

①

Input: Directed (or non-directed) graph $G = (V, E)$
↓ ↓
Vertices Edges

- Each edge has nonnegative len. l_e .
- Source vertex s .

Output : For each $v \in V$, compute

$L(v) :=$ length of a shortest $s-v$ path in G .

Assumptions:

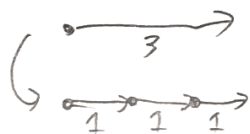
① [for convenience] $\forall v \in V, \exists$ an $s \rightsquigarrow v$ path. (Can use DFS, BFS for preprocessing to get rid of unreachable vertex)

② [Important] $l_e \geq 0 \quad \forall e \in E$

Is BFS enough?

\Rightarrow Yes, IF $l_e = 1$ for every edge e .

Can we replace the edges by unit length edges and do BFS?



\Rightarrow Blows up the graph too much.

Pseudo Code

(2)

Initialize: (Source vertex = s)

- $X = [s]$ [Explored vertices]
- $A[s] = 0$ [A : Func. to compute shortest path to dist. from s]
- $B[s] = \text{None}$ [Computed shortest path. Not needed in actual implementation]

Main loop

While $X \neq V$

$v \longrightarrow w$

- From edges $(v, w) \in E$ with $v \in X, w \notin X$, pick the one that minimizes

$$A[v] + l_{vw} \quad \left(\begin{array}{l} \text{Dijkstra's} \\ \text{greedy} \\ \text{criterion} \end{array} \right)$$

- add w^* to X mean the best choice
- Set $A[w^*] := A[v^*] + l_{v^*w^*}$
- Set $B[w^*] := B[v^*] \cup (v^*, w^*)$

\Rightarrow In naive implementation $O(m \cdot n)$.

while loop: $(n-1)$ iteration
 $O(m)$ for each loop

\Rightarrow How the data structure help us?

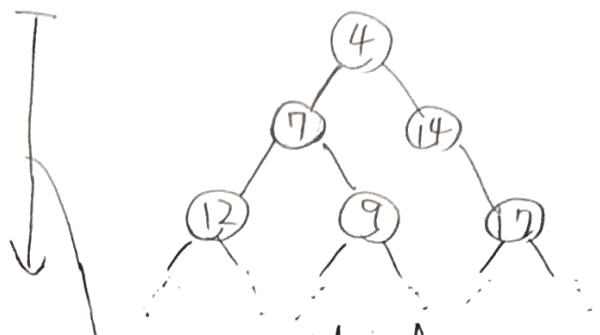
\Rightarrow One of the raison d'être of the data structure, heap, is to how to do the thing minimal.

What is "heap"?

\Rightarrow Conceptually, a perfect balanced binary tree that allows to perform Insert, Extract-min in $O(\log n)$ time.

heap

(3)



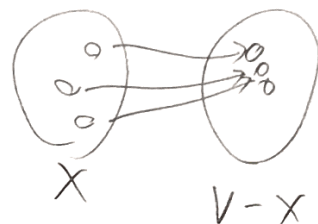
Ideally, height of the tree is $\log_2 n$

- At every node, $\text{key} \leq \text{Children's keys}$
- Root node is the min in tree.
- Extract-min by extract-root followed by heapifying.
- Insert via bubbling up.
- Need ability to delete from middle.

Heap invariants

#1: Elements in heap = vertices of $V-X$.

#2: $\text{key}[v]$ have to be smallest score of an possible edge to visit that node.



\Rightarrow tricky part is to update the key in heap.

\Rightarrow Decrease key

- when w extracted from heap, and added to x .

- For each edge $(w, v) \in E$:

- if $v \in V-X$ (i.e. in heap)

- delete v from heap.

- recompute $\text{key}[v] = \min(\text{key}[v], \underbrace{A[w] + l_{w,v}}_{\text{greedy score to } (w,v)})$

- re-insert v into heap.

Speed of Dijkstra

$\Rightarrow O(m \log n)$ like sorting

fast!