

Yusuf Hasan

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EDUCATION

University of British Columbia

Bachelor of Applied Science, Electrical Engineering

Vancouver, BC

Expected: May 2026

EXPERIENCE

Hardware Pre-Development Intern

June 2024 – April 2025

Robert Bosch Gmbh (Bosch)

Reutlingen, Germany

- Designed **STM32-based** sensor test and data-collection **PCBs** with onboard memory and multiple interfaces (FDCAN, SPI, I²C, UART, USB3300), enabling evaluation of **next-generation MEMS inertial sensors** at >12.8kHz in **Altium**
- Wrote efficient **C firmware** to validate sensor functionality and performed data collection and analysis on 10+ **automotive MEMS sensors** concurrently during field testing
- Analyzed and evaluated IMU data in **Matlab and Python** to characterize next-generation sensor performance (bias, noise, offset, sensitivity) under different vibration/stimulus profiles
- Researched and Developed robust measurement scheme to perform **characterization** MEMS gyroscope sensitivity to static linear acceleration (Offset G-sensitivity) using a modified maytagging approach accounting for the projections of earths rotation using **Python**
- Prepared a research on MEMS Gyro compassing with an array of consumer grade, 6-DoF IMUs

Automation Intern

May 2023 – August 2023

Inter Pipeline

Calgary, AB

- Automated service desk ticket routing and developed a generative AI service desk chatbot using Azure services saving a projected \$150,000 per year
- Utilized Azure API Management and REST to connect Cherwell Ticket Management to Microsoft Teams environment and automated HTTP requests for users through an authentication token system

RESEARCH/DESIGN TEAM EXPERIENCE

Undergraduate Research Assistant

Jan 2026 – Present

Radio Science Laboratory, University of British Columbia

Vancouver, BC

- Configured, tested, and monitored Weak Signal Propagation Reporting (WSPR)** transmitters for long-range HF propagation experiments
- Supported deployment of **WSPR** payloads aboard maritime platforms for ionospheric and propagation studies
- Assisted in **data collection** and analysis for **signal propagation characterization** under varying environmental conditions

Applied AI Developer

Sep. 2023 – Jan 2024

UBC AgroBot

Vancouver, BC

- Fine-tuned a faster R-CNN** to perform real-time weed detection in an autonomous agriculture robot in Python using TensorFlow and OpenCV
- Developed and implemented **image processing pipeline** for 2000+ images to create weed detection dataset

PROJECTS

Hybrid Localization Unit | C, Python, ESKF, PCB design, IMU

Sep 2025 – Present

- Designed and implemented a **sensor fusion system** combining **UWB ranging** and **inertial measurements** for indoor localization for indoor robotics applications
- Developed an **Modelled and tuned Error State Kalman Filter (ESKF)** for real-time sensor fusion of IMU and UWB data and implemented algorithm in C and physical hardware module
- Designed MCU PCB** with DWM3000 UWB module and MEMS IMUs and integrated sensor fusion algorithm

Two-Stage CMOS Operational Amplifier Design | Cadence Virtuoso, CMOS, Analog IC Design

Dec 2026

- Designed and simulated a **two-stage CMOS operational amplifier** in a **45 nm process** using Cadence Virtuoso
- Implemented a **fully differential first stage with common-mode feedback (CMFB)** and a **common-source second stage**
- Achieved **47.5 dB DC gain**, **616 MHz unity-gain frequency**, and **61° phase margin** under strict power requirements
- Performed **DC, AC, and transient analysis** including slew-rate, step response, and stability verification

TECHNICAL SKILLS

Software: C, Python, MATLAB, System Verilog, 8051 Assembly, ARM Assembly, JSON

Electrical: Altium, Cadence, PSIM, KiCad, LTspice, SolidWorks, Logic Analyser, Function Generator, Oscilloscopes

Development Tools: Git, Azure, Simulink, STM32 CubeIDE, Quartus, VS Code, Power BI, TensorFlow, PyTorch