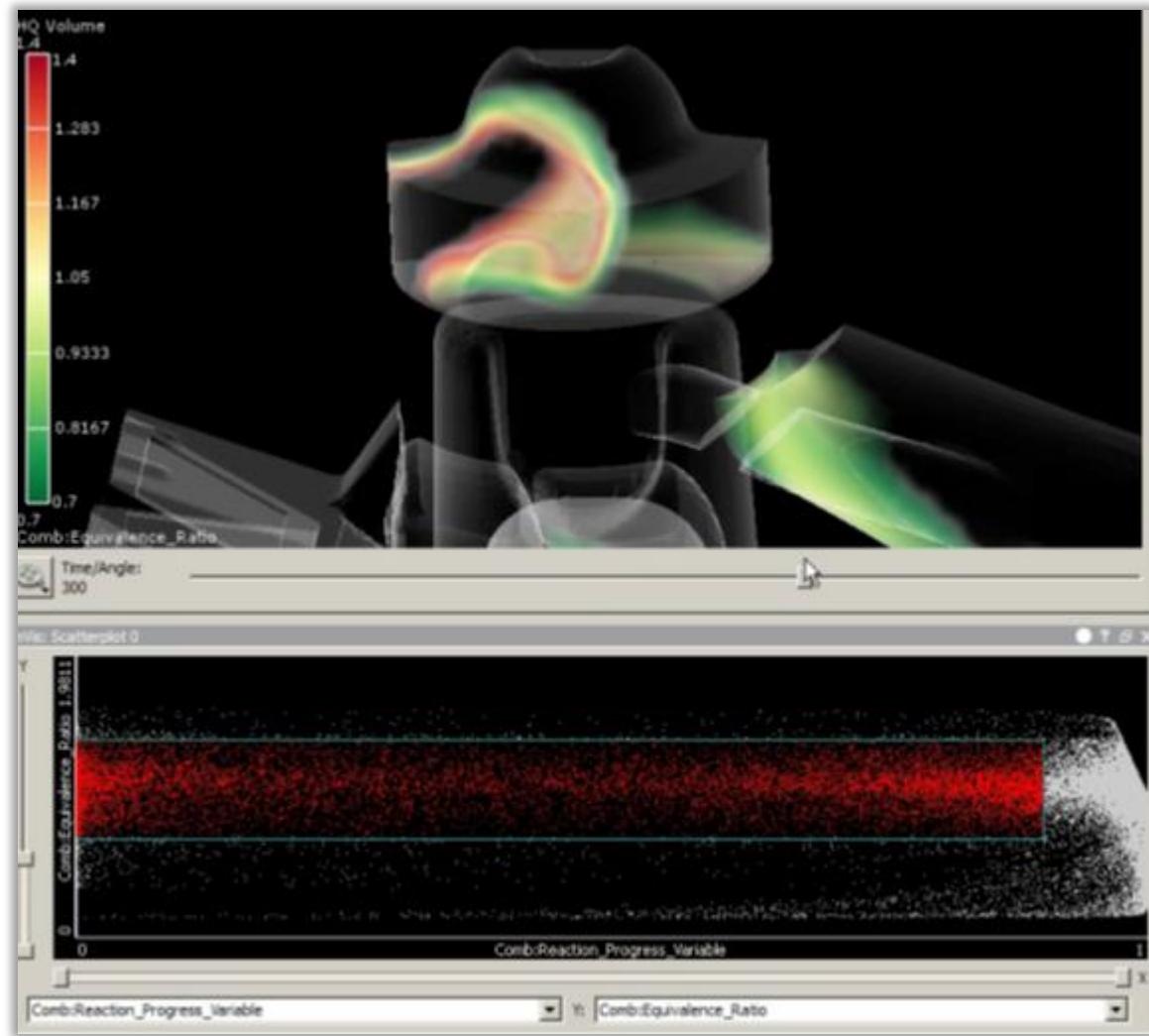
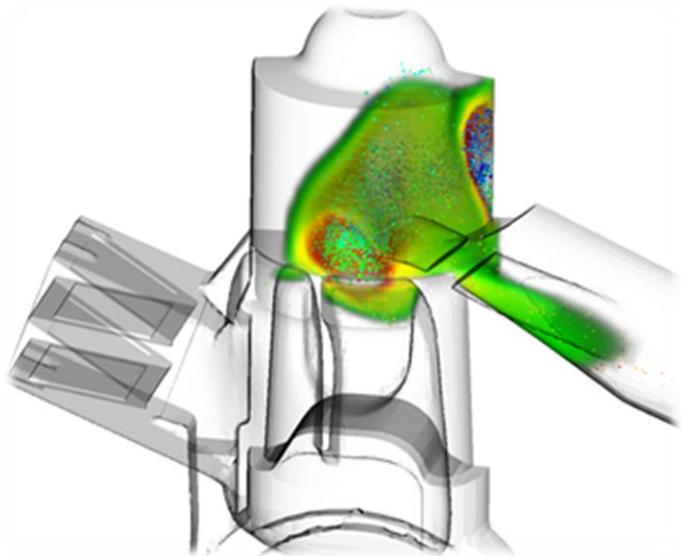
- Virtual Autopsy



<https://vimeo.com/6866296>

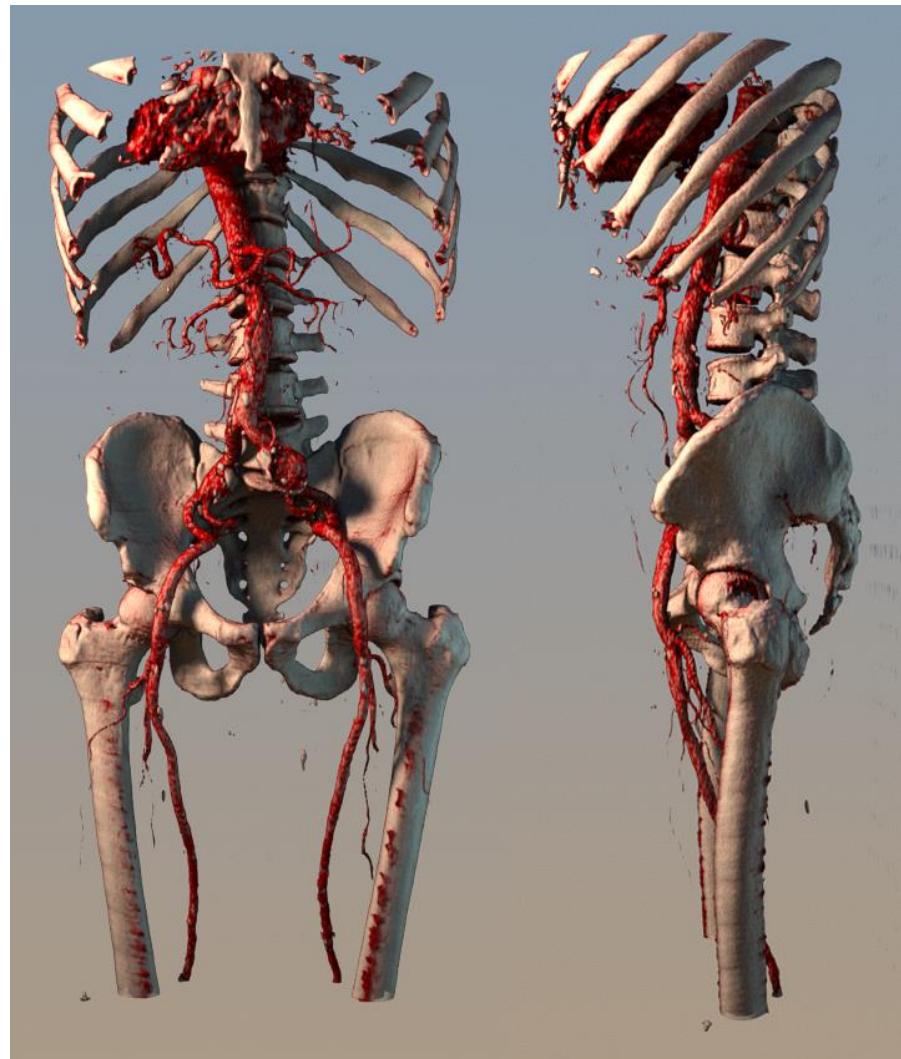
# Visualization – Examples

- Combustion process in a two-stroke engine



# Visualization – Examples

- Physically-based lighting



[Kroes et al. 2012]

# Volume visualization

- Volume rendering techniques
  - Techniques for 2D scalar fields (e.g. slicing)
  - Indirect volume rendering techniques (e.g. surface fitting)
    - Convert/reduce volume data to intermediate representation (surface representation), which can be rendered with traditional techniques – MC-algorithm
  - Direct volume rendering techniques
    - Consider the data as a semi-transparent gel with physical properties and directly get a 3D representation of it

Direct ve indirect volume rendering arasındaki fark nedir ?

Direct volume rendering, veri setinin doğrudan ekrana yansıtılmasını sağlar. Bu yöntem, veri setinin voxel değerlerine göre bir renk ataması yaparak, görüntüde gösterilen nesnelerin kalınlıklarını ve şekillerini belirler. Bu yöntem, veri setinin tamamını bir anda görüntüler ve katmanlı görüntüler oluşturmaz.

Indirect volume rendering ise, veri setinin önceden hesaplanan görüntülerini kullanır. Bu görüntüler, veri setinin voxel değerlerine göre oluşturulan "örtü"lerdir. Örtüler, veri setinin bir kesiti olarak düşünülebilir ve her bir örtü, veri setinin bir zaman diliminde ne gibi değişiklikler gösterdiğini gösterir. Bu örtüler arasında geçiş yaparak, veri setinin değişimlerini izleyebilirsiniz.

Direct volume rendering yöntemi, veri setinin tamamını bir anda görüntülerken, indirect volume rendering yöntemi ise veri setinin değişimlerini zaman içinde izlemek için kullanılır.

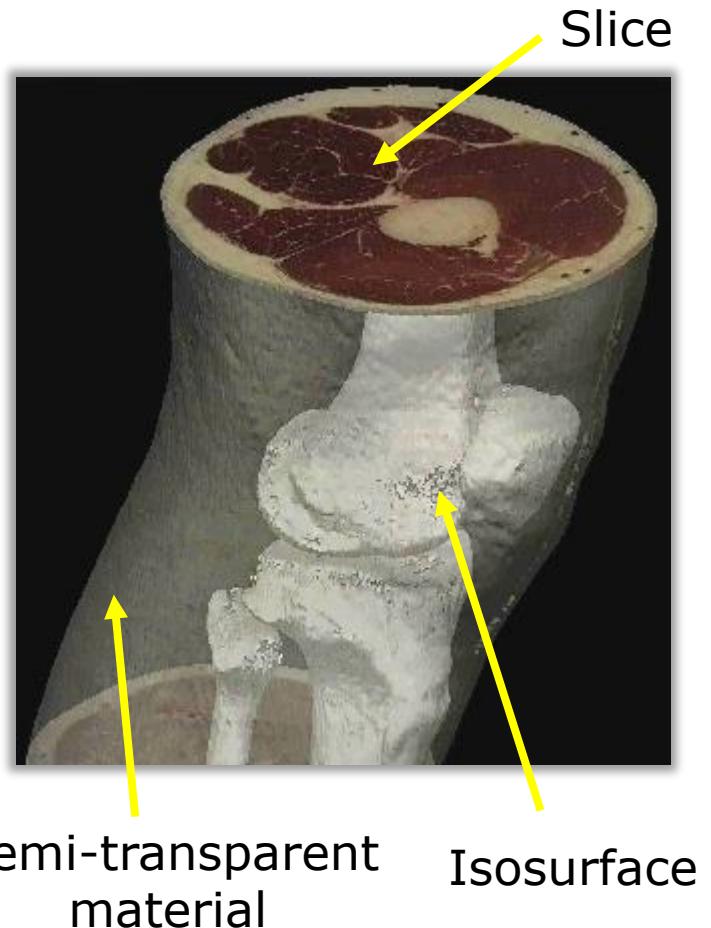
## Voxel değerleri nedir ve direct volume renderingde nasıl kullanılır

Voxel, veri setlerinde kullanılan 3 boyutlu piksellere verilen isimdir. Her voxel, veri setinin bir noktasını temsil eder ve bu noktanın koordinatları ile birlikte, bir değer içerir. Bu değer, voxelin belirli bir özelliğini temsil eder. Örneğin, bir CT görüntüsünde voxel değerleri, voxelin belirli bir bölgede bulunan doku yoğunluğunu gösterir.

Direct volume rendering yönteminde, voxel değerlerine göre bir renk ataması yapılır. Bu renk ataması, voxelin özelliğini göstermek için kullanılır. Örneğin, bir CT görüntüsünde, düşük yoğunlukta olan dokuların daha açık renklerle, yüksek yoğunlukta olan dokuların daha koyu renklerle gösterilmesi mümkündür. Bu renk ataması sayesinde, veri setindeki nesnelerin kalınlıkları ve şekilleri belirlenir ve görüntüde görülebilir hale gelir.

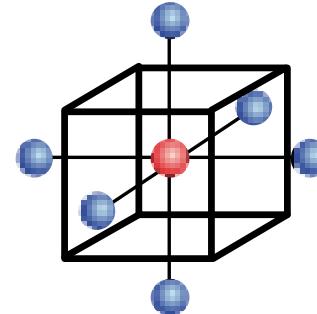
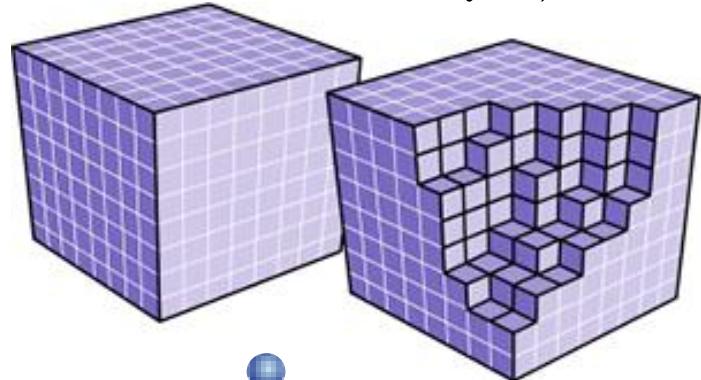
# Volume visualization

- **Slicing**  
Display volume data, mapped to colors, on a slice plane
- **Iso-surfacing**  
Generate opaque/semi-opaque surfaces (e.g., via the MC-Algorithm)
- **Direct Volume Rendering**  
Volume material attenuates reflected or emitted light

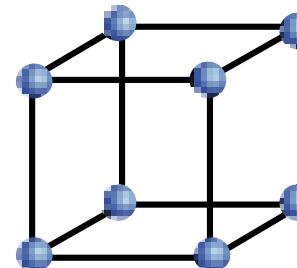


# Volume visualization

- Data values are initially given at vertices of a **3D grid**
  - These are called **voxels** (volume elements)
    - **Voxel = point sample in 3D**

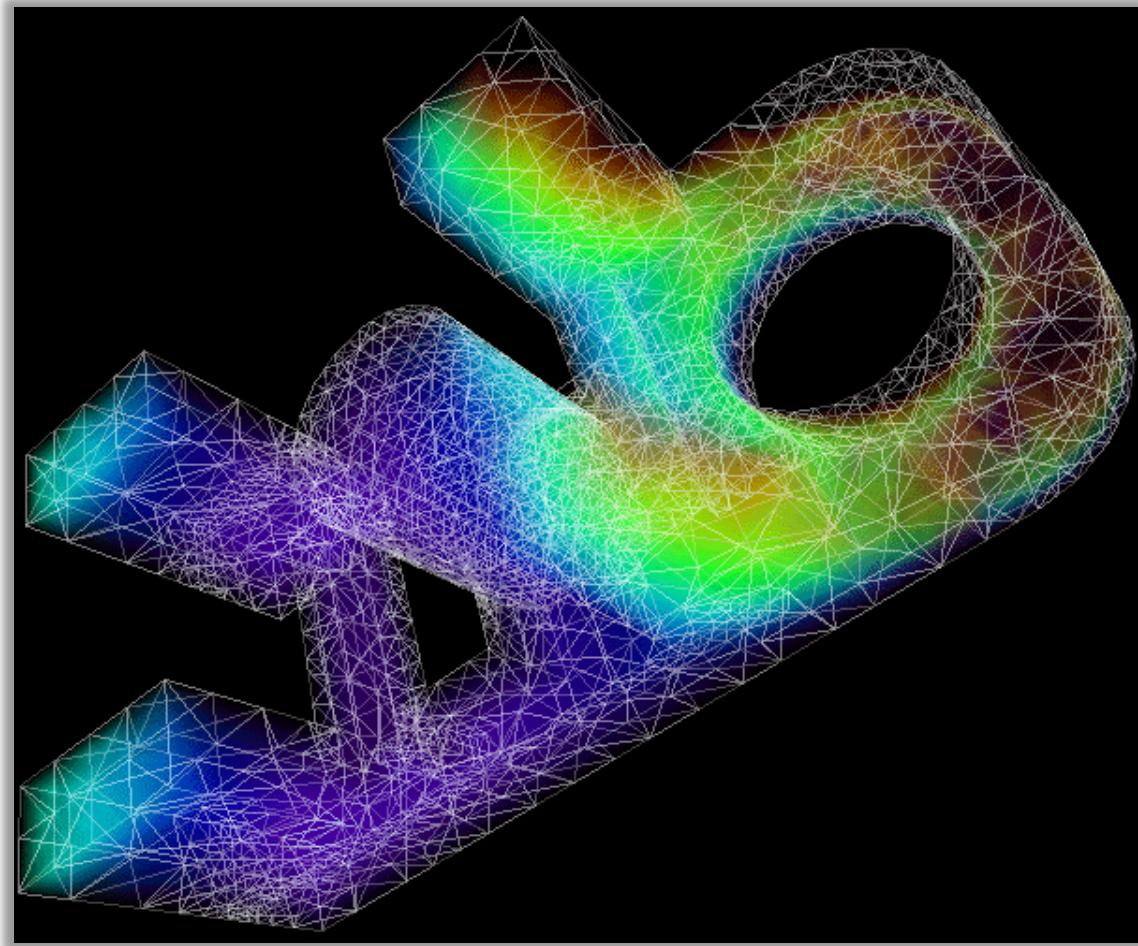


- “Adjacent” grid vertices make up a **cell**
  - Use interpolation for data **reconstruction** in a cell
  - Corners: 8 voxel



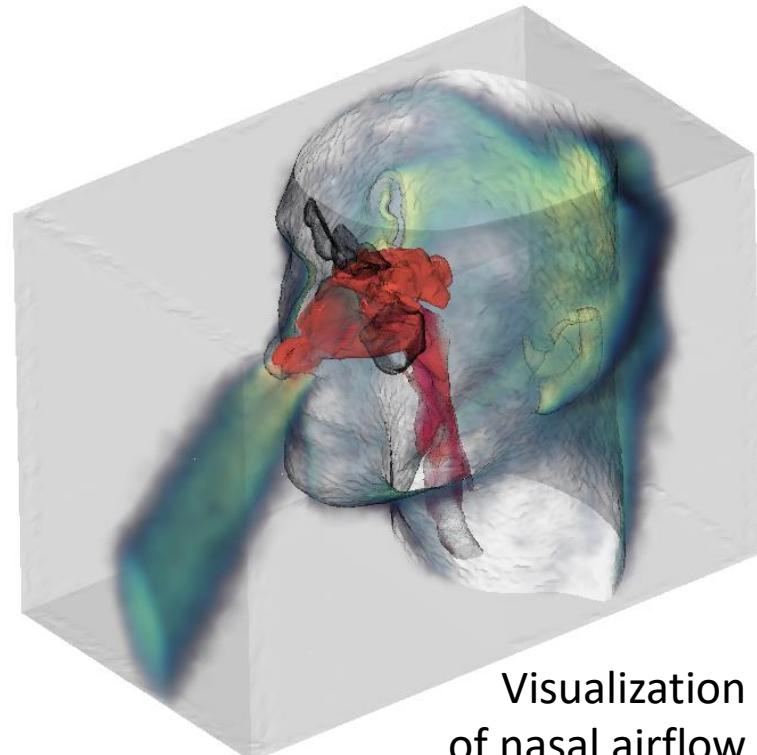
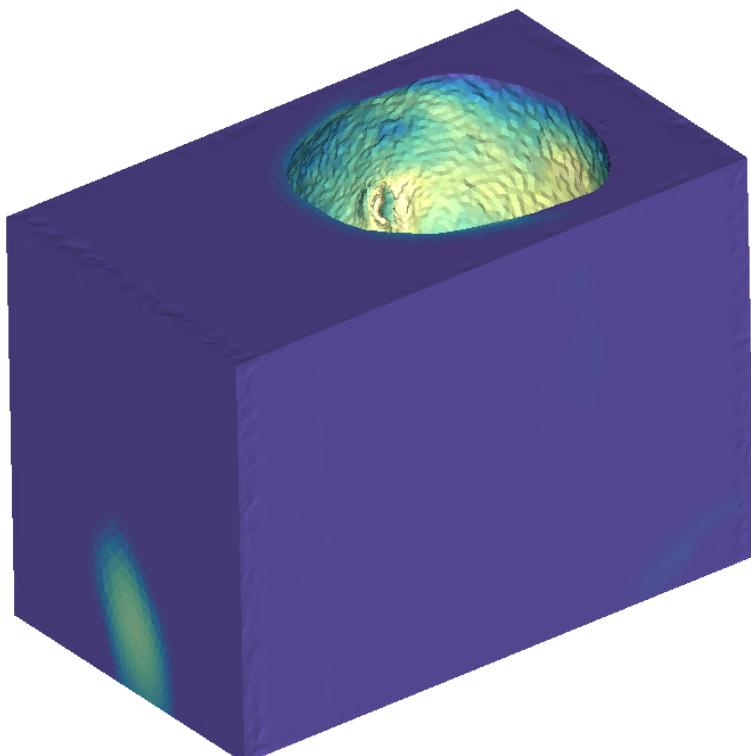
# Volume visualization

- A volumetric object has...
  - a **shape** (given by the geometry of the 3D grid)
  - an **appearance** (given by the data values)



# Volume visualization

- Some characteristics of volume data
  - Essential information in the **interior**
  - Often cannot be described by a **surface** in general (e.g., fire, clouds, gaseous phenomena)



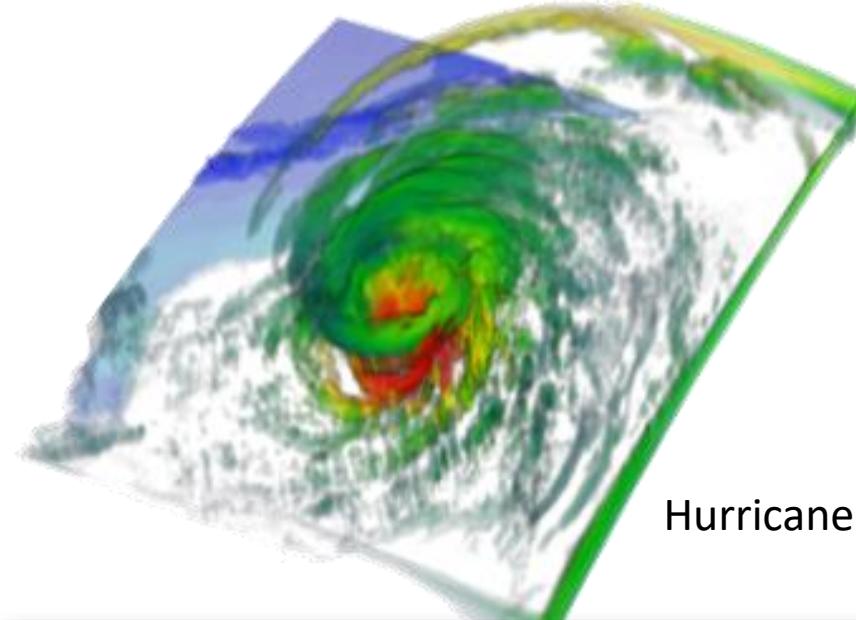
Visualization  
of nasal airflow

# Volume visualization

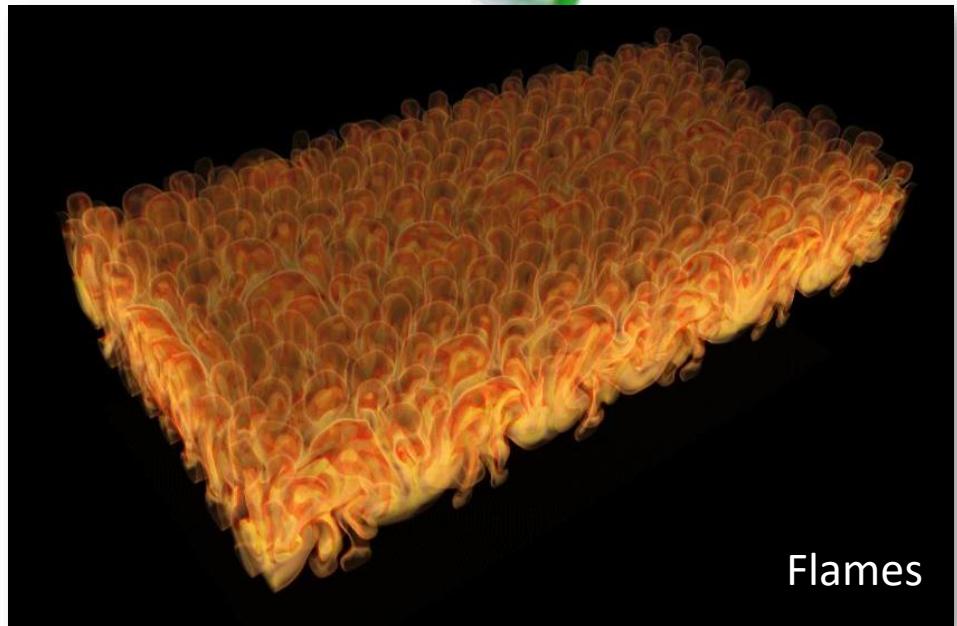
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Clouds



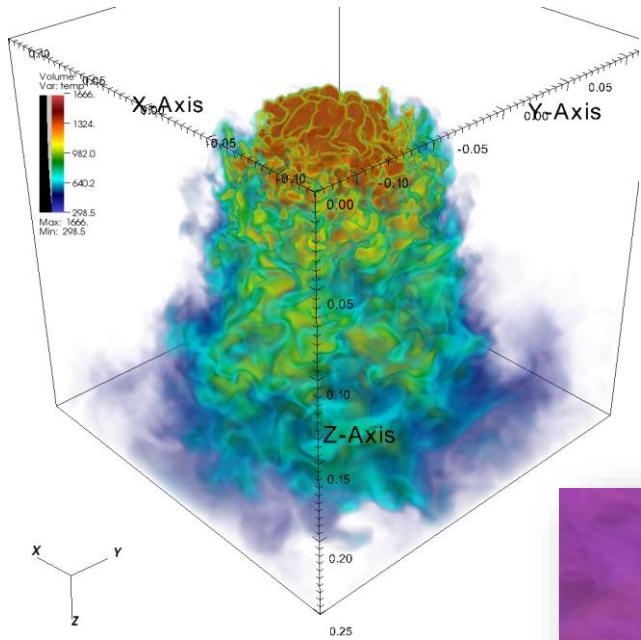
Hurricane



Flames

# Volume visualization

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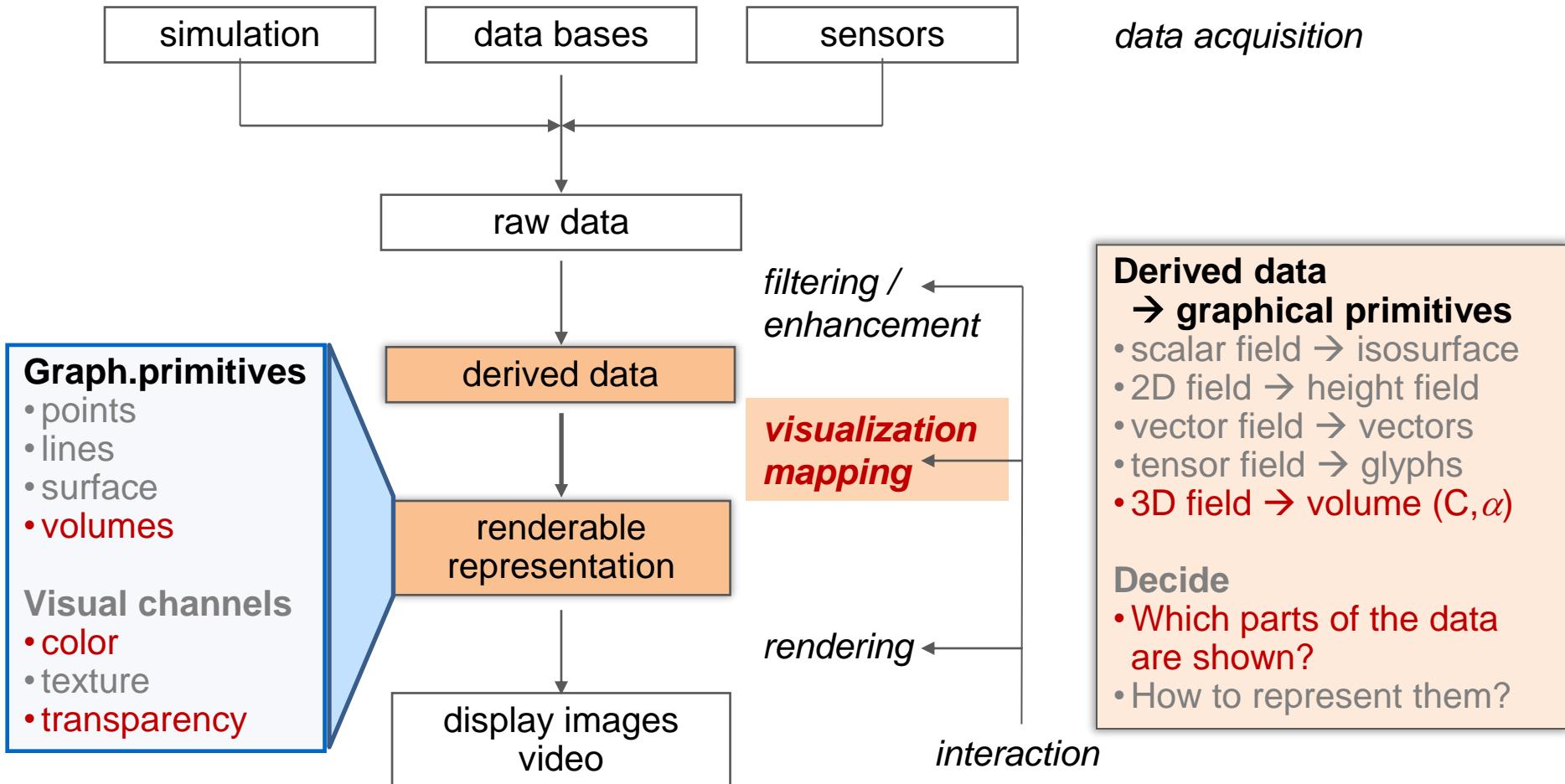


Hydrogen flame



Millennium Simulation: Distribution of matter in the Universe

# Volume Visualization



**Derived data**  
→ **graphical primitives**

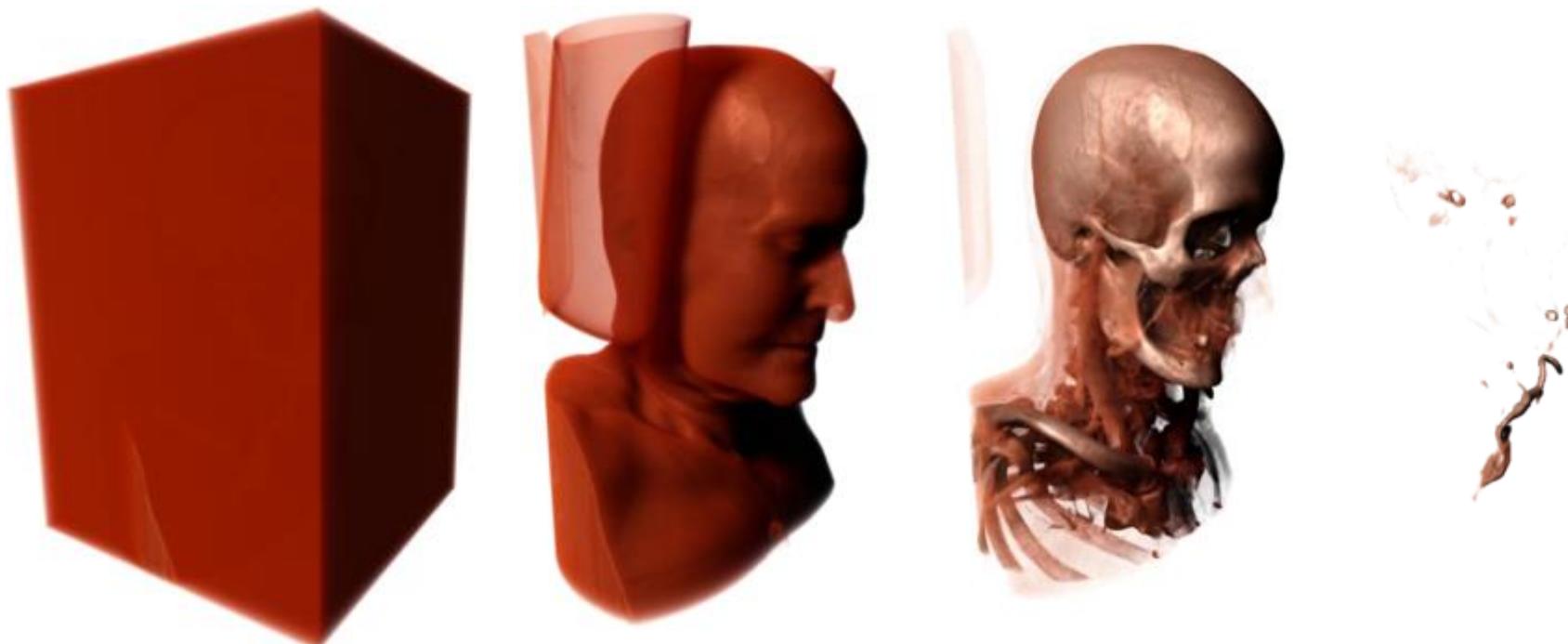
- scalar field → isosurface
- 2D field → height field
- vector field → vectors
- tensor field → glyphs
- **3D field → volume ( $C, \alpha$ )**

**Decide**

- Which parts of the data are shown?
- How to represent them?

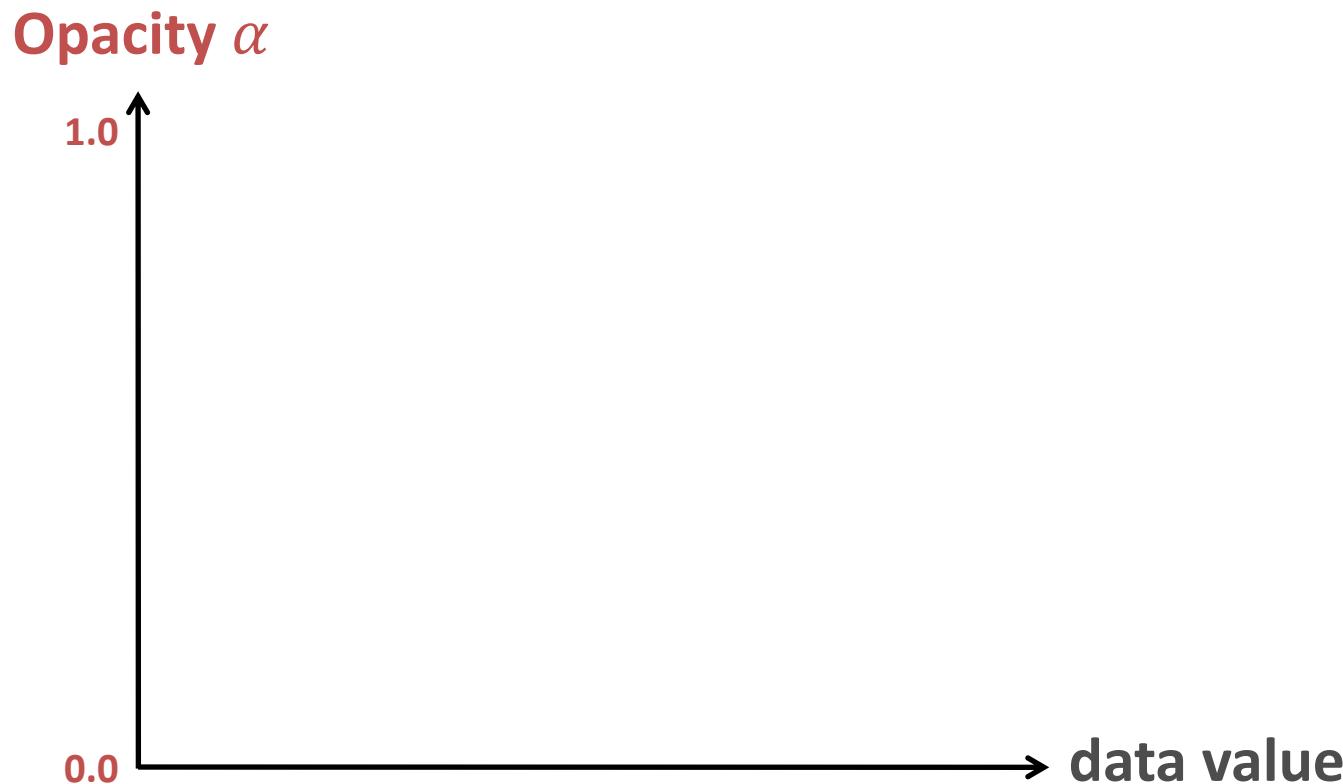
# Volume visualization

- Before data is visualized, it has to be **classified**, i.e., data values are mapped to visual properties like color and opacity
- Mapping is performed via a **transfer function**



# Volume visualization

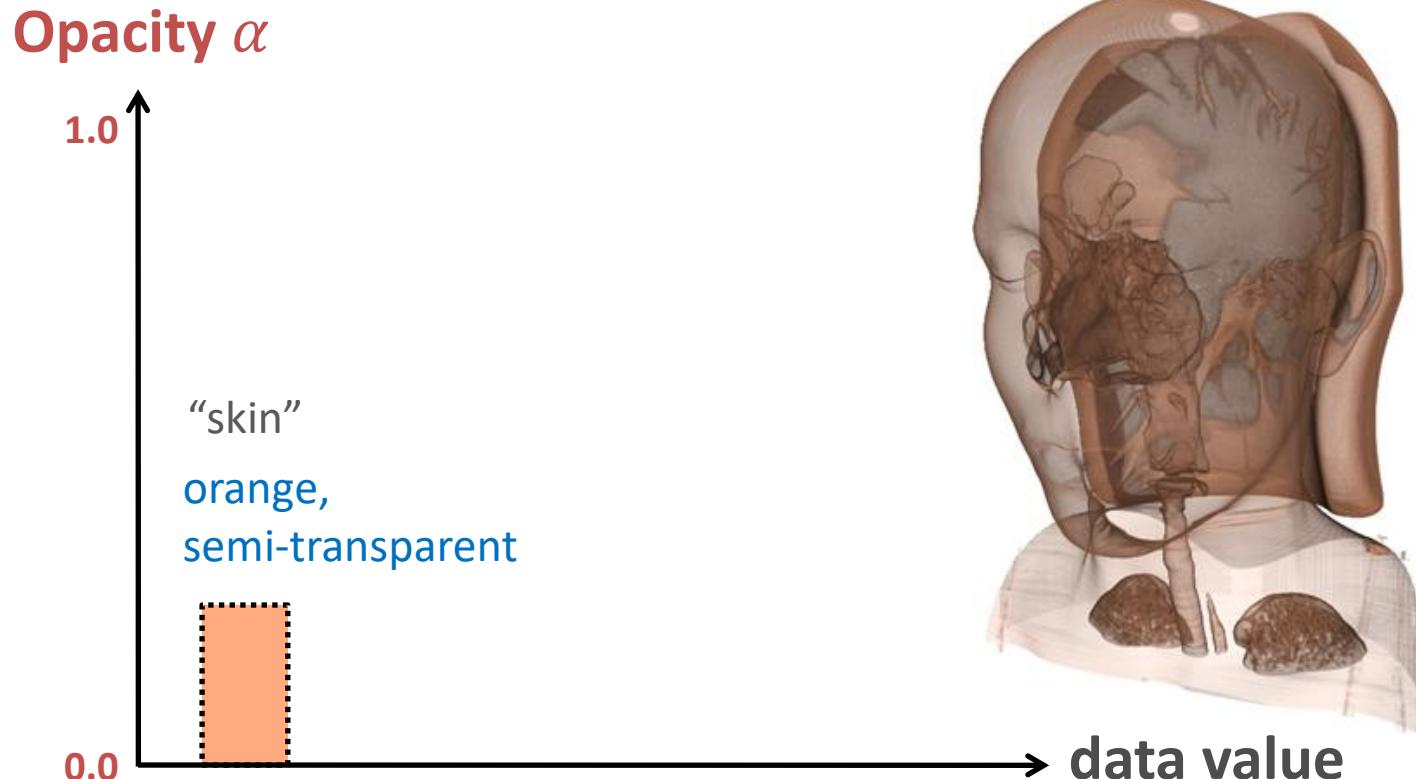
- Transfer function
  - Associate distinct materials (value ranges) to distinct properties (color & opacity)



# Volume visualization

- Transfer function
  - Data value → color:
  - Data value → opacity:

$$f(x) \rightarrow C(x)$$
$$f(x) \rightarrow \alpha(x)$$

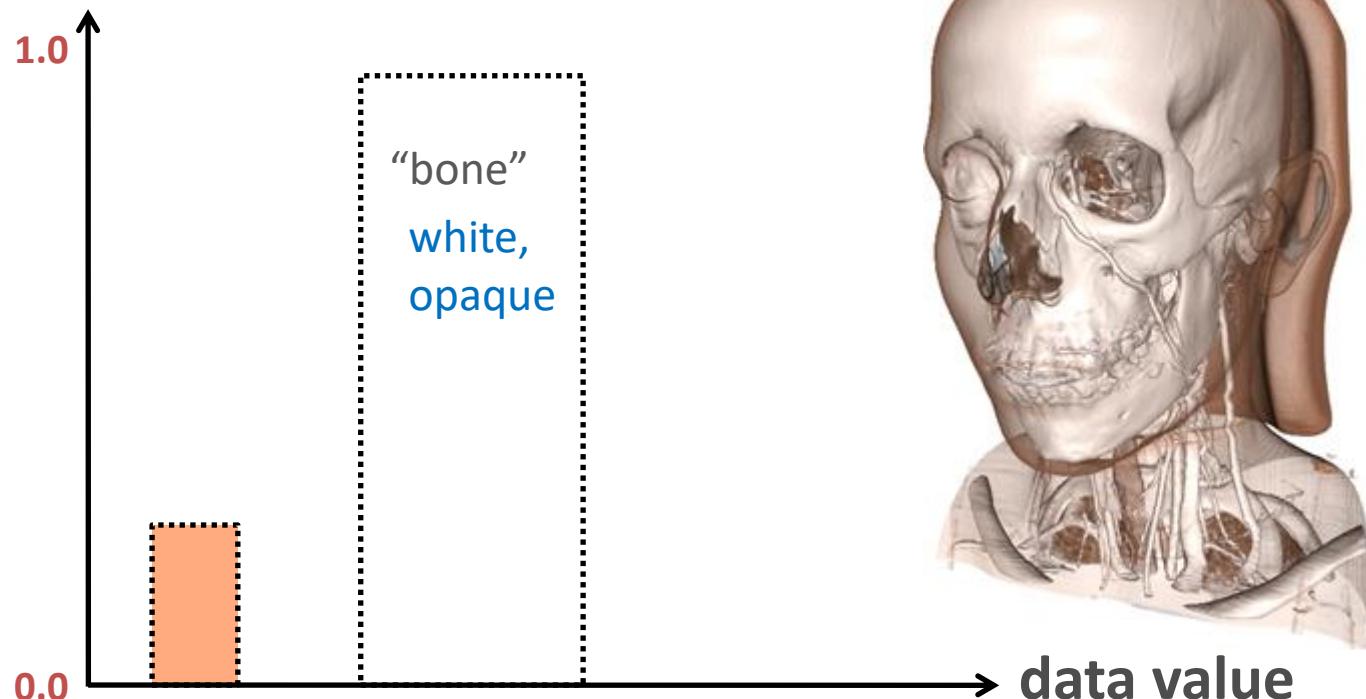


# Volume visualization

- Transfer function
  - Data value → color:
  - Data value → opacity:

$$f(x) \rightarrow C(x)$$
$$f(x) \rightarrow \alpha(x)$$

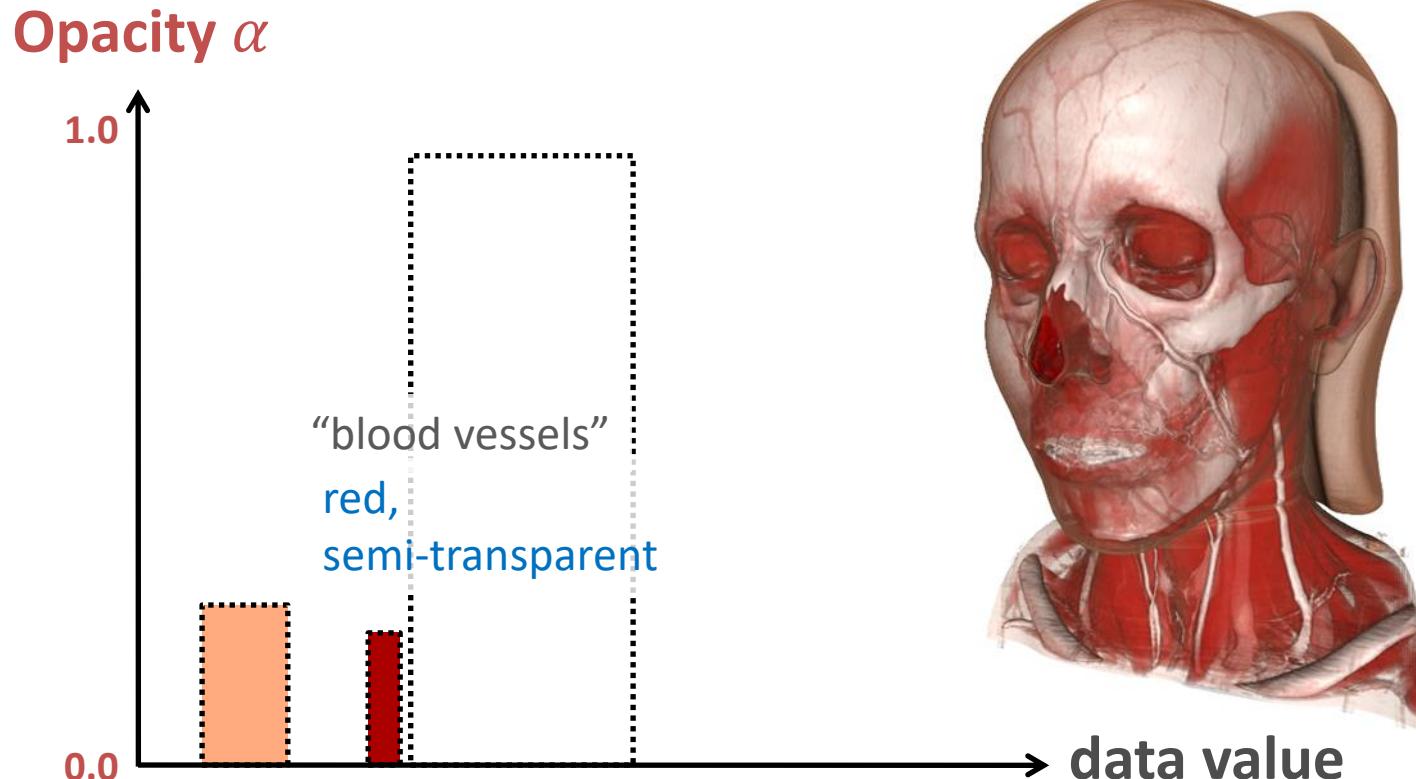
Opacity  $\alpha$



data value

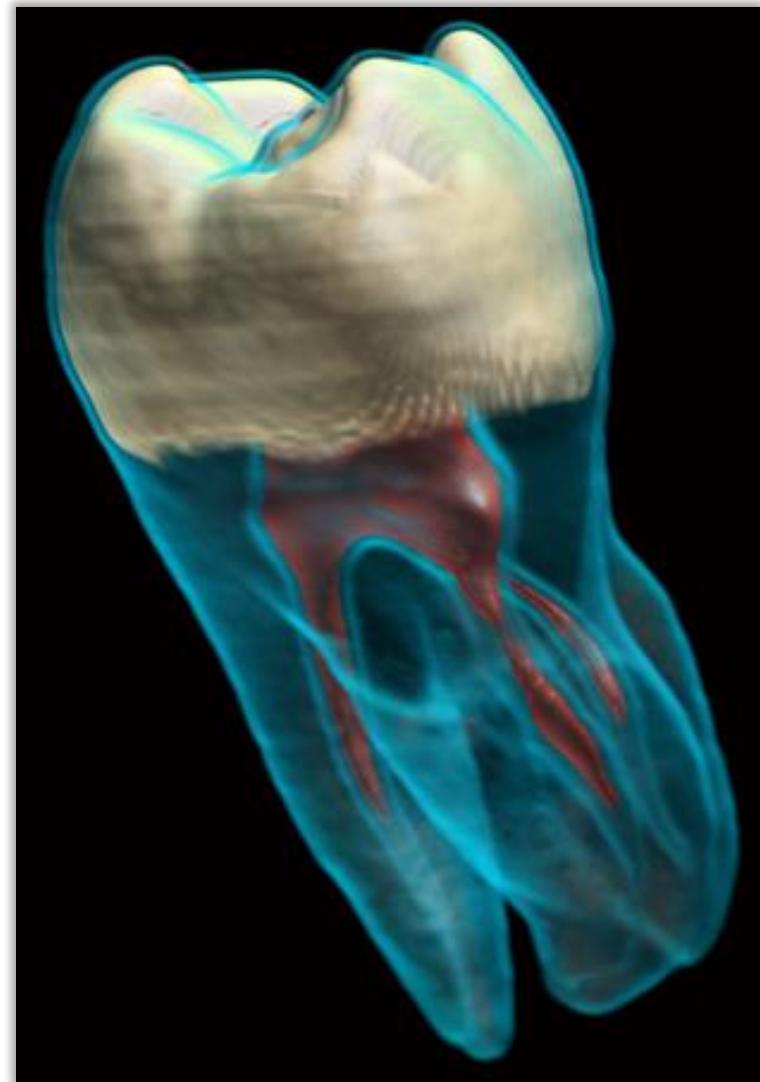
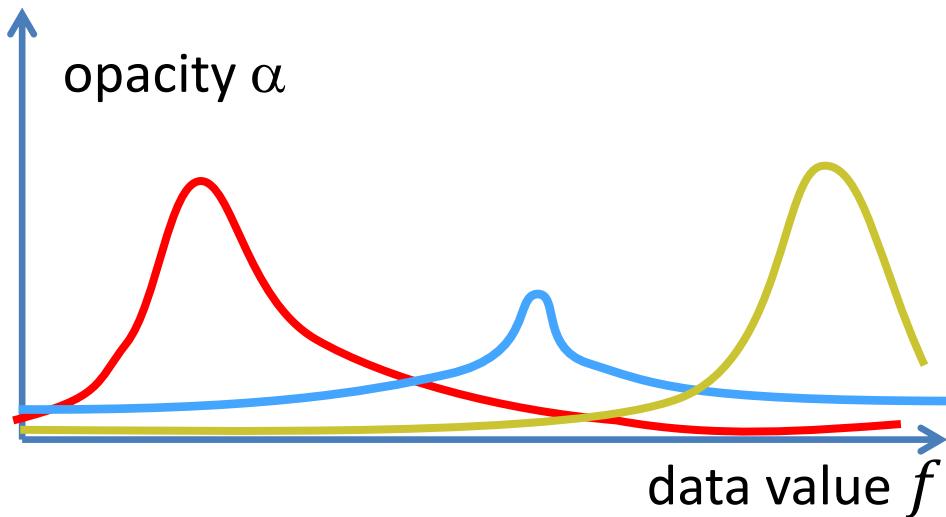
# Volume visualization

- Transfer function
  - Data value → color:  $f(x) \rightarrow C(x)$
  - Data value → opacity:  $f(x) \rightarrow \alpha(x)$



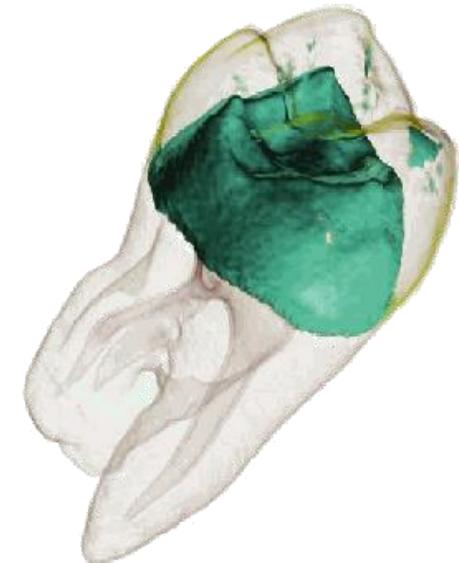
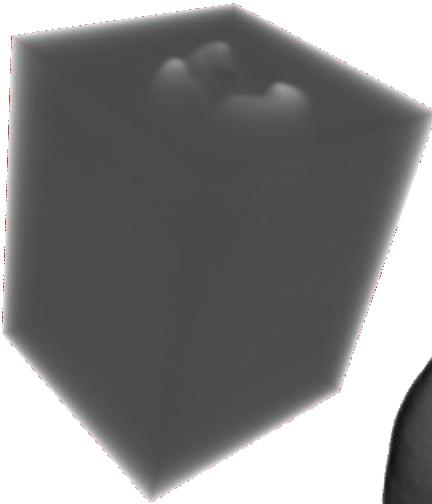
# Volume visualization

- Transfer function design



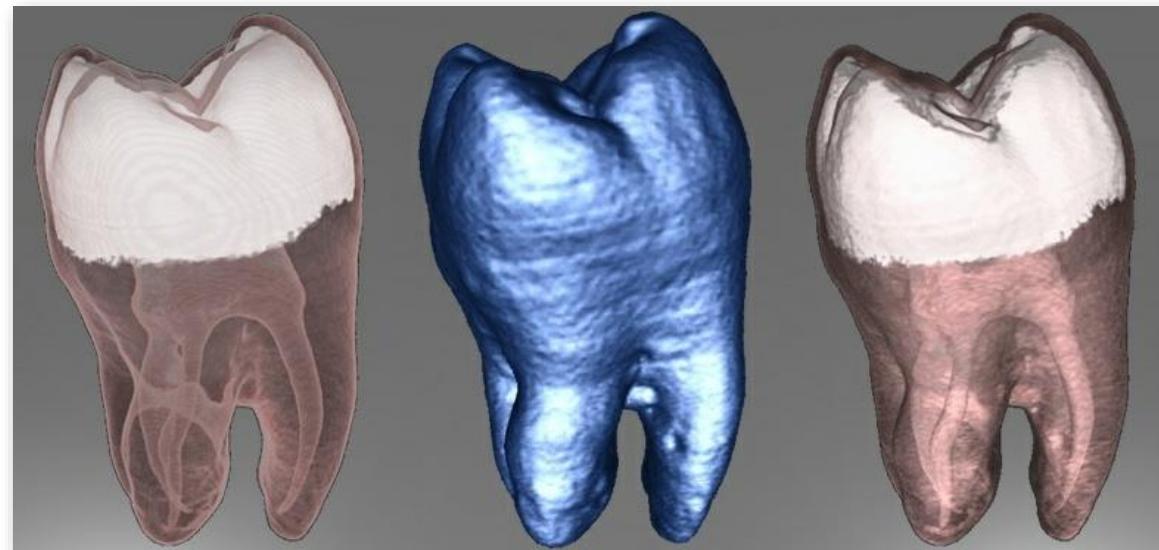
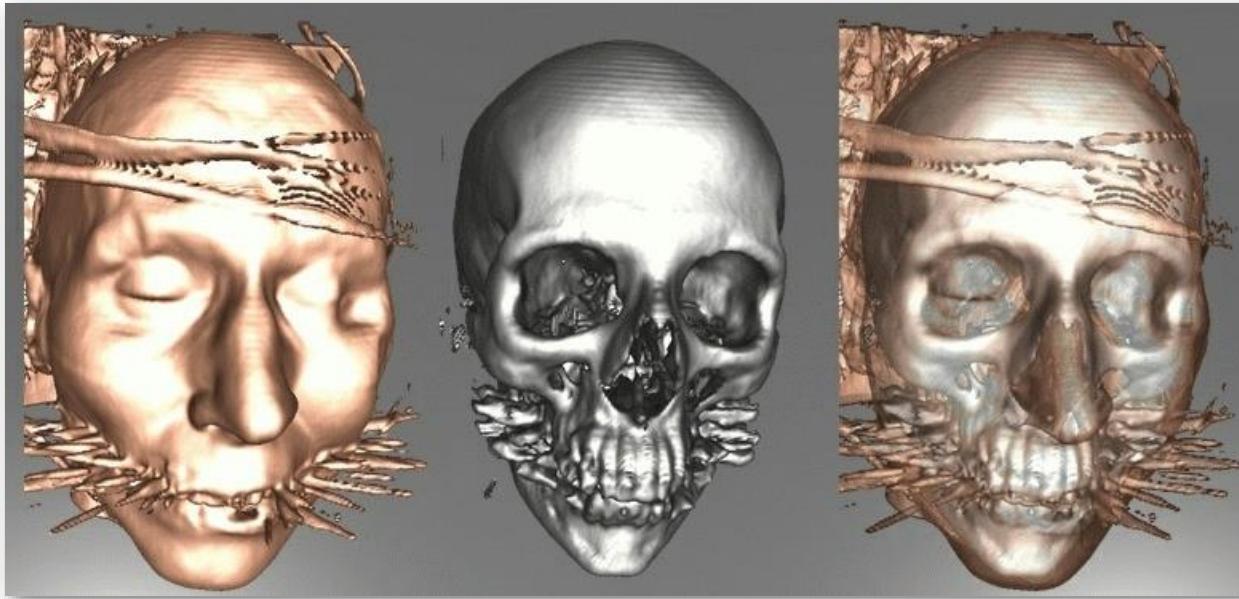
# Volume visualization

- Examples of different transfer functions for the same dataset



# Volume visualization

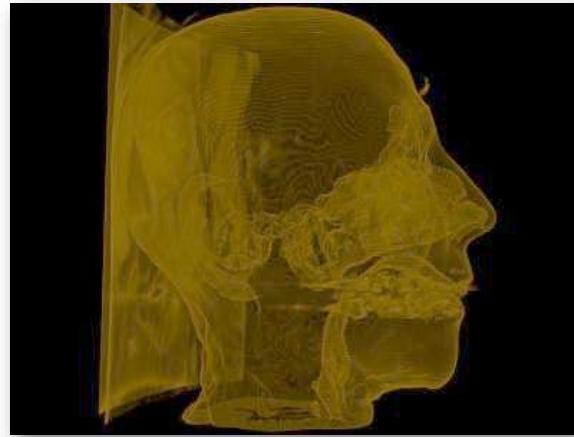
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[Engel et al. 06, Krüger & Westermann 03]

# Volume visualization

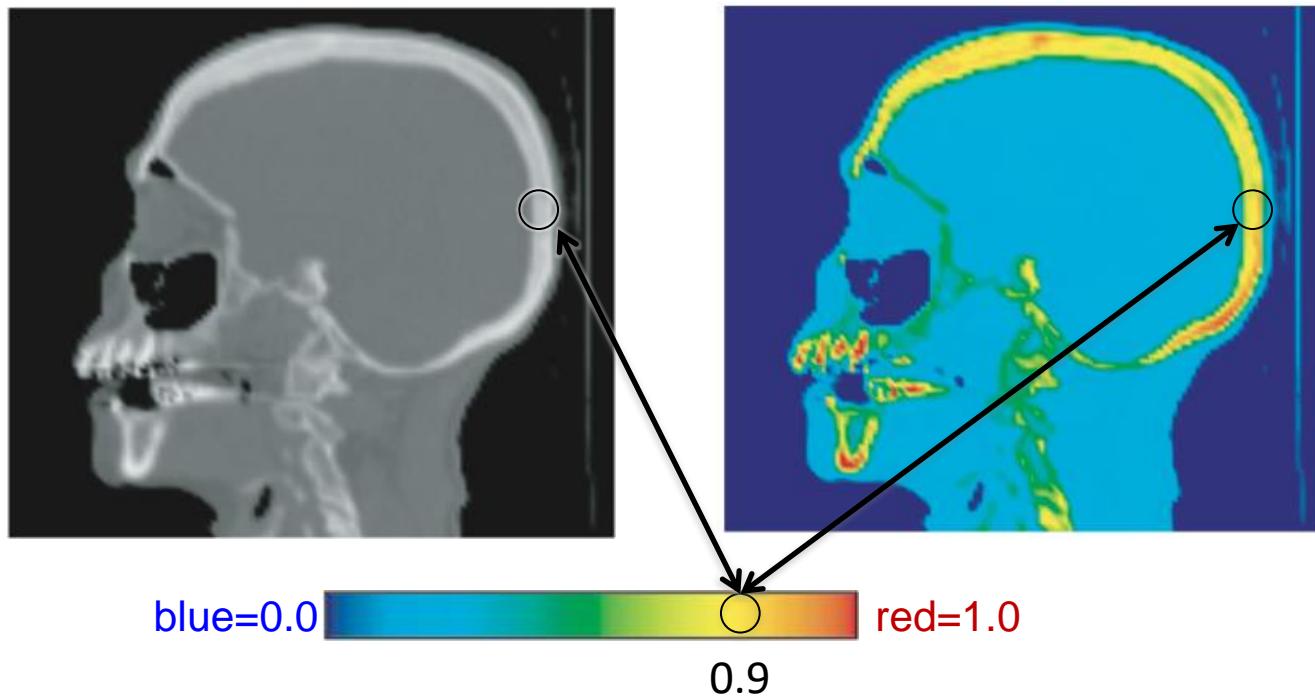
- Note that color is a material property
- Note that **opacity  $\alpha$**  is also such a property and can be assigned as well!
- Color is then a quadrupel (**RGB $\alpha$** )



# Volume visualization

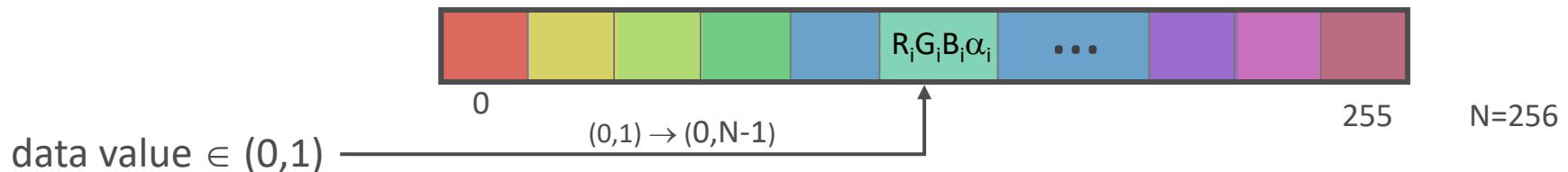
- Color mapping for scalar data
  - Assign a different color to each scalar value
  - Assignment via a so-called **transfer function  $T$**

$T : \text{scalar value} \rightarrow \text{color} + \alpha\text{-value}$



# Volume visualization

- Color mapping for scalar data
  - Assign a different color to each scalar value
  - Assignment via a so-called **transfer function**  $T$   
 $T : \text{scalar value} \rightarrow \text{color} + \alpha\text{-value}$
  - Realization
    - RGBA-color values are stored in a **color table**
    - For a data value, the color at the corresponding entry in the table is used



# Direct volume rendering

- Get a 3D representation of the volume data taking into account emission and absorption



# Direct volume rendering

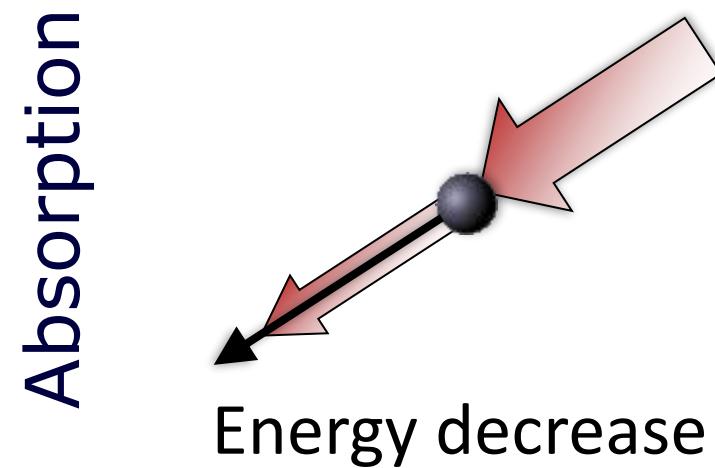
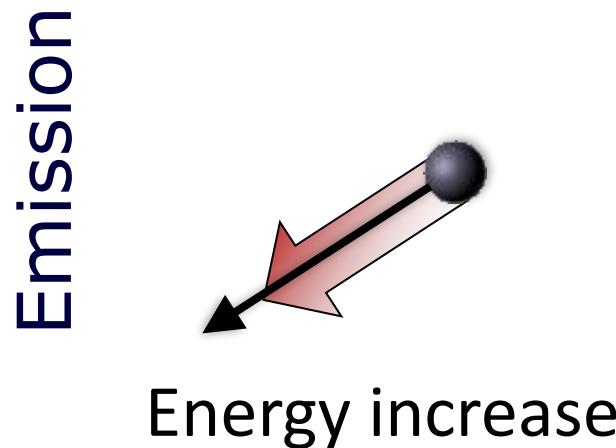
- Direct volume rendering (DVR) considers the physics of light transport in a dense medium
  - Optical properties are mapped to each voxel (emission = color, absorption = opacity)
  - The light reaching the viewer is simulated by ray casting

No need to extract intermediate explicit geometry (iso-surface)



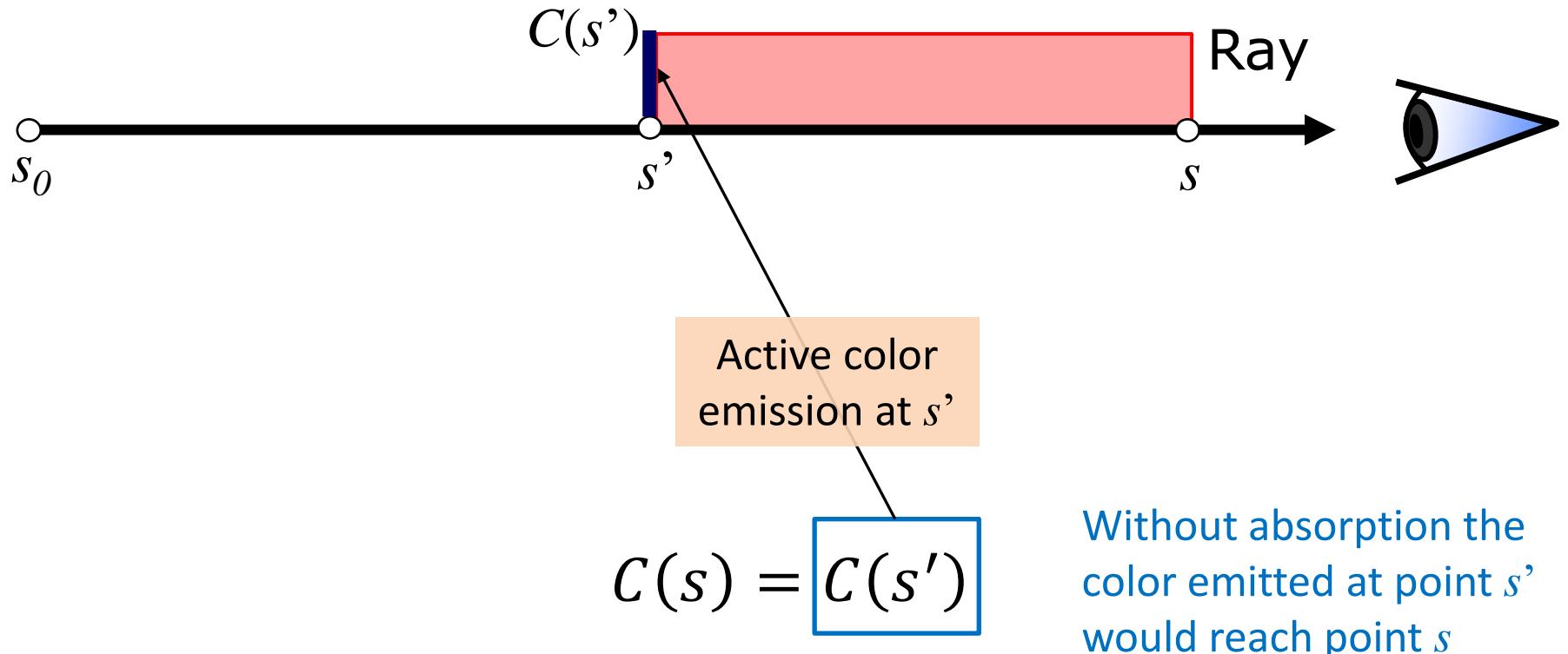
# Direct volume rendering

- Direct volume rendering
  - The collection of light along straight rays is based on an **emission/absorption model**
  - Assumption: Volume consists of small particles
  - Each voxel **emits light** of the color which is assigned to it, and **absorbs light** according to it's opacity



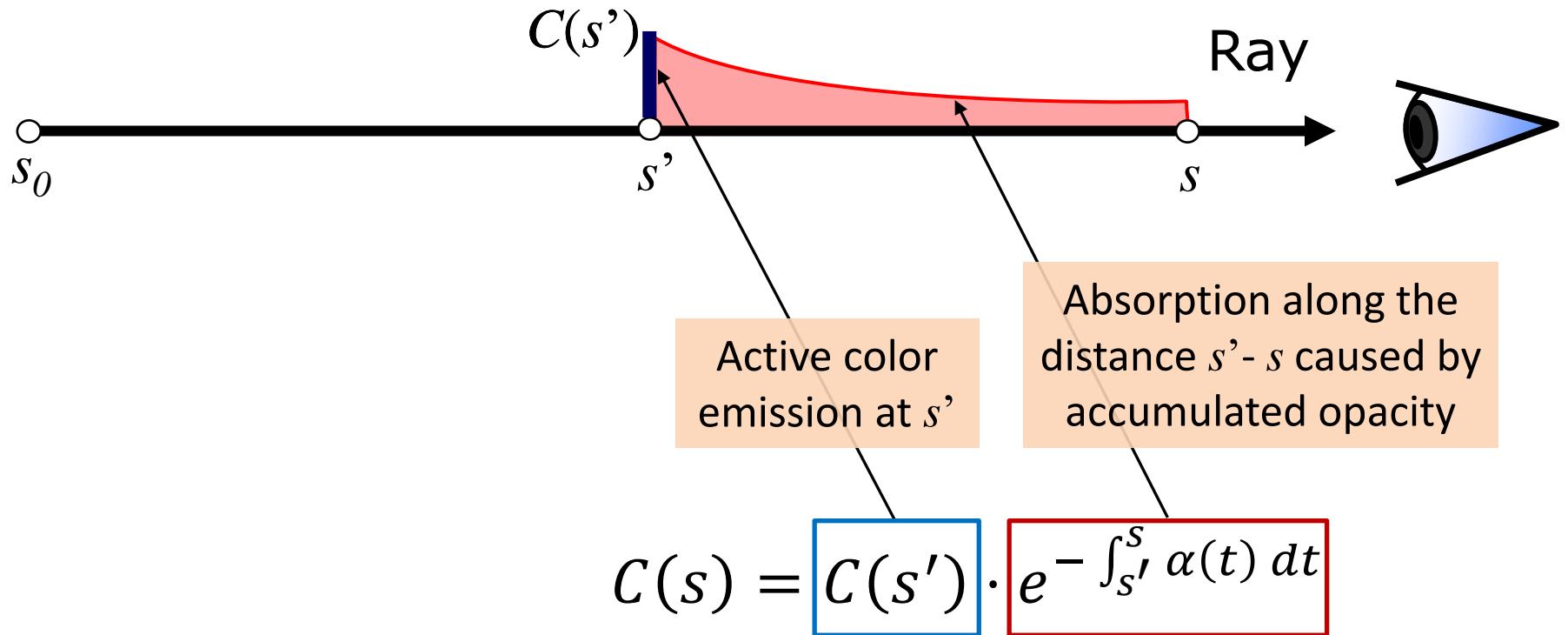
# Light emission and attenuation

- The volume rendering integral



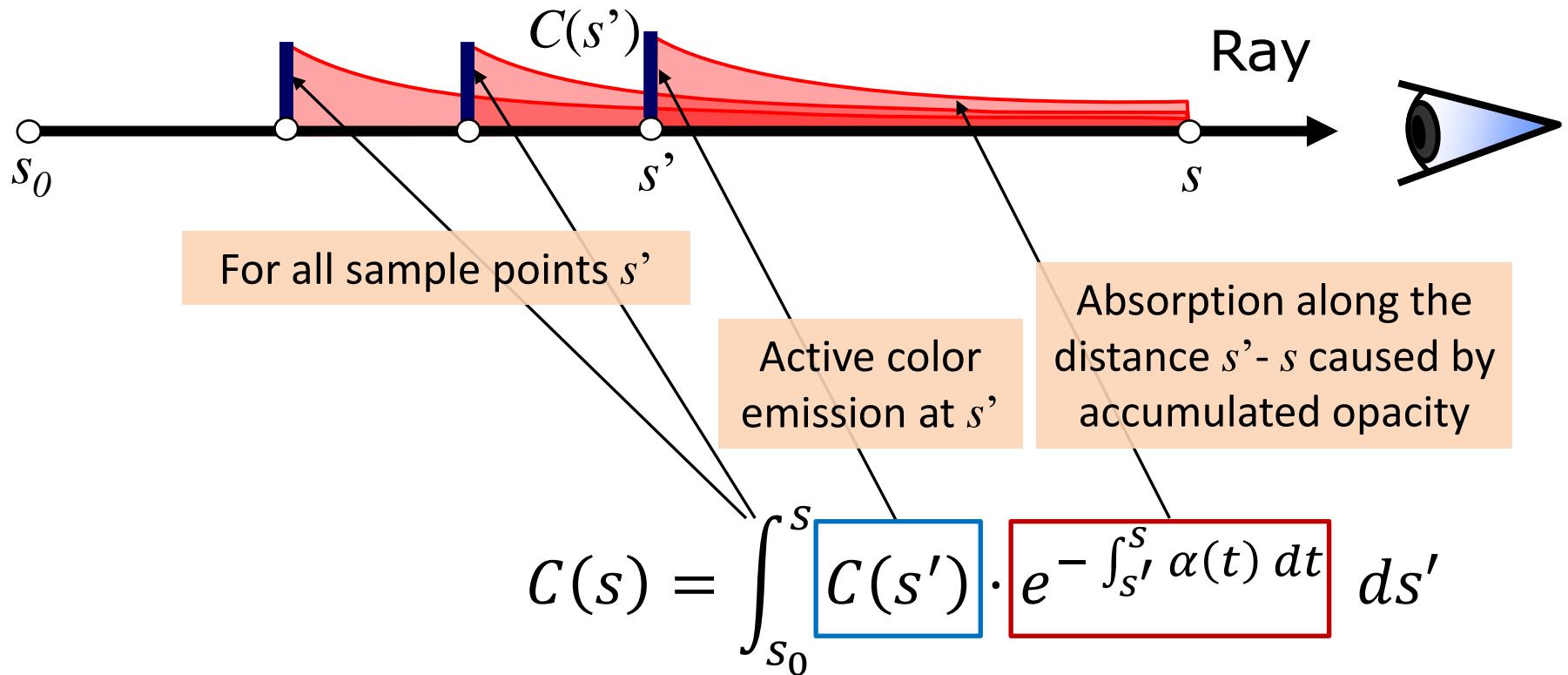
# Light emission and attenuation

- The volume rendering integral



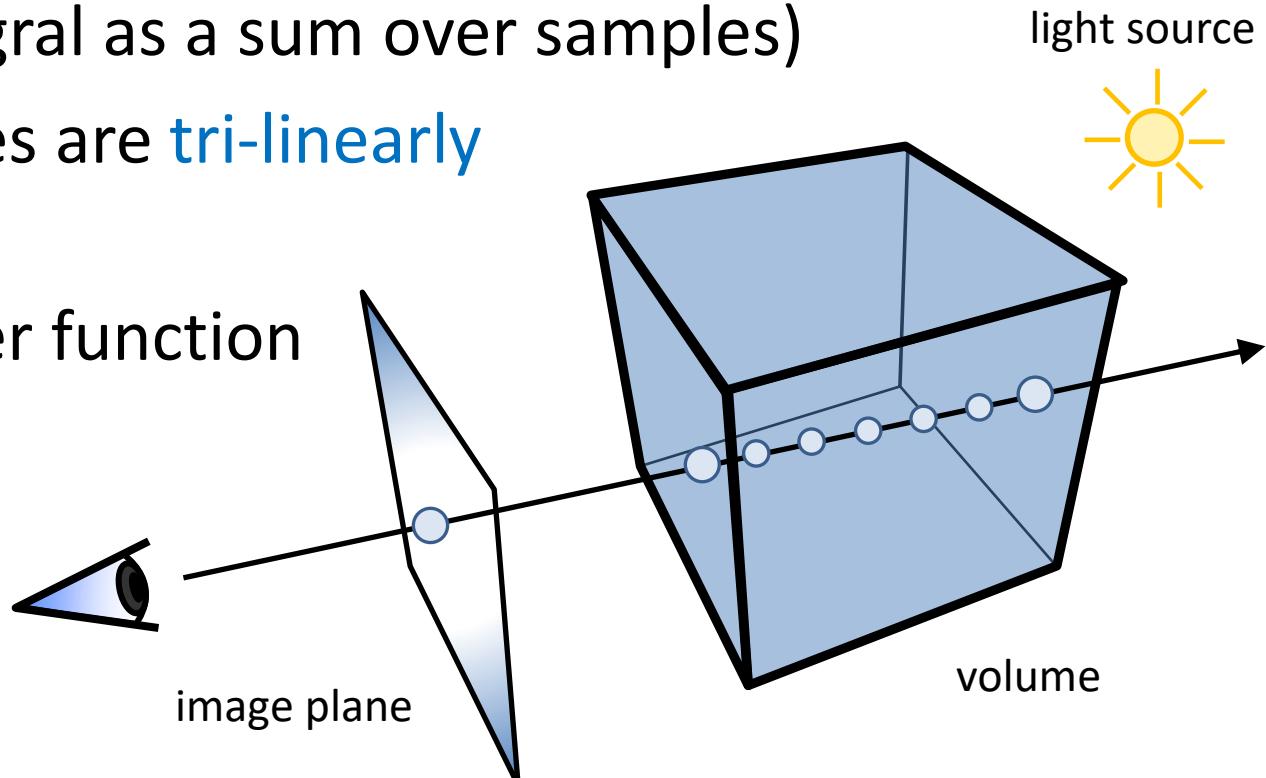
# Light emission and attenuation

- The volume rendering integral



# Direct volume rendering

- **Ray-casting:** Numerical approximation of the volume rendering integral
  - A ray is cast into volume for each output pixel
  - Volume is **resampled** at equidistant intervals along the ray (integral as a sum over samples)
  - Sample values are **tri-linearly interpolated**
  - Apply transfer function



# Direct volume rendering

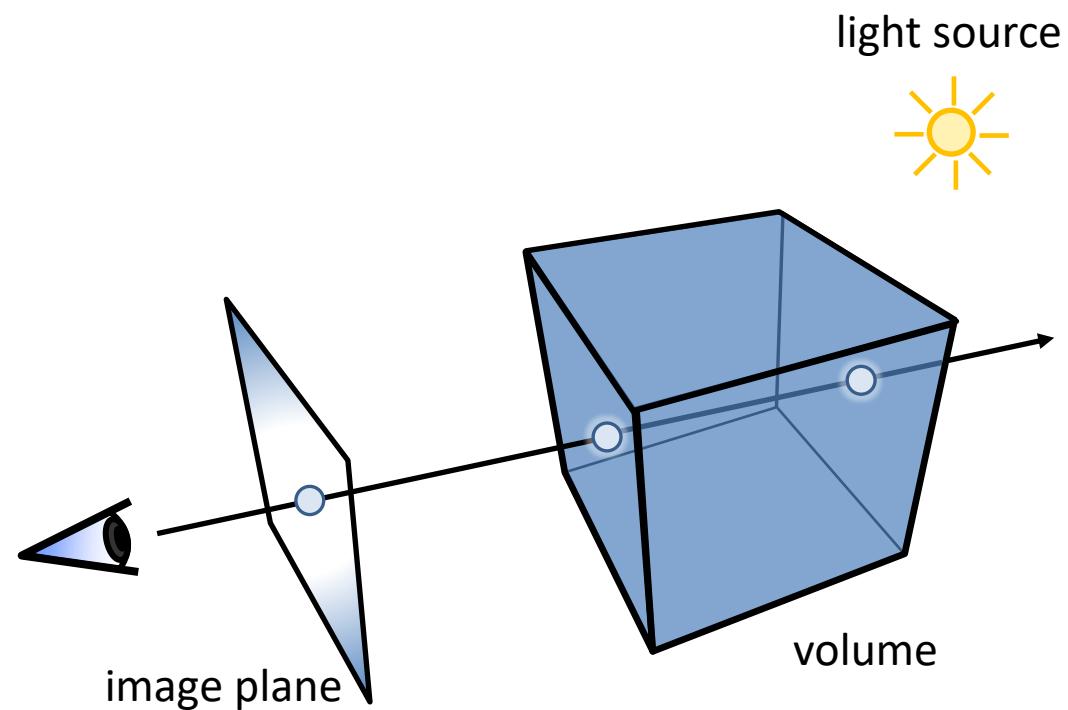
- **Ray-casting method**

- Defines a virtual image plane where viewer is looking through
- Cast a ray through every pixel on the screen

**for each** pixel on the image plane

compute entry- and exit-point in volume

**end for**



# Direct volume rendering

- Ray-casting method
  - Defines a virtual image plane where viewer is looking through
  - Cast a ray through every pixel on the screen

for each pixel on the image plane

compute entry- and exit-point in volume

**while** current position inside volume

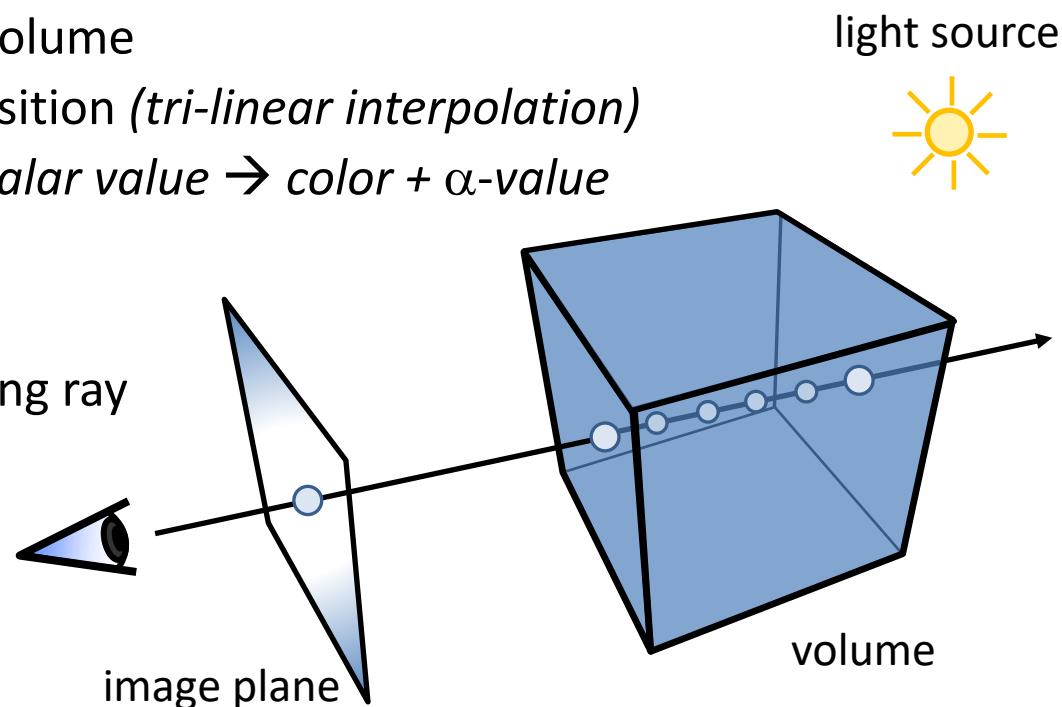
read density at current position (*tri-linear interpolation*)

apply transfer function: *scalar value* → *color + α-value*

compute new position along ray

**end while**

**end for**



# Direct volume rendering

- Ray-casting method
  - Defines a virtual image plane where viewer is looking through
  - Cast a ray through every pixel on the screen

for each pixel on the image plane

    compute entry- and exit-point in volume

**while** current position inside volume

        read density at current position

        apply transfer function: *scalar value*  $\rightarrow$  *color + α-value*

        compute shading

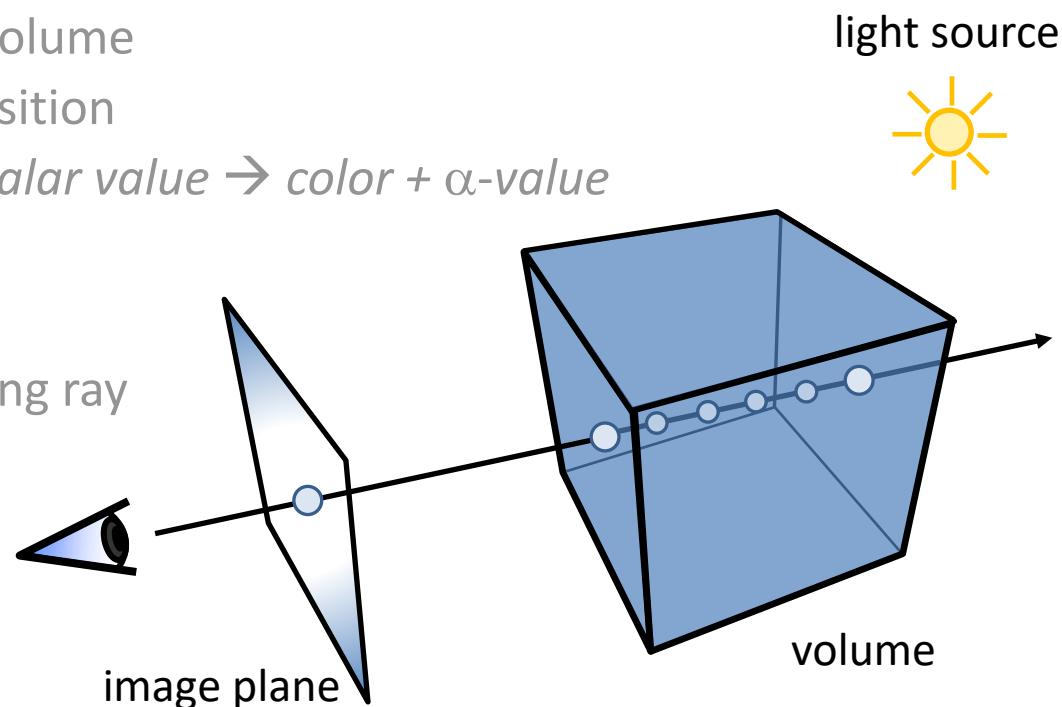
        apply compositing

        compute new position along ray

**end while**

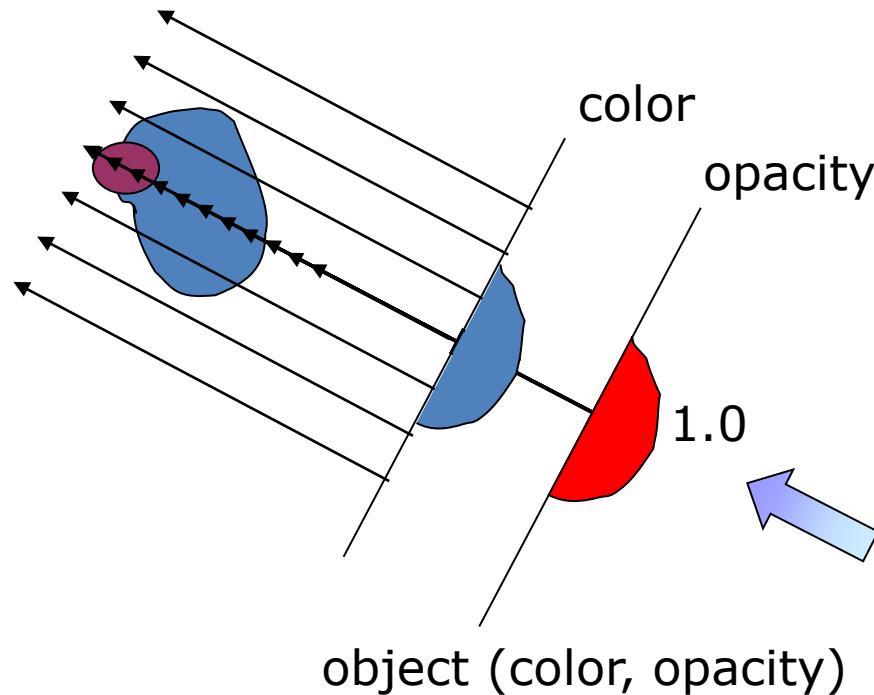
    set pixel color in image plane

**end for**

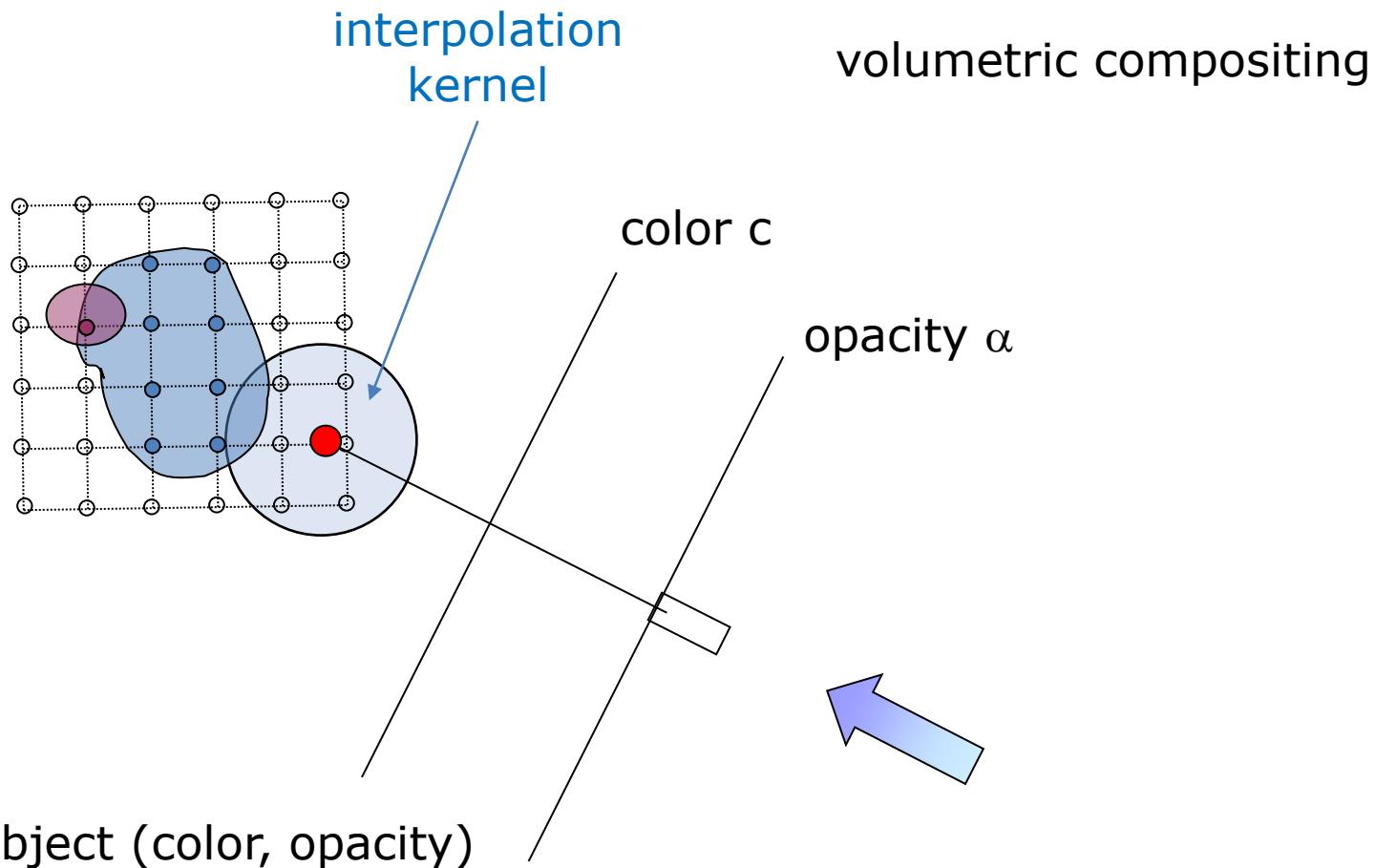


# Ray casting

- Volumetric ray integration:
  - **Compositing:** accumulation of color & opacity along rays

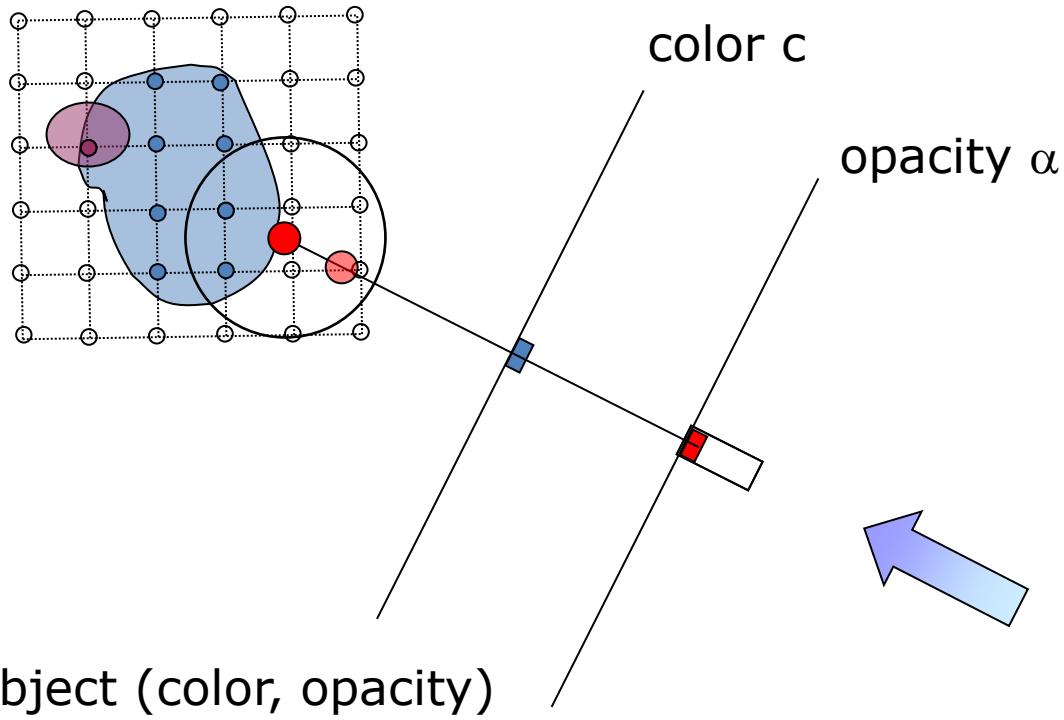


# Ray casting



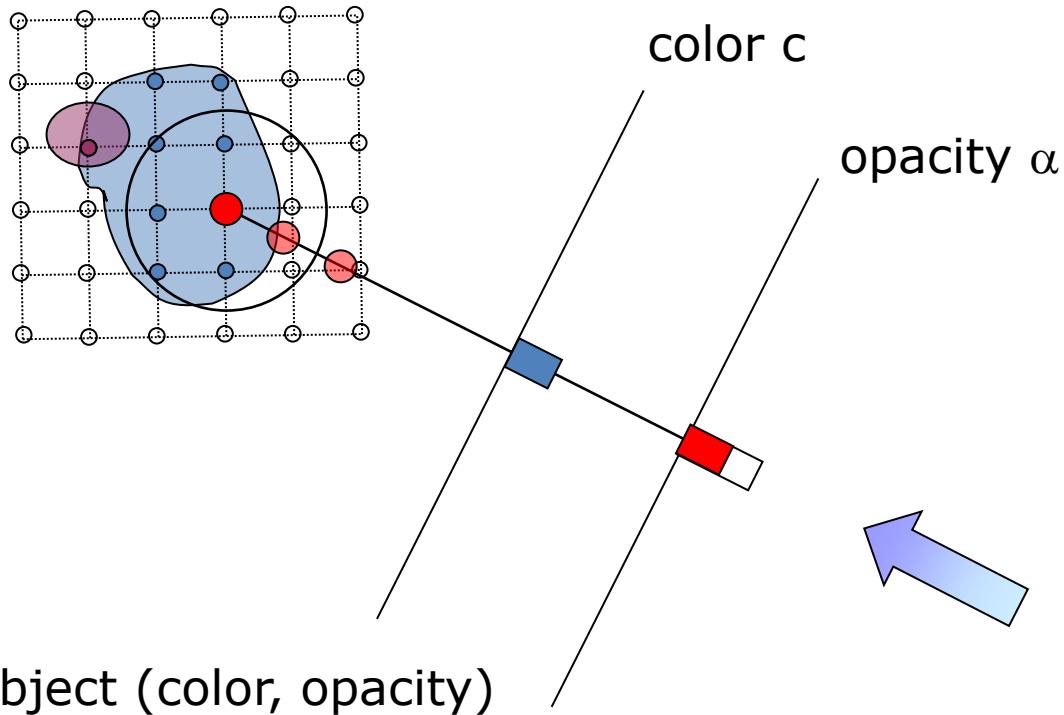
# Ray casting

volumetric compositing



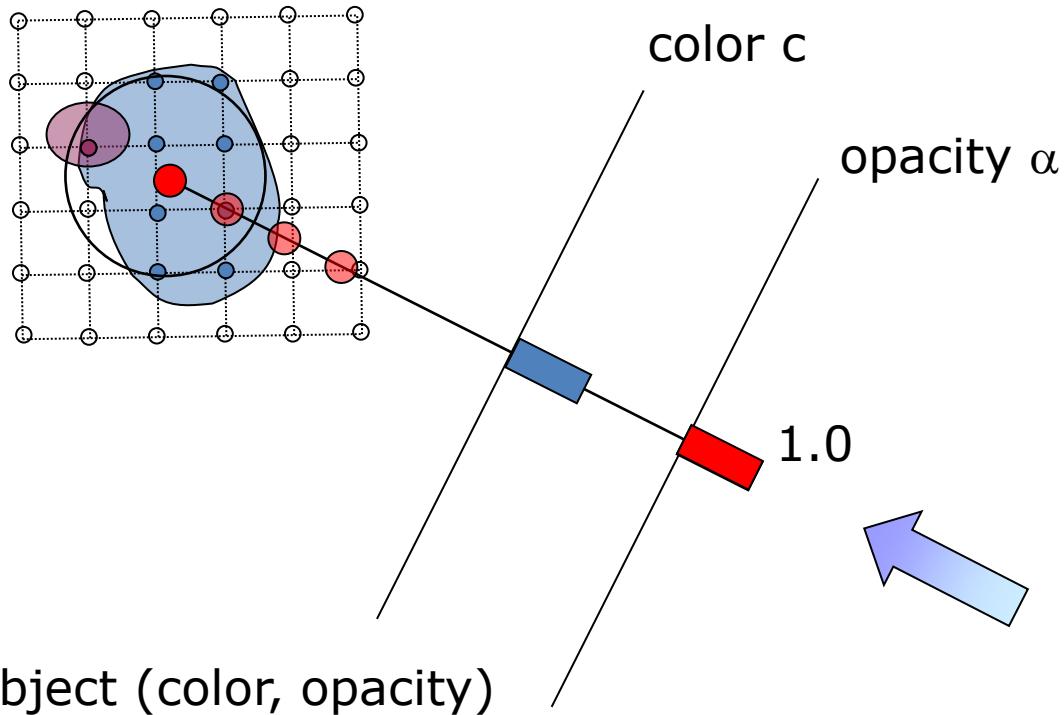
# Ray casting

volumetric compositing



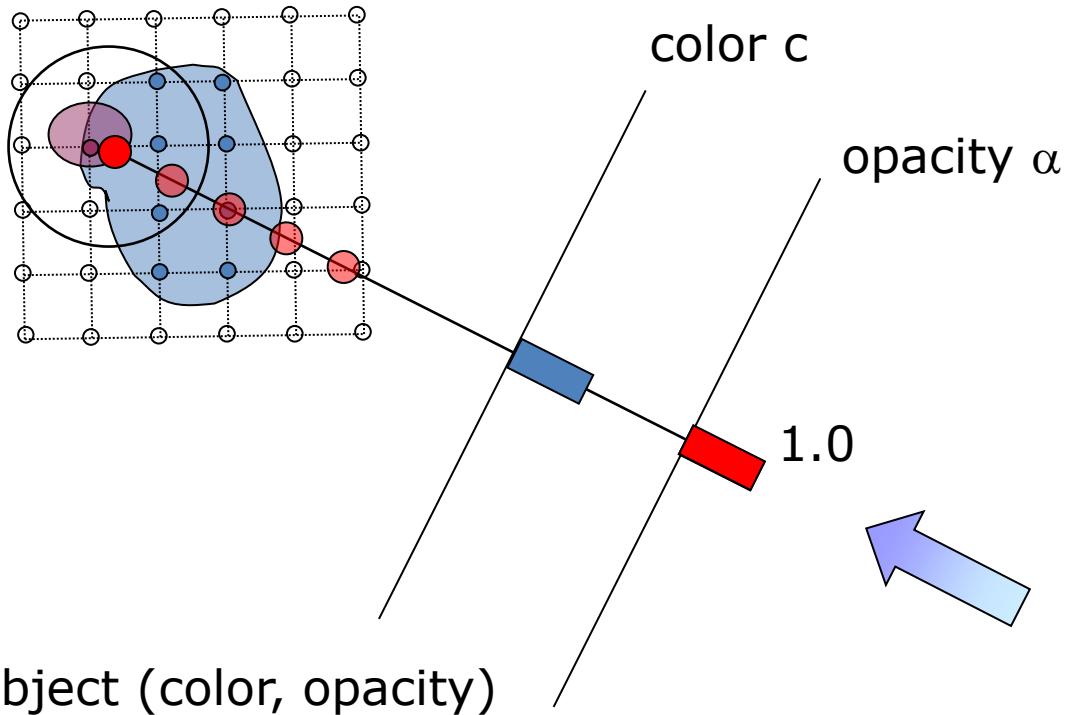
# Ray casting

volumetric compositing



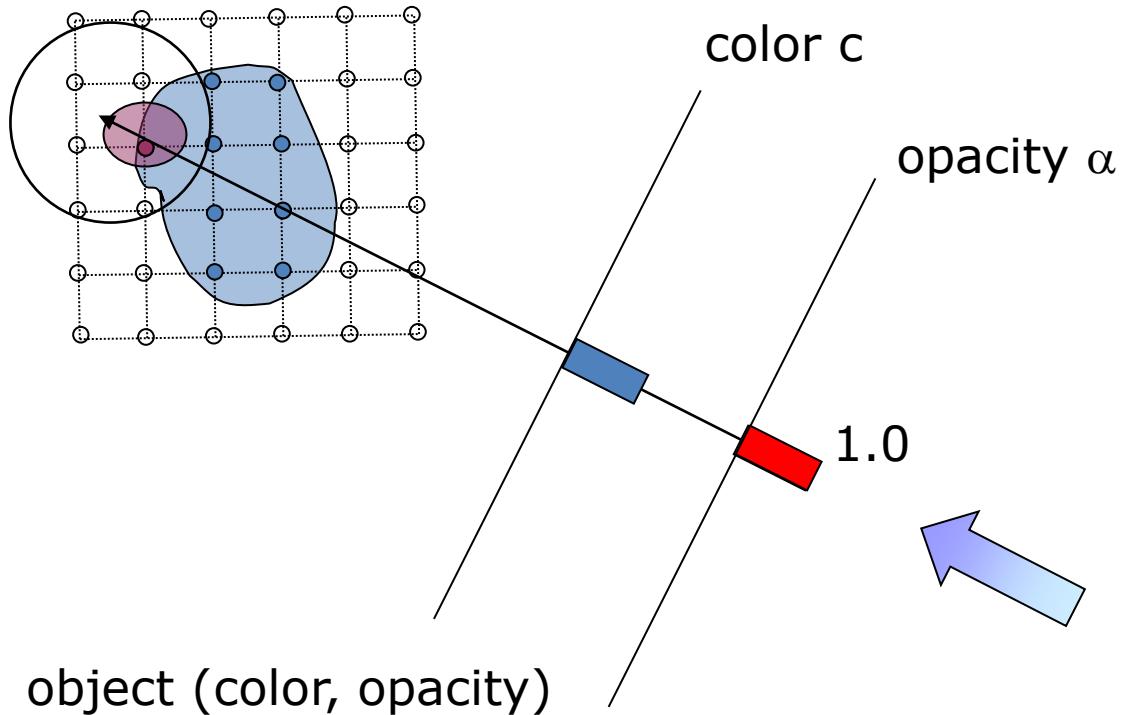
# Ray casting

volumetric compositing



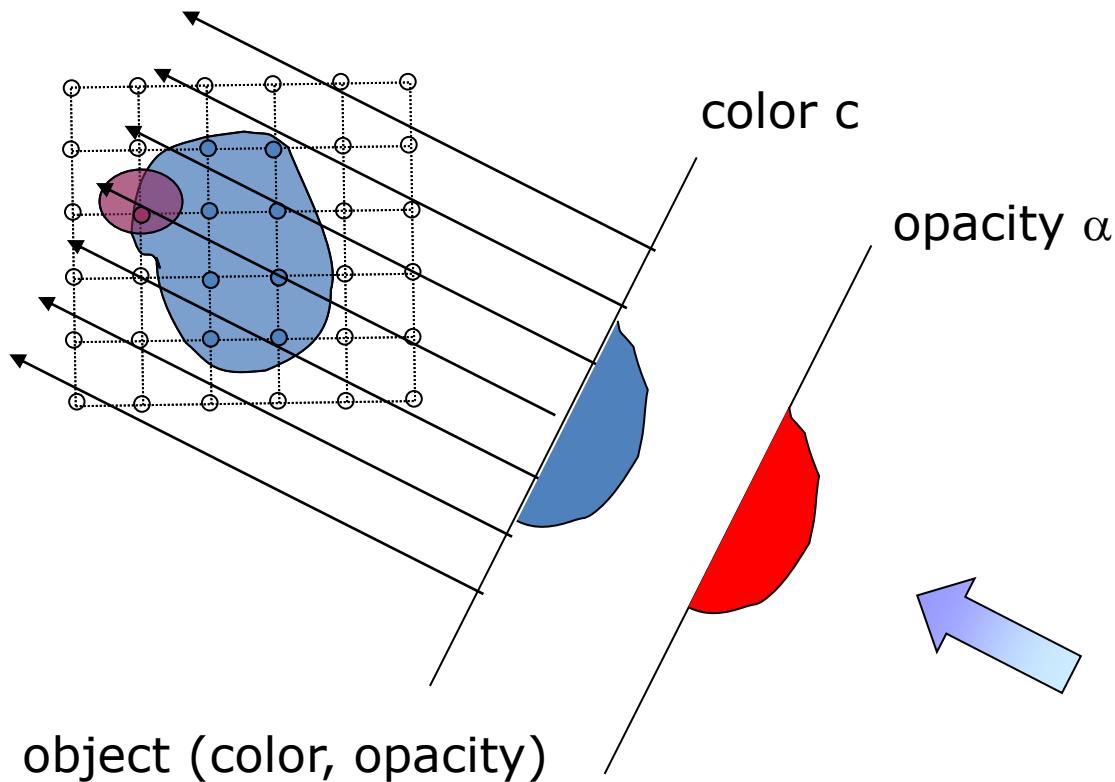
# Ray casting

volumetric compositing



# Ray casting

volumetric compositing

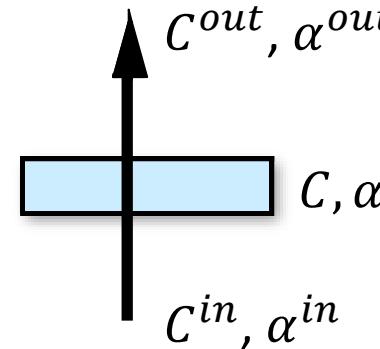


# Ray casting

- Compositing of semi-transparent voxels
  - Physical model: emissive gas with color  $C$  and opacity  $\alpha$
  - Front-to-back strategy,  
starts with  $C^{in} = (0,0,0)$  and  $\alpha^{in} = 0$

$$C^{out} = C^{in} + (1 - \alpha^{in}) \alpha C$$

$$\alpha^{out} = \alpha^{in} + (1 - \alpha^{in}) \alpha$$



front-to-back  
strategy



# Ray casting

- Example

$\alpha = 1 \rightarrow$  completely opaque

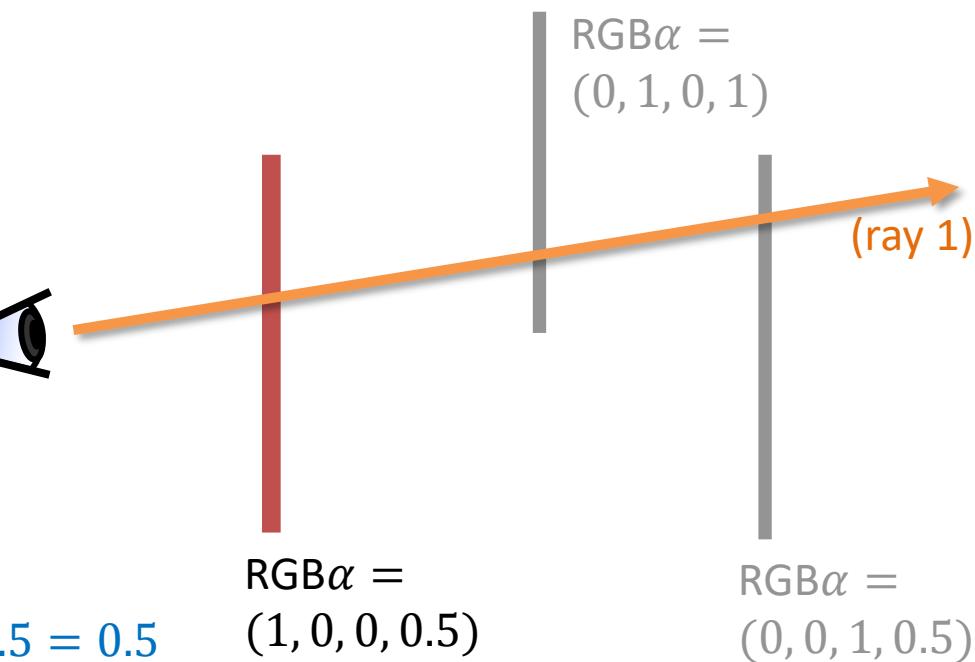
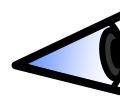
$\alpha = 0 \rightarrow$  completely transparent

$$\text{Ray 1: } C_{in} = (0, 0, 0)^T \quad \alpha_{in} = 0$$

$$C_{out} = C_{in} + (1 - \alpha_{in}) \alpha C$$

$$= \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} + (1 - 0) 0.5 \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} = \begin{pmatrix} 0.5 \\ 0 \\ 0 \end{pmatrix}$$

$$\alpha_{out} = \alpha_{in} + (1 - \alpha_{in}) \alpha = 0 + (1 - 0) 0.5 = 0.5$$



# Ray casting

- Example

$\alpha = 1 \rightarrow$  completely opaque

$\alpha = 0 \rightarrow$  completely transparent

$$\text{Ray 1: } C_{in} = (0, 0, 0)^T \quad \alpha_{in} = 0$$

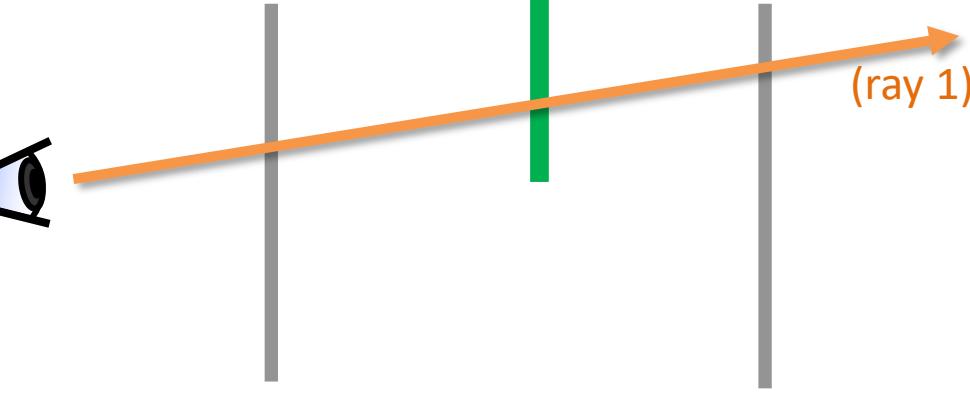
$$C_{out} = C_{in} + (1 - \alpha_{in}) \alpha C$$

$$= \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} + (1 - 0) 0.5 \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} = \begin{pmatrix} 0.5 \\ 0 \\ 0 \end{pmatrix}$$

$$\alpha_{out} = \alpha_{in} + (1 - \alpha_{in}) \alpha = 0 + (1 - 0) 0.5 = 0.5$$

$$C_{out} = \begin{pmatrix} 0.5 \\ 0 \\ 0 \end{pmatrix} + (1 - 0.5) 1 \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} = \begin{pmatrix} 0.5 \\ 0.5 \\ 0 \end{pmatrix}$$

$$\alpha_{out} = 0.5 + (1 - 0.5) 1 = 1$$



$$\text{RGB}\alpha = (1, 0, 0, 0.5)$$

$$\text{RGB}\alpha = (0, 0, 1, 0.5)$$

## Early ray termination:

Stop calculation when  $\alpha_{out} \approx 1$

# Ray casting

- Example

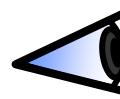
$\alpha = 1 \rightarrow$  completely opaque

$\alpha = 0 \rightarrow$  completely transparent

$$\text{Ray 1: } C_{in} = (0, 0, 0)^T \quad \alpha_{in} = 0$$

$$C_{out} = C_{in} + (1 - \alpha_{in}) \alpha C$$

$$= \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} + (1 - 0) 0.5 \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} = \begin{pmatrix} 0.5 \\ 0 \\ 0 \end{pmatrix}$$



$$\alpha_{out} = \alpha_{in} + (1 - \alpha_{in}) \alpha = 0 + (1 - 0) 0.5 = 0.5$$

$$C_{out} = \begin{pmatrix} 0.5 \\ 0 \\ 0 \end{pmatrix} + (1 - 0.5) 1 \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} = \begin{pmatrix} 0.5 \\ 0.5 \\ 0 \end{pmatrix}$$

$$\alpha_{out} = 0.5 + (1 - 0.5) 1 = 1$$

$$C_{out} = \begin{pmatrix} 0.5 \\ 0.5 \\ 0 \end{pmatrix} + (1 - 1) 0.5 \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} = \begin{pmatrix} 0.5 \\ 0.5 \\ 0 \end{pmatrix}$$

$$\alpha_{out} = 1 + (1 - 1) 0.5 = 1$$

$RGB\alpha = (0, 1, 0, 1)$

(ray 1)

$RGB\alpha = (1, 0, 0, 0.5)$

$RGB\alpha = (0, 0, 1, 0.5)$

## Early ray termination:

Stop calculation when  $\alpha_{out} \approx 1$

Last object does not affect result since  $\alpha_{in} = 1$

# Ray casting

- Example

$\alpha = 1 \rightarrow$  completely opaque

$\alpha = 0 \rightarrow$  completely transparent

$$\text{Ray 2: } C_{in} = (0, 0, 0)^T \quad \alpha_{in} = 0$$

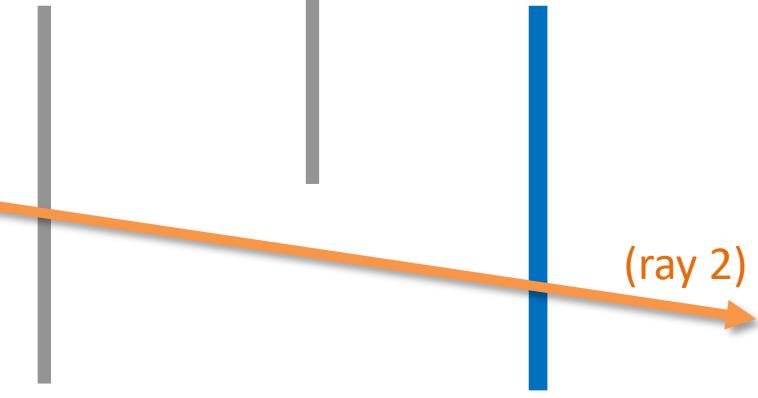
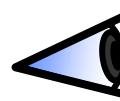
$$C_{out} = C_{in} + (1 - \alpha_{in}) \alpha C$$

$$= \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} + (1 - 0) 0.5 \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} = \begin{pmatrix} 0.5 \\ 0 \\ 0 \end{pmatrix}$$

$$\alpha_{out} = \alpha_{in} + (1 - \alpha_{in}) \alpha = 0 + (1 - 0) 0.5 = 0.5$$

$$C_{out} = \begin{pmatrix} 0.5 \\ 0 \\ 0 \end{pmatrix} + (1 - 0.5) 0.5 \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} = \begin{pmatrix} 0.5 \\ 0 \\ 0.25 \end{pmatrix}$$

$$\alpha_{out} = 0.5 + (1 - 0.5) 0.5 = 0.75$$



$\text{RGB}\alpha = (0, 1, 0, 1)$

$\text{RGB}\alpha = (1, 0, 0, 0.5)$

$\text{RGB}\alpha = (0, 0, 1, 0.5)$

# Lighting

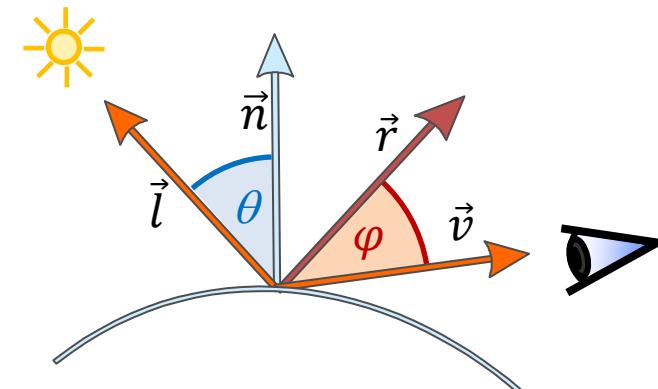
- Evaluate Phong's illumination model based on...
  - position of current sample and light source
  - samples' color emission assigned by transfer function
  - sample's normal / gradient (e.g., central differences)



DVR without shading



Phong shading



# Ray casting

- Gradient estimation
  - The gradient vector (normal) is the first-order derivative of the scalar field

$$\nabla f(\mathbf{x}) = \left( \begin{array}{c} \frac{\partial}{\partial x} f(\mathbf{x}) \\ \frac{\partial}{\partial y} f(\mathbf{x}) \\ \frac{\partial}{\partial z} f(\mathbf{x}) \end{array} \right)$$

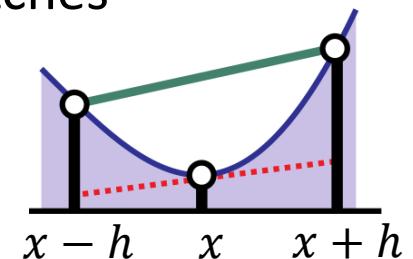
The diagram illustrates the components of the gradient vector. A blue bracket on the right side of the vector equation groups the three partial derivatives. Three blue arrows point from these grouped terms to three separate blue boxes, each containing the text "partial derivative in x-direction", "partial derivative in y-direction", and "partial derivative in z-direction" respectively.

- We can estimate the gradient using finite differencing schemes (e.g., forward or central differences)

# Ray casting

- Gradient estimation
  - Compute **on-the-fly** within fragment shader
    - Central differences require 6 additional texture fetches
  - Pre-compute and store together with voxel data
    - Pack into 3D RGBA texture for GPU-based rendering
    - One lookup to get interpolated gradient + value
    - Requires more memory → not applicable for large volume data

$$\nabla f(x, y, z) \approx \frac{1}{2h} \begin{pmatrix} f(x + h, y, z) - f(x - h, y, z) \\ f(x, y + h, z) - f(x, y - h, z) \\ f(x, y, z + h) - f(x, y, z - h) \end{pmatrix}$$



Voxel Data

- X Gradient
- Y Gradient
- Z Gradient
- Value

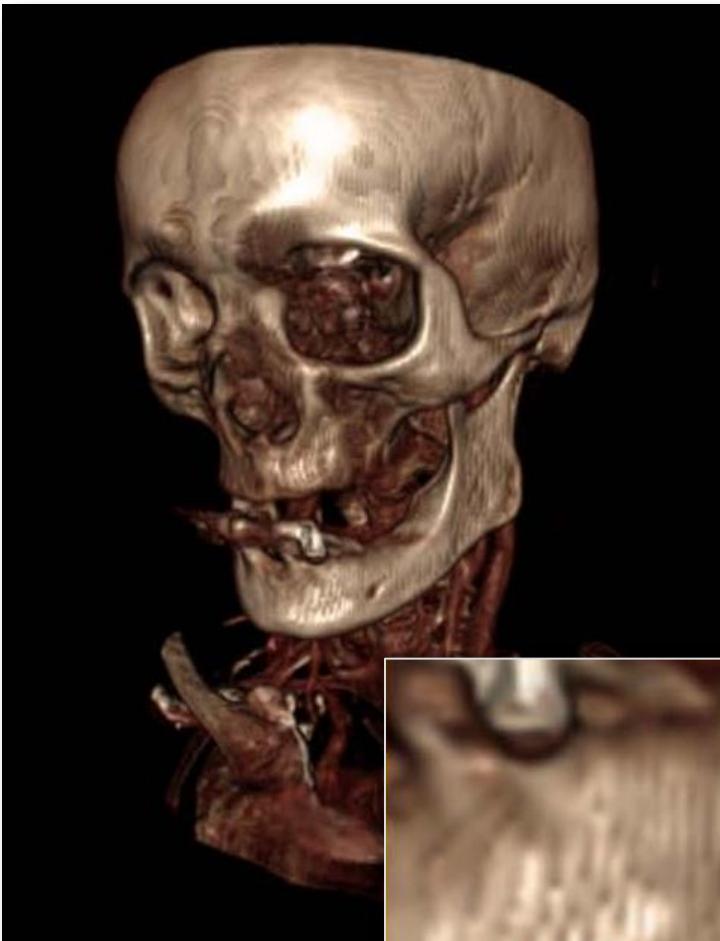


3D Texture

- R
- G
- B
- A

# Ray casting

- Gradient estimation



Pre-computed,  
8 bit per component



on-the-fly  
computation

# Ray casting

- Examples

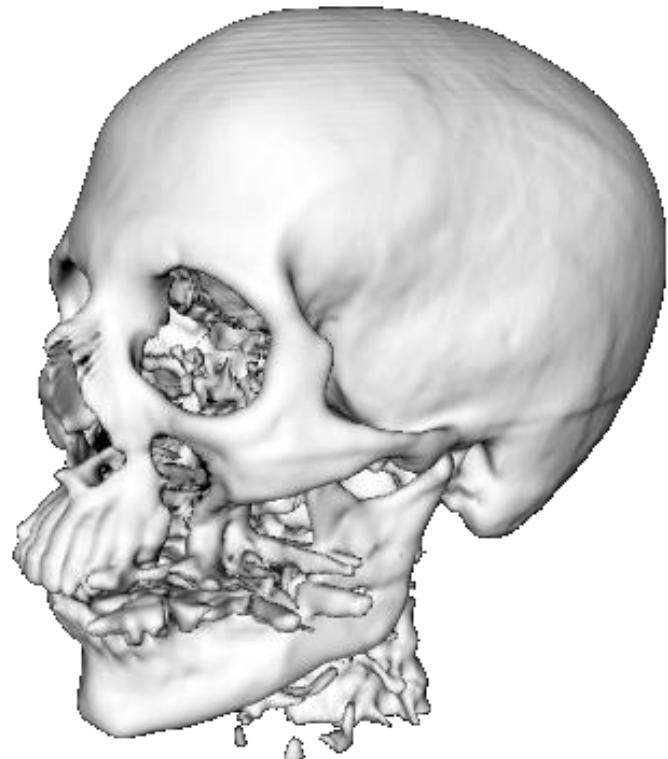
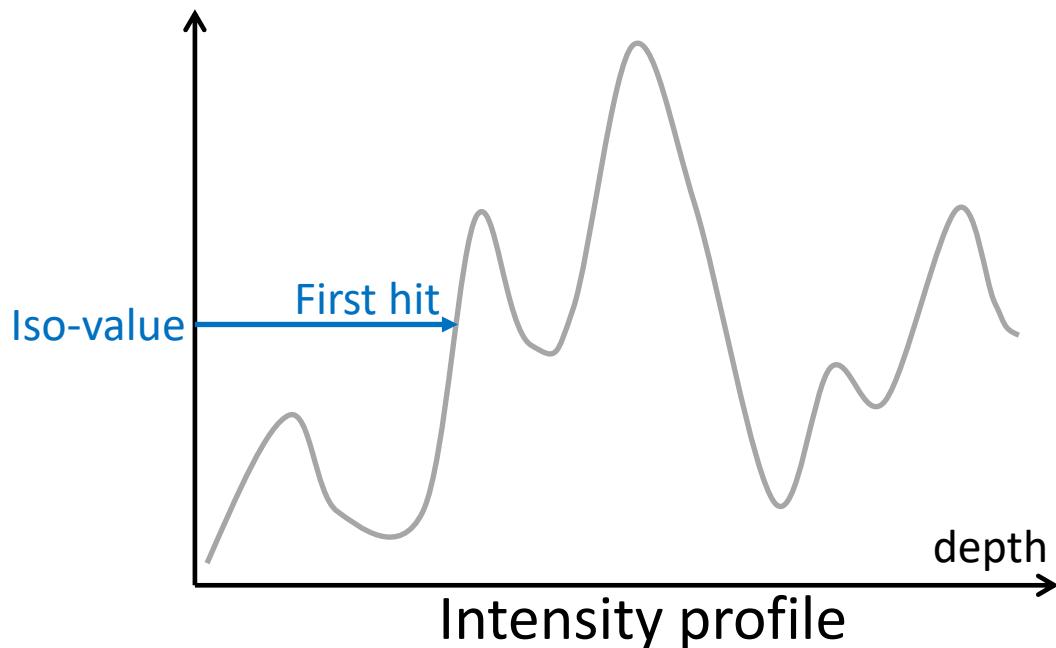


# Compositing Schemes

- Variations of compositing schemes
  - **Surface rendering / first hit**: stop ray traversal if an iso-surface is hit, and shade the surface points
  - **Average**: simply accumulate colors but do not account for opacity
  - **Maximum**: only takes the maximum color along the ray and displays it

# Compositing Schemes

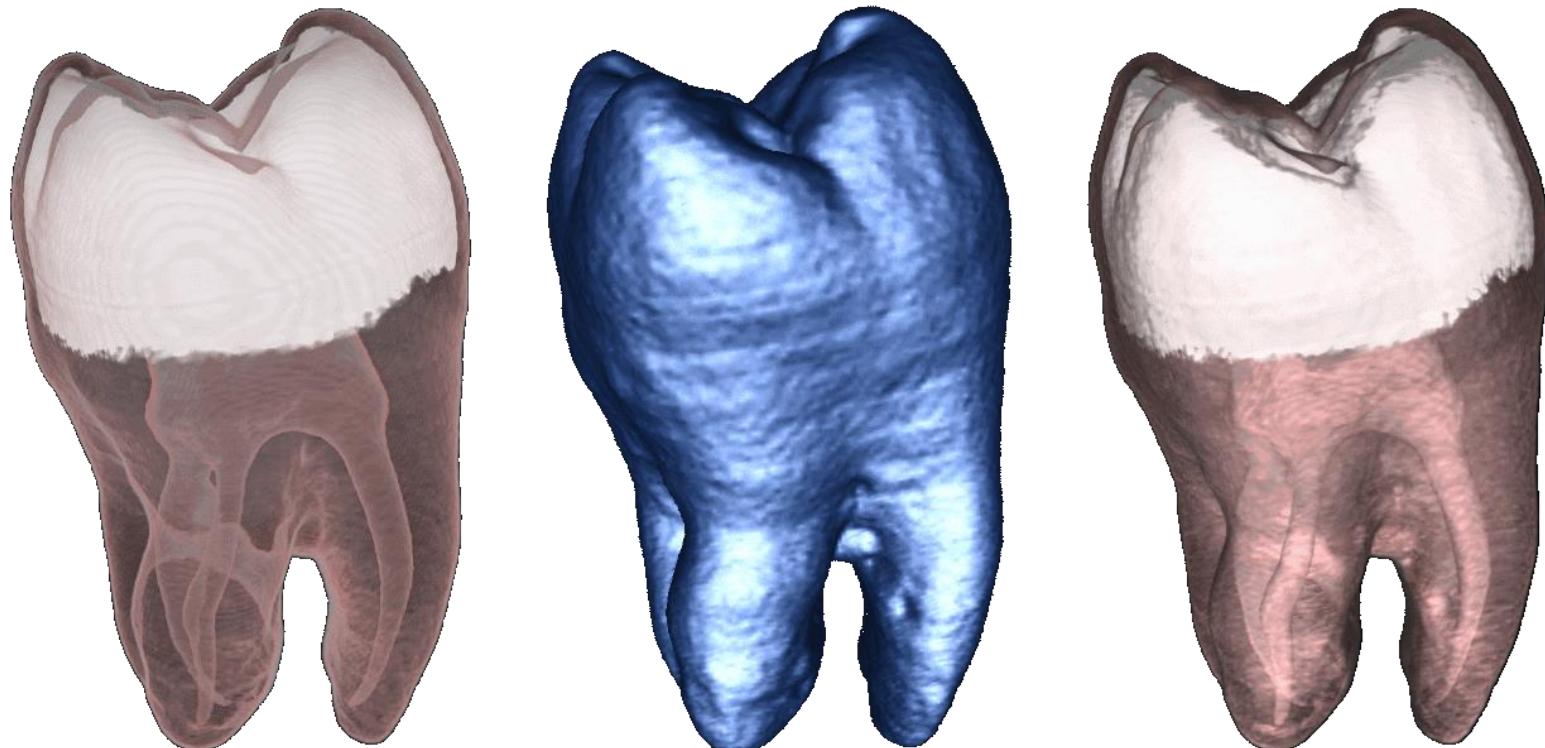
- Surface rendering / first hit
  - Stop ray traversal if an iso-surface is hit, and shade the surface points
  - Produces same result as marching cubes, but with higher accuracy



# Compositing Schemes

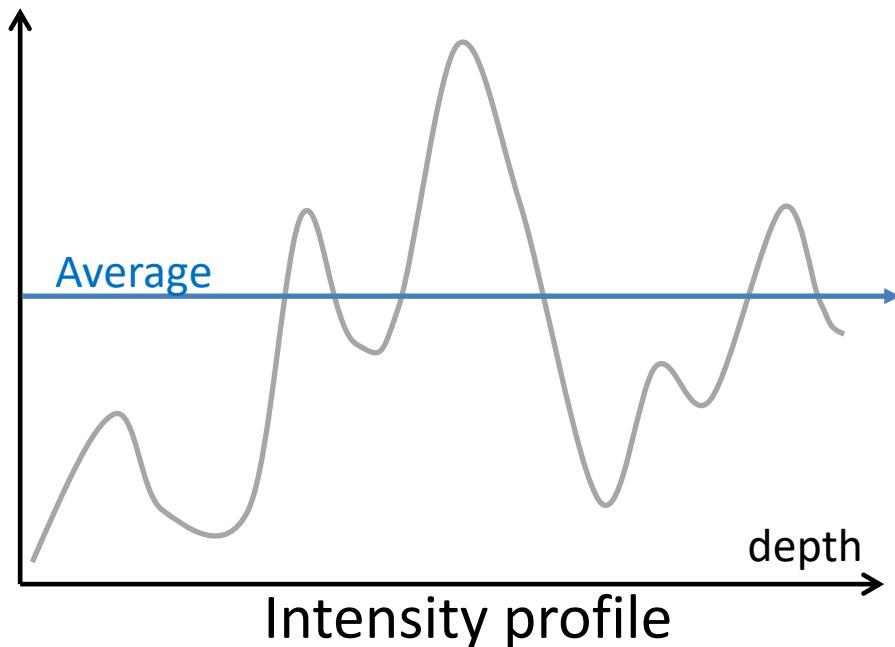
SIEMENS  
Ingenuity for life

- Compositing: First hit (middle image)



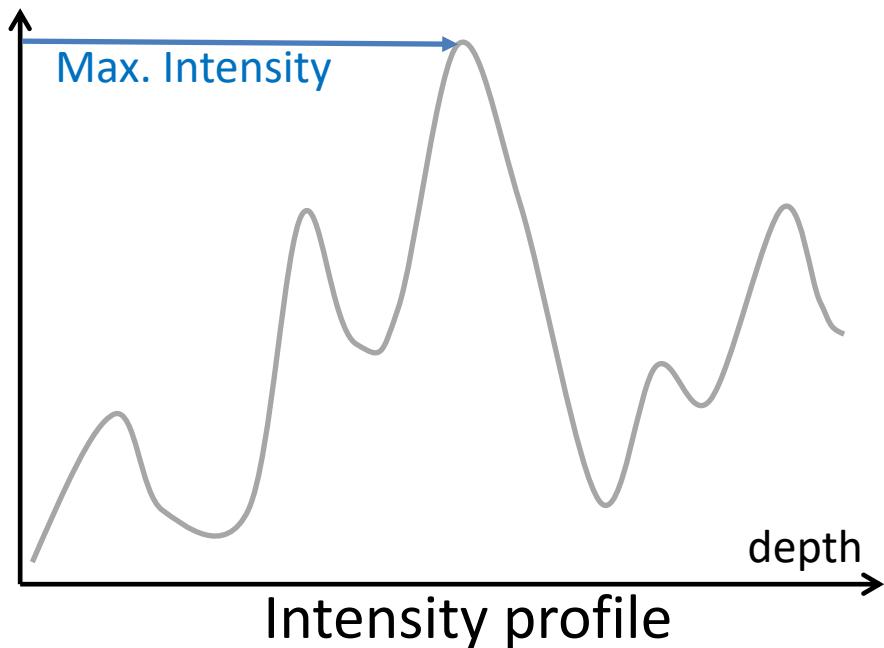
# Compositing Schemes

- Compositing: Average
  - Accumulate colors but do not account for opacity
  - Produces an X-ray image



# Compositing Schemes

- Maximum Intensity Projection (MIP)
  - Only takes the maximum color along the ray and displays it



# Compositing Schemes

- Maximum Intensity Projection (MIP)
  - Often used for magnetic resonance angiograms
  - Good to extract vessel structures



Direct volume rendering



Maximum intensity projection

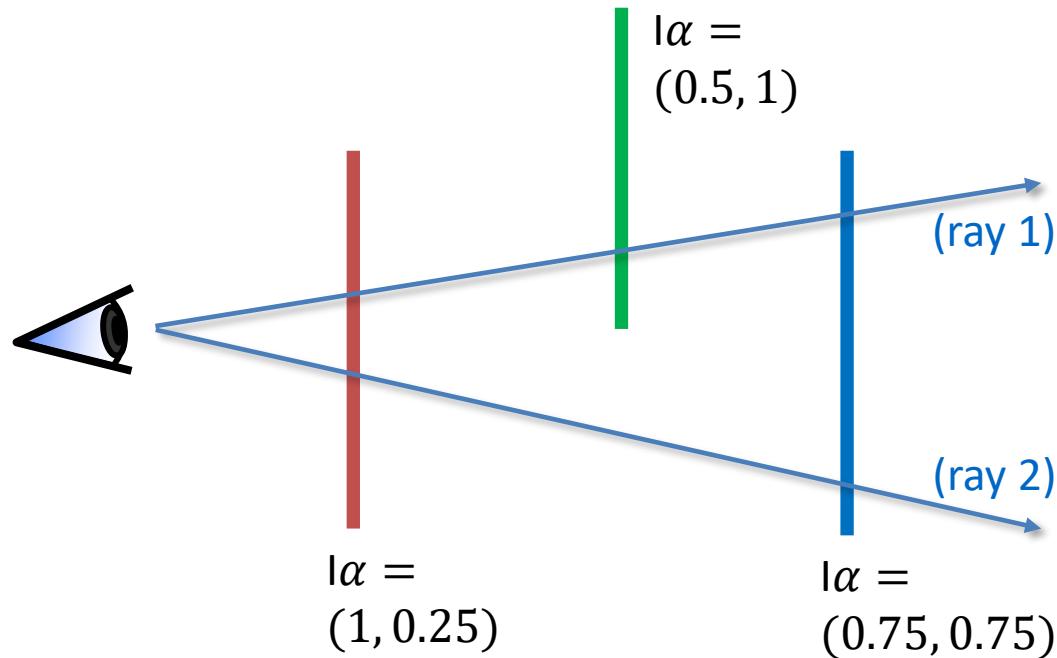
# Ray casting

- Example

$I$  ... intensity

$\alpha = 1 \rightarrow$  completely opaque

$\alpha = 0 \rightarrow$  completely transparent



Ray 1 with average compositing:

$$I_{out} = \frac{1}{3}(1 + 0.5 + 0.75) = 0.75$$

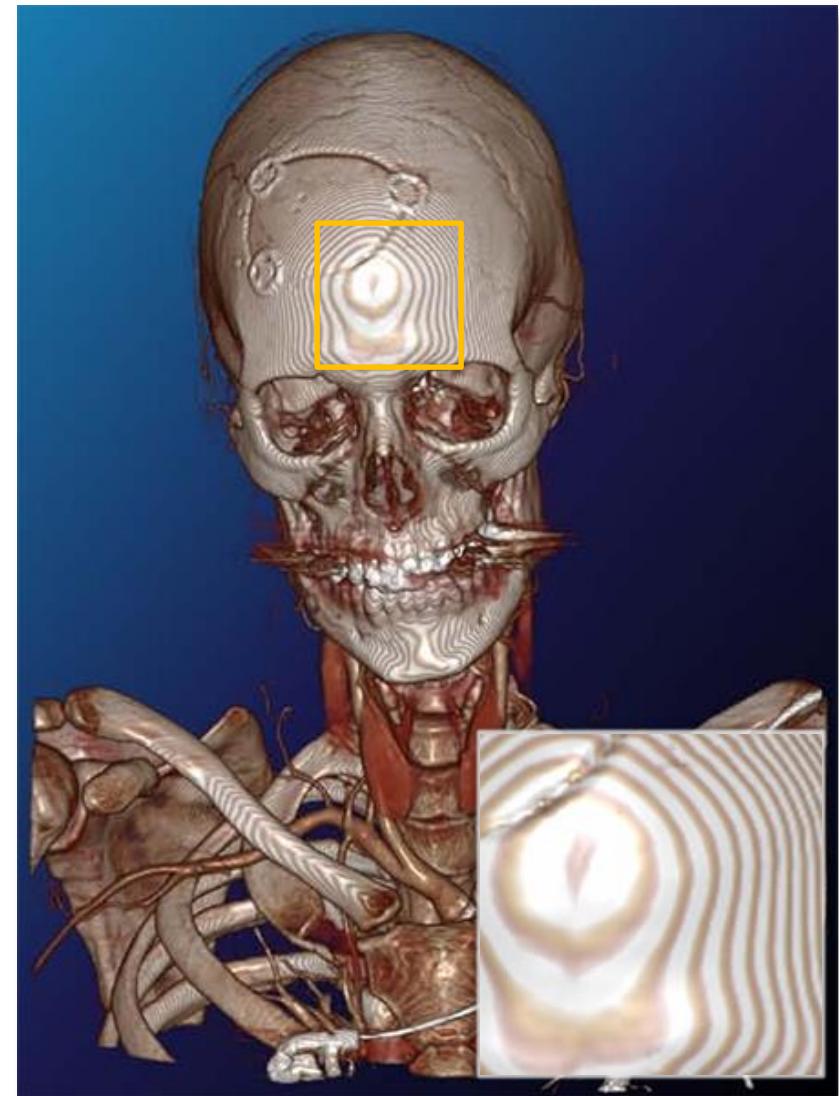
Ray 2 with maximum intensity projection:

$$I_{out} = \max(1, 0.75) = 1$$

Both average compositing and MIP do not account for opacity

# Ray casting

- Sampling artifacts
  - Too few samples along the ray
  - Solution: Increase sampling rate to Nyquist frequency  
→ at least 2 samples per voxel



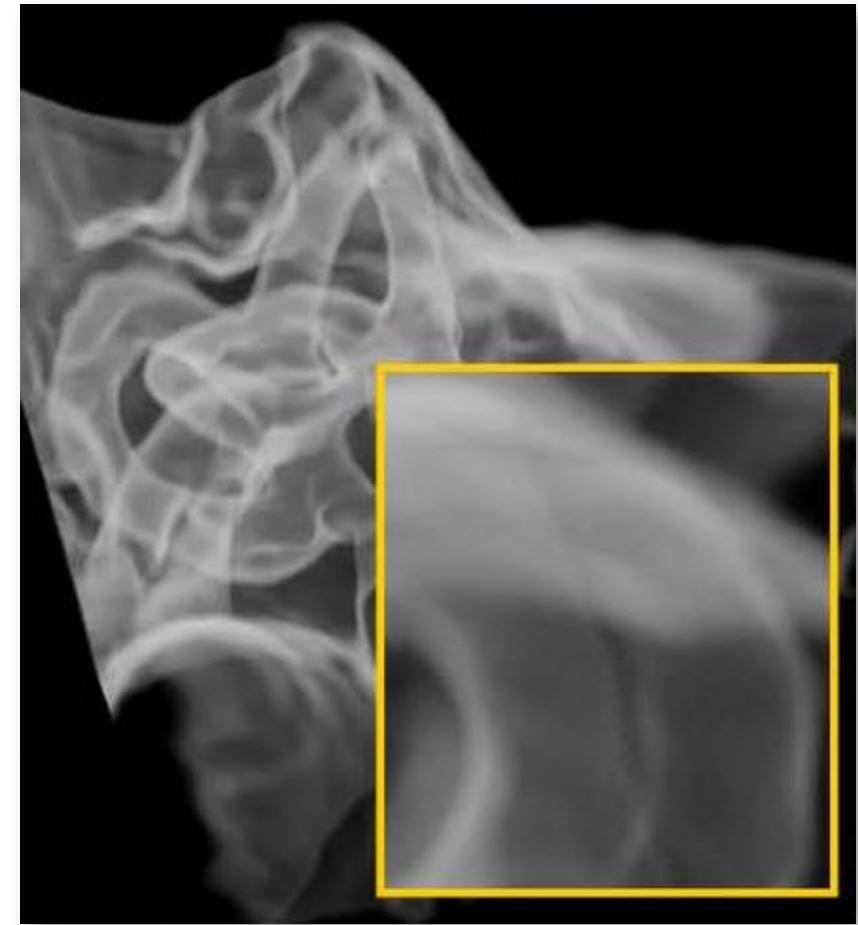
[Engel et al. 06]

# Ray casting

- Sampling artifacts



128 samples



284 samples

# Ray casting

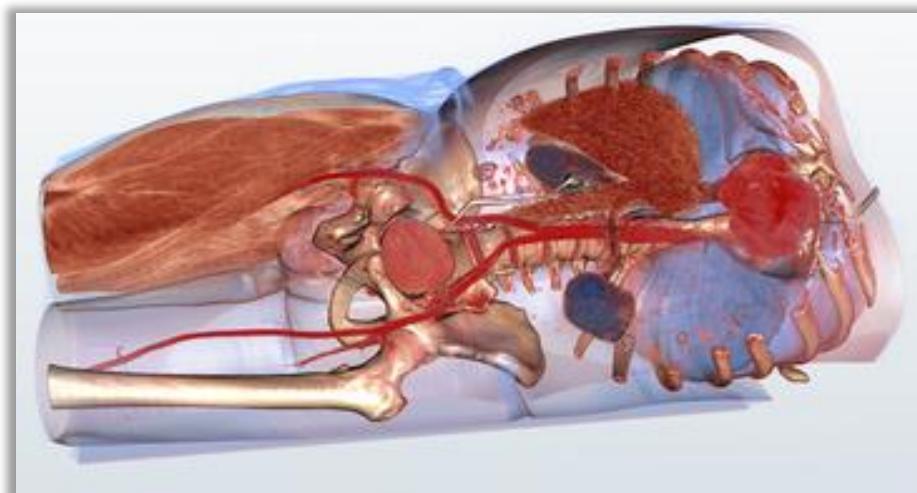
- Remove artifacts by stochastic jittering of ray-start position



[Engel et al. 06]

# Summary

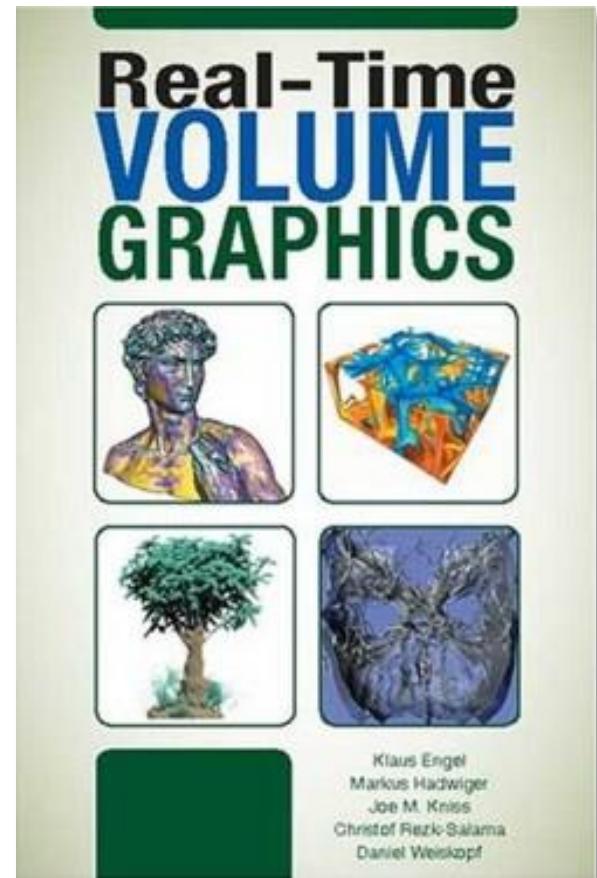
- Surface rendering
  - Indirect representation
  - Conveys surface impression
  - Hardware supported rendering (fast?!)
  - Iso-value-definition
- Direct volume rendering
  - Direct representation
  - Conveys volume impression
  - Often realized in software (slow?!)
  - Transfer function specification



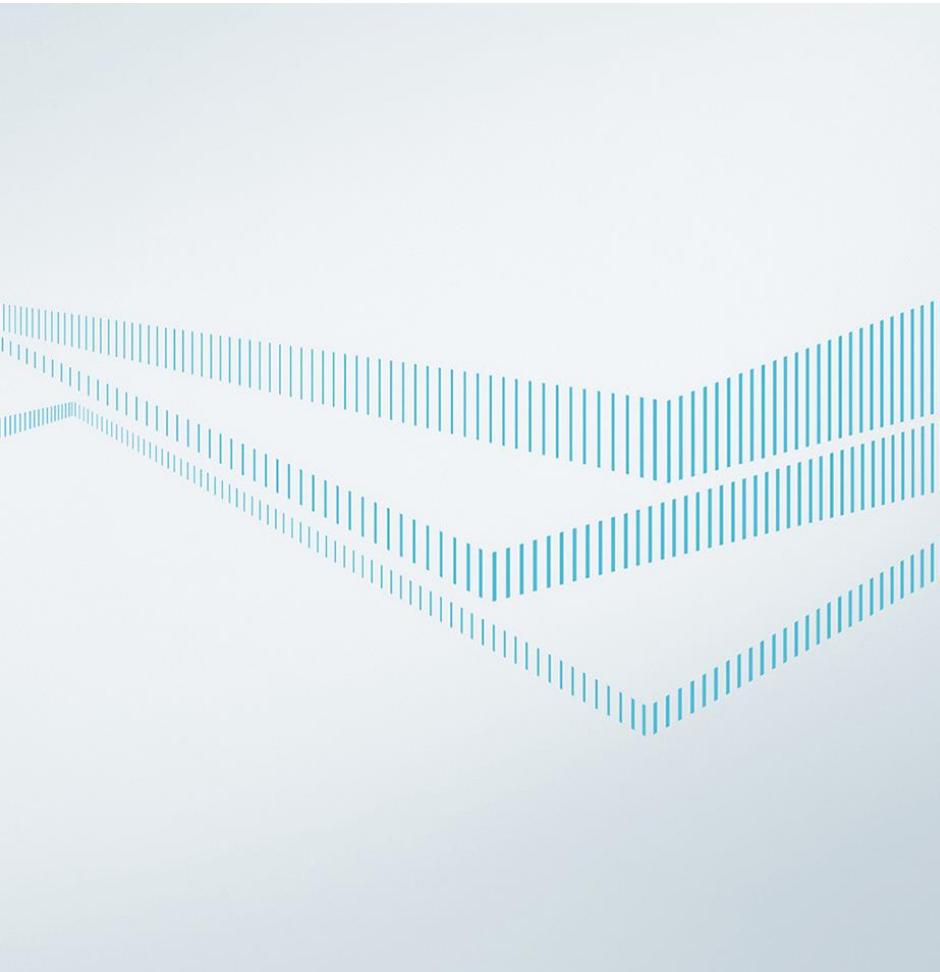
# Further Resources

**SIEMENS**  
Ingenuity for life

- Engel et al. 06:  
Real-time volume graphics
- Tutorial slides:  
[www.real-time-volume-graphics.org](http://www.real-time-volume-graphics.org)



# Contact information



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